

Nominal Disunification

Seminários Teoria da Computação - UnB

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Nominal Terms and Syntax

Consider countable disjoint sets of *meta-variables* (or just *variables*)

$\mathbb{X} = \{X, Y, Z, \dots\}$ and atoms $\mathbb{A} = \{a, b, c, d, \dots\}$.

Definition (Nominal Terms)

The set $T(\Sigma, \mathbb{A}, \mathbb{X})$ of all nominal terms is inductively generated by the following grammar:

$$s, t, u, v ::= a \mid \pi \cdot X \mid [a] t \mid f(t_1, \dots, t_n)$$

Terms are called, respectively, **atoms**, **moderated variable**, **abstractions**, and **function application**.

Definition

The **object-level** action of a permutation π on a term t is defined by induction on the structure of t , as follows:

$$\begin{aligned}\pi \cdot a &\equiv \pi(a) & \pi \cdot (\gamma \cdot X) &\equiv (\pi \cdot \gamma) \cdot X & \pi \cdot [a] t &\equiv [\pi \cdot a] (\pi \cdot t) \\ \pi \cdot f(t_1, \dots, t_n) &\equiv f(\pi \cdot t_1, \dots, \pi \cdot t_n)\end{aligned}$$

Definition

The **meta-level** action of a substitution σ on a term t , denoted as $t\sigma$, is inductively defined by:

$$\begin{aligned} a\sigma &\equiv a & (\pi \cdot X)\sigma &\equiv \pi \cdot (X\sigma) & ([a] t)\sigma &\equiv [a](t\sigma) \\ f(t_1, \dots, t_n)\sigma &\equiv f(t_1\sigma, \dots, t_n\sigma) \end{aligned}$$

Lemma (Commutation Lemma)

$$\pi \cdot (t\sigma) \equiv (\pi \cdot t)\sigma.$$

Freshness and Equality

Definition (Contexts)

A *freshness constraint* is a pair $a\#t$ of an atom a and a term t . Call freshness constraints $a\#a$ and $a\#X$ primitive and write Δ and ∇ for finite sets of primitive freshness constraints and call them **freshness contexts**.

We say a context Δ is consistent iff it does not contain any freshness constraint of the form $a\#a$.

Derivation Rules for Freshness

$$\begin{array}{c} \frac{}{a \# b} (\# ab) \qquad \frac{\pi^{-1}(a) \# X}{a \# \pi \cdot X} (\# X) \ (\pi \neq \text{id}) \\[2ex] \frac{}{a \# [a] t} (\# a) \\[2ex] \frac{a \# t}{a \# [b] t} (\# b) \qquad \frac{a \# t_1 \cdots a \# t_n}{a \# f(t_1, \dots, t_n)} (\# f) \end{array}$$

Table 1: Derivation rules for freshness

Derivation Rules for α -equivalence

$$\begin{array}{c} \frac{}{a \approx_{\alpha} a} (\#ab) \qquad \frac{\Delta \vdash \text{ds}(\pi, \gamma) \# X}{\pi \cdot X \approx_{\alpha} \gamma \cdot X} (\text{Ds}) \\[2ex] \frac{t_1 \approx_{\alpha} u_1 \cdots t_n \approx_{\alpha} u_n}{f(t_1, \dots, t_n) \approx_{\alpha} f(u_1, \dots, u_n)} (\text{F}) \\[2ex] \frac{t \approx_{\alpha} u}{[a] t \approx_{\alpha} [a] u} (\text{Abs-a}) \qquad \frac{(a \ b) \cdot t \approx_{\alpha} u \quad \Delta \vdash b \# t}{[a] t \approx_{\alpha} [b] u} (\text{Abs-b}) \end{array}$$

Table 2: Derivation rules for α -equivalence

Nominal algebra ([3]) has two judgment forms:

1. A *freshness judgment form* $\Delta \vdash a \# t$.
2. An *equality judgment form* $\Delta \vdash t \approx_{\alpha} u$.

We define a *notion of derivability* by the natural deduction rules given in Tables 1 and 2.

1. We say $\Delta \vdash a \# t$ is a valid judgment when there exists a derivation of $a \# t$ using the elements of Δ as assumptions.
2. We also say $\Delta \vdash t \approx_{\alpha} u$ is a valid judgment when there exists a derivation of $t \approx_{\alpha} u$ using elements of Δ as assumptions.

Nominal Unification

Definition

A *unification problem* P is a finite set

$$P = \left\langle a_1 \overset{?}{\#} u_1, \dots, a_n \overset{?}{\#} u_n \parallel s_1 \overset{?}{\approx}_{\alpha} t_1, \dots, s_n \overset{?}{\approx}_{\alpha} t_n \right\rangle$$

of *freshness problems* $a_i \overset{?}{\#} u_i$ and *equational problems* $s_k \overset{?}{\approx}_{\alpha} t_k$.

$$\begin{aligned}a \# b, P &\Longrightarrow P \\a \# \pi \cdot X, P &\Longrightarrow \pi^{-1}(a) \# X, P \quad \pi \neq \text{id} \\a \# [a] t, P &\Longrightarrow P \\a \# [b] t, P &\Longrightarrow a \# t, P \\a \# f(t_1, \dots, t_n), P &\Longrightarrow a \# t_1, \dots, a \# t_n, P\end{aligned}$$

Table 3: Simplification rules for freshness

Simplification Rules on Problems

$$\begin{aligned}a &\approx_\alpha a, P \implies P \\ \pi \cdot X &\approx_\alpha \gamma \cdot X, P \implies \text{ds}(\pi, \gamma) \# X, P \\ f(s_1, \dots, s_n) &\approx_\alpha f(t_1, \dots, t_n), P \implies s_1 \approx_\alpha t_1, \dots, s_n \approx_\alpha t_n, P \\ [a] t &\approx_\alpha [a] u, P \implies t \approx_\alpha u, P \\ [b] l &\approx_\alpha [a] r, P \implies (a \ b) \cdot l \approx_\alpha r, a \# l, P\end{aligned}$$

Table 4: Simplification rules for α -equivalence

Lemma

The relation \Rightarrow is confluent and strongly normalizing.

We write the *unique* normal form of an unification problem P as $\langle P \rangle \downarrow$. So the problem P can be written as

$$\langle P \rangle \downarrow = \left\langle \Delta \parallel s'_1 \overset{?}{\approx}_\alpha t'_1, \dots, s'_l \overset{?}{\approx}_\alpha t'_l \right\rangle$$

We call Δ an **initial context** and the equational predicates $s_i \overset{?}{\approx}_\alpha t_i$ the equations that remains to be solved.

From now on we always consider problems in normal forms.

A solution of an unification problem P is a pair (Γ, σ) of a consistent context Γ and a substitution σ such that:

1. $\Gamma \vdash \Delta\sigma$.
2. $\Gamma \vdash s_i\sigma \overset{?}{\approx}_\alpha t_i\sigma$, for all $1 \leq i \leq n$.

We write $\mathcal{U}(P)$ for the set of all solutions of P .

An Algorithm for Nominal Unification

We now derive an *algorithm* for nominal unification by enriching the *simplification rules* with the two following additional rules: (as done in [2]).

$$\begin{aligned} \pi \cdot X \overset{?}{\approx}_{\alpha} u, P &\xrightarrow{X \mapsto \pi^{-1} \cdot u} P[X \mapsto \pi^{-1} \cdot u] \quad (X \notin \text{vars}(u)) \\ u \overset{?}{\approx}_{\alpha} \pi \cdot X, P &\xrightarrow{X \mapsto \pi^{-1} \cdot u} P[X \mapsto \pi^{-1} \cdot u] \quad (X \notin \text{vars}(u)) \end{aligned}$$

We denote this algorithm as $\text{Unif}(P)$ or if we need to be more specific $\text{Unif}(\Delta, s_1 \approx_{\alpha} t_1, \dots, s_n \approx_{\alpha} t_n)$.

We order solutions by the *instantiation order*: We say (Γ_2, σ_2) is an *instance* of (Γ_1, σ_1) iff there exists a substitution δ such that for all variables X the following conditions hold:

1. $\Gamma_2 \vdash X\sigma_2 \approx_\alpha X\sigma_1\delta$.
2. $\Gamma_2 \vdash \Gamma_1\delta$.

We denote this fact by writing:

$$(\Gamma_1, \sigma_1) \leq_\delta (\Gamma_2, \sigma_2)$$

Lemma

The instantiation order is a partial order on $\mathcal{U}(P)$. ([2])

Nominal Disunification

Now we discuss an extension to the nominal syntax of the work on First Order Disunification done by W. Buntine and H. Bürckert in [1].

Disunification Problems

Definition

A *nominal disunification problem* P is an ordered pair $P = \langle E \parallel D \rangle$ where E is an equational problem and D is a *disequational problem* as follows:

$$E = \left\langle \Delta \parallel s_1 \overset{?}{\approx}_{\alpha} t_1, \dots, s_n \overset{?}{\approx}_{\alpha} t_n \right\rangle$$
$$D = \left\langle \nabla \parallel p_1 \overset{?}{\not\approx}_{\alpha} q_1, \dots, p_m \overset{?}{\not\approx}_{\alpha} q_m \right\rangle$$

and Δ, ∇ are consistent contexts. We call them the **initial contexts** of the problem P .

Remark

We consider Δ, ∇ as the initial freshness constraints we impose on equations and disequations of P , respectively.

Example

$$P_1 = \left\langle \emptyset, X \overset{?}{\approx}_{\alpha} Y \parallel \emptyset, X \overset{?}{\not\approx}_{\alpha} a \right\rangle$$

$$P_2 = \left\langle b \# Z, (b \ a) \cdot X \overset{?}{\approx}_{\alpha} Y \parallel \emptyset, [a] X \overset{?}{\not\approx}_{\alpha} [b] Y \right\rangle$$

Definition

A solution to a disunification problem $P = \langle E \parallel D \rangle$ is a pair (Γ, σ) of a consistent context Γ and a substitution σ satisfying the following conditions:

1. (Γ, σ) is a solution of E .
2. (Γ, σ) satisfies the disequations in D . That is:
 - 2.1 $\Gamma \not\vdash \Delta\sigma$, or
 - 2.2 $\Gamma \not\vdash p \approx_\alpha q$, for all $p \not\approx_\alpha q$ in D .

Definition

A “pair with exception” is a pair $\langle \Gamma \parallel \sigma \rangle - \Psi$ of a **pair** $\langle \Gamma \parallel \sigma \rangle$ and an indexed family of **pairs** $\Psi = \{(\nabla_I, \psi_I) \mid I \in I\}$

.

Definition

We say a **pair** (Γ, σ) is an instance of a family Ψ iff each instance of (Γ, σ) is a instance of some $(\nabla_I, \psi_I) \in \Psi$.

We then write $\Psi \leq (\Gamma, \sigma)$.

Definition

A pair (Δ, λ) is an instance of a “pair with exceptions” $\langle \Gamma \parallel \sigma \rangle - \Psi$ iff (Δ, λ) is an instance of (Γ, σ) but not an instance of Ψ .

We denote this fact by $\langle \Gamma \parallel \sigma \rangle - \Psi \leq (\Delta, \lambda)$.

Definition

We call a “pair with exceptions” $\langle \Gamma \parallel \sigma \rangle - \Psi$ consistent iff it has at least one instance.

Lemma (Inconsistence Lemma)

A “pair with exceptions” $\langle \Gamma \parallel \sigma \rangle - \Psi$ is inconsistent iff (Γ, σ) is an instance of Ψ .

Corollary

Let $\langle \Gamma \parallel \sigma \rangle - \Psi$ be a “pair with exceptions”. If there is some $(\nabla_I, \psi_I) \in \Psi$ such that: there exists δ a substitution, for all X ,

$$\Gamma \vdash X\sigma \approx_\alpha X\psi_I\delta$$

Then $\langle \Gamma \parallel \sigma \rangle - \Psi$ is inconsistent iff $\Gamma \cap \nabla_I \neq \text{emptyset}$ or $\Gamma \vdash X\delta$.

Representation of Solutions

As with the case for unification problems we are interested in generate a *complete set* of solutions to a disunification problem P .

Definition

We call a set S of “pair with exceptions” a *complete representation* of solutions to the disunification problem P iff S satisfies the following conditions:

1. If $(\Delta, \lambda) \geq \langle \Gamma \parallel \sigma \rangle - \Psi$ for some $\langle \Gamma \parallel \sigma \rangle - \Psi$ in S then (Δ, λ) solves P .
2. If (Δ, λ) solves P then it is an instance of some $\langle \Gamma \parallel \sigma \rangle - \Psi$ in S .
3. $\langle \Gamma \parallel \sigma \rangle - \Psi$ is consistent for all $\langle \Gamma \parallel \sigma \rangle - \Psi \in S$.

Representation Theorem

Theorem

Let

$$P = \left\langle \Delta, s_1 \overset{?}{\approx}_{\alpha} t_1, \dots, s_n \overset{?}{\approx}_{\alpha} t_n \parallel \nabla, p_1 \overset{?}{\not\approx}_{\alpha} q_1, \dots, p_m \overset{?}{\not\approx}_{\alpha} q_m \right\rangle$$

be a disunification problem. Define the family

$$\Psi := \bigcup_{p \overset{?}{\not\approx}_{\alpha} q \in D} c\mathcal{U} \left(p \overset{?}{\approx}_{\alpha} q \right)$$

Then the set

$$S = \{ \langle \Gamma \parallel \sigma \rangle - \Psi \mid (\Gamma, \sigma) \in c\mathcal{U}(E) \text{ but not } \Psi(\Gamma, \sigma) \}$$

is a complete representation of solutions to the problem P .

Inconsistence Algorithm

input : $\langle \Gamma \parallel \sigma \rangle - \psi$ a finite pair with exceptions

output : **BOOL**: True if the input is consistent False otherwise

```
1 LET CON : BOOL ;
2 foreach  $(\nabla_I, \psi_I) \in \Psi$  do
3   if matching( $(\Gamma, X\sigma \approx_\alpha X\psi_I) = (\Gamma', \delta)$ ) then
4     if  $\Gamma \cap \nabla_I \neq \emptyset$  OR  $\Gamma \vdash X\delta$  then
5       RETURN FALSE AND STOP
6     else
7       CON := TRUE
8     end
9   else
10    RETURN FALSE AND STOP
11  end
12 end
```

Algorithm 1: Inconsistence Algorithm

Disunification Algorithm

input : A disunification problem $P = \langle E \parallel D \rangle$.

output : a set S of pair with exceptions (can be emptyset)

1 LET $(\Gamma, \sigma) := \text{Unify}(E)$;

2 LET $\Psi := \bigcup_{\substack{p_i \not\approx_{\alpha}^? q_i \\ q_i \in D}} \{(\nabla_i, \psi_i) = \text{Unify}(\nabla, p_i \approx_{\alpha}^? q_i)\}$;

3 **if** Consistent($\langle \Gamma \parallel \sigma \rangle - \Psi$) **then**

4 | RETURN $\langle \Gamma \parallel \sigma \rangle - \Psi$

5 **else**

6 | RETURN \emptyset and STOP

7 **end**

Algorithm 2: Disunification Algorithm

We plan to continue working on Nominal Disunification. That's our task list:

1. Extend Disunification to Nominal Equational Theories E (in the the context of Nominal Universal Algebras, [3]), like AC and C for example.
2. Study more general equational problems, like *Disunification with parameters*.



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Thank you.