In [1]: #import necessary libraries import pandas as pd import numpy as np import matplotlib.pyplot as plt import torch from torch.utils.data import random_split from torch.utils.data import DataLoader,Dataset import torch.nn.functional as F from torch.utils.tensorboard import SummaryWriter from sklearn.metrics import r2_score import cv2 import os In [2]: #getting the path to the folder dir=os.getcwd() In [3]: #paths to data albedo=dir+"/DATA/Data_Albedo/Albedo_Map.csv" LPFe_Map=dir+"/DATA/Data_Albedo/LPFe_Map.csv" LPK_Map=dir+"/DATA/Data_Albedo/LPK_Map.csv" LPTh_Map=dir+"/DATA/Data_Albedo/LPTh_Map.csv" LPTi_Map=dir+"/DATA/Data_Albedo/LPTi_Map.csv" In [4]: #custom dataset for nearby pixels class dataset_nearby_pixel(Dataset): def __init__(self,path_1,path_2,path_3,path_4,path_5,mode): self.path_1=path_1 self.path_2=path_2 self.path_3=path_3 self.path_4=path_4 self.path_5=path_5 self.mode=mode #converting the data to ndarray self.X_1=np.array(pd.read_csv(path_1)) self.X_2=np.array(pd.read_csv(path_2)) self.X_3=np.array(pd.read_csv(path_3)) self.X_4=np.array(pd.read_csv(path_4)) self.X_5=cv2.GaussianBlur(np.array(pd.read_csv(path_5)),ksize=(0,0),sigmaX=9) self.X=[]self.Y=[] $n, m=np.shape(self.X_5)[0], np.shape(self.X_5)[1]$ for i in range(1, n-1): for j in range(1, m-1): nearby=[] for chem in [self.X_1, self.X_2, self.X_3, self.X_4]: for a in [-1,0,1]: for b in [-1,0,1]: nearby.append(chem[i+a][j+b]) self.X.append(nearby) self.Y.append([self.X_5[i][j]]) l=len(self.Y)//2 if mode == "Train" or "train": self.X=np.array(self.X)[:l] self.Y=np.array(self.Y)[:1] elif mode== "Test" or "test" self.X=np.array(self.X)[l:] self.Y=np.array(self.Y)[l:] def __len__(self): self.filelength=np.shape(self.Y)[0] return self.filelength def __getitem__(self,idx): return torch.from_numpy(self.X[idx]),torch.from_numpy(self.Y[idx]) In [5]: class autoencoder(torch.nn.Module): def __init__(self): super(autoencoder, self).__init__() # Encoder Network self.encoder = torch.nn.Sequential(torch.nn.Linear(36,72), torch.nn.ReLU(True), torch.nn.Linear(72,148))# Decoder Network self.decoder = torch.nn.Sequential(torch.nn.Linear(148,72), torch.nn.ReLU(**True**), torch.nn.Linear(72, 36), torch.nn.ReLU(True), torch.nn.Linear(36,1), torch.nn.ReLU(**True**)) def forward(self,x): x=self.encoder(x)x=self.decoder(x) return x In [6]: class train(): def __init__(self,batch_size,epochs,lr,train_val_split,scheduler,near): self.batch_size=batch_size self.scheduler=scheduler self.epochs=epochs self.lr=lr self.train_val_split=train_val_split self.near=near if self.near== True: self.data=dataset_nearby_pixel(LPFe_Map, LPK_Map, LPTh_Map, LPTi_Map, albedo, mode="train") self.train_data,self.val_data=random_split(self.data,[len(self.data)-int(self.train_val_split*len(s self.train_loader=DataLoader(self.train_data,batch_size=self.batch_size,shuffle=True) self.val_loader=DataLoader(self.val_data,batch_size=self.batch_size,shuffle=True) self.net=autoencoder() self.data=dataset(LPFe_Map,LPK_Map,LPTh_Map,LPTi_Map,albedo,0,360) self.train_data,self.val_data=random_split(self.data,[len(self.data)-int(self.train_val_split*len self.train_loader=DataLoader(self.train_data, batch_size=self.batch_size, shuffle=True) self.val_loader=DataLoader(self.val_data, batch_size=self.batch_size, shuffle=True) self.net=model(n_feature=4, n_hidden=4, n_output=1) self.optimizer = torch.optim.Adam(self.net.parameters(), lr=self.lr) if self.scheduler==True: self.sched=torch.optim.lr_scheduler.ExponentialLR(self.optimizer,gamma=0.7) self.loss_func = torch.nn.MSELoss() self.writer = SummaryWriter() def trainer(self): self.net=self.net.train() self.net=self.net.cuda() for epoch in range(self.epochs): for input, gt in self.train_loader: input = input.cuda() gt = gt.cuda() gt=torch.reshape(gt,(len(gt),1)) output = self.net(input.float()) loss = self.loss_func(output, gt.float()) self.optimizer.zero_grad() loss.backward() self.optimizer.step() if self.scheduler == True: self.sched.step() print('Epoch : {}, train loss : {}'.format(epoch+1, loss.item())) with torch.no_grad(): for input, gt in self.val_loader: input=input.cuda() gt= gt.cuda() gt=torch.reshape(gt,(len(gt),1)) val_output = self.net(input.float()) val_loss = self.loss_func(val_output,gt.float()) print('Epoch : {}, val_loss : {}'.format(epoch+1, val_loss.item())) self.writer.add_scalar("Loss/train", loss, epoch) self.writer.add_scalar("Loss/val", val_loss, epoch) if self.scheduler == True: self.writer.add_scalar("lr/epoch", self.lr, epoch) torch.save(self.net.state_dict(),f"albedo_autoencoder_{self.epochs}_{self.lr}_{self.batch_size}.pth") In [7]: | train_best_near=train(batch_size=64,epochs=100,lr=0.0001,train_val_split=0.3,scheduler=False,near=True) train_best_near.trainer() 2022-04-10 16:56:31.090501: W tensorflow/stream_executor/platform/default/dso_loader.cc:64] Could not load dyna mic library 'libcudart.so.11.0'; dlerror: libcudart.so.11.0: cannot open shared object file: No such file or di rectory; LD_LIBRARY_PATH: /home/g0kul6/miniconda3/lib/python3.9/site-packages/cv2/../../lib64: 2022-04-10 16:56:31.090532: I tensorflow/stream_executor/cuda/cudart_stub.cc:29] Ignore above cudart dlerror if you do not have a GPU set up on your machine Epoch: 1, train loss: 0.0878107100725174 Epoch: 1, val_loss: 0.09150587022304535 Epoch: 2, train loss: 0.08635705709457397 Epoch: 2, val_loss: 0.08455988019704819 Epoch: 3, train loss: 0.08399862796068192 Epoch: 3, val_loss: 0.09489002823829651 Epoch: 4, train loss: 0.08470350503921509 Epoch: 4, val_loss: 0.0816386342048645 Epoch: 5, train loss: 0.07871576398611069 Epoch: 5, val_loss: 0.07830406725406647 Epoch: 6, train loss: 0.08545029908418655 Epoch: 6, val_loss: 0.08926884829998016 Epoch: 7, train loss: 0.07614102959632874 Epoch: 7, val_loss: 0.08242516964673996 Epoch: 8, train loss: 0.001455507823266089 Epoch: 8, val_loss: 0.0037453914992511272 Epoch: 9, train loss: 0.002118888543918729 Epoch : 9, val_loss : 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0.00019196790526621044 Epoch: 98, val_loss: 0.00021482181909959763 Epoch: 99, train loss: 0.00023469347797799855 Epoch: 99, val_loss: 0.00019949045963585377 Epoch: 100, train loss: 0.00022595925838686526 Epoch : 100, val_loss : 0.00027036419487558305 In [7]: | test_data_nearby=dataset_nearby_pixel(LPFe_Map, LPK_Map, LPTh_Map, LPTi_Map, albedo, mode="test") test_loader_nearby=DataLoader(test_data_nearby,batch_size=1) loss_function=torch.nn.MSELoss() net_test=autoencoder() net_test=net_test.cuda() net_test.load_state_dict(torch.load(dir+"/albedo_autoencoder_100_0.0001_64.pth")) right_predicted_near=[] right_truth_near=[] total_loss_near=[] net_test=net_test.eval() for i, l in test_loader_nearby: i=i.cuda() l=l.cuda() l=torch.reshape(l,(len(l),1)) output=net_test(i.float()) loss=loss_function(output, l.float()) loss=loss.cpu().item() total_loss_near.append(np.sqrt(loss)) right_predicted_near.append(output.cpu().item()) right_truth_near.append(l.cpu().item()) print("RMSE Loss on right half :",np.mean(total_loss_near)) print("R2 score:",r2_score(right_truth_near,right_predicted_near)) residual_near=np.subtract(right_predicted_near,right_truth_near) plt.hist(residual_near, bins=100) plt.show() RMSE Loss on right half : 0.011029566272136759R2 score: 0.9282636140570228 6000 5000 4000 3000 2000 1000 -0.06-0.04 -0.02 0.00 0.02 0.04 0.06 0.08 In [10]: ffig, faxes = plt.subplots(2, 2, figsize=(10, 10)) faxes[0, 0].imshow(np.reshape(right_truth_near,(357,359))) faxes[0, 0].set_title("Actual map (right)") faxes[0, 0].grid(False) faxes[0, 1].imshow(np.reshape(right_predicted_near,(357,359))) faxes[0, 1].set_title("Predicted map (right)") faxes[0, 1].grid(False) faxes[1, 0].imshow(np.reshape(residual_near,(357,359))) faxes[1, 0].set_title("Residual map") faxes[1, 0].grid(False) faxes[1, 1].hist(residual_near, bins=100) faxes[1, 1].set_title("1D Histogram") faxes[1, 1].grid(False) Actual map (right) Predicted map (right) 0 0 50 100 100 150 150 200 200 250 250 300 300 350 350 100 150 200 250 300 0 50 100 150 200 250 300 0 Residual map 1D Histogram 0 6000 50 5000 100 4000 150 3000 2000 250 1000 300 In []: