

Assignment 2

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1. (1) likelihood function: $L = \prod_{i=1}^n f(\varepsilon_i) = \frac{1}{(2\pi\sigma^2)^{\frac{n}{2}}} \exp\left[-\frac{1}{2\sigma^2} \sum_{i=1}^n \varepsilon_i^2\right] = \frac{1}{(2\pi\sigma^2)^{\frac{n}{2}}} \exp\left[-\frac{1}{2\sigma^2} (y-X\beta)^T (y-X\beta)\right]$

(2) $\ell(\beta, \sigma^2) = -\frac{1}{2\sigma^2} (y-X\beta)^T (y-X\beta) - \frac{n}{2} \log(2\pi\sigma^2)$

(3) $\frac{\partial \ell(\beta, \sigma^2)}{\partial \beta} = \frac{1}{2\sigma^2} 2X^T (y-X\beta) = 0 \Rightarrow \beta = (X^T X)^{-1} X^T y$

$\frac{\partial \ell(\beta, \sigma^2)}{\partial \sigma^2} = \frac{1}{2\sigma^2} (y-X\beta)^T (y-X\beta) - \frac{n}{2\sigma^2} = 0 \Rightarrow \sigma^2 = \frac{(y-X\beta)^T (y-X\beta)}{n}$

2. Since the model is $y_t = \beta_0 + \beta_1 t + \varepsilon_t = X\beta + \varepsilon_t$ where $X = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ \vdots & \vdots \\ 1 & T \end{bmatrix}_{T \times 2}$ $\beta = \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix}$

$X^T X = \begin{bmatrix} 1 & \dots & 1 \\ 1 & 2 & \dots & T \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \\ 1 \\ 2 \\ \vdots \\ T \end{bmatrix} = \begin{bmatrix} T & \sum_{i=1}^T i \\ \sum_{i=1}^T i & \sum_{i=1}^T i^2 \end{bmatrix} = \begin{bmatrix} T & \frac{T(T+1)}{2} \\ \frac{T(T+1)}{2} & \frac{T(T+1)(2T+1)}{6} \end{bmatrix}$ $\det(X^T X) = \frac{T^2(T+1)(2T+1)}{6} - \frac{T^2(T+1)^2}{4} = \frac{T^2(T+1)(T-1)}{12}$

$(X^T X)^{-1} = \frac{12}{T^2(T+1)(T-1)} \begin{bmatrix} \frac{T(T+1)(2T+1)}{6} & -\frac{T(T+1)}{2} \\ -\frac{T(T+1)}{2} & T \end{bmatrix} = \begin{bmatrix} \frac{2(2T+1)}{T(T-1)} & -\frac{6}{T(T-1)} \\ -\frac{6}{T(T-1)} & \frac{12}{T(T+1)(T-1)} \end{bmatrix}$

$X^T y = \begin{bmatrix} 1 & \dots & 1 \\ 1 & 2 & \dots & T \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_T \end{bmatrix} = \begin{bmatrix} \sum_{t=1}^T y_t \\ \sum_{t=1}^T t y_t \end{bmatrix}$

$\hat{\beta} = \begin{bmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \end{bmatrix} = (X^T X)^{-1} X^T y = \begin{bmatrix} \frac{2(2T+1)}{T(T-1)} & -\frac{6}{T(T-1)} \\ -\frac{6}{T(T-1)} & \frac{12}{T(T+1)(T-1)} \end{bmatrix} \begin{bmatrix} \sum_{t=1}^T y_t \\ \sum_{t=1}^T t y_t \end{bmatrix} = \begin{bmatrix} \frac{2(2T+1)}{T(T-1)} \sum_{t=1}^T y_t - \frac{6}{T(T-1)} \sum_{t=1}^T t y_t \\ -\frac{6}{T(T-1)} \sum_{t=1}^T y_t + \frac{12}{T(T+1)(T-1)} \sum_{t=1}^T t y_t \end{bmatrix}$

$\text{Var}(\hat{\beta}) = \sigma^2 (X^T X)^{-1} = \begin{bmatrix} \frac{2\sigma^2(2T+1)}{T(T-1)} & -\frac{6\sigma^2}{T(T-1)} \\ -\frac{6\sigma^2}{T(T-1)} & \frac{12\sigma^2}{T(T+1)(T-1)} \end{bmatrix}$

So $\text{Var}(\hat{\beta}_0) = \frac{2\sigma^2(2T+1)}{T(T-1)}$ $\text{Var}(\hat{\beta}_1) = \frac{12\sigma^2}{T(T^2-1)}$

3. $\hat{y} = \hat{\beta}_0 + \hat{\beta}_1 x_i = \tilde{X} \tilde{\beta}$, where $\tilde{X} = (1 \ x_i)$, $\tilde{\beta} = \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix}$

Actual: $y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 = X\beta$, where $X = (1 \ x_1 \ x_2) = (\tilde{X} \ x_2)$, $\beta = \begin{pmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{pmatrix} = \begin{pmatrix} \tilde{\beta} \\ \beta_2 \end{pmatrix}$

$E(\beta) = E[(X^T X)^{-1} X^T y] = (\tilde{X}^T \tilde{X})^{-1} \tilde{X}^T E(y) = (\tilde{X}^T \tilde{X})^{-1} \tilde{X}^T X\beta = (\tilde{X}^T \tilde{X})^{-1} \tilde{X}^T [\tilde{X} \ x_2] \begin{bmatrix} \tilde{\beta} \\ \beta_2 \end{bmatrix} = \tilde{\beta} + (\tilde{X}^T \tilde{X})^{-1} \tilde{X}^T x_2 \beta_2$

(2) $E(\hat{\beta}_1) = \beta_1 + (X^T X)^{-1} X^T x_2 \beta_2$

4. keep taking the difference on y_t and X_t , until the residuals are uncorrelated

$y_t' = y_t - \phi y_{t-1} = \beta_0 + \beta_1 x_t + \varepsilon_t - \phi(\beta_0 + \beta_1 x_{t-1} + \varepsilon_{t-1}) = (1-\phi)\beta_0 + \beta_1(x_t - \phi x_{t-1}) + \varepsilon_t - \phi \varepsilon_{t-1}$

$y_t'' = y_t' - \phi y_{t-1}' = (1-\phi)\beta_0 + \beta_1(x_t - \phi x_{t-1}) + \varepsilon_t - \phi \varepsilon_{t-1} - \phi[(1-\phi)\beta_0 + \beta_1(x_{t-1} - \phi x_{t-2}) + \varepsilon_{t-1} - \phi \varepsilon_{t-2}]$

$= (1-2\phi+\phi^2)\beta_0 + \beta_1(x_t + x_{t-2} - 2x_{t-1}) + \varepsilon_t - 2\phi \varepsilon_{t-1} + \phi^2 \varepsilon_{t-2}$

Since $\phi = \frac{\sum_{t=2}^T \varepsilon_t \varepsilon_{t-1}}{\sum_{t=1}^T \varepsilon_t^2}$, $\varepsilon_t = \rho_1 \varepsilon_{t-1} + \rho_2 \varepsilon_{t-2} + a_t$ error term

So $\rho_1 = 2\phi = \frac{2 \sum_{t=2}^T \varepsilon_t \varepsilon_{t-1}}{\sum_{t=1}^T \varepsilon_t^2}$ $\rho_2 = \phi^2 = -\left(\frac{2 \sum_{t=2}^T \varepsilon_t \varepsilon_{t-1}}{\sum_{t=1}^T \varepsilon_t^2}\right)^2$

$$\text{so } \rho_1 = 2\phi = \frac{2 \sum_{t=1}^T e_t e_{t-1}}{\sum_{t=1}^T e_t^2} \quad \rho_2 = \phi^2 = - \left(\frac{2 \sum_{t=1}^T e_t e_{t-1}}{\sum_{t=1}^T e_t^2} \right)^2$$

5.

$$(a) X_t = a + bt + S_t + Y_t \quad S_t \text{ seasonal } 12.$$

Since S_t is a seasonal component with period 12.

$$S_t = S_{t-12} = S_{t-24} = \dots$$

$$\begin{aligned} \nabla \nabla_{12} X_t &= (1-B)(1-B^{12})X_t = (1-B)(1-B^{12})[a + bt + S_t + Y_t] = (1-B)[a - a + bt - b(t-12) + S_t - S_{t-12} + Y_t - Y_{t-12}] \\ &= (1-B)[12b + Y_t - Y_{t-12}] = Y_t - Y_{t-1} - Y_{t-12} + Y_{t-13} \end{aligned}$$

$$E(\nabla \nabla_{12} X_t) = E[Y_t - Y_{t-1} - Y_{t-12} + Y_{t-13}] = 0 - 0 + 0 + 0 = 0$$

$$\gamma_{\nabla \nabla_{12} X_t}(t, t+k) = \text{Cov}(Y_t - Y_{t-1} - Y_{t-12} + Y_{t-13}, Y_{t+k} - Y_{t+k-1} - Y_{t+k-12} + Y_{t+k-13})$$

$$= \underbrace{Y_t - Y_{t-1}}_{\sim} - \underbrace{Y_{t-12} + Y_{t-13}}_{\sim} - \underbrace{Y_{t+k} - Y_{t+k-1}}_{\sim} + \underbrace{Y_{t+k-11}}_{\sim} - \underbrace{Y_{t+k-12}}_{\sim} + \underbrace{Y_{t+k-11}}_{\sim} + \underbrace{Y_{t+k-13}}_{\sim} - \underbrace{Y_{t+k-12}}_{\sim} - \underbrace{Y_{t+k-11}}_{\sim} + \underbrace{Y_{t+k-13}}_{\sim}$$

$$= 4Y_t - 2Y_{t-1} - 2Y_{t+1} - 2Y_{t-12} - 2Y_{t+12} + Y_{t+11} + Y_{t-11} + Y_{t-13} + Y_{t+13}$$

$$= \begin{cases} 4\sigma^2 + f_1(k) & k=0 \\ -2\sigma^2 + f_2(k) & k=\pm 1 \\ -2\sigma^2 + f_3(k) & k=\pm 12 \\ \sigma^2 + f_4(k) & k=\pm 11 \\ \sigma^2 + f_5(k) & k=\pm 13 \\ \text{independent of } t. & \text{o.w.} \end{cases}$$

So $\nabla \nabla_{12} X_t = (1-B)(1-B^{12})X_t$ is stationary ts.

$$(b) X_t = (a+bt)S_t + Y_t$$

$$\nabla_{12}^2 X_t = (1-B^{12})^2 X_t = [(a+bt)S_t + Y_t - (a+b(t-12))S_{t-12} + Y_{t-12}] - [(a+b(t-12))S_{t-12} + Y_{t-12} - (a+b(t-24))S_{t-24} + Y_{t-24}]$$

$$= 12b S_t + Y_t - Y_{t-12} - (12b S_t + Y_{t-12} + Y_{t-24}) = Y_t + Y_{t-24} - 2Y_{t-12}$$

$$E[\nabla_{12}^2(X_t)] = E[Y_t + Y_{t-24} - 2Y_{t-12}] = 0$$

$$\gamma_{\nabla_{12}^2}(X_t, X_{t+k}) = \text{Cov}(X_t, X_{t+k}) = \text{Cov}(Y_t + Y_{t-24} - 2Y_{t-12}, Y_{t+k} + Y_{t+k-24} - 2Y_{t+k-12})$$

$$= \underbrace{Y_t + Y_{t-24}}_{\sim} - 2Y_{t-12} + \underbrace{Y_{t+k} + Y_{t+k-24}}_{\sim} - 2Y_{t+k-12} - 2Y_{t-12} - 2Y_{t+k-12} + 4Y_t$$

$$= 6Y_t - 4Y_{t-12} + 4Y_{t+12} + Y_{t+24} + Y_{t-24}$$

$$= \begin{cases} 6\sigma^2 + f_1(k) & k=0 \\ 4\sigma^2 + f_2(k) & k=\pm 12 \\ \sigma^2 + f_3(k) & k=\pm 24 \\ \text{independent with } t & \text{o.w.} \end{cases}$$

So $\nabla_{12}^2(X_t, X_{t+24})$ is a stationary ts.