

### **MIT's Altair 8800**

- Input: front panel switches
- Output: front panel LEDs
- Max RAM: 64K max
- Min RAM: 256 bytes
- CPU: Intel 8080, 2.0 MHz

### **MOS KIM-1**

- Input: on-board hexadecimal keypad
- Output: 6 digital LED display
- Max RAM: 1024 bytes
- Min RAM: 1024 bytes
- CPU: MOS 6502, 1MHz

### **Apple 1**

- Input: Keyboard
- Output: Monochrome 280X192, 40X24 Text
- Max RAM: 65K
- Min RAM: 4K
- CPU: MOS 6502, 1.0 MHz

### **IBM Personal Computer (PC) 5150**

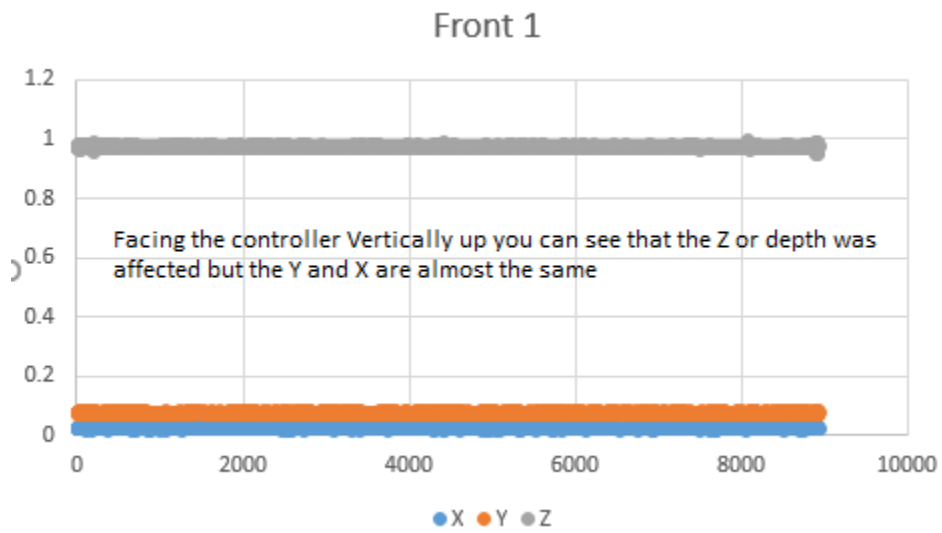
- Input: Keyboard
- Output: 80 X 24 text
- Max RAM: 640K
- Min RAM: 16Kilobytes
- CPU: Intel 8088, 4.77MHz

### **Apple Macintosh**

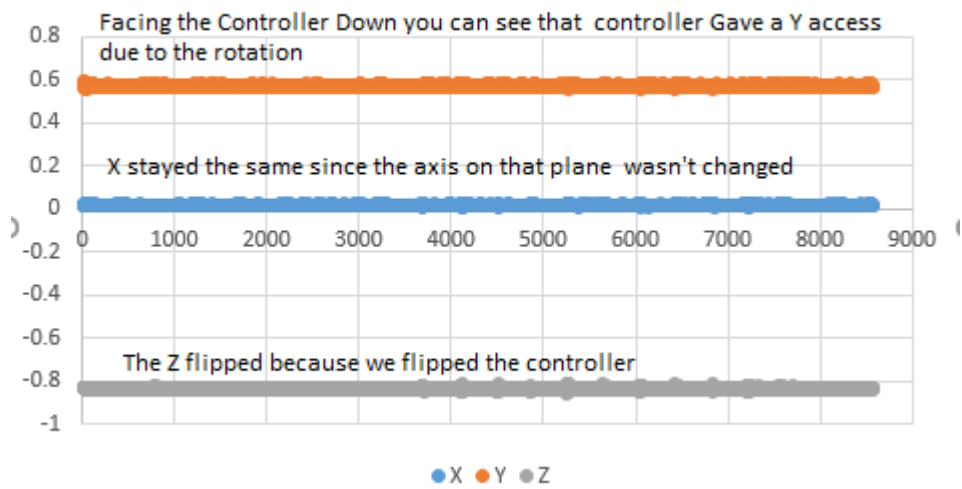
- Input: Keyboard & Mouse
- Output: 9-inch monochrome screen, 512x342 pixels
- Max RAM: 512K
- Min RAM: 128K
- CPU: Motorola 68000, 7.83 Mhz

1. What do you think each column of data represent?  
Each Column represents an Axis. X, Y, Z.
2. How does this relate the the flags (-t and -g) that you used?  
-t = Time  
-g = Gyro
3. What unit of measure are the data in?  
3-axis gyroscope(X, Y, Z) from the accelerometer, Its recorded into a csv.
4. On each of your plots, explain what is going on. Try to understand why the graphs look like they do and then relate the graphs to what you did when you

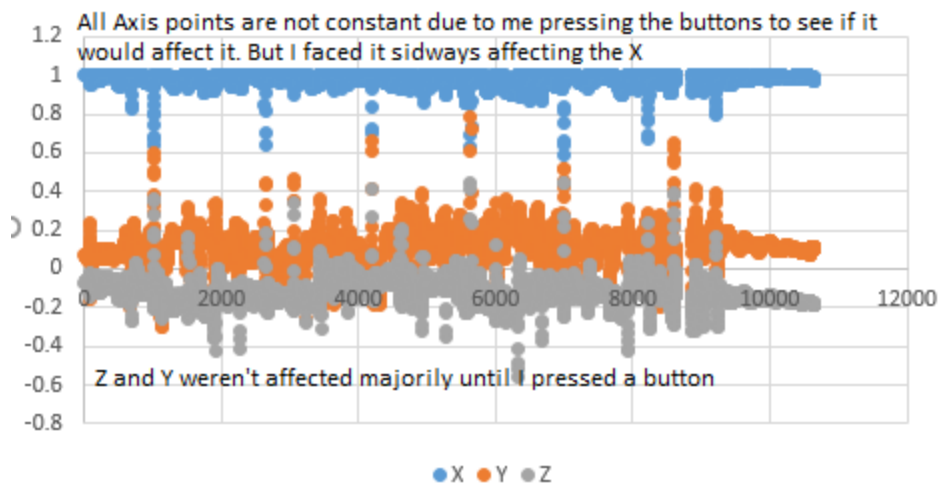
took the data. Label, by hand (scan and include in your PDF), parts of the graphs and then describe what is going on.



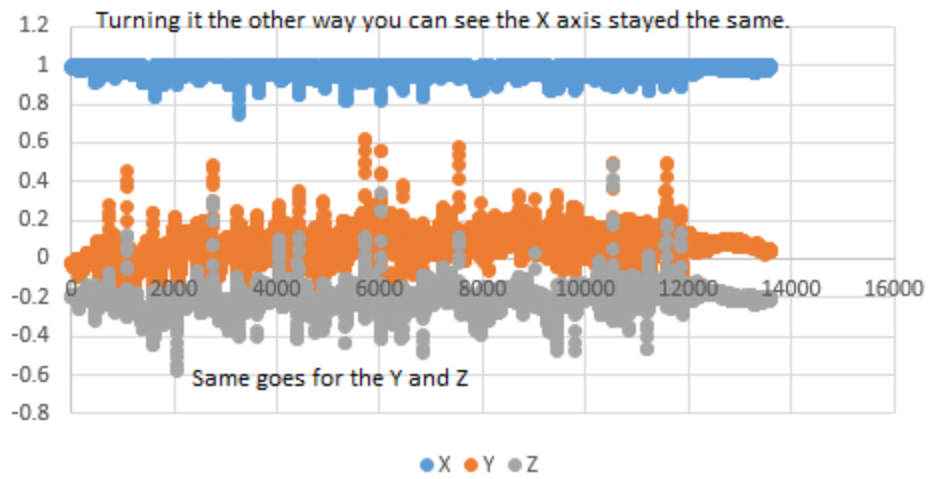
## Front 2



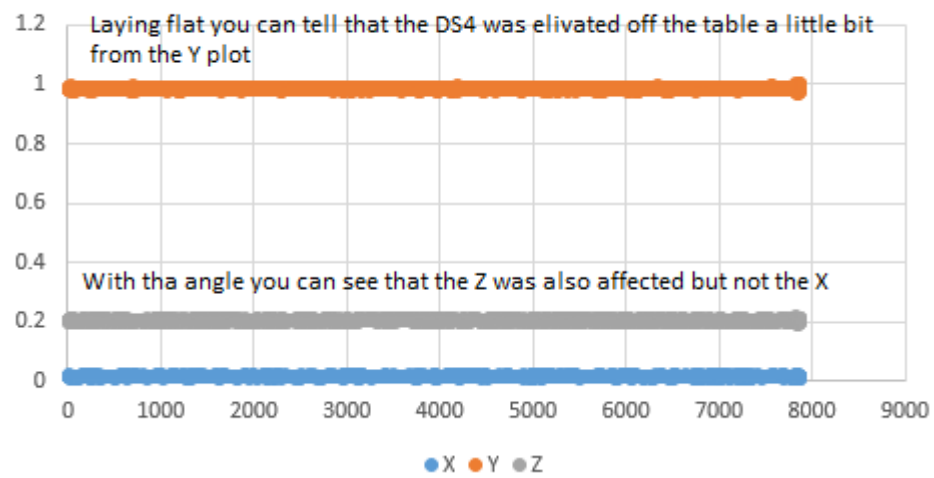
### Custom 1



## Custom 2



## Flat 1



## Flat 2

