

✔ Applying boundary conditions

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Again, a plane truss is defined through the vectors x and y as in Prob. 1. Similarly, the connectivity is also defined in conn . As before, sketch the geometry on a piece of paper. The ground on which the truss rests is perpendicular to the x axis.

A force P of 1000 KN is applied at node 1 in the positive y direction.

Nodes 2 and 3 are hinged. All truss elements are made of steel with $E = 210 \text{ GPa}$ and area of cross section $A = 6 \times 10^{-4} \text{ m}^2$.

In addition to the load P , node 1 has an additional displacement of 50 mm in the negative x direction caused by a gradual sinking of the support into the ground.

Form the destination array dest and assemble the global stiffness Kg , like in the previous problem. Also form the global force vector F .

Finally modify Kg and F for the given boundary conditions. Note that, after modification, Kg must be non-singular and hence, invertible. In other words $\text{eig}(\text{Kg})$ should yield all non-zero eigenvalues.

Use N for force units and m for length.

```
% problem 2 for quiz 2, plane truss, boundary conditions
EA=210e09*6e-04;
% nodal coordinates
x=[0 3 0];
y=[0 4 4];
nnode=length(x);
% element connectivity
conn = [2 1;1 3];
nelem= size(conn, 1);
% destination array
for ielem=1:nelem
    n1=conn(ielem,1); n2=conn(ielem,2);
    dest(ielem,:)= [2*n1-1;2*n1;2*n2-1;2*n2];
end
% form element stiffness and assemble
tot_ndof = 2*nnode; %size of the global stiffness
Kg = zeros(tot_ndof); % initialise global stiffness to zeros

for ielem=1:nelem
    n1=conn(ielem,1); n2=conn(ielem,2);
    dx=x(n2)-x(n1); dy=y(n2)-y(n1);
    L=sqrt(dx^2+dy^2);
    c=dx/L; s=dy/L;
    Ke = (EA/L)*[ c^2      c*s     -c^2     -c*s;
                  c*s      s^2     -c*s     -s^2;
                  -c^2     -c*s     c^2      c*s;
                  -c*s     -s^2     c*s      s^2];
    dofs = dest(ielem,:);
    Kg(dofs,dofs) = Kg(dofs,dofs) + Ke;
end
```

```

% % form rhs force vector
P=1000e03;
F = zeros(tot_ndof,1);
F(2)=P;

% % apply boundary conditions, modify force and global stiffness store
in Kgprime and Fprime
Fprime=F;
Kgprime=Kg;
% === impose essential BCs, keep sizes 6x6 and 6x1 ===
% known displacements: u1x = -0.05 m; node 2 and node 3 fully fixed
bc_dofs = [1 3 4 5 6];
u_presc = zeros(tot_ndof,1);
u_presc(1) = -0.05;

% move known displacements to RHS using ORIGINAL Kg (not yet modified)
Fprime = F - Kg(:,bc_dofs)*u_presc(bc_dofs);

% modify stiffness and put prescribed values into Fprime at BC dofs
Kgprime = Kg;
for d = bc_dofs
    Kgprime(d,:) = 0;
    Kgprime(:,d) = 0;
    Kgprime(d,d) = 1;
    Fprime(d) = u_presc(d);
end

```