

1 Differential Forms

In \mathbb{R}^3 differential forms can be defined as:

- A 0-form is a function $f(x, y, z)$.
- A 1-form is of the form

$$F_1 dx + F_2 dy + F_3 dz$$

- A 2-form is of the form

$$F_1 dy \wedge dz + F_2 dz \wedge dx + F_3 dx \wedge dy$$

- A 3-form is of the form

$$f(x, y, z) dx \wedge dy \wedge dz$$

Differential forms behave somewhat as expected with addition.

1.1 Multiplication of Differential Forms

Multiplication of differential forms is **noncommutative** (but it is associative). Multiplication by 0-forms (i.e. functions) behaves as you would expect and is usually written without the \wedge .

Let ω be a k -form and ω' be a k' -form. Their product is a $(k + k')$ -form and is denoted by $\omega \wedge \omega'$. It behaves as follows:

- $\omega \wedge \omega'$ is linear. That is, $\omega = f_1 \omega_1 + f_2 \omega_2$ then
 $(f_1 \omega_1 + f_2 \omega_2) \wedge \omega' = f_1 (\omega_1 \wedge \omega') + f_2 (\omega_2 \wedge \omega')$
- $\omega \wedge \omega' = (-1)^{kk'} \omega' \wedge \omega$
- $\omega \wedge \omega = 0$

1.1.1 Addendum: The Hodge Star operator

We define the Hodge Star (*) operation on a form ω of $k \geq 2$ in \mathbb{R}^n as follows

$$\omega \wedge * \omega = \Omega_n$$

where Ω_n is the complete $n = k$ -form. An example makes this clearer. In \mathbb{R}^3 :

$$* dx = dy \wedge dz$$

1.2 Differentiation of Differential Forms

One of the main reasons differential forms are so useful is that they very nicely with differentiation. Let ω be a k -form, then

$$d := \omega_k \rightarrow \omega_{k+1}$$

Still working within the scope of \mathbb{R}^3 , consider a 0-form f . Then

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz$$

Is the equivalent $(k+1)$ -form after differentiation. Note that this is an edge case, for all other k -forms, the differential operator behaves as follows:

1. Apply d to coefficients;
2. Expand with the wedge product.

1.2.1 Example:

Let ω be a 1-form. Then

$$\omega = P dx + Q dy + R dz$$

$$d\omega = dP \wedge dx + dQ \wedge dy + dR \wedge dz$$

$$= (P_x dx + P_y dy + P_z dz) \wedge dx +$$

$$+ (Q_x dx + Q_y dy + Q_z dz) \wedge dy +$$

$$+ (R_x dx + R_y dy + R_z dz) \wedge dz =$$

$$= P_y dy \wedge dx + P_z dz \wedge dx +$$

$$+ Q_x dx \wedge dy + Q_z dz \wedge dy +$$

$$+ R_x dx \wedge dz + R_y dy \wedge dz =$$

$$= (R_y - Q_z) dy \wedge dz + (P_z - R_x) dz \wedge dx + (Q_x - P_y) dx \wedge dy$$

Which corresponds to the **curl** operation.

1.3 Integration of Differential Forms

A k -form may be integrated over a k -dimensional manifold. Or, in simpler terms: We may integrate k times a k -form. For example, we integrate a 1-form over a 1-manifold C (curve):

$$\int_C P dx + Q dy + R dz$$

Similarly, the integral of a 3-form over a 3-manifold (solid) is just:

$$\iiint_V f dx \wedge dy \wedge dz$$

Where the \wedge 's are usually omitted.

1.3.1 Parametrization

Consider a parametrization of a surface \mathcal{S} :

$$\mathbf{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$$

Then we can change the basis of our differential forms using the definition of the differential operator:

$$dx = \frac{\partial x}{\partial u} du + \frac{\partial x}{\partial v} dv = x_u du + x_v dv$$

and similarly for y, z . Then for 2-form ω defined as

$$\omega = P dy \wedge dz + Q dz \wedge dx + R dx \wedge dy$$

notice that

$$\begin{aligned} dx \wedge dy &= (x_u du + x_v dv) \wedge (y_u du + y_v dv) \\ &= (x_u y_v - x_v y_u) du \wedge dv \end{aligned}$$

1.4 Generalized Stoke's Theorem

Let ω be a k -form and Ω be a $(k + 1)$ manifold. Then

$$\int_{\Omega} d\omega = \int_{\partial\Omega} \omega$$