1 Least Square Estimators. 平稳,差分会算 UD ULS North less important (non-constant variance & correlated weight or variance & correlated weight or variance & correlated weight or variance & correlated & (non-constant variance & correlated) 0°V is known non-constant variance & 只告诉年卷 uncorrelated. independent of T(4) weight of Time lag => non-constant vasiance & L= 2 212 = 1 (y= 10 - 2 B)xj)2 (2) NOLS: uncorrelated Least squares normal equations:  $\frac{\partial L}{\partial B_0} = 0 \qquad \frac{\partial L}{\partial B_1} = 0 \qquad \frac{\partial L}{\partial B_1} = 0$ B= (x'x) + x'y / E[Bos] = B Varifices) = o2(x'x)-27.WLS: L= (y-x/5)/W (y-x/5) = 2 wit (0) - Bo- 3 | Bj xj)2. To find Bucs, we can me normal equations or matrix Bucs = (XWX) + X'Wy. - El Bucs] = P \ varifswis) = (x'wx) 7 3) CLS: Transform original medy. Transform V-= y = V-= xp + V-= 2 -> satisfies ous requirement Bau= (XVTX) TXVTy / F[Bais]=p Var(|3acs)=8(XV-1X)-1

3) Underfitting & Overfitting.

Check unbiased/biased estimate. If biased, finel the bias.

[Idea: substitute the small matrix into the large one]

(4). Some Conclusions.

1) als estimator is the most attitient/smallest variance.
of the model coefficients / unbiased linear estimator.
( Proof is required).

2). When the errors are positively autocorrelated,
the residual mean square, may seriously underestimate
the error variance 52 by OLS.

3> In the above care, the selfs.) may be too small

2. Utility Tests & CI & PI

D SST = SSR + SSE  $\sum_{i=1}^{n} (y_i - \hat{y}_i)^2$   $\sum_{i=1}^{n} (y_i - \hat{y}_i)^2$   $SST \xrightarrow{DoF} DoF$   $SSR \xrightarrow{DoF} P-1$   $SSE \xrightarrow{PoF} DoF$   $SSE \xrightarrow{P$ 

E). T-test: Test on individual regression coefficients.

F-test: Test on groups of coefficients.

(3) 17 CI on regression welfinients Bi 的 = tay, n-p se(的) 公式要完多 where se (pj)= 12°55. where  $g^2 = \frac{sst}{n-p}$ . Ci) is the j-th diagonal of  $(x'x)^{-1}$ . 27 CI on mean response MyIXO y(x0) = to/2, n-p/82x0'(x'x)7x0 where  $g^2 = \frac{550}{n-p}$ 3> PI on the new observations. y(x0). g(x0) + to/2, np /32[1+x0/(x/x)7x0], 32= 35E 3. First-order autoregressive process W. Yt= βο+β, Xt + 2t., 2t= \$ 2t-1 + at } intere | φ| < 1, at ~NID (0, 5 m²) D If stil are positively autocorrelated. =) If we stirl apply of s, the consequences are a) Underestimate the error variance 10> Underestimate standard errors of welfinients.

10> Test & F-test no longer convincible. d) CISPI are narrower than the actual 因为任更小了 a) Anding missing variable (too hard to implement)
b) CLS (Require V), 就WLS
c) Use a nethod that accounts for autocorrelation muit 3) Solution.

(D) D-W test -> check the first-order autocorrelation a) Test statistiz: d & 2U-ri) D-W test Ho: \$=0 Ho: 中部 Hi: ゆ>a 気積を打型を Draste to interval 中 (本水水学の) in conclusive b) If d < 2 => Testing 1st-order positive autocorrelation. dedl, reject Ho., positively autocorrelated. dodu, accept He, uncorrelated > ded edu: test is incommissive If d>2 => Testing 1st-order regative autownelation. \_d= q-d (b) For St = 984+ at , At ~ NID(0.50), we have the following results ( & Proof is required) a) [t= \(\bar{\gamma}\) \(\Omega \tau - \bar{\gamma}\) a) Qu((2+, 2++j) = \$\frac{6a^2}{Lax} b) E[[i+]=0 e> Pr= p c>  $van(z+) = \sigma^2 = \sigma a^2 \left(\frac{1}{1-p^2}\right)$ especially P. = \$ (6) C-O Method. Yt'= Yt-PY+7= BOILD)+ BIX+-DX+0) +Ex-9 Ex-1 => Y== po+pix+ + a+ 17 Estimate \$ by using residuals of ols. lag-one sample correlation = n = \frac{1}{2} et2. 2) Apply the OLS to obtain 3 = PI/CI > OLS'S PI/CI (如河川岛,宾岛

D Maximum - Likelihood Method



a). Can unternt the likelihood / leg-likelihood function.

b). Should be able to how to obtain the estimate.

ex If E[[t] = 0 & St are normal and independent.
the MIE = LSE (无法溢 linear 治 non. -.