System Dynamics Final Exam

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```
[1]: import control as ct
import numpy as np
import matplotlib.pyplot as plt
import sympy as sp
from scipy.optimize import fsolve

plt.style.use('../maroon_ipynb.mplstyle')
```

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1 Problem 1

1.1 Given

$$T(s) = \frac{X(s)}{Y(s)} = \frac{10}{10s^2 + 15s + 17}$$

1.2 Find

For the transfer function above,

- a. Plot the magnitude $(M(\omega))$ not in decibels) and phase response for $0.1 \le \omega < 10 \, rad/s$. You can use whichever method you prefer, but only use the bode() function for checking.
- b. Find the resonant frequency ω_r .
- c. If the input function is $y(t) = 11\sin(5t)$, find the steady state function $x_{ss}(t)$. Plot the result with the transient response up to 6 seconds.

1.3 Solution

1.3.1 Part A - Plotting the Frequency Response (20 Points)

```
[2]: m, c, k = 10, 15, 17

T_jw = lambda om: 10/(m*(1j*om)**2 + c*1j*om + k)

T = ct.tf(10, [m, c, k])
T
```

[2]:

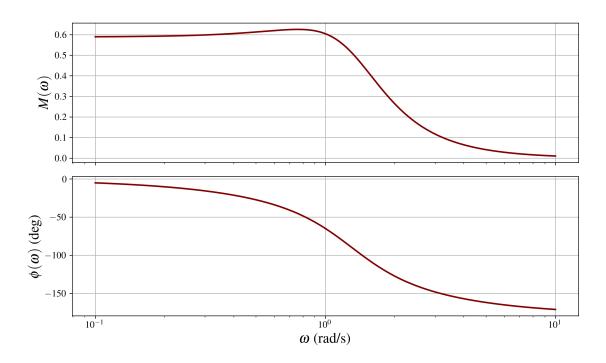
$$\frac{10}{10s^2 + 15s + 17}$$

```
[3]: omegas = np.linspace(0.1, 10, 10_000)
    mag = np.abs(T_jw(omegas))
    phase = np.angle(T_jw(omegas))

fig, (ax1, ax2) = plt.subplots(nrows=2, ncols=1, sharex=True)
    ax1.set_xscale('log')

ax1.plot(omegas, mag)
# ax1.plot(omegas, 20*np.log10(mag))
    ax1.set_ylabel(r'$M(\omega)$')

ax2.plot(omegas, np.rad2deg(phase))
    ax2.set_ylabel(r'$\phi(\omega)$ (deg)')
    ax2.set_xlabel(r'$\omega$ (rad/s)')
    plt.show()
```



1.3.2 Part B - Finding the Resonant Frequency (10 Points)

```
[4]: wn = np.sqrt(k/m)
zeta = c/(2*np.sqrt(k*m))
wr = wn*np.sqrt(1 - 2*zeta**2)
wr # rad/s
```

[4]: 0.7582875444051551

```
[5]: omegas[max(mag) == mag][0] # rad/s
```

[5]: 0.758415841584

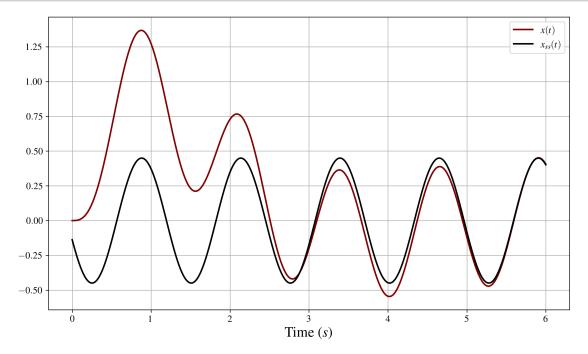
1.3.3 Part C - Getting the Transient and Steady State Response (20 Points)

```
[6]: A = 11
w = 5

B = A*np.abs(T_jw(w))
phi = np.angle(T_jw(w))
x_ss = lambda t_: B*np.sin(w*t_ + phi)

t_array = np.linspace(0, 6, 1000)
_, x_t = ct.forced_response(T, T=t_array, U=A*np.sin(t_array*w))
```

```
plt.plot(t_array, x_t, label='$x(t)$')
plt.plot(t_array, x_ss(t_array), label='$x_{ss}(t)$')
plt.legend()
plt.xlabel('Time ($s$)')
plt.show()
```



2 Problem 2

2.1 Given

$$T(s) = \frac{1}{30s^2 + 30s + 40}$$

2.2 Find

For the transfer function above,

- a. Find the analytical solution for the magnitude response $(M(\omega))$.
- b. Plot the magnitude response from $0.1 \le \omega < 10 \, rad/s$.
- c. Find the bandwidth (ω_1 to ω_2) and classify the filter type.

2.3 Solution

2.3.1 Part A - Finding the Magnitude Response Analytically (15 Points)

```
[7]: m, c, k = 30, 30, 40
T = ct.tf(1, [m, c, k])
T
```

[7]:

$$\frac{1}{30s^2 + 30s + 40}$$

[8]:
$$\frac{1}{30s^2 + 30s + 40}$$

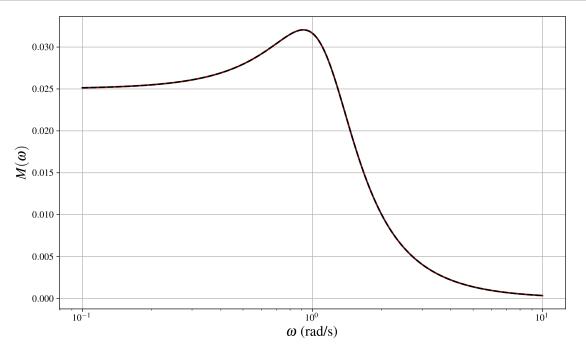
[9]:
$$\frac{1}{-30\omega^2 + 30i\omega + 40}$$

[10]:
$$\frac{1}{\sqrt{900\omega^4 - 1500\omega^2 + 1600}}$$

2.3.2 Part B - Plotting the Magnitude Response (15 Points)

```
[11]: mag, _, _ = ct.frequency_response(T, omegas) # Using the same omegas from above

plt.xscale('log')
plt.plot(omegas, mag)
plt.plot(omegas, mag_lamb(omegas), ls='--')
plt.xlabel(r'$\omega$ (rad/s)')
plt.ylabel(r'$M(\omega)$')
plt.show()
```



2.3.3 Part C - Finding the Bandwidth (20 Points)

```
[12]: wn = np.sqrt(k/m)
   zeta = c/(2*np.sqrt(k*m))
   wr = wn*np.sqrt(1 - 2*zeta**2)
   M_peak, _, _ = ct.frequency_response(T, wr)
   M_peak = M_peak[0]
   wr
```

[12]: 0.9128709291752769

```
[13]: omegas[max(mag) == mag][0]
```

[13]: 0.9128712871287129

```
[14]: M_peak = max(mag)
wr = omegas[M_peak == mag][0]

def find_band(om):
    mag_, _, _ = ct.frequency_response(T, om)
    # mag_ = mag_lamb(om)[0]
    return mag_[0] - M_peak/np.sqrt(2)

mag0, _, _ = ct.frequency_response(T, 0)
mag0[0] > M_peak/np.sqrt(2)
```

[14]: True

Because the magnitude at $\omega=0$ is greater than $\frac{M_{peak}}{\sqrt{2}}$, this is a low-pass filter and $\omega_1=0$. Furthermore, the damping ratio is greater than 0.382.

```
[15]: w2 = fsolve(find_band, np.array([wr + 1, ]))[0]
w2 # rad/s
```

[15]: 1.3690019477951116

Thus, the bandwidth is $0 \le \omega \le 1.36 \, rad/s$.