

# Reconstructing initial data using iterative observers for wave type systems. A numerical analysis.

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FRANCE

WAVES 2011 - Simon Fraser University - July, 25–29

Let

- $H$  be a Hilbert space,
- $A_0 : \mathcal{D}(A_0) \rightarrow H$  be a positive self-adjoint operator,

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$$\begin{cases} \ddot{w}(t) + A_0 w(t) = 0, & \forall t \in [0, \infty), \\ w(0) = \textcolor{red}{w}_0 \in \mathcal{D}(A_0), \\ \dot{w}(0) = \textcolor{red}{w}_1 \in \mathcal{D}\left(A_0^{\frac{1}{2}}\right). \end{cases}$$

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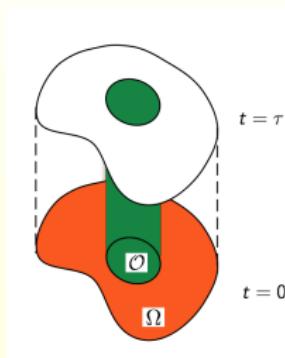
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We observe the velocity  $\dot{w}$  of this system on a non-empty subdomain  $\mathcal{O}$ , over a time interval  $[0, \tau]$ , leading to the measurement

$$y(t) = \chi_{|\mathcal{O}} \dot{w}(t).$$



*Observation on  $\mathcal{O} \times [0, \tau]$ .*

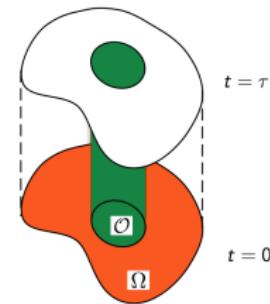
## Our problem

Reconstruct the unknown  $(w_0, w_1)$  in  $\mathcal{D}\left(A_0^{\frac{1}{2}}\right) \times H$  from the measurement  $y(t)$ .

A similar problem arises for instance in Thermo-Acoustic Tomography.

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## 2 Main result

## 3 Numerical study

## 4 Conclusion

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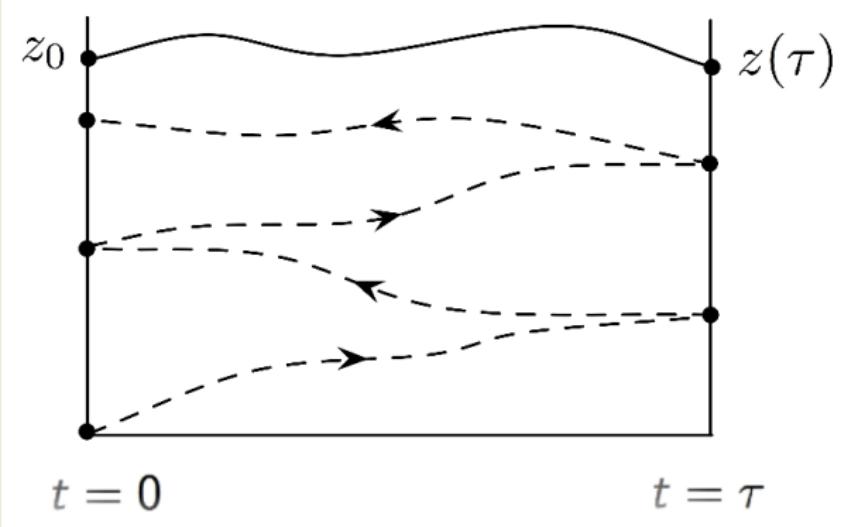
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K. RAMDANI, M. TUCSNAK, AND G. WEISS

*Recovering the initial state of an infinite-dimensional system using observers* (AUTOMATICA, 2010)

### Intuitive representation



2 iterations, observation on  $[0, \tau]$ .

We construct the **forward observer**

$$\begin{cases} \ddot{w}^+(t) + A_0 w^+(t) + \gamma \chi_{|\mathcal{O}} \dot{w}^+(t) = \gamma y(t), \\ w^+(0) = 0, \\ \dot{w}^+(0) = 0, \end{cases} \quad \forall t \in [0, \tau],$$

$$-\begin{cases} \ddot{w}(t) + A_0 w(t) = 0, \\ w(0) = w_0, \\ \dot{w}(0) = w_1, \end{cases} \quad \forall t \in [0, \tau],$$

*remember that  $y(t) = \chi_{|\mathcal{O}} \dot{w}(t)$*

$$= \begin{cases} \ddot{e}(t) + A_0 e(t) + \gamma \chi_{|\mathcal{O}} \dot{e}(t) = 0, \\ e(0) = -w_0, \\ \dot{e}(0) = -w_1, \end{cases} \quad \forall t \in [0, \tau],$$

which is known to be exponentially stable for suitable  $\mathcal{O}$  and  $\tau$  (for instance verifying Geometric Optic Condition of Bardos, Lebeau and Rauch (1992) in the classical wave case) and all  $\gamma > 0$ .

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The exponential stability gives the existence of two constants  $M > 0$  and  $\beta > 0$  such that

$$\|\dot{w}^+(\tau) - \dot{w}(\tau)\| + \|w^+(\tau) - w(\tau)\|_{\frac{1}{2}} \leq M e^{-\beta\tau} \left( \|w_1\| + \|w_0\|_{\frac{1}{2}} \right).$$

We construct a similar system, called **backward observer**.

$$\begin{cases} \ddot{w}^-(t) + A_0 w^-(t) - \gamma \chi_{\mathcal{O}} \dot{w}^-(t) = -\gamma y(t), & \forall t \in [0, \tau], \\ w^-(\tau) = w^+(\tau), \\ \dot{w}^-(\tau) = w^+(\tau), \end{cases}$$

Then, we easily get that

$$\begin{aligned} \|\dot{w}^-(0) - w_1\| + \|w^-(0) - w_0\|_{\frac{1}{2}} \\ \leq M e^{-\beta\tau} \left( \|\dot{w}^+(\tau) - \dot{w}(\tau)\| + \|w^+(\tau) - w(\tau)\|_{\frac{1}{2}} \right), \\ \leq M e^{-2\beta\tau} \left( \|w_1\| + \|w_0\|_{\frac{1}{2}} \right). \end{aligned}$$

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Ito, Ramdani and Tucsnak (2011) showed that  $\alpha := M e^{-2\beta\tau} < 1$ . Thus the reconstruction of  $(w_0, w_1)$  can be achieved by iterating these two systems by taking  $(w^+(0), \dot{w}^+(0)) = (w^-(0), \dot{w}^-(0))$ . This leads to the algorithm

$$\begin{cases} \ddot{w}_n^+(t) + A_0 w_n^+(t) + \gamma \chi|_{\mathcal{O}} \dot{w}_n^+(t) = \gamma y(t), \\ w_n^+(0) = w_{n-1}^-(0), \quad n \geq 1, \quad w_0^+(0) = 0, \\ \dot{w}_n^+(0) = \dot{w}_{n-1}^-(0), \quad n \geq 1, \quad \dot{w}_0^+(0) = 0, \end{cases} \quad \forall t \in [0, \tau],$$

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For all  $N \geq 1$ , we then have

$$\|\dot{w}_N^-(0) - w_1\| + \|w_N^-(0) - w_0\|_{\frac{1}{2}} \leq \alpha^N \left( \|w_1\| + \|w_0\|_{\frac{1}{2}} \right).$$

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## Question

Can we obtain an error estimate for the reconstruction algorithm in its fully discretized version ?

We need some regularity assumptions

- $w_0 \in \mathcal{D}\left(A_0^{\frac{3}{2}}\right)$ ,  $w_1 \in \mathcal{D}(A_0)$ ,
- $\chi_{|O}$  will be replaced by a smooth cut-off function.

In the sequel, let

- $h$  be the mesh size of the space discretization,
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- **Galerkin space discretization**

$(H_h)_{h>0}$  is a family of finite-dimensional subspaces of  $\mathcal{D}\left(A_0^{\frac{1}{2}}\right)$  such that there exist  $M > 0$ ,  $\theta > 0$  and  $h^* > 0$  such that

$$\|\pi_h \varphi - \varphi\| \leq M h^\theta \|\varphi\|_{\frac{1}{2}}, \quad \forall \varphi \in \mathcal{D}\left(A_0^{\frac{1}{2}}\right), \quad h \in (0, h^*).$$

- **Implicit finite difference discretization in time**

$[0, \tau]$  is splitting with a time step  $\Delta t > 0$ :  $t_k = k\Delta t$ , with  $0 \leq k \leq K$ . We approximate the first and second derivative at time  $t_k$  of a function  $f$  by

$$f'(t_k) \simeq \frac{f(t_k) - f(t_{k-1})}{\Delta t},$$

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## Theorem

Let  $(w_0, w_1) \in \mathcal{D}\left(A_0^{\frac{3}{2}}\right) \times \mathcal{D}(A_0)$  and denote  $(w_{0,h,\Delta t}, w_{1,h,\Delta t})$  the numerical reconstruction of  $(w_0, w_1)$ .

Taking  $N_{h,\Delta t} = \frac{\ln(h^\theta + \Delta t)}{\ln \alpha}$  iterations, there exist  $M_\tau > 0$ ,  $h^* > 0$  and  $\Delta t^* > 0$  such that for all  $h \in (0, h^*)$  and  $\Delta t \in (0, \Delta t^*)$

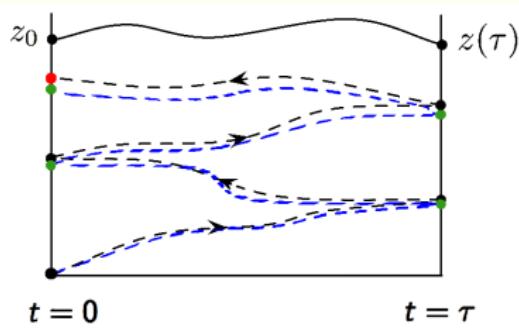
$$\begin{aligned} \|w_0 - w_{0,h,\Delta t}\|_{\frac{1}{2}} + \|w_1 - w_{1,h,\Delta t}\| \\ \leq M_\tau \left[ (h^\theta + \Delta t) \ln^2(h^\theta + \Delta t) \left( \|w_0\|_{\frac{3}{2}} + \|w_1\|_1 \right) \right. \\ \left. + |\ln(h^\theta + \Delta t)| \Delta t \sum_{\ell=0}^K \|y(t_\ell) - y_h^\ell\| \right]. \end{aligned}$$

To prove this, we split the error

$$\|w_0 - w_{0,h,\Delta t}\|_{\frac{1}{2}} + \|w_1 - w_{1,h,\Delta t}\|$$

into three parts, taking into account the fact that

- ① we stop the iteration,
- ② we discretize the observers,
- ③ we take approximation as initial and final data.



3 error types.

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Consider the 1D wave equation with unit speed on  $(0, 1)$  and observe the velocity of the sub-interval  $(0, 0.1)$  (in red) during 2 seconds.

We code the algorithm presented above on Matlab, and focus our attention on three aspects

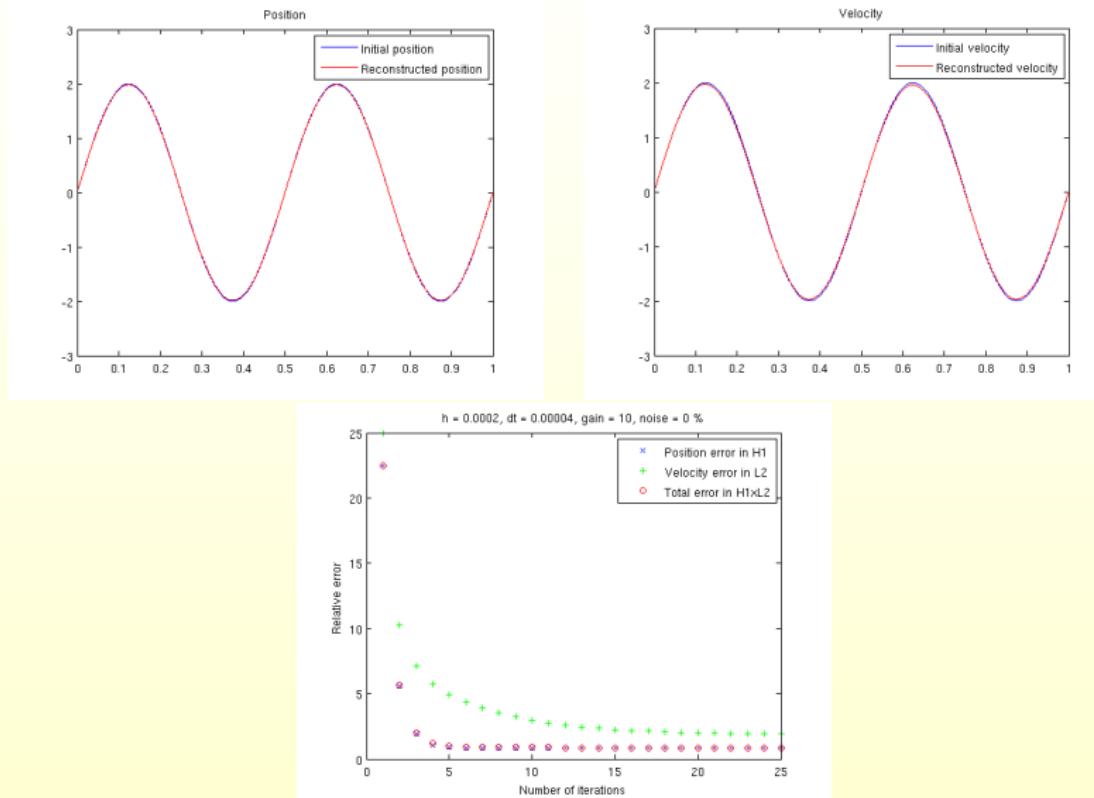
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- Influence of the gain coefficient (parameter  $\gamma$ )
- Robustness to noise



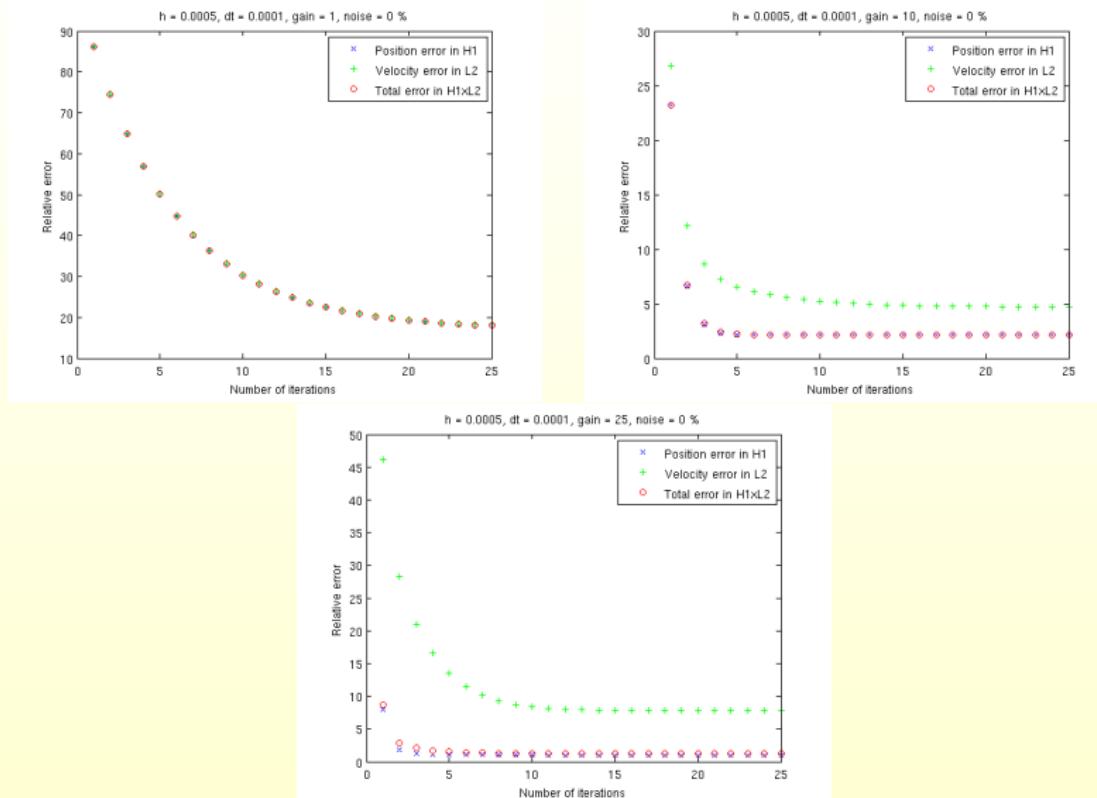
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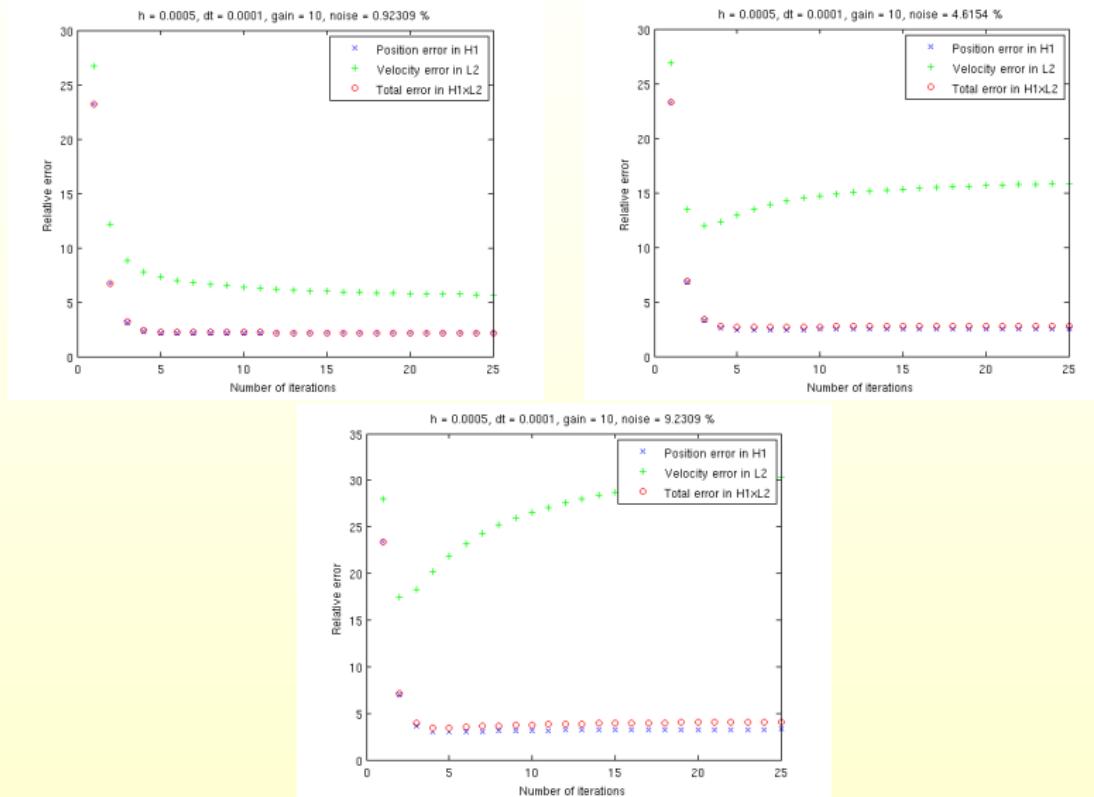
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$$\gamma = 10, h = 2 \cdot 10^{-4} \text{ and } \Delta t = 4 \cdot 10^{-5}$$



*Influence of the gain coefficient :  $\gamma = 1, 10, 25$*



*Robustness to noise : 1%, 5%, 10%*

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- Maxwell's equations

$$\begin{cases} \varepsilon \dot{\mathbf{E}} - \operatorname{rot} \mathbf{H} = 0, & \Omega, \\ \mu \dot{\mathbf{H}} + \operatorname{rot} \mathbf{E} = 0, & \Omega, \\ \operatorname{div} \mathbf{E} = 0, \operatorname{div} \mathbf{H} = 0, & \Omega, \\ \mathbf{E} \wedge \nu = 0, \mathbf{H} \cdot \nu = 0, & \partial\Omega, \\ \mathbf{E}(., 0) = \mathbf{E}_0, & \Omega, \\ \mathbf{H}(., 0) = \mathbf{H}_0, & \Omega, \end{cases} \quad y = \chi \mathbf{E}.$$

We are able to reconstruct  $(\mathbf{E}_0, \mathbf{H}_0)$  from  $y$ .

- Source identification

$$\begin{cases} \ddot{w}(x, t) - \Delta w(x, t) = \lambda(t)j(x), & \Omega \times \mathbb{R}^+, \\ w(x, t) = 0, & \partial\Omega \times \mathbb{R}^+, \\ w(x, 0) = 0, & \Omega, \\ \dot{w}(x, 0) = 0, & \Omega, \end{cases} \quad y(t) = \chi \dot{w}(t).$$

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- Stability under perturbations

$$\begin{cases} \ddot{w} - \Delta w = 0, & \Omega, \\ w = 0, & \partial\Omega, \\ w(., 0) = w_0, & \Omega, \\ \dot{w}(., 0) = w_1, & \Omega. \end{cases}$$

⇓ ?

$$\begin{cases} \ddot{w} - \Delta w + w^3 = 0, & \Omega, \\ w = 0, & \partial\Omega, \\ w(., 0) = w_0, & \Omega, \\ \dot{w}(., 0) = w_1, & \Omega. \end{cases}$$

# Thanks for your attention !

G. HAINE AND K. RAMDANI

*Reconstructing initial data using observers : error analysis of the semi-discrete and fully discrete approximations  
(NUMERISCHE MATHEMATIK, In Revision)*