



ESEO Downlink Data

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Summary

This document provides details of downlink data for the AMSAT ESEO payload – based upon the FUNCube-1 spec for compatibility with the dashboard and data warehouse

Distribution: Confidential

Keywords:

Document-ID:

Issue: 1.1M

Date: 26 July 2016

Prepared: Graham Shirville

Revised: Chris Bridges, David Bowman

Checked:

Approved:

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Revision Record

| issue | date | total pages | Authorisation | affected pages | brief description of change |
|--------------|----------|-------------|---------------|----------------|---|
| 1.1 DRAFT | 22.03.15 | | | | Added details of where to look for extended sat-id. |
| 1.1 ESEO wip | 11.08.15 | | Graham | | Modified to reflect ESEO tlm..more work needed to finalise bit counts and channels in RT and WOD frames |
| 1.1f | 23.08.15 | | Graham | | Updated after discussions VZV/MRF and with FC team...pending further redefinitions on a skype Thursday 27th August |
| 1.1g | 24.08.15 | | Duncan | | Bit order defined – see section 2 |
| 1.1h | 28.08.15 | | Graham | | Revised after telcall. Agreed to concentrate on the RT and WOD coming from the EPS board directly and via the CAN bus from the RX & TX boards for the time being so that thermal testing can be undertaken asap Also followed Duncan's advice to make WOD frames parse better. |
| 1.1j | 28.08.15 | | Graham | | Various tweaks and move WOD frames |
| 1.1k | 18.06.16 | | Chris, ALL | | ESEO Workshop at Surrey Space Centre: Update RTT & WOD definitions for FSW & Dashboard |



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|------|------------|--|-------------------------|-----|---|
| 1.1L | 28.06.2016 | | Chris, David (Skype) | ALL | Updated RTT, WOD, Schedule |
| 1.1M | 19.07.2016 | | Chris, Pete | | Defined 2B as payload_header in 4k8 payload mode. Further edits from Skype call with team. |

List of TBD's and TBC's

| <i>TBC/TBD</i> | <i>Location</i> | <i>Subject</i> | <i>Due date</i> | <i>Action by</i> |
|----------------|-----------------|---|-----------------|------------------|
| | | Internally generated CCT debug / status data | | |
| | | Confirmation of platform EPS data via CAN | | |
| | | Detail of data format and limits from science payloads. – e.g. How much memory holds current valid data. / Start - finish address | | |



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List of Acronyms

| | |
|------|---------------------------------------|
| ANT | Antenna (board) |
| ADC | Analogue to Digital Converter |
| ACS | Attitude Control Subsystem |
| BCR | Battery Charge Regulator |
| BPSK | Binary Phase Shift Keying |
| CCT | Command Control and Telemetry (board) |
| EPS | Electrical Power Subsystem |
| FEC | Forward Error Correction |
| MSE | Material Science Experiment |
| PA | Power Amplifier (board) |
| RF | Radio Frequency (board) |
| RS | Reed Solomon (error-correction code) |
| SW | Software |
| TBC | To Be Confirmed |
| TBD | To Be Determined |
| TBW | To Be Written |
| TCS | Thermal Control Subsystem |
| TRX | Transponder |



1 Overview

This document defines the data downlink format for the telemetry transmitted by the AMSAT payload on ESEO. Both the content of each downlink frame and the transmission order of the different frame types will be addressed.

The FEC encoding method and frame size remains unchanged from the original :

"The Telemetry uses 1200bps BPSK with both convolution and block coding based on the proven AMSAT OSCAR-40 FEC telemetry model. The encoding starts with a 256 byte (2048 bit) data frame, this is passed through a pair of RS(160,128) encoders, a scrambler, convolution encoder and the interleaver. This produces 5200 bits to transmit. Thus, ignoring pre- and post-amble, each data frame will take 4.3s to transmit"

| | | |
|-----------------------------------|------------------|------------------|
| <i>8 bits</i> | <i>432 bits</i> | <i>1600 bits</i> |
| <i>Sat Id</i> | <i>Real Time</i> | |
| <i>8 bits</i> | <i>Telemetry</i> | <i>Payload</i> |
| <i>Frame</i> | | |
| <i>Type</i> | | |
| 2048 bits (256 byte) Frame | | |

Each frame consists of an 8 bit satellite id and a 8 bit frame type indicator then 432 bits of real time data followed by 1600 bits of payload data. This results in the required total frame size of 2048 bits (256 bytes). The FEC encoded data (5200 bits) together with 700ms of idle tones fixes the frame transmission rate to one frame every five seconds.

Additionally it is possible to configure the spacecraft to downlink debug status information in Fitter message slot 5.

2 Frame types

All data is transmitted MSB first i.e. in "network byte order" and the first 16 bits of each frame will indicate the Satellite Identification number as well as defining the contents of the final 1600 bits of the frame. i.e. Fitter message number or whole orbit data frame number. Values for Sat ID and frame type can be found in the Transmission Schedule table at the end of the document.

Frame types:

- Whole orbit data.
- Fitter messages.

Real Time Telemetry

Each 5 second frame starts with Sat ID and frame type then 432 bits of real time data. This real time data is updated every 5 seconds from sensors in the AMSAT Payload, from the AMSAT CCT board and from the ESEO platform housekeeping data.

Whole Orbit Data

This is intended to provide all the information required to demonstrate the physical and operational characteristics of the satellite over an entire orbit. The data will be sampled once per minute for 104 minutes and a full set of data is transmitted once every 24 frames or 2 minutes. Whole Orbit Data is received on the ground and presented in graphical form for educational outreach. Included are the battery voltage, system current and solar current collected together temperatures current and voltages from many subsystems.



Fitter Messages

These are the text messages received from ground stations to be periodically retransmitted within the 2 minutes telemetry sequence. Messages will not be broken up and sent over multiple frames, so the maximum length of a message is 200 bytes. The format of messages is transparent to the satellite, each received message will just be copied out verbatim.

Messages can be uploaded to specific AT32 memory slots with the slot id specified at upload time. After an upload attempt status bits in the Real Time Telemetry will be set to indicate the slot id and success or failure. An authentication (not encryption) scheme will be used to verify message validity.

3 Extended Sat Id/Frame Types

To ensure the data format and transmission type can be used with multiple satellites the ID scheme allows the ground station to determine the Sat Identity.

The format of the first two bytes is shown below. Satellite ID and frame type information are contained within these 16 bits.

| Byte 0 | | | | | | | | Byte 1 | | | | | | | |
|--------|----|------------|----------|----|----|----|----|--------|----|----|----|----|----|------------|----|
| Sat ID | | Frame Type | | | | | | Sat ID | | | | | | Frame Type | |
| S6 | S7 | F2 | F3 | F4 | F5 | F6 | F7 | S0 | S1 | S2 | S3 | S4 | S5 | F0 | F1 |
| 1 | 1 | D | Variable | | | | | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |

The original two bits of Sat ID are the least significant bits of a byte of Sat ID data, and first six bits of Frame Type are now the least significant bits of a byte of Frame Type data. Frame Type 40 is used for debugging.

For ESEO payload transfer, F0 is set to 1 and the following 2B is for ESEO Science payload data which is a packet index (or counter) addressing 64 KB in 252B chunks (256B – 2B header – 2B packet index).

For satellites using this Extended Identification scheme, the overview diagram of a 5 second frame is:

| | | | |
|-----------------------------------|---------------|------------------|------------------|
| <i>2 bits</i> | <i>6 bits</i> | <i>432 bits</i> | <i>1600 bits</i> |
| <i>Sat Id</i> | <i>Sat Id</i> | <i>Real Time</i> | <i>Payload</i> |
| <i>6 bits</i> | <i>2 bits</i> | <i>Telemetry</i> | |
| <i>Frame</i> | <i>Frame</i> | | |
| <i>Type</i> | <i>Type</i> | | |
| 2048 bits (256 byte) Frame | | | |



4 Data sources:

AMSAT – The AMSAT payload via internal wiring and I2C
OBD – The main on board data handling computer via CAN bus
STX – S Band transmitter
ACS – Attitude Control System
SSM – Sun Sensor main
MWM – Momentum Wheel main
GPS – Global positioning system receiver
PMM – Power Management Unit main

5 Data Collection/Transmission

This section details the rate at which data is collected and from which sensors. The table also defines the order and bit format for transmission.

Real Time Telemetry: Total 448 bits / 56 bytes (inc 8 bits sat ID and 8 bits frame type)

Collection Frequency: every 5 seconds

Storage Count: 0 (real time!)



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| Bit total | Frame Type + SAT ID | Data Source | Data Type | Data Channel Name |
|-----------|---------------------|-------------|-------------|---|
| 8 | 1 & 2 | Local | UNSIGNED8 | SAT ID 2 bits, Frame type 6 bits |
| 16 | 1 & 2 | Local | UNSIGNED8 | SAT ID 6 Bits, Frame type 2 bits |
| Bit total | Real Time | Data Source | Data Type | Data Channel Name |
| 24 | 1 & 2 | AMSAT CCT | UNSIGNED8 | EPS DC/DC Converter output voltage (10b) |
| 32 | 1 & 2 | AMSAT CCT | UNSIGNED8 | EPS DC/DC Converter output current (10b) |
| 40 | 1 & 2 | AMSAT CCT | UNSIGNED8 | EPS DC/DC Converter temperature (10b) |
| 48 | 1 & 2 | AMSAT CCT | UNSIGNED8 | EPS Enclosure temperature (10b) |
| 56 | 1 & 2 | AMSAT CCT | UNSIGNED8 | CCT Processor temperature (10b) |
| 64 | 1 & 2 | AMSAT CCT | UNSIGNED8 | EPS 3.3 V Voltage (10b) |
| 72 | 1 & 2 | AMSAT CCT | UNSIGNED8 | EPS 3.3 V Current (10b) |
| 80 | 1 & 2 | AMSAT CCT | UNSIGNED8 | EPS 6/9 V Voltage (10b) |
| 88 | 1 & 2 | AMSAT CCT | UNSIGNED8 | EPS 6/9 V Current (10b) |
| 96 | 1 & 2 | AMSAT CCT | UNSIGNED8 | EPS 9 V Voltage (10b) |
| 104 | 1 & 2 | AMSAT CCT | UNSIGNED8 | EPS 9 V Current (10b) |
| 112 | 1 & 2 | AMSAT TX | UNSIGNED8 | VHF transmitter forward power |
| 120 | 1 & 2 | AMSAT TX | UNSIGNED8 | VHF transmitter reflected power |
| 128 | 1 & 2 | AMSAT TX | UNSIGNED8 | FM power amplifier temperature (10b) |
| 136 | 1 & 2 | AMSAT TX | UNSIGNED8 | BPSK power amplifier temperature (10b) |
| 144 | 1 & 2 | AMSAT TX | UNSIGNED8 | BPSK power amplifier current (10b) |
| 152 | 1 & 2 | AMSAT TX | UNSIGNED8 | BPSK 3.3V supply current (Osc + driver amp) |
| 160 | 1 & 2 | AMSAT RX | UNSIGNED8 | L-Band transponder receiver RSSI (10b) |
| 168 | 1 & 2 | AMSAT RX | UNSIGNED8 | L-Band command receiver RSSI (10b) |
| 176 | 1 & 2 | AMSAT RX | UNSIGNED8 | L-Band command receiver Doppler (10b) |
| 184 | 1 & 2 | AMSAT RX | UNSIGNED8 | L-Band CMD receiver oscillator temperature (10b) |
| 192 | 1 & 2 | AMSAT CCT | UNSIGNED24 | Sequence number |
| 216 | 1 & 2 | AMSAT CCT | UNSIGNED8 | Last Command |
| 224 | 1 & 2 | AMSAT CCT | UNSIGNED3 | RF Mode: 0x00: Receive only, with data collection 0x01: Low power BPSK telem mode 0x02: High power BPSK telem mode 0x03: Low power transponder mode 0x04: High power transponder mode 0x05: Autonomous Mode |
| 227 | 1 & 2 | AMSAT CCT | UNSIGNED2 | Data Mode: 0x00: AMS + ESEO data mode at 1k2 (default) 0x01: AMS + ESEO data + Payload mode at 4k8 |
| 229 | 1 & 2 | AMSAT CCT | 1 | Payload Transfer Status: 0x00: Get data from payload 0x01: Downlink data to ground |
| 230 | 1 & 2 | AMSAT CCT | 1 1 1 | FM Transponder Status: ESEO Eclipse State (0 = no, 1 = yes) Autonomous Mode State (0 = A, 1 = B) CTCSS Detect State (0 = OFF, 1 = ON) |
| 233 | 1 & 2 | AMSAT CCT | 1 | Safe mode state |
| 234 | 1 & 2 | AMSAT CCT | 1 | In Safe mode (over temperature protection - Traco) |



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| Bit total | Real Time | Data Source | Data Type | Data Channel Name |
|-----------|-----------|--------------------------|-----------------------|--|
| 235 | Only 1 | ESEO OBC | UNSIGNED16 | PMM_VOLTAGE_SP1_STRING_1 Solar panel voltage for eclipse detection |
| 251 | Only 1 | ESEO OBC | UNSIGNED16 | PMM_VOLTAGE_SP2_STRING_1 |
| 267 | Only 1 | ESEO OBC | UNSIGNED16 | PMM_VOLTAGE_SP3_STRING_1 |
| 283 | Only 1 | ESEO OBC | UNSIGNED8 | ESEO_OBD_MODE 0x00: OBDH power up 0x01: AOCS initialization 0x02: AOCS damping 0x04: AOCS normal SUN 0x08: AOCS normal ECLIPSE 0x10: Safe mode S1: minor main bus power down 0x20: Safe mode S2: sever main bus power down 0x40: Safe mode S3: major main bus power down |
| 291 | Only 1 | ESEO OBC | UNSIGNED20 | ESEO_OBD_EQUIPMENT_STATUS: 0: TMTC main ON/OFF 1: TMTC redundant ON/OFF 2: Power Management Unit main ON/OFF 3: Power Management Unit redundant ON/OFF 4: Sun sensor main ON/OFF 5: Sun sensor redundant ON/OFF 6: Earth sensor ON/OFF 7: Magnetometer main ON/OFF 8: Magnetometer redundant ON/OFF 9: Magnetic Torquer main ON/OFF 10: Magnetic Torquer redundant ON/OFF 11: Momentum Wheel main ON/OFF 12: Momentum Wheel redundant ON/OFF 13: TRITEL ON/OFF 14: Langmuir Probe ON/OFF 15: uCAM ON/OFF 16: De-orbit mechanism ON/OFF 17: AMSAT-UK ON/OFF (Always on) 18: S-Band ON/OFF 19: GPS receiver ON/OFF |
| 311 | Only 1 | ESEO OBC | UNSIGNED8 | OBD_WD_RESET_COUNT |
| 319 | Only 1 | ESEO OBC | REAL32 | ACS_OMEGA_P (Roll, deg/s) |
| 351 | Only 1 | ESEO OBC | REAL32 | ACS_OMEGA_Q (Pitch) |
| 383 | Only 1 | ESEO OBC | REAL32 | ACS_OMEGA_R (Yaw) |
| 415 | Only 1 | ESEO OBC | UNSIGNED8 | STX_TEMP_4 (S-band Amplifier temperature) |
| 423 | Only 1 | ESEO OBC | UNSIGNED8 | PMM_VOLTAGE_MB (16b) (Main Bus Voltage) |
| Total | 431 bits | Spare = 1 bits | | |
| 235 | Only 2 | ESEO OBC | REAL32 | ACS_ORBIT_x (Orbital position) |
| 267 | Only 2 | ESEO OBC | REAL32 | ACS_ORBIT_y |
| 299 | Only 2 | ESEO OBC | REAL32 | ACS_ORBIT_z |
| 331 | Only 2 | ESEO OBC | UNSIGNED16 | PMM_AMSAT_CURRENT (16b) (AMSAT Switch current) |
| 347 | Only 2 | ESEO OBC | UNSIGNED8 (was 16) | MWM_VOLTAGE (Momentum wheel Measured DC-link voltage) |
| 355 | Only 2 | ESEO OBC | UNSIGNED16 | MWM_CURRENT (Momentum wheel Measured current) |
| 371 | Only 2 | ESEO OBC | UNSIGNED16 | MWM_OMEGAMESURED (Measured rotation speed) |
| 387 | Only 2 | ESEO OBC | SIGNED16 | MPS_HPT01 (High Pressure Transducer measures tank pressure) |
| 403 | Only 2 | ESEO OBC | SIGNED12 | PMM_TEMP_SP1_SENS_1 (Temp. of the solar panel 1) |
| 415 | Only 2 | ESEO OBC | SIGNED12 | PMM_TEMP_BP1_SENS_1 (Temp. of battery pack 1) |
| Total | 427 bits | Spare = 5 bits | | |



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Whole Orbit Data:

Collection Frequency: Every 60 seconds

Storage Count: 100 (minutes)

| Total Bits | Frame Type | Bits per src | Data Source | Bits Per Channel | Data Channel Name |
|---|-------------------------|--|-----------------------|---|---|
| 298 Bits x 100 = 298 bits 3725 bytes | Whole Orbit Data | 88 | AMSAT EPS | UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 | A: Processor Temp. (10b) B: Enclosure temp. (10b) C: DCDC Converter temp. (10b) D: DCDC Supply Current (10b) E: DCDC Supply Voltage (10b) F: 6/9V Transponder amp. supply voltage (10b) G: EPS 9V Voltage (10b) H: EPS 3V3 Voltage (10b) I: 6/9V Transponder amp. supply current (10b) J: EPS 3V3 Current (10b) K: EPS 9V Current (10b) |
| | | 32 | AMSAT L-RECEIVER | UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 | L-Band transponder RSSI freq. (10b) L-Band command Doppler (10b) L-Band command RSSI (10b) L-Band command oscillator temp. (10b) |
| | | 48 | AMSAT VHF TRANSMITTER | UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 UNSIGNED8 | A: BPSK PA temp. (10b) B: Forward power (10b) C: Reverse power (10b) D: BPSK PA Current (10b) E: FM PA Current (10b) F: FM PA temp. (10b) G: <Unused> H: <Unused> |
| | | 50 | AMSAT CCT | UNSIGNED8 UNSIGNED4 UNSIGNED8 UNSIGNED13 UNSIGNED4 UNSIGNED13 | Command Watchdog time remaining (hours) No. of uplink packets received (16b) RAM Memory Error Count CAN Bus Communications Status Packet 1: ESEO Master, CANopen Transactions (32b) AMS Master, Payload Number (4b), AMS Master, CANopen Transactions (32b) |
| | | 48 | ESEO CAN (EPS) | SIGNED8 SIGNED8 SIGNED8 SIGNED8 UNSIGNED16 | From AS-12_0005-SYS-PLA-OBDAH-AR-03.pdf: PMM_TEMP_SP1_SENS_1 (16b), Solar panel 1 temperature PMM_TEMP_SP2_SENS_1 (16b) PMM_TEMP_SP3_SENS_1 (16b) PMM_CURRENT_BP1 (16b), Battery pack 1 current PMM_VOLTAGE_MB (16b), Main Bus Voltage |
| | | 32 | ESEO CAN (ADCS) | SIGNED32 | Absolute angular rotation (use ACS P, Q, R) |
| | | (37.25 Bytes * 100 Storage Count) = 3725 bytes | | | |
| | | 4000 bytes / 200 (payload size) = 20 = Transmitted in 20 payloads | | | |



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Fitter Messages:

Collection Frequency: N/A

Storage Count: 4

| Total Bits | Frame Type | Bits per source | Data Source | Bits Per Channel | Data Chanel Name |
|--|----------------------------|-----------------|-------------|------------------|------------------|
| 1600 bits 200 bytes | Fitter Message Data | 1600 | RAM | 1600 | Fitter message |
| (200 Bytes * 4 Storage Count) = 800 bytes TBC | | | | | |
| 800 bytes / 200 (payload size) = 4 =Transmitted in 4 payloads TBC | | | | | |

6 Transmission Schedule

The above data collection strategy results in:

20 Whole orbit frames

4 Fitter message frames

Each frame also contains the Real Time Telemetry information, so this will be sent every 5 seconds. The order of frames will be as shown below

| Frame Type | Frame Type | Frame id |
|-----------------------|------------|----------|
| RTT1 + Fitter Message | FM1 | 01 |
| RTT2 + Whole Orbit | W01 | 02 |
| RTT1 + Whole Orbit | W02 | 03 |
| RTT2 + Whole Orbit | W03 | 04 |
| RTT1 + Whole Orbit | W04 | 05 |
| RTT2 + Whole Orbit | W05 | 06 |
| RTT1 + Fitter Message | FM2 | 07 |
| RTT2 + Whole Orbit | W06 | 08 |
| RTT1 + Whole Orbit | W07 | 09 |
| RTT2 + Whole Orbit | W08 | 10 |
| RTT1 + Whole Orbit | W09 | 11 |
| RTT2 + Whole Orbit | W10 | 12 |
| RTT1 + Fitter Message | FM3 | 13 |
| RTT2 + Whole Orbit | W11 | 14 |
| RTT1 + Whole Orbit | W12 | 15 |
| RTT2 + Whole Orbit | W13 | 16 |
| RTT1 + Whole Orbit | W14 | 17 |
| RTT2 + Whole Orbit | W15 | 18 |
| RTT1 + Fitter Message | FM4 | 16 |
| RTT2 + Whole Orbit | W16 | 20 |
| RTT1 + Whole Orbit | W17 | 21 |
| RTT2 + Whole Orbit | W18 | 22 |
| RTT1 + Whole Orbit | W19 | 23 |
| RTT2 + Whole Orbit | W20 | 24 |



With each frame requiring 5 seconds to transmit the sequence of frames will repeat every 120 seconds (two minutes).

7 Fitter Message Slot x debug data

Fitter message slot 4 can be used on command to send de-bug data from the AMSAT CCT board to assist with fault identification.

Size 200 bytes. Content TBD