

Exercise 1)

part a.

$$E = \sum_{i=1}^n \|x'_i - Mx_i - t\|^2$$

$$= \sum_{i=1}^n (x'_i - Mx_i - t)^T (x'_i - Mx_i - t)$$

$$\frac{\partial E}{\partial M} = 2 \sum_{i=1}^n (x'_i - Mx_i - t) x_i^T$$

$$\frac{\partial E}{\partial t} = 2 \sum_{i=1}^n (x'_i - Mx_i - t)$$

part b

$$\frac{\partial E}{\partial M} = 2 \sum_{i=1}^n (x'_i - Mx_i - t) x_i^T = 0$$

$$\Rightarrow \sum_{i=1}^n (x'_i - Mx_i - t) x_i^T = 0$$

$$\frac{\partial E}{\partial t} = 2 \sum_{i=1}^n (x'_i - Mx_i - t) = 0$$

$$\Rightarrow \sum_{i=1}^n (x'_i - Mx_i - t) = 0$$

Let h be a vector that includes the unknown parameter M and t .

$$h = \begin{bmatrix} a \\ b \\ c \\ d \\ t_x \\ t_y \end{bmatrix},$$

$Sh = u$, where

\rightarrow Coordinates of the original points x_i
 S is 6×6 matrix
 u is 6×1 matrix
 \rightarrow transformed points x'_i

part c

$$x_1 = (0, 0) \rightarrow x'_1 = (1, 2)$$

$$x_2 = (1, 0) \rightarrow x'_2 = (3, 2)$$

$$x_3 = (0, 1) \rightarrow x'_3 = (1, 4)$$

$$x'_i = Mx_i + t, \text{ where } M = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, t = \begin{bmatrix} t_x \\ t_y \end{bmatrix}$$

$$x_1: a \cdot 0 + b \cdot 0 + t_x = 1 \Rightarrow t_x = 1$$

$$c \cdot 0 + d \cdot 0 + t_y = 2 \Rightarrow t_y = 2$$

$$x_2: a \cdot 1 + b \cdot 0 + t_x = 3 \Rightarrow a + 1 = 3 \Rightarrow a = 2$$

$$c \cdot 1 + d \cdot 0 + t_y = 2 \Rightarrow c + 2 = 2 \Rightarrow c = 0$$

$$x_3: a \cdot 0 + b \cdot 1 + t_x = 1 \Rightarrow b + 1 = 1 \Rightarrow b = 0$$

$$c \cdot 0 + d \cdot 1 + t_y = 4 \Rightarrow d + 2 = 4 \Rightarrow d = 2$$

$$M = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}, t = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\therefore x'_i = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} x_i + \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

\Rightarrow This one scales the original coordinates by a factor of 2 & translate them by (1, 2)

Exercise 2)

Part a

$$x_1 = \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}, \quad x_2 = \begin{bmatrix} x_2 \\ y_2 \end{bmatrix}, \quad v = x_2 - x_1 = \begin{bmatrix} x_2 - x_1 \\ y_2 - y_1 \end{bmatrix}$$

$$x'_1 = \begin{bmatrix} x'_1 \\ y'_1 \end{bmatrix}, \quad x'_2 = \begin{bmatrix} x'_2 \\ y'_2 \end{bmatrix}, \quad v' = x'_2 - x'_1 = \begin{bmatrix} x'_2 - x'_1 \\ y'_2 - y'_1 \end{bmatrix}$$

$$\cos(\theta) = \frac{v' \cdot v}{|v'| |v|} \quad \text{dot product}$$

$$\sin(\theta) = \frac{v' \times v}{|v'| |v|}$$

$$\theta = \text{atan2}(\sin(\theta), \cos(\theta))$$

Part b

$$s = \frac{|v'|}{|v|} = \frac{\sqrt{(x'_2 - x'_1)^2 + (y'_2 - y'_1)^2}}{\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}}$$

Part c

$$t = x'_1 - s R x_1, \quad \text{where } x'_1 \text{ is transformed point}$$

x_1 is the original point

s is the scale factor

R is the rotation matrix

$$R = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$$

Part d)

$$\left(\frac{1}{2}, 0\right) \rightarrow (0, 0), \quad \left(0, \frac{1}{2}\right) \rightarrow (-1, -1)$$

$$x_1 = \begin{bmatrix} \frac{1}{2} \\ 0 \end{bmatrix}, \quad x_2 = \begin{bmatrix} 0 \\ \frac{1}{2} \end{bmatrix}$$

$$x'_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad x'_2 = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$$

$$v = x_2 - x_1 = \begin{bmatrix} 0 \\ \frac{1}{2} \end{bmatrix} - \begin{bmatrix} \frac{1}{2} \\ 0 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \end{bmatrix}$$

$$v' = x'_2 - x'_1 = \begin{bmatrix} -1 \\ -1 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$$

$$s = \frac{v' \cdot v}{|v'| |v|} = \frac{(-1)\cancel{\left(\frac{1}{2}\right)} + (-1)\cancel{\left(\frac{1}{2}\right)}}{\cancel{\sqrt{2}} \cdot \frac{1}{\cancel{\sqrt{2}}}} = 0$$

$$\sin(\theta) = \frac{v' \times v}{|v'| |v|} = \frac{0 + (-1)}{\sqrt{2} \cdot \frac{1}{\sqrt{2}}} = -1$$

$$\theta = \frac{3\pi}{2} \text{ radians} = 270^\circ$$

$$\begin{aligned} t &= x'_1 - s R x_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix} - 2 \cdot \begin{bmatrix} \cos\left(\frac{3\pi}{2}\right) & -\sin\left(\frac{3\pi}{2}\right) \\ \sin\left(\frac{3\pi}{2}\right) & \cos\left(\frac{3\pi}{2}\right) \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} - 2 \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{2} \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{aligned}$$

$$\therefore t = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$