EV Fleet Route Planning - Optimization (Write-up in progress)

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1 Variables

1.1 Constants:

- \bullet N: Number of Vehicles
- \bullet T: Number of Time Steps to Run Optimization For
- \bullet C: Number of Charging Stations
- ullet K: Number of Chargers Per Charging Station
- \bullet MROC: Max Rate of Charge
- CO2 : Charge CO2 Emissions

1.2 Optimization Variables:

- X, (Vehicle Trajectories)
- B (Battery Level of Cars)
- C (How much charge is being provided at a given time step),
- D (Helper var for encapsulating L1 Distance).

1.3 Variables Dimensions:

- |X| : [N, T, 2]
- |B| : [N, T]
- |C| : [N, C, T]
- $|C_{cond}| : [N, C, T]$
- $|C_{diff}| : [N, C, T, 2]$
- |D|:[N,C,2]

2 Constraints

$$0 \le X_{i,j,k} \le Size \quad \forall i \in \{1, 2, \dots, N\}, j \in \{1, 2, \dots, T\}, k \in \{1, 2, \dots, D\}$$
 (2)

$$10 \le B_{i,j} \le 100 \quad \forall i \in \{1, 2, \dots, N\}, j \in \{1, 2, \dots, T\}$$
(3)

$$D_{i,j,k} \ge 0 \quad \forall i \in \{1,\dots,N\}, j \in \{1,\dots,T-1\}, k \in \{1,2,\dots,D\}$$
 (4)

$$0 \le C_{i,c,t} \le MROC \quad \forall c \in \{1, \dots, C\}, i \in \{1, \dots, N\}, t \in \{1, \dots, T-1\}$$
 (5)

$$0 \le Ccond_{i,c,t} \le 1 \quad \forall c \in \{1, \dots, C\}, i \in \{1, \dots, N\}, t \in \{1, \dots, T-1\}$$
 (6)

$$B_{i,0} = starting_battery_i \quad \forall i \in \{1, 2, \dots, N\}$$

$$B_{i,T-1} = end_battery_i \quad \forall i \in \{1, 2, \dots, N\}$$

$$(8)$$

$$B_{i,T-1} = end_battery_i \quad \forall i \in \{1, 2, \dots, N\}$$

$$C_{\text{diff},c,i,t,0} \ge X_{i,t,0} - charger_loc_{c,i,0}$$

$$(9)$$

$$C_{\text{diff},ci,t,0} \ge I_{i,t,0} \quad \text{entar ger } \exists cc_{i,0}$$

$$C_{\text{diff},ci,t,0} \ge -(X_{i,t,0} - charger \rfloor cc_{ci,0})$$

$$\tag{10}$$

$$C_{\text{diff},c,t,1} \ge X_{i,t,1} - charger loc_{ci,1} \tag{11}$$

$$C_{\text{diff}i,ci,t,1} \ge -(X_{i,t,1} - charger \rfloor loc_{ci,1}) \tag{12}$$

$$B_{i,j} = B_{i,j-1} + \sum_{k=1}^{D} D_{i,j-1,k} - \sum_{c=1}^{C} C_{i,ci,j-1} \quad \forall i \in \{1, 2, \dots, N\}, j \in \{1, 2, \dots, T\}$$

(13)

$$C_{\operatorname{cond}i,ci,t} = C_{\operatorname{diff}i,ci,t,0} + C_{\operatorname{diff}i,ci,t,1} \tag{14}$$

$$C_{i,ci,t} \le C_{\text{cond}\,i,ci,t} - 1 \tag{15}$$

$$\sum_{i=1}^{N} C_{i,ci,t} \le K \cdot MROC \tag{16}$$

(17)

(to be continued)

3 Objective Function

Emissions =
$$\sum_{ci=0}^{C-1} \sum_{t=0}^{T-2} \left(\sum_{i=0}^{N-1} c_{i,ci,t} \cdot CO_{2_{ci}} \right)$$
 (19)

$$Dist = \sum_{i=1}^{N} \sum_{t=1}^{T-1} \sum_{k=0}^{1} d_{i,t-1,k}$$
(20)

Time =
$$\sum_{i=1}^{N} \sum_{t=1}^{T-1} ((d[i, t, 0] + d[i, t, 1]) * t)$$
 (21)

Objective =
$$\alpha * Emissions + \beta * Dist + \gamma * Time$$
 (22)