

# Understanding Convolution

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## Definition

The convolution of two sequences  $x[n]$  and  $h[n]$ :

$$(x * h)[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

Intuitively, we are placing a shifted copy of the sequence  $h$  centered at  $x = k$ , and multiplying this by the  $k_{th}$  element in the sequence  $x[n]$ . We do this for all elements  $x[k]$  in the input sequence and add the results.

Note that convolution is commutative, distributive, and associative.

## Output of LTI System

Assume  $T$  is a linear time invariant system. Then:

$$\begin{aligned} T\{\delta[n]\} &= h[n] \text{ (impulse response)} \\ \implies T\{x[n]\} &= \sum_{k=-\infty}^{k=\infty} x[k]h[n-k] \end{aligned}$$

## Model Ultrasound System as LTI System

Consider a single ultrasound transducer, and assume that we use it to transmit a signal, which is then reflected and received by the transducer. Let us define an ultrasound system  $U$  that maps from transducer input excitation to the final signal decoded by the transducer:

$$U = T_x \circ M_x \circ R_x$$

where  $T_x$  is the transmission operator,  $M_x$  is the reflection operator (acts like a “mirror”), and  $R_x$  is the receiving operator.

If we ignore the transmission delay, and assume that the reflected signal is identical to the transmitted signal up to a change in amplitude, then:

$$M_x\{x[n]\} = A \cdot x[n]$$

where  $A \in \mathbb{R}$ .

In our simulations we assume that the both  $T_x$  and  $R_x$  are LTI systems, with the same impulse response. Call this common transducer impulse response  $h$ .

Using these definitions, we can calculate the output of the ultrasound system:

$$\begin{aligned} U\{x[n]\} &= T_x \circ M_x \circ R_x\{x[n]\} \\ &= h[n] * (A \cdot h[n] * x[n]) \\ &= A \cdot (h[n] * h[n]) * x[n] \end{aligned}$$

where we have used the fact that convolution is commutative.

## Motivation

So, in order to understand the action of the ultrasound system, it would be useful to understand the properties of  $h[n] * h[n]$ , since this is the impulse response of the entire system (up to a scalar multiple).

## Problem Statement

Investigate the properties of the self convolution  $(h * h)[n]$  of a sequence  $h : \mathbb{Z} \rightarrow \mathbb{R}$ , in the context of an ultrasound system.

## Solution

### Causal

I assume there is no noise in the ultrasound system to be modeled. I assume that in a noise free ultrasound system, the system will not begin to transmit data prior to excitation, and the system will not begin to receive data prior to a transmitted signal hitting the receiver. Therefore:

$$h[n] = 0 \text{ for } n < 0 \implies (h * h)[n] = 0 \text{ for } n < 0$$

This implies that the LTI system  $h * h$  is causal.

### Stable

I assume that if we stop exciting the transducer, then after a finite amount of time the ultrasound receiver will stop receiving anything. That is:

$$(h * h)[n] = 0 \text{ for } n \geq N$$

This implies that we are working with a finite impulse response system, and therefore the system is stable.

### Not Memory-less

The output  $y[n]$  depends on all values of the input  $h[n]$ , not just the current value of  $n$ . Therefore, the system is not memory-less.

### Equation for Output

The output of the system  $(h * h)[n]$  is explicitly:

$$(h * h)[n] = \sum_{k=-\infty}^{\infty} h[k]h[n-k]$$

Since the system is causal, we only need to sum over the terms where  $k \geq 0$  and  $n - k \geq 0 \implies k \leq n$ :

$$(h * h)[n] = \sum_{k=0}^n h[k]h[n-k]$$

To get some intuition, we write out this sum explicitly in the case when  $h[0] = 1, h[1] = 2, h[2] = 3, h[3] = 4, h[4] = 5$  and  $h[j] = 0$  for all other  $j \in \mathbb{Z}$ :

$$(h * h)[n] = h[0]h[n] + h[1]h[n-1] + h[2]h[n-2] + h[3]h[n-3] + h[4]h[n-4]$$

## Nonzero Output Region As Function of Length

Let  $L$  be an integer called the “length” of the impulse response. We provide elements  $h[0], h[1], \dots, h[L-1]$  to MATLAB when specifying the impulse response. We require  $L \geq 1$  and  $h[n] = 0$  for all  $n \geq L$ .

We assume that our impulse response starts at zero and ends at zero, so set  $h[0] = h[L-1] = 0$ .

Using this information, we can rewrite the form of the output  $(h * h)[n]$ . We are interesting in determining exactly at which times the output can be nonzero. The output  $(h * h)[n]$  will be zero at  $n$  if:

$$h[k]h[n-k] = 0 \text{ for } k = 0, 1, \dots, n$$

Since we assume  $h[0] = 0$  and  $(h * h)[n] = 0$  for all  $n \geq L-1$ , we can reduce the number of terms under consideration. Specifically, if  $n \geq L-1$ , then the output is zero, and if  $n \leq 0$  then the output is zero. So, it remains to consider the cases in which  $1 \leq n \leq L-2$ . These are the only cases in which would possibly get nonzero output.

We can further restrict these cases by realizing that if  $L \leq 2$ , then the entire sequence is zero and so the output will be zero. So, we only need to consider the cases  $1 \leq n \leq L-2$  where  $L \geq 3$ . We want to know for which of these  $n$  values we have a chance for nonzero output, as a function of  $L$  (clearly the maximum  $n$  for nonzero output will increase with  $L$ ).

Our strategy is to start small and search for a pattern:

If  $n = 1$ :

$$h[k]h[n-k] = h[k]h[1-k]$$

Since  $1-k \leq 0$  for  $k = 1, \dots, L-2$ , the output is always zero in this case. As a result, we only need to consider the possible nonzero cases as consisting of  $2 \leq n \leq L-2$ .

If  $n = 2$ :

$$h[k]h[n-k] = h[k]h[2-k]$$

The possible nonzero  $h[i]$  range is  $i = 1, 2, \dots, L-2$ . Checking when we are in this range:

$$\begin{aligned} 1 \leq 2-k \leq L-2 \\ \implies k \leq 1 \text{ and} \\ \implies 4 \leq L+k \implies k \geq 4-L \end{aligned}$$

Together:

$$4-L \leq k \leq 1$$

In order to satisfy this inequality, we need:

$$4-L \leq 1 \implies L \geq 3$$

We also need:

$$4-L \leq k_{max}, 1 \geq k_{min}$$

Where  $k_{max}$  is the largest value  $k$  can take on, and  $k_{min}$  is the smallest value  $k$  can take on, while preserving the fact that  $h[k]$  might be nonzero. From our work before,  $k_{max} = L-2$  and  $k_{min} = 1$ .

So, we need:

$$\begin{aligned} 4-L \leq L-2, 1 \geq 1 \\ \implies 2L \geq 6 \implies L \geq 3 \end{aligned}$$

So,  $(h * h)[2]$  has a chance to be nonzero when  $L \geq 3$ .

Let's generalize this argument, setting  $n = a$ :

$$h[k]h[n-k] = h[k]h[a-k]$$

The possible nonzero  $h[i]$  range is  $i = 1, 2, \dots, L-2$ . Checking when we are in this range:

$$1 \leq a-k \leq L-2$$

$$\implies k \leq a-1 \text{ and}$$

$$\implies a+2 \leq L+k \implies k \geq a+2-L$$

Together:

$$a+2-L \leq k \leq a-1 \implies L \geq 3$$

We also need:

$$a+2-L \leq k_{max}, a-1 \geq k_{min}$$

Where  $k_{max}$  is the largest value  $k$  can take on, and  $k_{min}$  is the smallest value  $k$  can take on, while preserving the chance that  $h[k]$  might be nonzero. From our work before,  $k_{max} = L-2$  and  $k_{min} = 1$ .

So, we need:

$$\begin{aligned} a+2-L &\leq L-2, \quad a-1 \geq 1 \\ \implies 2L &\geq a+4 \implies L \geq \frac{a+4}{2} \end{aligned}$$

Substituting  $n = a$ , we find  $(h * h)[n]$  has a chance to be nonzero when  $L \geq \frac{n+4}{2}$ . That means when we are computing the sum to get the response, we only need to add terms from  $n = 1$  to  $2L-4$ .