

$$2.1. \quad \dot{x} = \sin x \quad (1)$$

$$\frac{dx}{dt} = \sin x.$$

$$\frac{dt}{dx} = \frac{1}{\sin x}.$$

$$\int_0^t dt' = \int_0^x \frac{du}{\sin u}$$

$$t = - \int_0^x \frac{\sin u}{\sin^2 u} du \\ = \int_0^x \frac{1}{1 - \cos^2 u} du$$

$$\cos u = w \Leftrightarrow u = \arccos w.$$

$$\begin{array}{c|c} u & 0 \rightarrow x \\ w & 1 \rightarrow \cos x \end{array}$$

$$\Leftrightarrow t = - \int_1^{\cos x} \frac{dw}{1 - w^2}$$

$$= - \frac{1}{2} \left[ \int_1^{\cos x} \frac{dw}{1+w} + \int_1^{\cos x} \frac{dw}{1-w} \right]$$

$$\left. \begin{aligned} \frac{1}{(1+w)(1-w)} &= \frac{a}{1-w} + \frac{b}{1+w} \\ 1 &= a(1-w) + b(1+w). \\ (w+1) \cdot 1 &= 0 + b \cdot 2 \\ \therefore b &= \frac{1}{2} \\ (w-1) \cdot 1 &= a(1-w) + 0. \\ \therefore a &= \frac{1}{2} \end{aligned} \right\}$$

$$t = - \frac{1}{2} \left( \left[ \log |1+w| \right]_{-1}^{\cos x} - \left[ \log |1-w| \right]_{-1}^{\cos x} \right)$$

$$= - \frac{1}{2} \left( \log |1+\cos x| - \log |1-\cos x| - (\log^2 + \log^0) \right).$$

$$= - \frac{1}{2} \left( \log \left| \frac{1+\cos x}{1-\cos x} \right| \right) + \frac{1}{2} \log \frac{0}{2}$$

const. M.C. etc.

$$\therefore t = \frac{1}{2} \log \left| \frac{1-\cos x}{1+\cos x} \right| + C$$

(C: const.)

The initial condition exists

$$x = x_0 \text{ where } t = 0.$$

Then

$$0 = \frac{1}{2} \log \left| \frac{1-\cos x_0}{1+\cos x_0} \right| + C$$

$$C = - \frac{1}{2} \log \left| \frac{1-\cos x_0}{1+\cos x_0} \right|$$

The solution of the equation (1) is

$$t = \frac{1}{2} \log \left| \frac{1-\cos x}{1+\cos x} \right| - \frac{1}{2} \log \left| \frac{1-\cos x_0}{1+\cos x_0} \right| \quad (2)$$

Now,

$$(1) \quad x_0 = \frac{\pi}{4}, \text{ for any } t > 0.$$

What is character of (2), especially  $t \rightarrow \infty$ .

$$t = \frac{1}{2} \log \left| \frac{1+\cos x}{1-\cos x} \right| - \frac{1}{2} \log \left| \frac{\sqrt{2} + 1}{\sqrt{2} - 1} \right|$$

$$(2) \quad \text{for any initial conditions, } x_0, \quad ?$$

$$t \rightarrow \infty, \text{ then}$$

How move

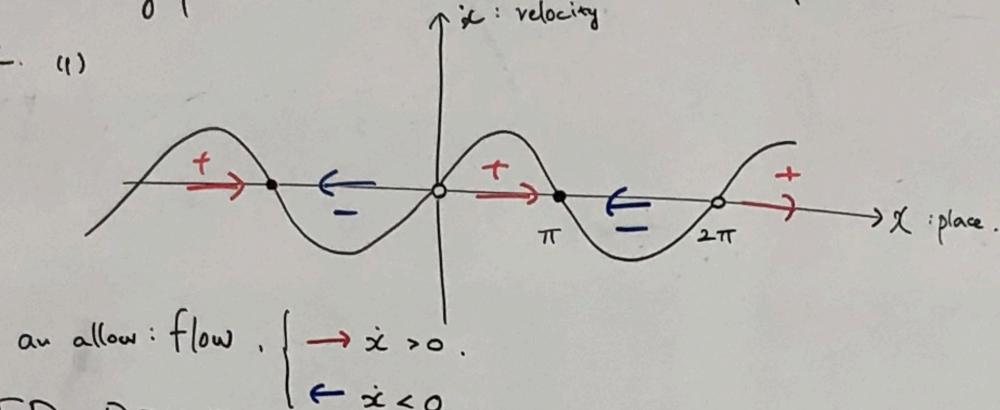
$$t = \gamma(t), \quad ?$$

→ These are too difficult...

まちがい  
あります

In contrast, a graphical analysis of (1) is clear and simple as shown in Figure followed:

$$\dot{x} = \sin x. \quad (1)$$



### FIXED POINT

- solid black point : stable fixed points , attractors or repellers → end points of flows
- open circle : unstable fixed points , sinks or sources (  $\because$  There is no flow  $\dot{x}$ , where  $\dot{x}=0$  ) → start points of flows

简单  $\Rightarrow$   $\dot{x} = \sin x$

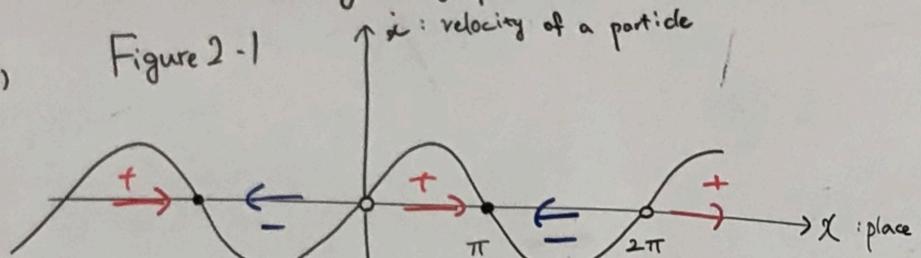
With this Figure,

We can now easily understand the solutions to the differential equation  $\dot{x} = \sin x$

We just start our imaginary particle at  $x_0$  and watch how it is carried along by the flow.

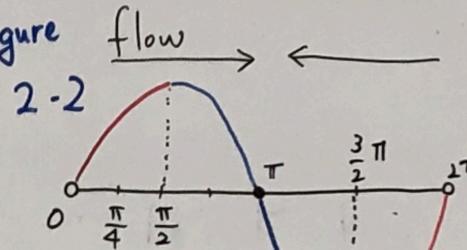
$$\dot{x} = \sin x. \quad (1)$$

Figure 2-1



an arrow: flow .  $\begin{cases} \rightarrow \dot{x} > 0 \\ \leftarrow \dot{x} < 0. \end{cases}$

Figure 2-2



$$\frac{d\dot{x}}{dt} = \ddot{x}: \text{Acceleration } (+)$$

if  $\dot{x} > 0 (+)$ .

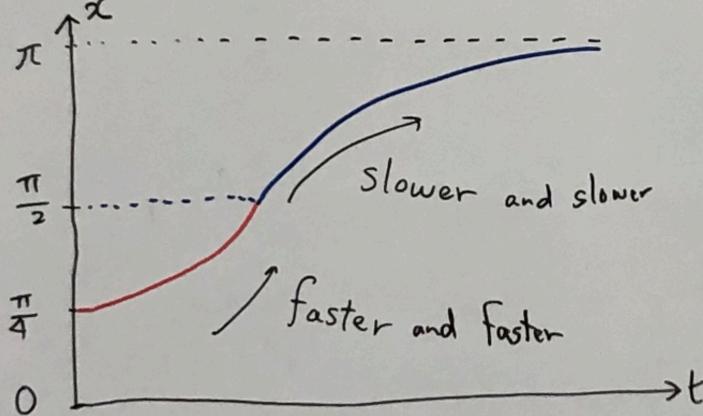
a particle moves faster  
and faster until  $\frac{2n+1}{2}\pi$   
( $n = 0, 1, 2, \dots$ ).

if  $\dot{x} < 0 (-)$ .

a particle moves slower  
and slower until  $(2n+1)\pi$   
( $n = 0, 1, 2, \dots$ )

This approach allows us to answer the questions above as follows:

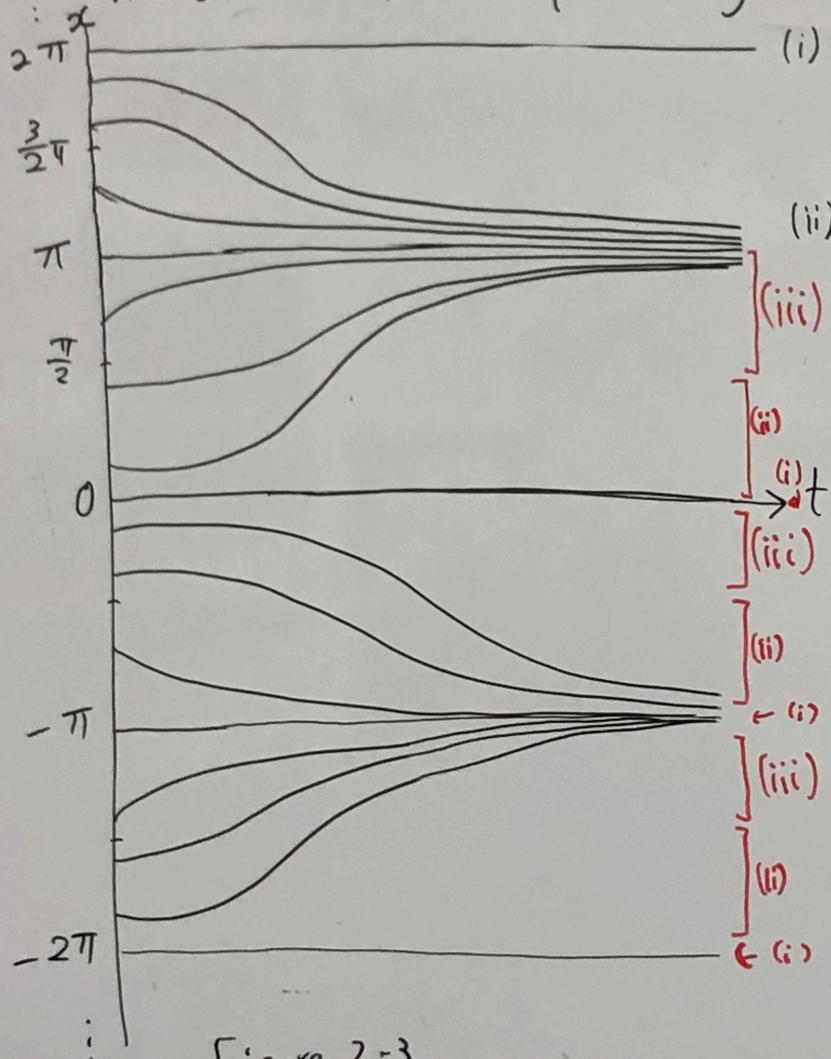
- (1) From Figure 2-2 helps to understand a trajectory of the particle,  
and Figure 2-3 shows one.



$t \rightarrow \infty$ , the particle moves  
and stable  $x = \pi$

Figure 2-3.

(2) For any initial condition,  $x_0$ . By same way (1), figure 2-3,  
we can understand the particles trajectories.



(i)  $x_0 = 2n\pi$  ( $n=0, 1, 2, \dots$ ), e.g.  $x_0 = 0, x_0 = \pi$   
the particles do not move.

(ii)  $2n\pi < x_0 < \frac{2n+1}{2}\pi$  ( $n=0, 1, 2, \dots$ ), e.g.  $x_0 = \frac{\pi}{4}$

First, the particles moves to  $x = 2(n+1)\pi$  faster and faster  
until  $x = \frac{2n+1}{2}\pi$

Next, from  $x = \frac{2n+1}{2}\pi$ , these velocities slow down  
until  $x = 2(n+1)\pi$

Finally,  $t \rightarrow \infty$ , they will be stable at  $x = 2(n+1)\pi$ .

(iii)  $\frac{2n+1}{2}\pi < x_0 < 2n\pi$  ( $n=0, 1, 2, \dots$ ) e.g.  $x_0 = \frac{3}{2}\pi$

The particles moves to  $x = 2n\pi$  and slower and slower.

Afterwards,  $t \rightarrow \infty$ , they also become stable at  $x = 2n\pi$ .

Figure 2-3

# EXERCISES FOR CHAPTER 2-1.

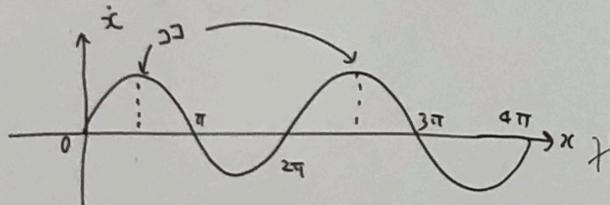
In the next three exercises, interpret  $\dot{x} = \sin x$  as a flow on the line. (20.0 μm)

2.1.1 Find all the fixed points of the flow.

No flows are  $\dot{x} = 0$ . So we can find  $x$ , where  $\sin x = 0$ .

$$\therefore x = n\pi \quad (n = 0, 1, 2, \dots)$$

2.1.2 At which points  $x$  does the flow have greatest velocity to the right?



$\dot{x} = 0$  is greatest velocity. Now, a direction of particles is right, then the range is  $[2n\pi, (2n+1)\pi] \quad (n = 0, 1, 2, \dots)$ . ( $\because \dot{x} > 0$ )  
The maximum velocitys are  $x = \frac{5n+1}{2}\pi \quad (n = 0, 1, 2, \dots)$

# EXERCISES FOR CHAPTER 2-1.

2.1.3.

- a) Find the flow's acceleration  $\ddot{x}$  as a function of  $x$ .

$$\ddot{x} = \frac{d\dot{x}}{dt} = \frac{dx}{dx} \cdot \frac{d\dot{x}}{dt} = \frac{d}{dx}(\sin x) \cdot \sin x = \cos x \sin x = \frac{1}{2} \sin 2x$$

- b) Find the points  $x$  where the flow has maximum positive acceleration.

Same solution at 2.1.2.

# EXERCISES FOR CHAPTER 2-1.

$$\begin{aligned}
 t &= \frac{1}{2} \log \left| \frac{1 - \cos x}{1 + \cos x} \right| \xrightarrow{-\frac{1}{2} \log \left| \frac{1 - \frac{1}{\sqrt{2}}}{1 + \frac{1}{\sqrt{2}}} \right|} \frac{\sqrt{2} - 1}{\sqrt{2} + 1} \\
 &= \frac{1}{2} \log \left| \frac{1 - \cos x}{1 + \cos x} \right| + \frac{1}{2} \log \left| \frac{\sqrt{2} + 1}{\sqrt{2} - 1} \right| \xrightarrow{\text{rationalizing the denominator}} \frac{3+2\sqrt{2}}{3-2\sqrt{2}} \\
 &= \log \left( \tan \frac{x}{2} \right) + \log (1 + \sqrt{2}) \quad \left( \sqrt{3+2\sqrt{2}} = 1 + \sqrt{2} \right)
 \end{aligned}$$

$$\frac{1 - \cos x}{1 + \cos x} = \tan^2 \left( \frac{x}{2} \right)$$

$$e^t = \left( \tan \frac{x}{2} \right) (1 + \sqrt{2}).$$

$$\frac{e^t}{1 + \sqrt{2}} = \tan \frac{x}{2}$$

$$\therefore x(t) = 2 \operatorname{Arctan} \left( \frac{e^t}{1 + \sqrt{2}} \right)$$

# EXERCISES FOR CHAPTER 2-1.

2.1.4

(a)

$$x(t) = 2 \tan^{-1} \left( \frac{e^t}{1 + \sqrt{2}} \right) \quad (\tan^{-1} \alpha = \text{Arctan } \alpha)$$

$(t \rightarrow \infty)$

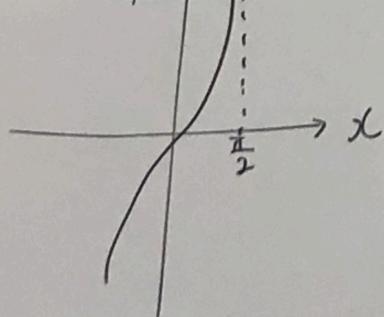
$$\tan \left( \frac{x(t)}{2} \right) = \frac{e^t}{1 + \sqrt{2}}$$

$t \rightarrow \infty \Rightarrow \alpha \in \mathbb{R}$

$(f_0 \in \mathbb{R}) = \infty$ .

$$\Leftrightarrow \tan \left( \frac{x(t)}{2} \right) \rightarrow \infty$$

$\therefore x = \pi$ ,  $f(x) = \tan x$ .



# EXERCISES FOR CHAPTER 2-1.

2.1.4

(b)

$$\begin{aligned}
 t &= \frac{1}{2} \log \left| \frac{1 - \cos x}{1 + \cos x} \right| - \frac{1}{2} \log \left| \frac{1 - \cos x_0}{1 + \cos x_0} \right| \\
 &= \frac{1}{2} \log \left( \tan^2 \frac{x}{2} \right) - \frac{1}{2} \log \left( \tan^2 \frac{x_0}{2} \right). \\
 &= \log \left( \frac{\tan \frac{x}{2}}{\tan \frac{x_0}{2}} \right).
 \end{aligned}$$

$$e^t \tan \frac{x_0}{2} = \tan \frac{x}{2}.$$

$$x(t) = 2 \tan^{-1} \left( e^t \tan \frac{x_0}{2} \right).$$

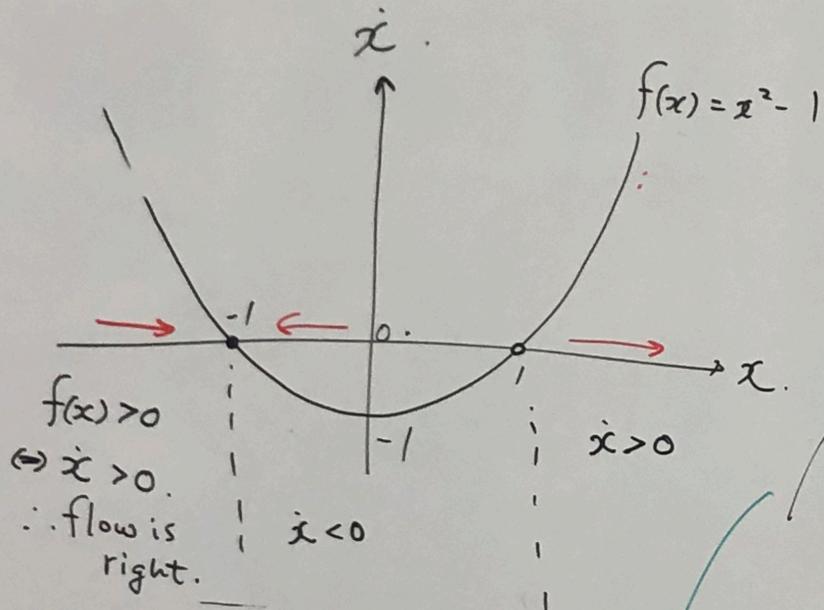
→

## EXAMPLE 2.2.1.

Find all fixed points for  $\dot{x} = x^2 - 1$ , and classify their stability.

$$\begin{cases} \dot{x} = f(x) \\ f(x) = x^2 - 1 \end{cases}$$

$$f(x) = x^2 - 1$$



the fixed points (equilibrium solutions),  $x^*$ .

$$x^* = -1, 1$$

$\rightarrow x^* = -1$  is stable,  
 $x^* = 1$  is unstable.

From 2.1.

$\dot{x} = \sin x$   
extend  
to any  
1-dimensional  
system  
 $\dot{x} = f(x)$ .

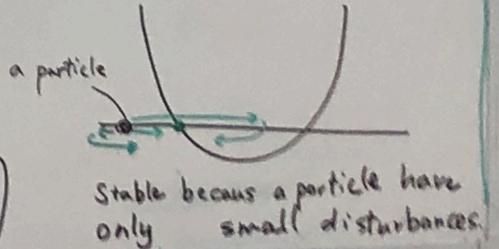
NOTE:

The definition of stable equilibrium is based on small disturbances; certain large disturbance may fail to decay (減衰).

Intuition

a particle

It does not move to stable fixed point.



Stable because a particle have only small disturbances.

2.7.2

$$f(x) = \frac{dV}{dx} = x(1+x)(1-x), \quad \frac{dV}{dx} = -x + x^3 = 0, \quad x(x^2 - 1) = 0.$$

$$\int dV = \int (x - x^3) dx$$

$$-V = \frac{x^2}{2} - \frac{x^4}{4} - C$$

$$V = -\frac{x^2}{2} + \frac{x^4}{4} + C$$

Set  $C=0$

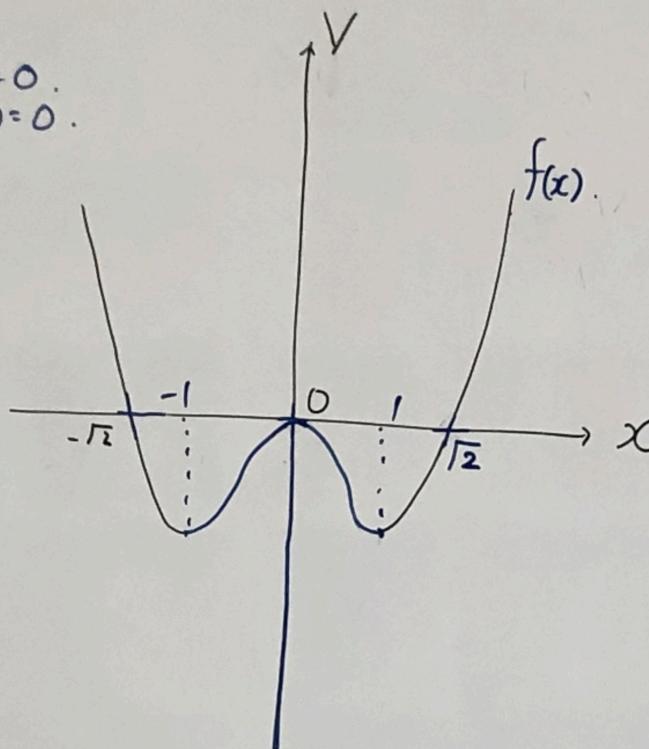
$$V = \frac{1}{2} \left(-1 + \frac{x^2}{2}\right) x^2$$

$$= \frac{1}{4} (x^2 - 2)x^2$$

$$= \frac{x^2}{4} (x + \sqrt{2})(x - \sqrt{2})$$

(trajectory)

$$\begin{aligned} \text{Set } x = 3\sqrt{2} \\ V &= \frac{(3\sqrt{2})^2}{4} (3\sqrt{2} + \sqrt{2})(3\sqrt{2} - \sqrt{2}) \\ &= \frac{9 \cdot 2}{4} (3+1)\sqrt{2} \cdot (3-1)\sqrt{2} \\ &= \frac{9 \cdot 2}{2} (4)(2) \\ &= 72 > 0 \end{aligned}$$



This potential is called

a double-well potential.

(2重井戸型ポテンシャル)

The system is said to be  
bistable, since it has  
two stable equilibria.

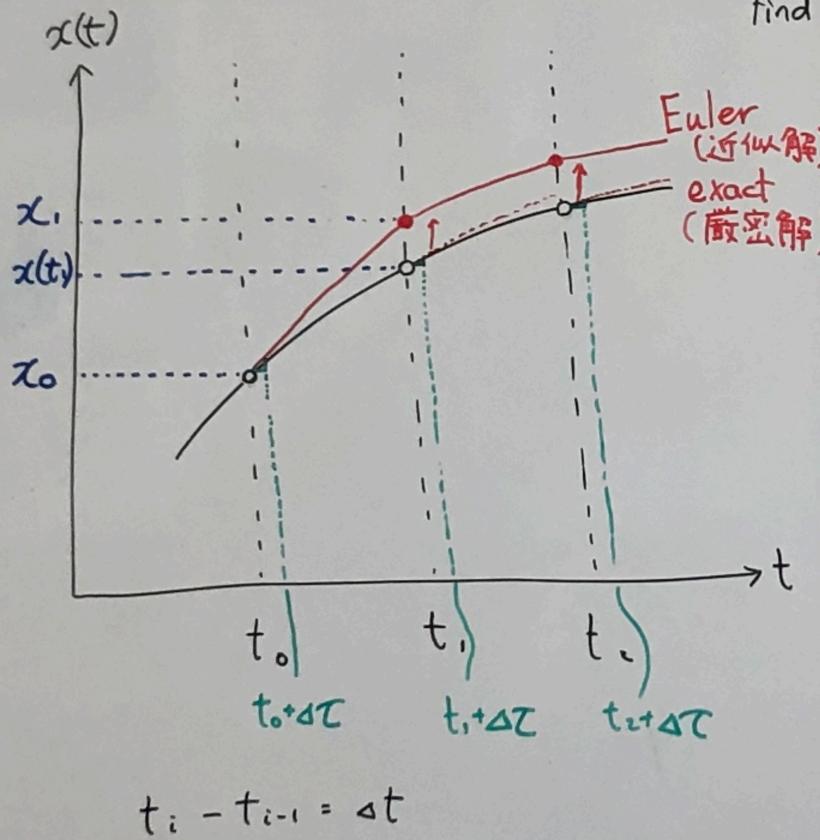
The local minima at  $x = \pm 1$  correspond to stable equilibria.

The local maximum at  $x = 0$  corresponds to unstable equilibrium.

## 2.8. Solving Equations on the Computer

### Euler's Method

The problem can be posed this way : given the differential equation  $\dot{x} = f(x)$ , subject to the condition  $x = x_0$  at  $t = t_0$ , find a systematic way to approximate the solution  $x(t)$ .



Suppose we use the vector field interpretation of  $\dot{x} = f(x) \Leftrightarrow f(x)$  : velocity

The rule of Euler's Method. at location  $x$ .

$$x(t_0 + \Delta t) \approx x_1 = x_0 + f(x_0) \Delta t$$

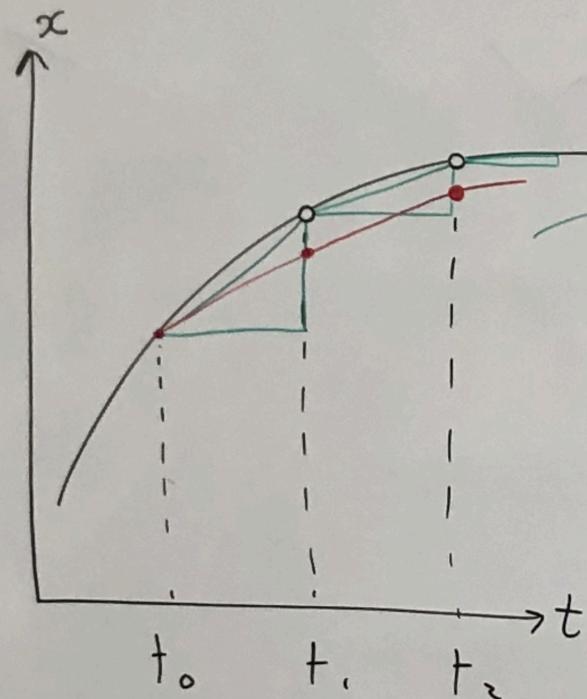
$$\hookrightarrow x_{n+1} = x_n + f(x_n) \Delta t$$

The approximation gets bad in a hurry unless  $\Delta t$  is extremely small.

Next, it contains the conceptual essence of more accurate methods to be discussed.

## 2.8. Solving Equations on the Computer

### Euler's Method : Refinements



$$f(x_n) \quad f(\tilde{x}_{n+1})$$

$$\left( \frac{f(x_n) + f(\tilde{x}_{n+1})}{2} \right) \Rightarrow \text{new Velocity}$$

$$g(x_n)$$

Improved Euler's Method

$$\tilde{x}_{n+1} = x_n + f(x_n) \Delta t$$

$$x_{n+1} = x_n + g(x_n) \Delta t$$

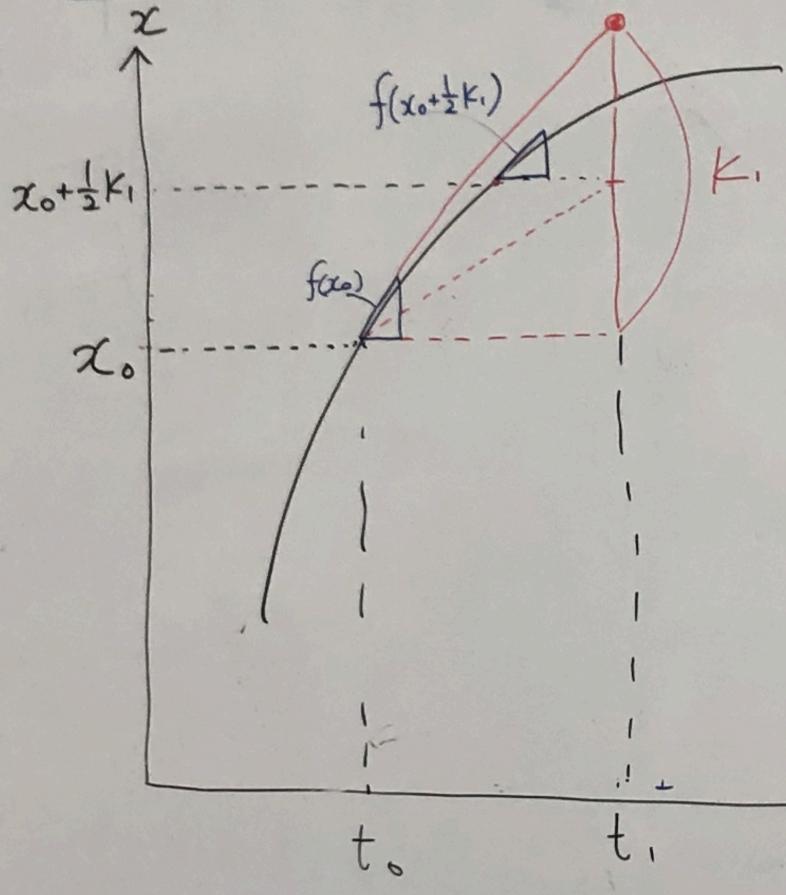
$$g(x_n) = \frac{1}{2} [f(x_n) + f(\tilde{x}_{n+1})]$$

## 2.8. Solving Equations on the Computer

Runge-Kutta method (4th-order)

Intuition

Step 1: get  $k_1, k_2$

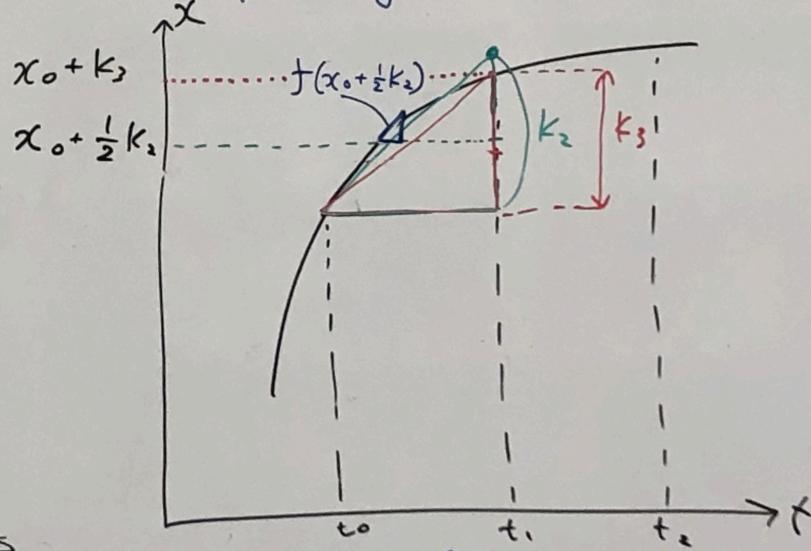


Euler's Method: 1st-order

Improved Euler's Method: 2nd-order

$$\begin{cases} k_1 = f(x_n) \Delta t \\ k_2 = f(x_n + \frac{1}{2}k_1) \Delta t \\ k_3 = f(x_n + \frac{1}{2}k_2) \Delta t \\ k_4 = f(x_n + k_3) \Delta t \end{cases}$$

Step 2: get  $k_3, k_4$



Step 3: Get  $x_{n+1}$

$$x_{n+1} = x_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)$$