1 lenet

April 1, 2025

Deadline: January 22, 2025 (Wednesday) 23:00

1 Exercise 1. Convolutional neural networks. LeNet-5.

In this exercise, you will train a very simple convolutional neural network used for image classification tasks.

You may find it useful to look at this tutorial: * Neural Networks

```
[26]: skip_training = True  # Set this flag to True before validation and submission

[2]: # During evaluation, this cell sets skip_training to True
  # skip_training = True

import tools, warnings
warnings.showwarning = tools.customwarn
```

```
[3]: import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline

import torch
import torchvision
import torchvision.transforms as transforms

import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim

import tools
import tests
```

```
[4]: # When running on your own computer, you can specify the data directory by: # data_dir = tools.select_data_dir('/your/local/data/directory')
data_dir = tools.select_data_dir()
```

The data directory is /coursedata

```
[5]: # Select the device for training (use GPU if you have one)
#device = torch.device('cuda:0')
device = torch.device('cpu')
```

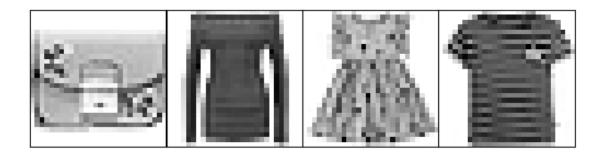
```
[6]: if skip_training:
    # The models are always evaluated on CPU
    device = torch.device("cpu")
```

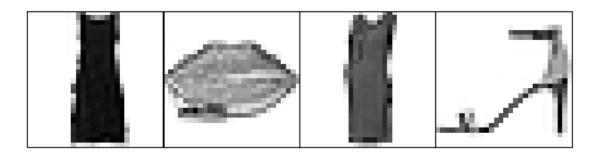
1.1 FashionMNIST dataset

Let us use the FashionMNIST dataset. It consists of 60,000 training images of 10 classes: 'T-shirt/top', 'Trouser', 'Pullover', 'Dress', 'Coat', 'Sandal', 'Shirt', 'Sneaker', 'Bag', 'Ankle boot'.

Let us visualize the data.

```
[8]: images, labels = next(iter(trainloader))
tests.plot_images(images[:8], n_rows=2)
```





2 1. Simple convolutional network

In the first exercise, your task is to create a convolutional neural network with the architecture inspired by the classical LeNet-5 (LeCun et al., 1998).

The architecture of the convolutional network that you need to create: * 2d convolutional layer with: * one input channel * 6 output channels * kernel size 5 (no padding) * followed by ReLU * Max-pooling layer with kernel size 2 and stride 2 * 2d convolutional layer with: * 16 output channels * kernel size 5 (no padding) * followed by ReLU * Max-pooling layer with kernel size 2 and stride 2 * A fully-connected layer with: * 120 outputs * followed by ReLU * A fully-connected layer with: * 84 outputs * followed by ReLU * A fully-connected layer with 10 outputs and without nonlinearity.

```
[9]: class LeNet5(nn.Module):
    def __init__(self):
        super(LeNet5, self).__init__()
        # YOUR CODE HERE
        # Convolutional layers
        self.conv1 = nn.Conv2d(1, 6, kernel_size=5) # Input: 1 channel, Output:
        4 channels
        self.pool1 = nn.MaxPool2d(kernel_size=2, stride=2) # Max pooling 1

        self.conv2 = nn.Conv2d(6, 16, kernel_size=5) # Input: 6 channels,
        Output: 16 channels
        self.pool2 = nn.MaxPool2d(kernel_size=2, stride=2) # Max pooling 2
```

```
# Fully connected layers
      self.fc1 = nn.Linear(16 * 4 * 4, 120) # Input size: 16 * 4 * 4, Output
⇔size: 120
      self.fc2 = nn.Linear(120, 84) # Input size: 120, Output size: 84
      self.fc3 = nn.Linear(84, 10) # Input size: 84, Output size: 10
  def forward(self, x):
      Args:
        x of shape (batch_size, 1, 28, 28): Input images.
      Returns:
        y of shape (batch_size, 10): Outputs of the network.
      # YOUR CODE HERE
      # Convolutional layers with ReLU and MaxPooling
      x = F.relu(self.conv1(x)) # Conv1 + ReLU
      x = self.pool1(x) # Pool1
      x = F.relu(self.conv2(x)) # Conv2 + ReLU
      x = self.pool2(x) # Pool2
      # Flatten the output for fully connected layers
      x = torch.flatten(x, 1) # Flatten to (batch_size, 16 * 4 * 4)
      # Fully connected layers
      x = F.relu(self.fc1(x)) # Fully Connected 1 + ReLU
      x = F.relu(self.fc2(x)) # Fully Connected 2 + ReLU
      x = self.fc3(x) # Fully Connected 3 (No activation for logits)
      return x
  net = LeNet5()
```

```
[10]: def test_LeNet5_shapes():
    net = LeNet5()

# Feed a batch of images from the training data to test the network
with torch.no_grad():
    images, labels = next(iter(trainloader))
    print('Shape of the input tensor:', images.shape)

y = net(images)
    assert y.shape == torch.Size([trainloader.batch_size, 10]), "Bad shape_u
of y: y.shape={}".format(y.shape)

print('Success')

test_LeNet5_shapes()
```

Shape of the input tensor: torch.Size([32, 1, 28, 28]) Success

```
[11]: def test_LeNet5():
    net = LeNet5()

# get gradients for parameters in forward path
    net.zero_grad()
    x = torch.randn(1, 1, 28, 28)
    outputs = net(x)
    outputs[0,0].backward()

parameter_shapes = sorted(tuple(p.shape) for p in net.parameters() if p.
    -grad is not None)
    print(parameter_shapes)
    expected = [(6,), (6, 1, 5, 5), (10,), (10, 84), (16,), (16, 6, 5, 5), ...
    -(84,), (84, 120), (120,), (120, 256)]
    assert parameter_shapes == expected, "Wrong number of training parameters."

    print('Success')

test_LeNet5()
```

```
[(6,), (6, 1, 5, 5), (10,), (10, 84), (16,), (16, 6, 5, 5), (84,), (84, 120), (120,), (120, 256)]
Success
```

3 Train the network

```
[12]: # This function computes the accuracy on the test dataset

def compute_accuracy(net, testloader):
    net.eval()
    correct = 0
    total = 0
    with torch.no_grad():
        for images, labels in testloader:
            images, labels = images.to(device), labels.to(device)
            outputs = net(images)
            _, predicted = torch.max(outputs.data, 1)
            total += labels.size(0)
            correct += (predicted == labels).sum().item()
    return correct / total
```

3.0.1 Training loop

Your task is to implement the training loop. The recommended hyperparameters: * Stochastic Gradient Descent (SGD) optimizer with learning rate 0.001 and momentum 0.9. * Cross-entropy

loss. Note that we did not use softmax nonlinearity in the final layer of our network. Therefore, we need to use a loss function with log_softmax implemented, such as nn.CrossEntropyLoss. * Number of epochs: 10. Please use mini-batches produces by trainloader defined above.

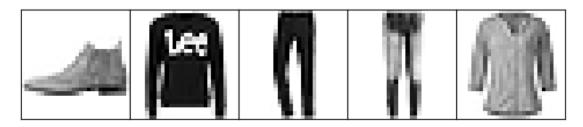
We recommend you to use function compute_accuracy() defined above to track the accuracy during training. The test accuracy should be above 0.87.

```
[13]: # Create network
net = LeNet5()
```

```
[21]: # Implement the training loop in this cell
      if not skip_training:
         # YOUR CODE HERE
          # Hyperparameters
          learning_rate = 0.001
          momentum = 0.9
          num_epochs = 10
          # Loss function and optimizer
          criterion = nn.CrossEntropyLoss() # Cross-entropy loss for classification
          optimizer = optim.SGD(net.parameters(), lr=learning_rate,_
       →momentum=momentum) # SGD optimizer
          # Move the model to the appropriate device
          net.to(device)
          # Training loop
          for epoch in range(num_epochs):
              net.train() # Set the network to training mode
              running_loss = 0.0
              for inputs, labels in trainloader:
                  # Move data to the correct device
                  inputs, labels = inputs.to(device), labels.to(device)
                  # Zero the parameter gradients
                  optimizer.zero_grad()
                  # Forward pass
                  outputs = net(inputs)
                  # Compute the loss
                  loss = criterion(outputs, labels)
                  # Backward pass
                  loss.backward()
                  # Update the parameters
```

```
optimizer.step()
                  # Accumulate the loss
                  running_loss += loss.item()
              # Compute accuracy after each epoch
              accuracy = compute_accuracy(net, testloader)
              # Print statistics for the epoch
              print(f"Epoch {epoch + 1}/{num_epochs}, Loss: {running_loss /_
       ⇔len(trainloader):.4f}, Accuracy: {accuracy:.4f}")
      else:
          print("Training skipped.")
     Epoch 1/10, Loss: 0.3123, Accuracy: 0.8789
     Epoch 2/10, Loss: 0.3024, Accuracy: 0.8778
     Epoch 3/10, Loss: 0.2953, Accuracy: 0.8759
     Epoch 4/10, Loss: 0.2876, Accuracy: 0.8799
     Epoch 5/10, Loss: 0.2808, Accuracy: 0.8816
     Epoch 6/10, Loss: 0.2746, Accuracy: 0.8777
     Epoch 7/10, Loss: 0.2686, Accuracy: 0.8871
     Epoch 8/10, Loss: 0.2621, Accuracy: 0.8792
     Epoch 9/10, Loss: 0.2585, Accuracy: 0.8849
     Epoch 10/10, Loss: 0.2539, Accuracy: 0.8877
[22]: # Save the model to disk (the pth-files will be submitted automatically ...
      →together with your notebook)
      # Set confirm=False if you do not want to be asked for confirmation before
       ⇔savinq.
      if not skip training:
          tools.save model(net, '1 lenet5.pth', confirm=True)
     Do you want to save the model (type yes to confirm)? yes
     Model saved to 1_lenet5.pth.
[23]: if skip_training:
          net = LeNet5()
          tools.load_model(net, '1_lenet5.pth', device)
[24]: # Display random images from the test set, the ground truth labels and the
      ⇔network's predictions
      net.eval()
      with torch.no_grad():
          images, labels = next(iter(testloader))
          tests.plot_images(images[:5], n_rows=1)
```

Ground truth labels: Ankle boot Pullover Trouser Trouser Shirt Predictions: Ankle boot Pullover Trouser Trouser Shirt



```
[25]: # Compute the accuracy on the test set
accuracy = compute_accuracy(net, testloader)
print('Accuracy of the network on the test images: %.3f' % accuracy)
assert accuracy > 0.85, "Poor accuracy {:.3f}".format(accuracy)
print('Success')
```

Accuracy of the network on the test images: 0.888 Success