

Smart Material Chapter 4 Solutions

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```
[1]: # toc
import sympy as sp
import numpy as np
import matplotlib.pyplot as plt

plt.style.use('maroon_ipynb.mplstyle')
```

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Problem 4.1

Compute the stress required to produce 100 microstrain in APC 856 when the applied electric field is held constant at zero. Compute the stress required to produce 100 microstrain when the electric displacement is held equal to zero.

Property	Unit	Symbol	APC 856	PZT-5H	PVDF
Relative dielectric constant	unitless	ϵ_r	4100	3800	12–13
Curie temperature	°C	T_c	150	250	
Coupling coefficient	unitless	k_{33}	0.73	0.75	
		k_{31}	0.36		0.12
		k_{15}	0.65		
Strain coefficient	10^{-12} C/N or m/V	d_{33}	620	650	–33
		$-d_{31}$	260	320	–23
		d_{15}	710		
Elastic compliance	10^{-12} m ² /N	s_{11}^E	15	16.1	250–500
		s_{33}^E	17	20	
Density	g/cm ³	ρ	7.5	7.8	1.78

Solution

We can use the constitutive equations.

$$S = sT + dE$$

$$D = dT + \epsilon E$$

```
[2]: S = 100e-6
      s = 17e-12 # m^2/N
      T = S/s
      T # Pa
```

```
[2]: 5882352.941176471
```

For finding the open circuit stress, we need the open circuit compliance.

$$s^D = s^E(1 - k^2)$$

```
[3]: SD = s*(1 - 0.73**2)
      T = S/SD
      T # Pa
```

```
[3]: 12593348.193484202
```

Problem 4.2

A new composition of piezoelectric material is found to have a compliance at zero electric field of $18.2\mu\text{m}^2/N$, a piezoelectric strain coefficient of $330\text{pm}/V$, and a relative permittivity of 1500.

- Write the one-dimensional constitutive relationship for the material with strain and electric displacement as the dependent variables.
- Write the one-dimensional constitutive relationship with stress and electric field as the dependent variables.

Solution**Part A**

```
[4]: S, D, s, d, eps, T, E = sp.symbols(r'S D s d \epsilon T E')
A = sp.Matrix([[s, d], [d, eps]])
x = sp.Matrix([T, E])
b = sp.Matrix([S, D])
eq = sp.Eq(b, sp.MatMul(A, x))
eq
```

[4]:
$$\begin{bmatrix} S \\ D \end{bmatrix} = \begin{bmatrix} s & d \\ d & \epsilon \end{bmatrix} \begin{bmatrix} T \\ E \end{bmatrix}$$

$\epsilon = \epsilon_r \cdot \epsilon_o$

```
[5]: subs = {s: sp.S('18.2e-6'), d: sp.S('330e-12'), eps: 1500*sp.S('8.854e-12')}
eq.subs(subs)
```

[5]:
$$\begin{bmatrix} S \\ D \end{bmatrix} = \begin{bmatrix} 1.82 \cdot 10^{-5} & 3.3 \cdot 10^{-10} \\ 3.3 \cdot 10^{-10} & 1.3281 \cdot 10^{-8} \end{bmatrix} \begin{bmatrix} T \\ E \end{bmatrix}$$

Part B

```
[6]: eq = sp.Eq(x, sp.MatMul(A.inv(), b))
eq
```

[6]:
$$\begin{bmatrix} T \\ E \end{bmatrix} = \begin{bmatrix} \frac{\epsilon}{\epsilon s - d^2} & -\frac{d}{\epsilon s - d^2} \\ -\frac{d}{\epsilon s - d^2} & \frac{s}{\epsilon s - d^2} \end{bmatrix} \begin{bmatrix} S \\ D \end{bmatrix}$$

```
[7]: eq.subs(subs)
```

[7]:
$$\begin{bmatrix} T \\ E \end{bmatrix} = \begin{bmatrix} 54945.0796995757 & -1365.24932616971 \\ -1365.24932616971 & 75295568.8978449 \end{bmatrix} \begin{bmatrix} S \\ D \end{bmatrix}$$

Problem 4.4

The short-circuit mechanical compliance of a piezoelectric material has been measured to be $20 \mu\text{m}^2/\text{N}$ and the open-circuit mechanical compliance has been measured to be $16.2 \mu\text{m}^2/\text{N}$. If the stress-free relative permittivity is equal to 2800, compute the relative permittivity of the material when the strain is constrained to be zero.

Solution

We can use the equation for the open circuit compliance to find the piezoelectric coupling coefficient, and apply that to the no strain permittivity relationship.

$$s^D = s^E(1 - k^2)$$

$$\epsilon^S = \epsilon^T(1 - k^2)$$

```
[8]: sD, sE, epsT = 16.2e-6, 20e-6, 2800  
k = np.sqrt(1 - sD/sE)  
k
```

```
[8]: 0.43588989435406744
```

```
[9]: epsS = epsT*(1 - k**2)  
epsS
```

```
[9]: 2268.0
```

Problem 4.5

Compute the sensitivity between strain and electric displacement for a piezoelectric material whose material parameters are $s^E = 16\mu\text{m}^2/\text{N}$ and $d = 220\text{pm}/\text{V}$, with a relative permittivity of 1800. Assume that the signal conditioning circuit for the sensor maintains a zero electric field.

Solution

The sensitivity is going to be defined as the ratio between electric displacement and strain. With the zero electric field,

$$S = s^E T$$

$$D = d T$$

These equations can be re-arranged to find the sensitivity.

$$\frac{D}{S} = \frac{d}{s^E}$$

```
[10]: sE, d, eps = 16e-12, 220e-12, 1800  
      d/sE # C/m^2
```

```
[10]: 13.75
```

Problem 4.6

Beginning with equation 4.55, write the constitutive relationships for a piezoelectric material with an electric field applied in the direction of polarization (the 3 direction). Assume that the applied stress is zero except for the 1 and 2 material directions.

Solution

Equation 4.55 is

$$\begin{Bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \\ S_6 \end{Bmatrix} = \begin{bmatrix} \frac{1}{Y_1^E} & -\frac{\nu_{12}}{Y_1^E} & -\frac{\nu_{13}}{Y_1^E} & 0 & 0 & 0 \\ -\frac{\nu_{12}}{Y_1^E} & \frac{1}{Y_1^E} & -\frac{\nu_{23}}{Y_1^E} & 0 & 0 & 0 \\ -\frac{\nu_{31}}{Y_3^E} & -\frac{\nu_{32}}{Y_3^E} & \frac{1}{Y_3^E} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{G_{23}^E} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{G_{13}^E} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{G_{12}^E} \end{bmatrix} \begin{Bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \\ T_5 \\ T_6 \end{Bmatrix} + \begin{bmatrix} 0 & 0 & d_{13} \\ 0 & 0 & d_{23} \\ 0 & 0 & d_{33} \\ 0 & d_{24} & 0 \\ d_{15} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{Bmatrix} E_1 \\ E_2 \\ E_3 \end{Bmatrix}$$

$$\begin{Bmatrix} D_1 \\ D_2 \\ D_3 \end{Bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 & d_{15} & 0 \\ 0 & 0 & 0 & d_{24} & 0 & 0 \\ d_{13} & d_{23} & d_{33} & 0 & 0 & 0 \end{bmatrix} \begin{Bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \\ T_5 \\ T_6 \end{Bmatrix} + \begin{bmatrix} \varepsilon_{11} & 0 & 0 \\ 0 & \varepsilon_{22} & 0 \\ 0 & 0 & \varepsilon_{33} \end{bmatrix} \begin{Bmatrix} E_1 \\ E_2 \\ E_3 \end{Bmatrix}$$

```
[11]: S1, S2, S3, S4, S5, S6 = sp.symbols(r'S1:7')
T1, T2, T3, T4, T5, T6 = sp.symbols(r'T1:7')
E1, E2, E3 = sp.symbols(r'E1:4')
D1, D2, D3 = sp.symbols(r'D1 D2 D3')
eps11, eps22, eps33 = sp.symbols(r'\varepsilon_{11} \varepsilon_{22} \varepsilon_{33}')
d13, d23, d33, d24, d15 = sp.symbols(r'd13 d23 d33 d24 d15')
Y1E, Y3E, G23E, G13E, G12E = sp.symbols(r'Y_1^E Y_3^E G_{23}^E G_{13}^E G_{12}^E')
nu12, nu13, nu23, nu31, nu32 = sp.symbols(r'\nu_{12} \nu_{13} \nu_{23} \nu_{31} \nu_{32}')

sE = sp.Matrix([
    [1/Y1E, -nu12/Y1E, -nu13/Y1E, 0, 0, 0],
    [-nu12/Y1E, 1/Y1E, -nu23/Y1E, 0, 0, 0],
    [-nu31/Y3E, -nu32/Y3E, 1/Y3E, 0, 0, 0],
    [0, 0, 0, 1/G23E, 0, 0],
    [0, 0, 0, 0, 1/G13E, 0],
    [0, 0, 0, 0, 0, 1/G12E]
])
S = sp.Matrix([S1, S2, S3, S4, S5, S6])
```

```

T = sp.Matrix([T1, T2, T3, T4, T5, T6])
d = sp.Matrix([
    [0, 0, d13],
    [0, 0, d23],
    [0, 0, d33],
    [0, d24, 0],
    [d15, 0, 0],
    [0, 0, 0]
])
E = sp.Matrix([E1, E2, E3])

D = sp.Matrix([D1, D2, D3])
eps = sp.Matrix([
    [eps11, 0, 0],
    [0, eps22, 0],
    [0, 0, eps33]
])

eq1 = sp.Eq(S, sp.Add(sp.MatMul(sE, T), sp.MatMul(d, E)))
eq2 = sp.Eq(D, sp.Add(sp.MatMul(d.transpose(), T), sp.MatMul(eps, E)))
display(eq1, eq2)

```

$$\begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \\ S_6 \end{bmatrix} = \begin{bmatrix} 0 & 0 & d_{13} \\ 0 & 0 & d_{23} \\ 0 & 0 & d_{33} \\ 0 & d_{24} & 0 \\ d_{15} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} E_1 \\ E_2 \\ E_3 \end{bmatrix} + \begin{bmatrix} \frac{1}{Y_1^E} & -\frac{\nu_{12}}{Y_1^E} & -\frac{\nu_{13}}{Y_1^E} & 0 & 0 & 0 \\ -\frac{\nu_{12}}{Y_1^E} & \frac{1}{Y_1^E} & -\frac{\nu_{23}}{Y_1^E} & 0 & 0 & 0 \\ -\frac{\nu_{31}}{Y_3^E} & -\frac{\nu_{32}}{Y_3^E} & \frac{1}{Y_3^E} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{G_{23}^E} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{G_{13}^E} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{G_{12}^E} \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \\ T_5 \\ T_6 \end{bmatrix}$$

$$\begin{bmatrix} D_1 \\ D_2 \\ D_3 \end{bmatrix} = \begin{bmatrix} \varepsilon_{11} & 0 & 0 \\ 0 & \varepsilon_{22} & 0 \\ 0 & 0 & \varepsilon_{33} \end{bmatrix} \begin{bmatrix} E_1 \\ E_2 \\ E_3 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 & 0 & d_{15} & 0 \\ 0 & 0 & 0 & d_{24} & 0 & 0 \\ d_{13} & d_{23} & d_{33} & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \\ T_5 \\ T_6 \end{bmatrix}$$

```

[12]: subs = {T3: 0, T4: 0, T5: 0, T6: 0, E1: 0, E2: 0}
eq1 = eq1.subs(subs)
eq2 = eq2.subs(subs)
display(eq1, eq2)

```


$$\begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \\ S_6 \end{bmatrix} = \begin{bmatrix} 0 & 0 & d_{13} \\ 0 & 0 & d_{23} \\ 0 & 0 & d_{33} \\ 0 & d_{24} & 0 \\ d_{15} & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ E_3 \end{bmatrix} + \begin{bmatrix} \frac{1}{Y_1^E} & -\frac{\nu_{12}}{Y_1^E} & -\frac{\nu_{13}}{Y_1^E} & 0 & 0 & 0 \\ -\frac{\nu_{12}}{Y_1^E} & \frac{1}{Y_1^E} & -\frac{\nu_{23}}{Y_1^E} & 0 & 0 & 0 \\ -\frac{\nu_{31}}{Y_3^E} & -\frac{\nu_{32}}{Y_3^E} & \frac{1}{Y_3^E} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{G_{23}^E} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{G_{13}^E} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{G_{12}^E} \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} D_1 \\ D_2 \\ D_3 \end{bmatrix} = \begin{bmatrix} \varepsilon_{11} & 0 & 0 \\ 0 & \varepsilon_{22} & 0 \\ 0 & 0 & \varepsilon_{33} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ E_3 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 & 0 & d_{15} & 0 \\ 0 & 0 & 0 & d_{24} & 0 & 0 \\ d_{13} & d_{23} & d_{33} & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

[13]: `display(eq1.doit(), eq2.doit())`

$$\begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \\ S_6 \end{bmatrix} = \begin{bmatrix} E_3 d_{13} + \frac{T_1}{Y_1^E} - \frac{T_2 \nu_{12}}{Y_1^E} \\ E_3 d_{23} - \frac{T_1 \nu_{12}}{Y_1^E} + \frac{T_2}{Y_1^E} \\ E_3 d_{33} - \frac{T_1 \nu_{31}}{Y_3^E} - \frac{T_2 \nu_{32}}{Y_3^E} \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} D_1 \\ D_2 \\ D_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ E_3 \varepsilon_{33} + T_1 d_{13} + T_2 d_{23} \end{bmatrix}$$

So, the final equations would be,

```
[14]: for eq in [eq1, eq2]:
        for i, rhs in enumerate(eq.rhs.doit()):
            if rhs != 0:
                display(sp.Eq(list(eq.lhs)[i], rhs))
```

$$S_1 = E_3 d_{13} + \frac{T_1}{Y_1^E} - \frac{T_2 \nu_{12}}{Y_1^E}$$

$$S_2 = E_3 d_{23} - \frac{T_1 \nu_{12}}{Y_1^E} + \frac{T_2}{Y_1^E}$$

$$S_3 = E_3 d_{33} - \frac{T_1 \nu_{31}}{Y_3^E} - \frac{T_2 \nu_{32}}{Y_3^E}$$

$$D_3 = E_3 \varepsilon_{33} + T_1 d_{13} + T_2 d_{23}$$

Problem 4.9

A piezoelectric material operating in the 33 mode has the material properties $d_{33} = 450 \text{ pm/V}$ and $Y_3^E = 63 \text{ GPa}$.

- Compute the blocked stress and free strain under the application of an electric field of 0.75 MV/m .
- Compute the voltage required to achieve this blocked stress or free displacement for a wafer that is $250 \mu\text{m}$ thick.

Solution**Part A**

The blocking stress as a result of zeroing displacement is

$$T_{bl} = d_{33} Y_3^E E_3$$

The free strain as a result of zeroing stress is

$$S_{fr} = d_{33} E_3$$

```
[15]: d33, Y3E, E3 = 450e-12, 63e9, 0.75e6
      T_bl = d33*Y3E*E3
      T_bl  # Pa
```

```
[15]: 21262500.0
```

```
[16]: S_fr = d33*E3
      S_fr
```

```
[16]: 0.0003375
```

Part B

```
[17]: # Voltage = Electric field * thickness
      V = E3*250e-6
      V  # V
```

```
[17]: 187.5
```

Problem 4.10

	PZT-A	PZT-B	PZT-C	PZT-D	PZT-E
ε_{33}	1400	1400	1100	5440	1800
ε_{11}	1350	1300	1400	5000	2000
s_{11}^E ($\mu\text{m}^2/\text{N}$)	12.7	13.1	11.2	14.8	16.5
s_{33}^E ($\mu\text{m}^2/\text{N}$)	15.4	15.6	15.2	18.1	19.9
d_{13} (pm/V)	-133	-132	-99	-287	-198
d_{33} (pm/V)	302	296	226	635	417

For each material above,

- Plot the blocked stress and free strain on a single plot.
- Compute the volumetric energy density of each type of material for operation in the 33 mode for an electric field of $1\text{MV}/\text{m}$.

Solution**Part A**

```
[18]: d33 = np.array([302, 296, 226, 635, 417])*1e-12
s33 = np.array([15.4, 15.6, 15.2, 18.1, 19.9])*1e-12
materials = ['PZT-A', 'PZT-B', 'PZT-C', 'PZT-D', 'PZT-E']
Y33 = 1/s33 # Pa

fig, ax = plt.subplots()
E = 1e6 # V/m
for d, Y, mat in zip(d33, Y33, materials):
    T = d*Y*E*1e-6 # MPa
    S = d*E*1e6 # microstrain
    ax.plot([0, S], [T, 0], label=mat)
    print(mat)
    print('Blocking Stress:', T, 'MPa')
    print('Free Strain:', S, 'microstrain')
    print()
ax.legend()
ax.set_xlabel('Strain (microstrain)')
ax.set_ylabel('Stress (MPa)')
plt.show()
```

PZT-A

Blocking Stress: 19.610389610389607 MPa

Free Strain: 301.99999999999994 microstrain

PZT-B

Blocking Stress: 18.974358974358974 MPa

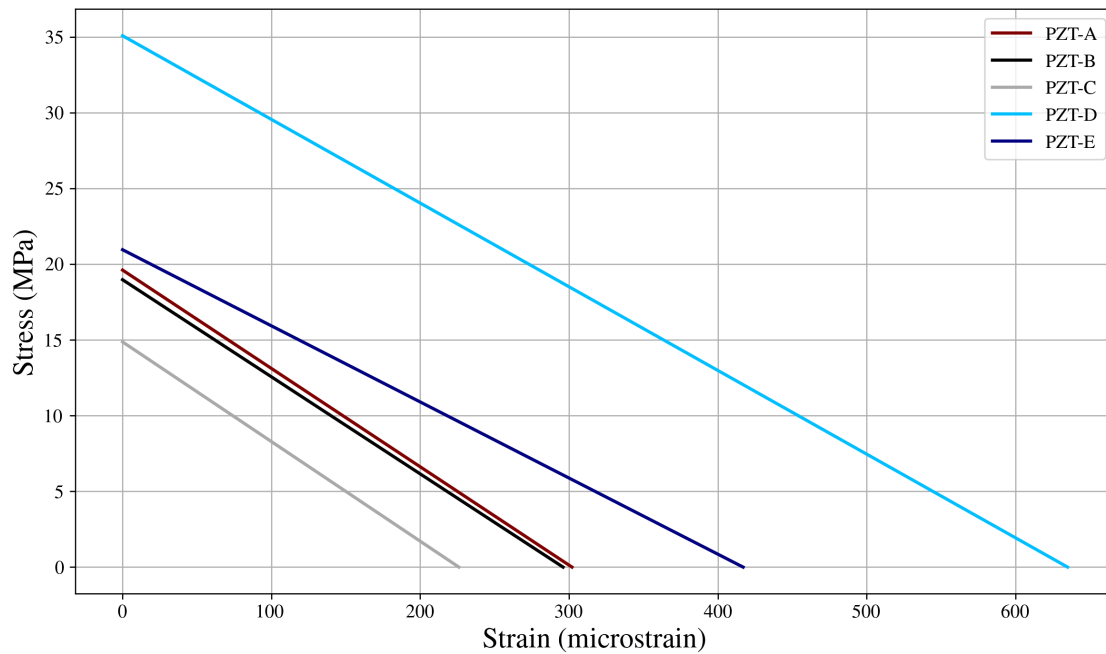
Free Strain: 296.0 microstrain

PZT-C

Blocking Stress: 14.868421052631579 MPa
Free Strain: 226.0 microstrain

PZT-D
Blocking Stress: 35.0828729281768 MPa
Free Strain: 634.9999999999999 microstrain

PZT-E
Blocking Stress: 20.954773869346738 MPa
Free Strain: 417.0 microstrain



Part B

The volumetric energy density is given by

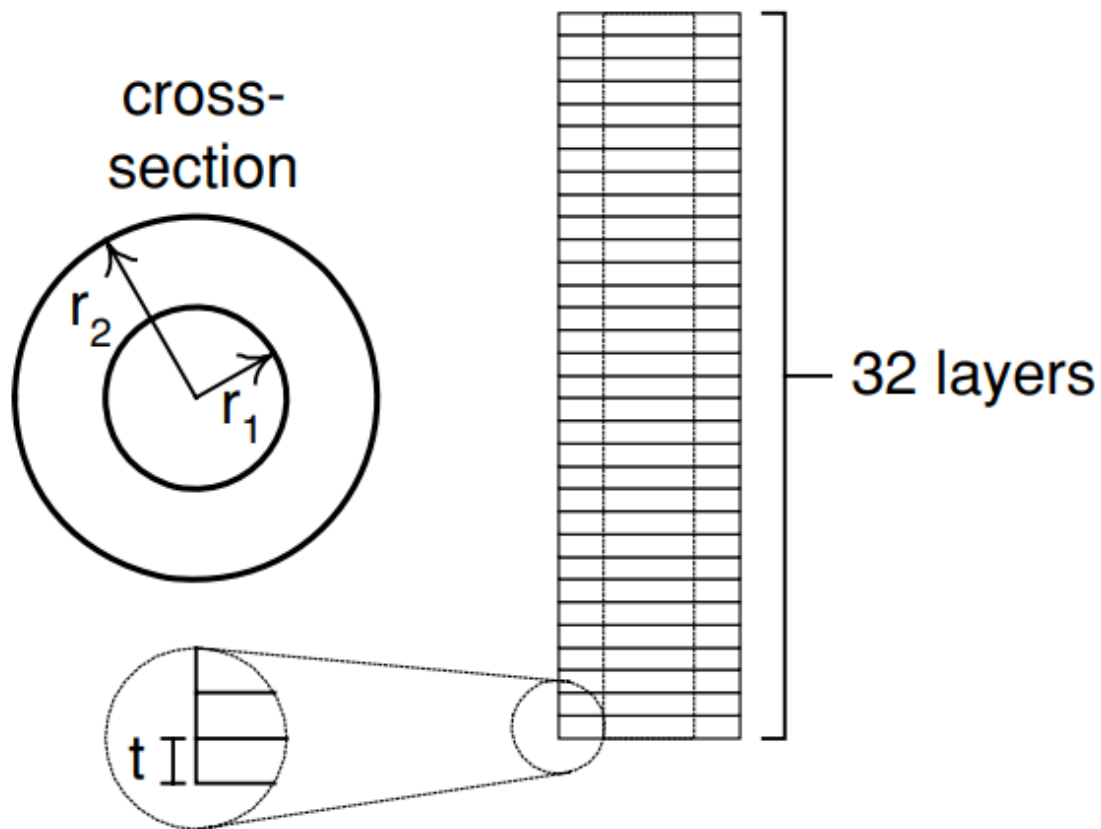
$$E_v = \frac{1}{2} Y_3^E d_{33}^2 E_3^2$$

This is the area under the line in the graph above. The $\frac{1}{2} Y_3^E d_{33}^2$ term is a good metric for showing that a PZT material can provide more mechanical work for a given electric field.

```
[19]: E_v = 0.5*Y33*d33**2*E**2
      E_v/1000 # kJ/m^3
```

```
[19]: array([ 2.96116883,  2.80820513,  1.68013158, 11.13881215,  4.36907035])
```

Note that the soft PZT material exhibits the highest volumetric energy density.

Problem 4.11

The geometry of a piezoelectric stack with annular cross section is shown in the figure above. Compute the stiffness, free displacement, and blocked force of the stack assuming that $r_1 = 5 \text{ mm}$, $r_2 = 15 \text{ mm}$, $t = 0.25 \text{ mm}$, and the applied voltage is 150 V. Assume the material properties of PZT-5H.

Solution

The stiffness of the stack is given by

$$k_s^E = \frac{Y_3^E A}{nt_p}$$

```
[20]: Y = 1/20e-12 # Pa
A = np.pi*(0.015**2 - 0.005**2) # m^2
n, tp = 32, 0.25e-3 # number of layers, m
k = Y*A/(n*tp)
k/1e6 # N/um
```

```
[20]: 3926.9908169872415
```

The free displacement is given by

$$\delta_o = n d_{33} v$$

```
[21]: d33 = 650e-12 # m/V  
delta = n*d33*150  
delta*1e6 # um
```

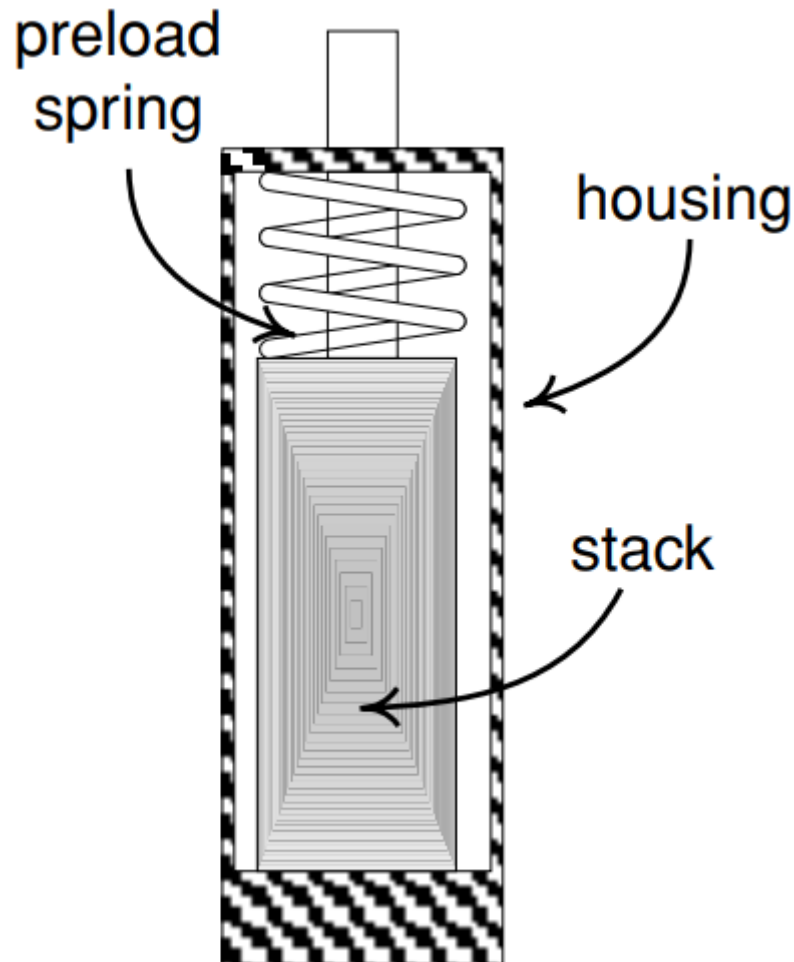
```
[21]: 3.12
```

The blocked force is given by

$$f_{bl} = d_{33} Y_3^E \frac{A_p}{t_p} v$$

```
[22]: f_bl = d33*Y*A/tp*150  
f_bl # N
```

```
[22]: 12252.211349000192
```

Problem 4.13

Piezoelectric stack actuators are often preloaded to reduce the risk of placing the brittle ceramic in tension. A piezoelectric stack with a free displacement of $30\ \mu\text{m}$ and a stiffness of $40\ \text{N}/\mu\text{m}$ is placed in a housing as shown in the figure above.

- Compute the stiffness of the preload spring such that the output displacement is $20\ \mu\text{m}$.
- Compute the output force of the preloaded stack.

Solution**Part A**

From equation 4.86,

$$u = \frac{\delta_o}{1 + k_l/k_s^E}$$


```
[23]: delta_o, kl, ks, u = sp.symbols(r'\delta_o k_l k_s u')
eq = sp.Eq(u, delta_o/(1 + kl/ks))
eq
```

[23]:
$$u = \frac{\delta_o}{\frac{k_l}{k_s} + 1}$$

```
[24]: eq_subs = eq.subs({delta_o: 30e-6, ks: 40e6, u: 20e-6})
eq_subs
```

[24]:
$$2.0 \cdot 10^{-5} = \frac{3.0 \cdot 10^{-5}}{2.5 \cdot 10^{-8} k_l + 1}$$

```
[25]: kl_solved = sp.solve(eq_subs, kl)[0]
kl_solved/1e6 # N/um
```

[25]: 20.0

Part B

```
[26]: f = kl_solved*20e-6
f # N
```

[26]: 400.0