Digita l'equazione qui.

marted) 11 ottobre 2022 12:13

$$\mathcal{J}_{it} = \mathcal{X}_{it} \mathcal{X}_{i} + \mathcal{T}_{it} + \mathcal{E}_{it} + \mathcal{Z}_{it} \mathcal{B}_{i}$$

$$\mathcal{J}_{it} = \mathcal{P}_{it-1} + \mathcal{V}_{it} \quad \mathcal{D}_{i} \mathcal{N}_{i}(o, R)$$

$$y_{t}(s) = \chi_{t}(s) + \chi_{t}(s) + \chi_{t}(s) + \xi_{t}(s) + \xi_{t}(s)$$

1)
$$\partial_{t}(s) = \gamma_{t} + \omega(s)$$

$$\gamma_{t} = P\gamma_{t-2} + \gamma_{t} \longrightarrow \gamma_{n} N_{t}(o, \delta R(p))$$

$$\omega(s) \sim GP(o, \delta H(p)) \qquad \omega \sim N_{n}(o, H(p))$$

$$V \sim N_{n}(o, H(p))$$

CORR. Spaziole exp{-\$d(s:,s;)}

2)
$$\theta_{t}(s) = Y_{t} \cdot \omega(s)$$

3)
$$T_{+}(s) = PT_{+-2}(s) + V_{+}(s)$$
 Modello Dinamico
$$V_{+}(s) \sim CP(0, Z^{2}H(\phi))$$