

## Enhancing Experimental and Numerical Data Validation through Acoustic Noise Signal Demodulation for Estimating Drone Propeller Rotational Speed

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**Abstract.** *This study addresses a novel approach for estimating the rotational speed of small-scale propellers, typically found in drones, through the analysis of their acoustic noise signal. Accurately determining the instantaneous rotational speed of propellers in anechoic wind-tunnels poses significant challenges due to inherent experimental rotational speed fluctuations. These fluctuations can distort harmonic peaks levels, or deteriorate the process of applying comparable techniques when validating constant rotational speed numerical simulations with experimental data. This can be overcome by the knowledge of the propeller instantaneous rotational speed, allowing the signal to be resampled, correcting it to a constant rotational speed. Measured tachometer data is often not available nor reliable, as the use of external devices is not always feasible due to space constraints, costs, and sensitivity to adverse environmental conditions. An alternative approach is to directly estimate the propeller rotational speed from the measured acoustic signal, which is the focus of this study. The proposed methodology is based on the signal demodulation, which is a tacholeless method that calculates the Hilbert Transform of the acoustic signal to obtain the frequency and phase related to the shaft rotation. To evaluate the technique, a synthetic propeller noise data are generated with a previous established rotational speed fluctuation, allowing a characteristic error for the algorithm predicted instantaneous rotation to be obtained. Secondly, the process is repeated for a real propeller noise signal, and the results are compared with the actual rotational speed measurement obtained with the tachometer. Finally, the obtained instantaneous rotation is employed to resample the experimental signal, allowing it to be suitable for validating numerical simulated signals. The spectra obtained from both signals are then compared, and the signal components are evaluated using a Time Synchronous Averaging (TSA) analysis. Preliminary results indicate the consistency and feasibility of the technique.*

**Keywords:** *Propeller noise, frequency estimation, signal processing, aerodynamic noise.*

### 1. INTRODUCTION

In the ever-evolving realm of drone technology, the precise estimation of propeller rotational speed stands as a pivotal challenge. The need of knowing this information provides further analysis, such as dynamic control, precise noise sources identifications with decomposition techniques and failure prediction. Small-scale propellers, typically found in drones, necessitate accurate measurement techniques amidst the backdrop of inherent experimental fluctuations. Traditional methods, reliant on tachometer data, often falter due to practical constraints and environmental sensitivities, prompting a quest for alternative methodologies.

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The manuscripts should be written in English, typed in A4 size pages, using font Times New Roman, size 10, except for the title, authors affiliation, abstract and keywords, for which particular formatting instructions are indicated above. Single space between lines is to be used throughout the text.

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The section titles and subtitles must be aligned at left, typed with Times New Roman, size 10, bold style font. They must be numbered using Arabic numerals separated by points. No more than 3 sublevels should be used. One single line must be included above and below each section title/subtitle.

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One single line must be included above and below each equation.

$$[M]\{\ddot{x}\} + [C]\{\dot{x}(t)\} + [K]\{x(t)\} = f(t) \quad (1)$$

$$\mathbf{M}\ddot{\mathbf{x}}(t) + \mathbf{C}\dot{\mathbf{x}}(t) + \mathbf{K}\mathbf{x}(t) = \mathbf{f}(t) \quad (2)$$

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One blank line must be left before and after each table.

The style of table borders is left free. An example is given in Tab. 1.



Figure 1. United States crude oil imports from Norway versus number of drivers killed in collision with railway train.  
Available from: <http://tylervigen.com/spurious-correlations>

Table 1. Experimental results for flexural properties of CFRC-4HS and CFRC-TWILL composites.  
Span/depth ratio = 35:1. Average results of 7 specimens.

Composite Properties	CFRC-TWILL	CFRC-4HS
Flexural Strength (MPa) <sup>(1)</sup>	209 ± 10	180 ± 15
Flexural Modulus (GPa) <sup>(1)</sup>	57.0 ± 2.8	18.0 ± 1.3
Mid-span deflection at the failure stress (mm)	2.15 ± 1.90	6.40 ± 0.25

<sup>(1)</sup> measured at 25°C

### 3. ACKNOWLEDGEMENTS

This optional section must be placed before the list of references.

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- Bandarra Filho, E.P. and Jabardo, J.M.S., 2011. "Convective boiling performance of refrigerant R-134a in herringbone and microfin copper tubes". *International Journal of Refrigeration*, Vol. 29, No. 1, pp. 81–91.
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fluids inside a cavity”. In *Proceedings of the 22nd International Congress of Mechanical Engineering - COBEM 2013*.  
Ribeirão Preto, Brazil.

Santos, D.D., Furtado, G.M., Frey, S.L., Naccache, M.F. and de Souza Mendes, P.R., 2013b. “Numerical investigation of elastic and viscous effects on inertial viscoplastic fluid flows”. In *Proceedings of the 22nd International Congress of Mechanical Engineering - COBEM 2013*. Ribeirão Preto, Brazil.

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