

Lecture #12

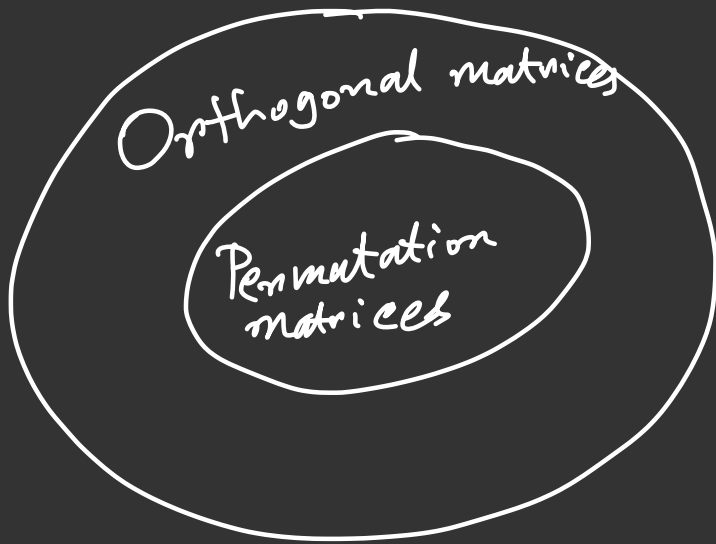
02/06/2023

Example of 3×3 permutation matrices:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

In general, $n!$ permutation matrices of size $n \times n$.



Orthogonal matrices:

$n \times n$ real matrices Q
such that:

$$Q^{-1} = Q^T$$

$$\Leftrightarrow QQ^T = I_n = Q^T Q$$

$$\Leftrightarrow \underbrace{\det(Q)} \underbrace{\det(Q^T)} = \underbrace{\det(I_n)}$$

$$\Rightarrow \det(Q) \cdot \det(Q) = 1$$

$$\Rightarrow (\det(Q))^2 = 1$$

$$\Rightarrow \det(Q) = \pm 1$$

Uniqueness of LU decomposition:

Consider $A = LU$ exists.

Such LU decomposition/factorization may NOT be unique unless we impose extra constraint on the diagonal entries.

Why?

$$A = LU$$

$$= L(I)U$$

$$= L(DD^{-1})U,$$

$$= (LD)(D^{-1}U)$$

$$= L_1 U_1$$

where D is any diagonal matrix with nonzero diag. entries

This is why we artificially imposed the constraint earlier that $L_{ii} = 1$ for all $i = 1, \dots, n$.

This constraint makes LU decomposition unique provided it exists.

In many practical science & engineering problems, the matrix $A \in \mathbb{R}^{n \times n}$ has additional structure: for example, often A happens to be "positive (semi)definite" matrix.

Definition: (Positive (semi) definite matrix)

Matrix $A \in \mathbb{R}^{n \times n}$ is called positive (semi) definite if

- A is symmetric ($A = A^T$)

- $\underline{x}^T A \underline{x} \geq 0$ for all $\underline{x} \neq \underline{0}$

↑
semi-definite

> 0 for all $\underline{x} \neq \underline{0}$

↑
definite

A is positive semi-definite $\Leftrightarrow \lambda_i(A) \geq 0$

" " " definite $\Leftrightarrow \lambda_i > 0$ for all $i=1, \dots, n$

Suppose we want to solve : $A \underline{x} = \underline{b}$

where $\underline{b} \neq \underline{0}$, and we know that the matrix A is positive definite.

Then, $A = LU$ exists, is unique, $U = L^T$.

$$\Leftrightarrow A = LU = \underbrace{LL^T}_{\text{Cholesky decomposition.}}$$

Cholesky decomposition.

Example: (positive definite matrix and Cholesky decomposition)

$$A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$

$$\underline{x}^T A \underline{x} = (x_1 \ x_2 \ x_3) A \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$= (x_1 \ x_2 \ x_3) \begin{pmatrix} 2x_1 - x_2 \\ -x_1 + 2x_2 - x_3 \\ -x_2 + 2x_3 \end{pmatrix}$$

$$= 2x_1^2 + 2x_2^2 + 2x_3^2 - 2x_1x_2 - 2x_2x_3$$

$$= (x_1 - x_2)^2 + (x_2 - x_3)^2 + x_3^2 + x_1^2$$

$$\therefore \underline{x}^T A \underline{x} > 0 \text{ for all } \underline{x} \neq 0$$

$\therefore A$ is positive definite matrix.

$$(\lambda_1, \lambda_2, \lambda_3) = (0.5858, 2, 3.4142)$$

$$A = L L^T$$

$$L = \begin{bmatrix} 1.4142 & 0 & 0 \\ -0.7071 & 1.2247 & 0 \\ 0 & -0.8165 & 1.1547 \end{bmatrix}$$

MATLAB commands:

$\gg [L, U, P] = \text{lu}(\cdot)$ } LU decomposition
 $\gg [L, U] = \text{lu}(\cdot)$ }

$\gg \text{chol}(\cdot) \leftarrow$ Cholesky decomposition

$\gg A \backslash b \leftarrow$ will return the unique solution vector \underline{x} satisfying
 $A \underline{x} = \underline{b}$