

Cyber Physical Systems Security

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1. Step 1: **To save a parameter file**, first run your simulation (you do not need to load the CMAC-toff.txt path to do this), then save the default parameters:

- `cd ~ /ardupilot/ArduPlane/`
- `sim_vehicle.py - -map - -console`
To show the parameters:
- `param show`
To save the parameters to a file called default.parm:
- `param save /home/<user>/default.parm`
For me, I use the command below, but you will have your own user name for your computer:
- `param save /home/colletti/default.parm`

To change the appropriate values to 0, choose an editor of your choice and change `RLL_RATE_I`, `RLL_RATE_D`, `PTCH_RATE_I`, and `PTCH_RATE_D` to 0. Below is a demonstration for vim:

- `cd ~ /`
- `vim default.parm` Press the escape button on your keyboard, then type `":w"`
- `:w`
- Scroll down to `PTCH_RATE_D` and change it to 0
- Scroll down to `PTCH_RATE_I` and change it to 0
- Scroll down to `RLL_RATE_D` and change it to 0
- Scroll down to `RLL_RATE_I` and change it to 0 Press the escape button on your keyboard, then type:
- `: saveas noid.parm`

2. Step 2: **To run a flight with noid.parm parameters**

- `cd ~ /ardupilot/ArduPlane/`
The following command will save the flight in a folder called "noid_flight"
- `sim_vehicle.py - -out=udp:10.103.44.96:14550 - -aircraft "noid_flight" - -map - -console`
While the sim is setting up, use the following command to load the parameter file
- `param load /home/colletti/noid.parm`
- `wp load ../Tools/autotest/Generic_Missions/CMAC-toff-loop.txt`
- `arm throttle`
- `mode auto`

To convert the flight.tlog to csv

- `python /pymavlink/tools/mavlogdump.py -format=csv -types=ATTITUDE,
SERVO_OUTPUT_RAW, NAV_CONTROLLER_OUTPUT
/ardupilot/ArduPlane/noid_flight/logs/2021-10-13/flight1/flight.tlog >~ /noid.csv`
- `python /pymavlink/tools/mavlogdump.py -format=csv
-types=ATTITUDE,SERVO_OUTPUT_RAW,NAV_CONTROLLER_OUTPUT
/ardupilot/ArduPlane/changed_flight/logs/2021-10-14/flight1/flight.tlog
>~ /changed_flight.csv`