Operating Systems: Process Management

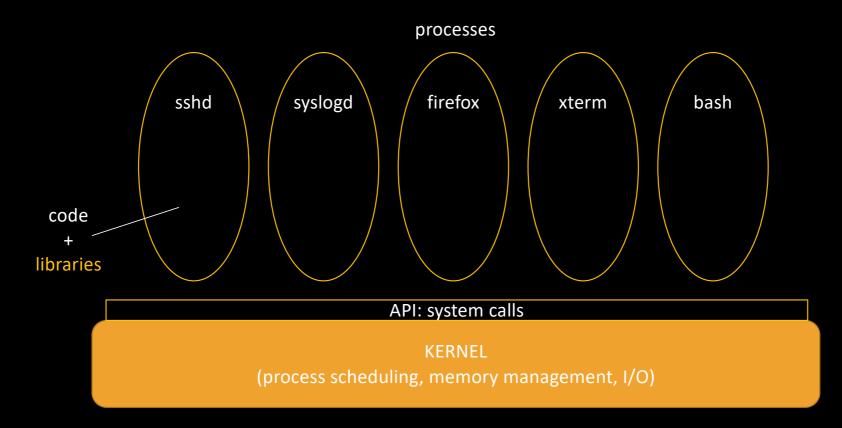
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https://gforgeron.gitlab.io/se/

Structure of an OS



Hardware

Processes

- Processes are lively instances of programs
 - Program = binary code stored on disk
 - Multiple processes can run the same program independently
- Process = Address Space + Execution Context
 - Address space
 - Set of visible memory addresses
 - Code, Data, Heap, Stack, Shared Libraries, etc.
 - Execution Context
 - Stack + content of processor registers

- Typically composed of distinct memory regions
 - A region being a contiguous range of valid addresses

- Typically composed of the following regions
 - Code
 - (aka text segment)
 - Contains executable instructions
 - Usually a read-only region

Code

- Typically composed of the following regions
 - Code
 - Data
 - Allocation of static variables
 - int i

Data

Code

- Typically composed of the following regions
 - Code
 - Data
 - Allocation of static variables
 - Actually two segments
 - Initialized data (data segment)

```
• float pi = 3.1415;
```

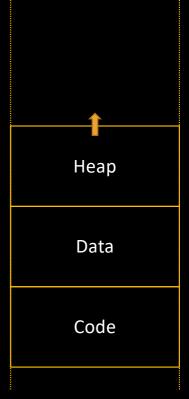
- Stored in object file
- Uninitialized data (bss segment)
 - int i;
 - Only segment size is stored in object file

bss

data

Code

- Typically composed of the following regions
 - Code
 - Data
 - Heap
 - Dynamic allocations
 - malloc/free
 - Managed by libc
 - Dynamic expansion
 - OS cannot (always) detect accesses outside malloc'ed buffers...



- Typically composed of the following regions
 - Code
 - Data
 - Heap
 - Stack
 - Allocation of function parameters and local variables
 - Automatic growth
 - 8 MiB default limit under Linux

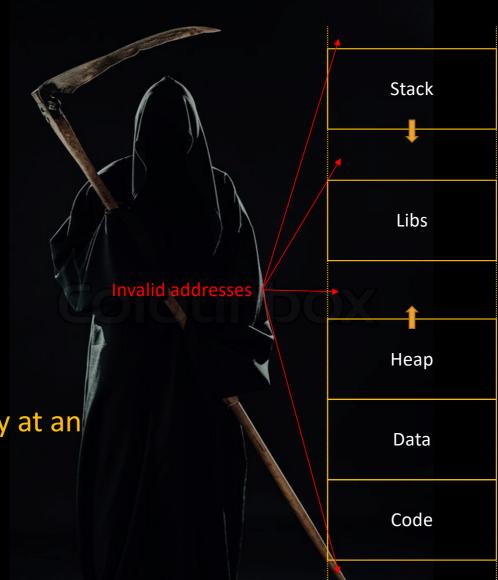


- Typically composed of the following regions
 - Code
 - Data
 - Heap
 - Stack
 - Shared Libraries
 - libc, libm, libGL, etc.
 - Mapped on demand



- Typically composed of the following regions
 - Code
 - Data
 - Heap
 - Stack
 - Shared Libraries

 Attempt to access memory at an invalid address leads to a Segmentation Fault



Inspecting Memory Regions under Linux

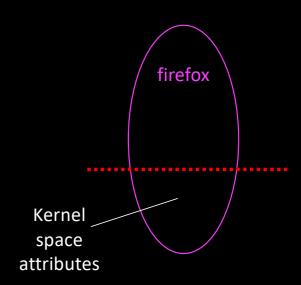
[jolicoeur] cat /proc/self/maps

```
55ad0226e000-55ad02276000r-xp0000000008:01157328955ad02475000-55ad02476000r-p0000700008:01157328955ad02476000-55ad02477000rw-p0000800008:01157328955ad02c0d000-55ad02c2e000rw-p0000000000:0007f9a1646b000-7f9a1669e000r-xp0000000008:0170792597f9a16838000-7f9a16a38000r-xp0000000008:0181312257f9a16a38000-7f9a16a3c000r-p0019500008:0181312257f9a16a3c000-7f9a16a3c000rw-p0019900008:0181312257f9a16a43000-7f9a16a66000r-xp0000000008:0181281927f9a16c66000-7f9a16c67000r-p0002300008:0181281927f9a16c67000-7ffeaea98000rw-p0000000008:018128192
```

```
/bin/cat
/bin/cat
/bin/cat
[heap]
/usr/lib/locale/locale-archive
/lib/x86_64-linux-gnu/libc-2.24.so
/lib/x86_64-linux-gnu/libc-2.24.so
/lib/x86_64-linux-gnu/libc-2.24.so
/lib/x86_64-linux-gnu/libc-2.24.so
/lib/x86_64-linux-gnu/ld-2.24.so
/lib/x86_64-linux-gnu/ld-2.24.so
/lib/x86_64-linux-gnu/ld-2.24.so
/lib/x86_64-linux-gnu/ld-2.24.so
/lib/x86_64-linux-gnu/ld-2.24.so
[stack]
```

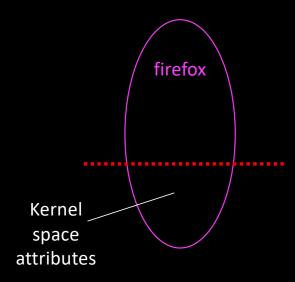
Process Attributes

- In addition to Address Space description, the kernel stores the following information about each process:
 - Process ID (pid)
 - Priority
 - User ID (real/effective)
 - File descriptor table
 - Signal handling table
 - Space for registers backup
 - Etc.

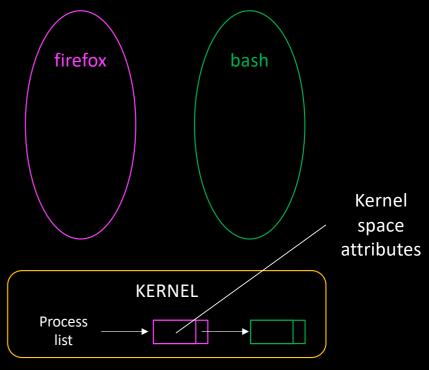


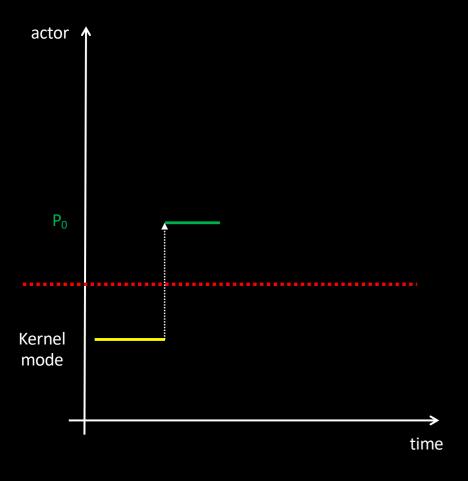
Process Attributes

Processes can be represented this way:

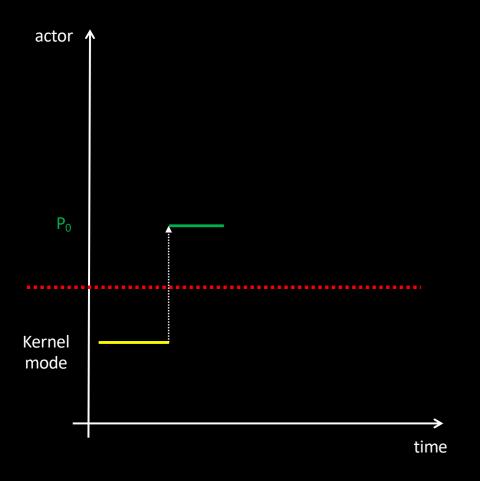


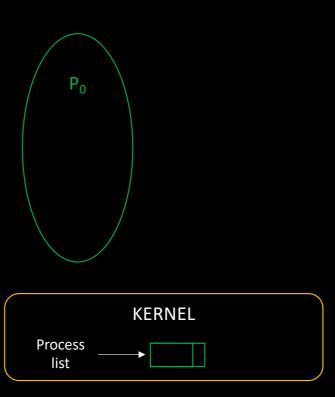
But reality is (obviously) more like:

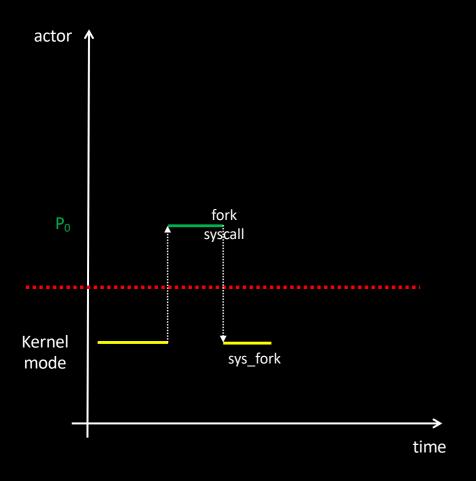


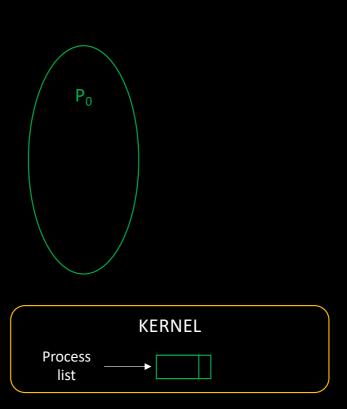


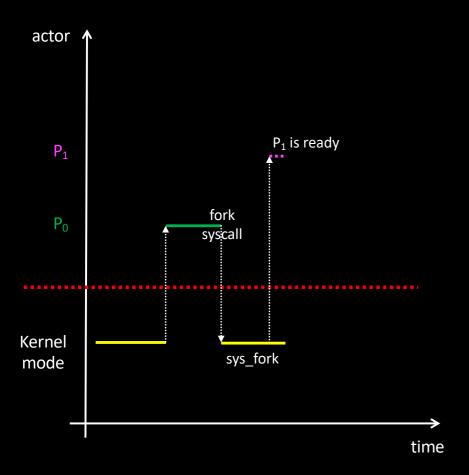
- The Kernel originally spawns one process
 - This process will in turn create several processes (background DAEMONs)
 - Using a system call (what else?)

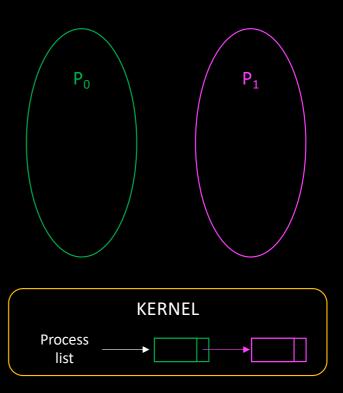


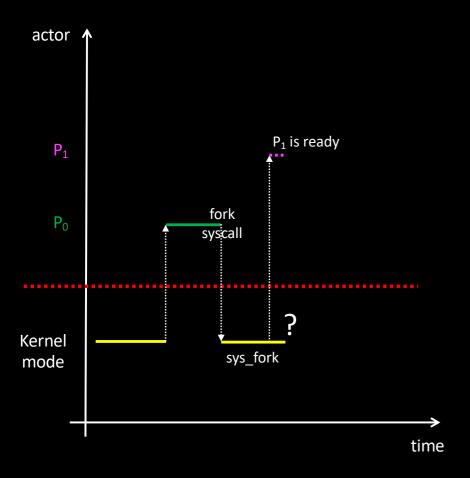


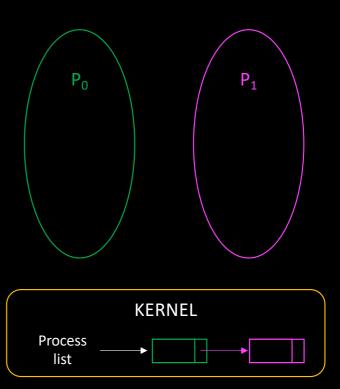


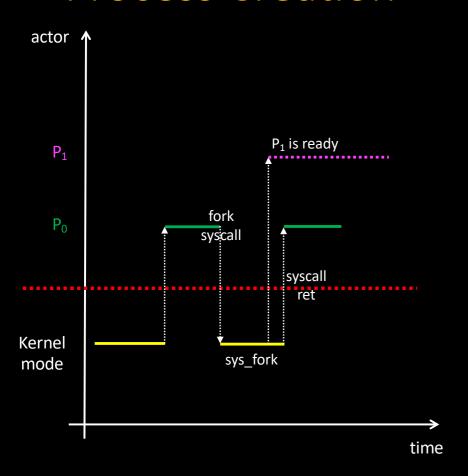


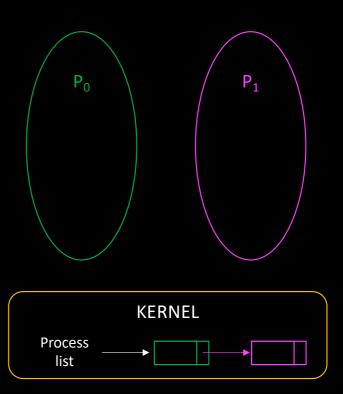


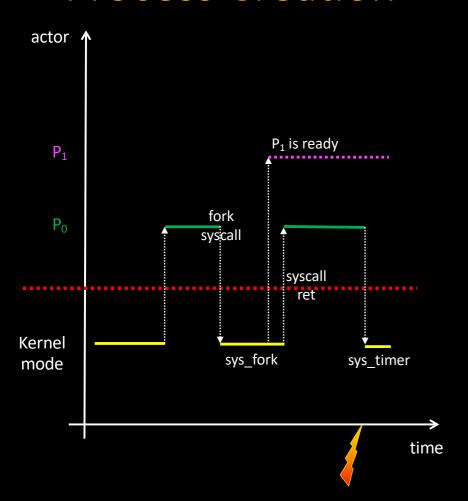


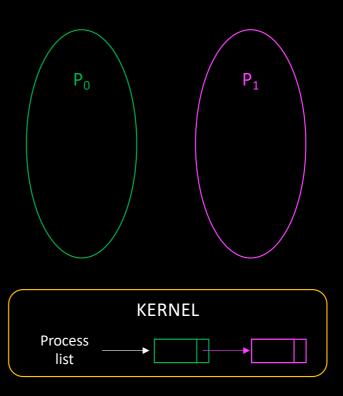




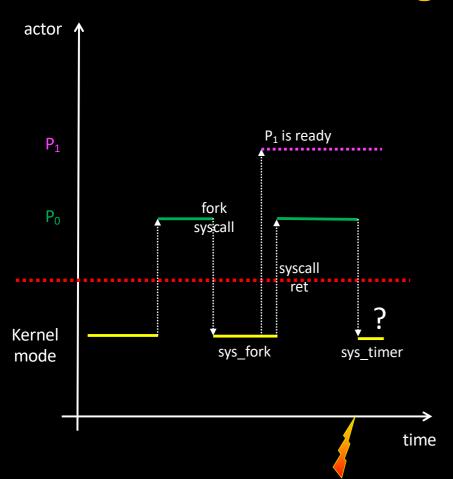








Process Scheduling

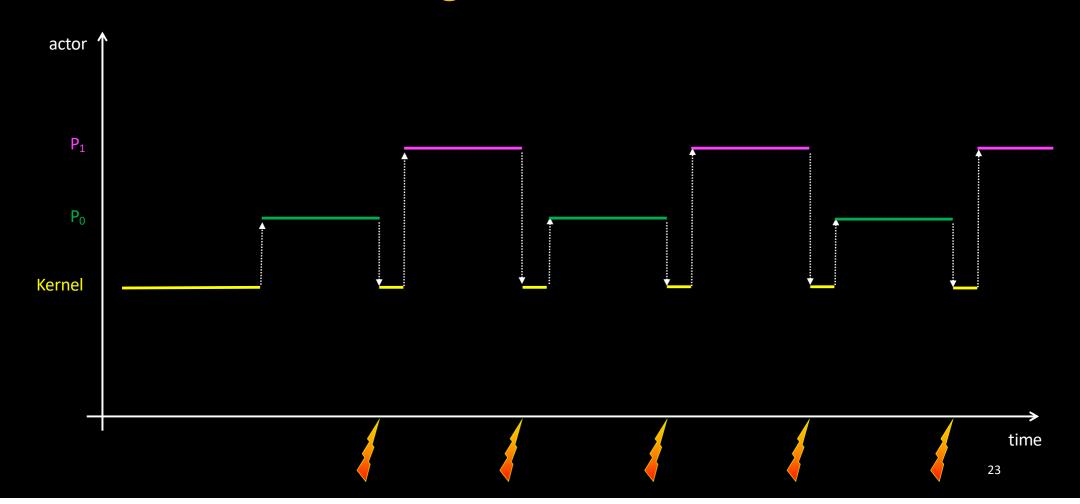


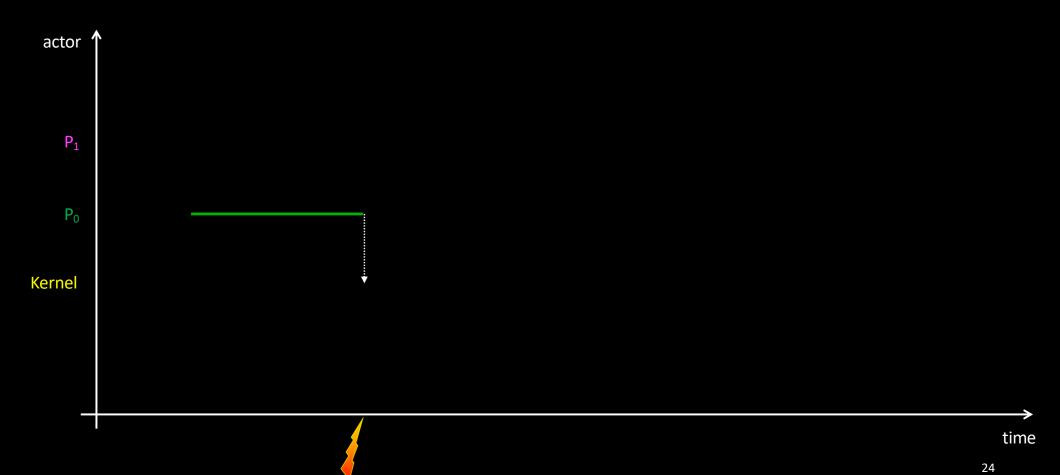
- At some point, the kernel must decide "which process should run now?"
 - = Process Scheduling

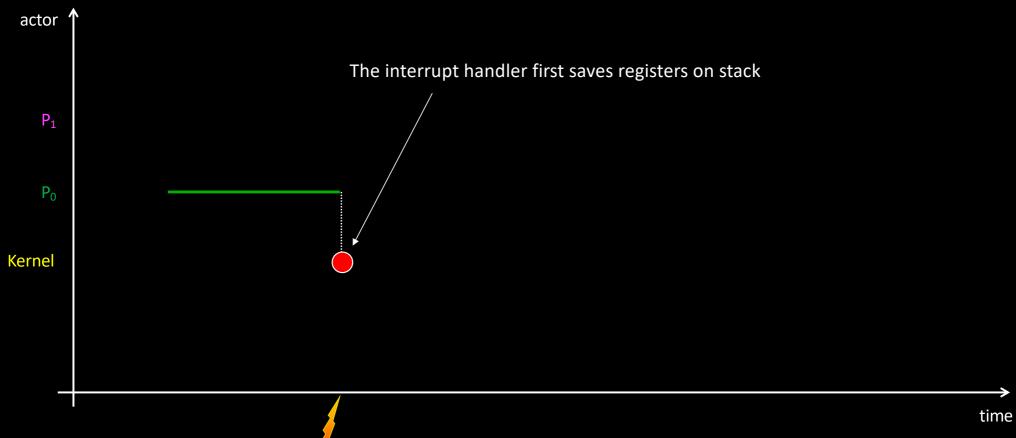
• NB

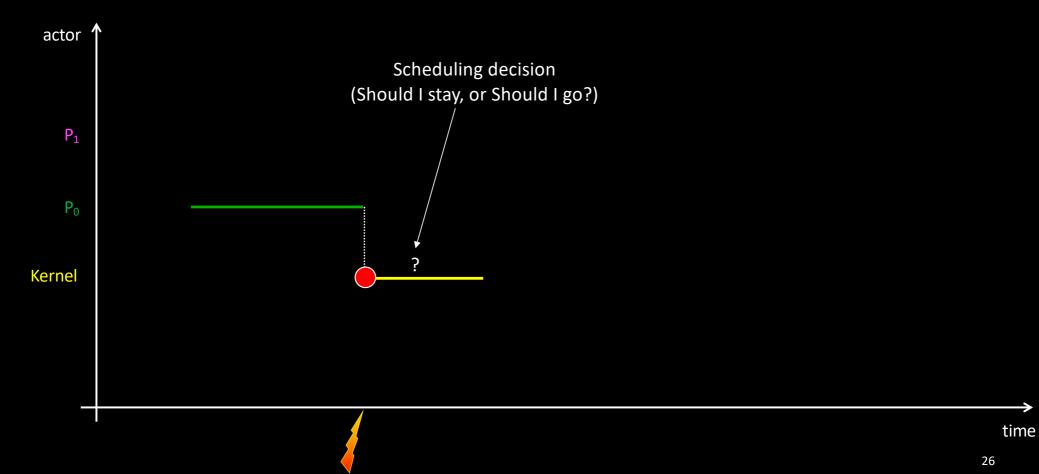
- A CPU executes one program at a time
- There can be only #CPU processes running simultaneously

Process Scheduling

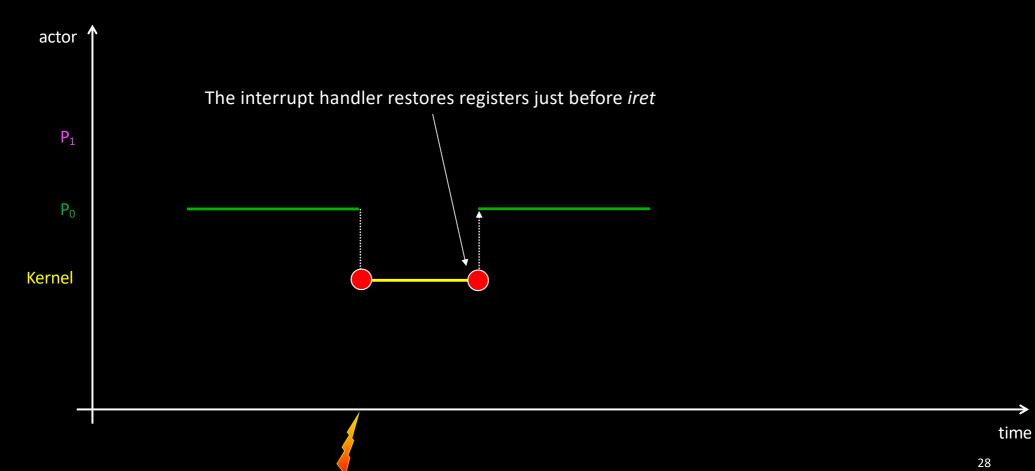


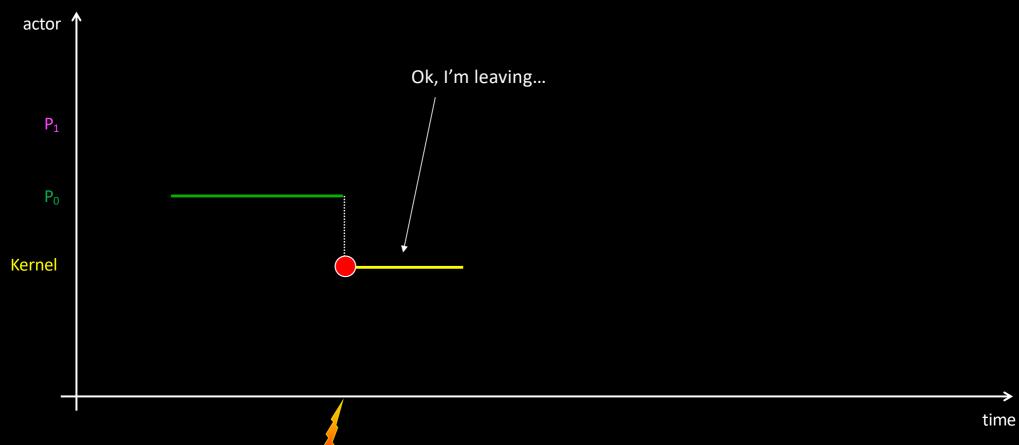


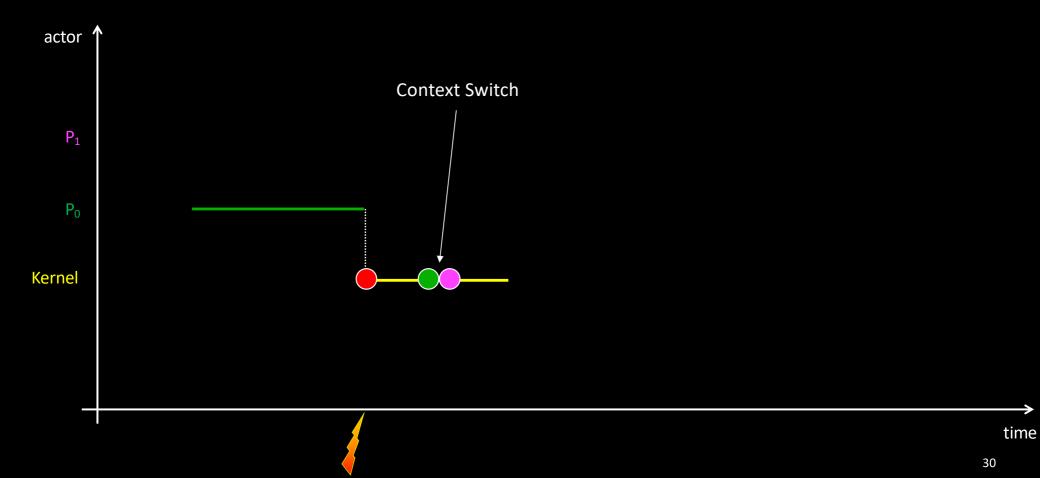


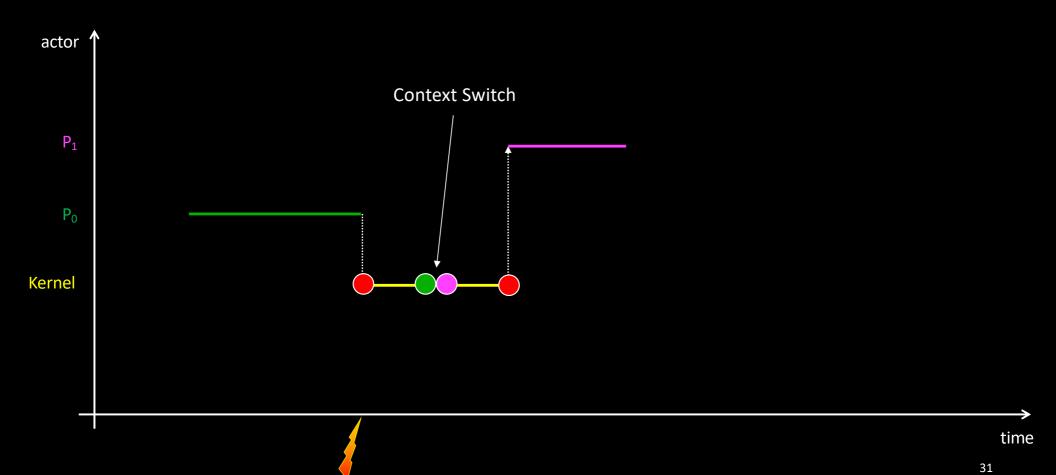












Context Switching

- switch_to (P_{prev}, P_{next})
 - Save P_{prev} registers
 - Restore P_{next} registers
 - P_{prev} becomes P_{next}
 - P_{next} resumes execution and returns from "one" switch_to call
 - P_{prev} will resume execution when some process will switch back to it

```
kernel_f()
{
    ...
    switch_to (prev, next);
    ...
}
kernel_g()
{
    ...
    switch_to (prev, next);
    ...
}
```

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Segmentation Fault





- Survient lorsque la mémoire du processus est trop fragmentée
- Survient torsque la memoire du processus est trop fragmentee
- Surgit toujours au CREMI mais jamais de mon code!

noi : donc ça ne vient pas







- Cliquez sur l'écran projeté pour lancer la question
- Résulte d'une tentative d'accès à une adresse non accessible

95%

14%

81 🚢

12



4

N'est pas forcément déclenchée lors d'un accès mémoire illicite

44% 37 💄









Process States

Just Created

Process States

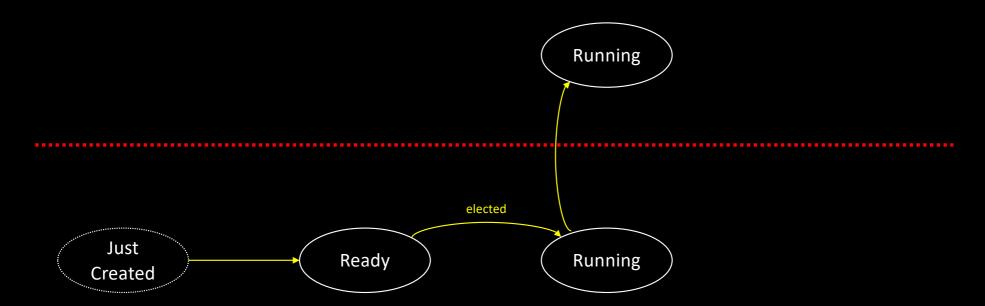
.....

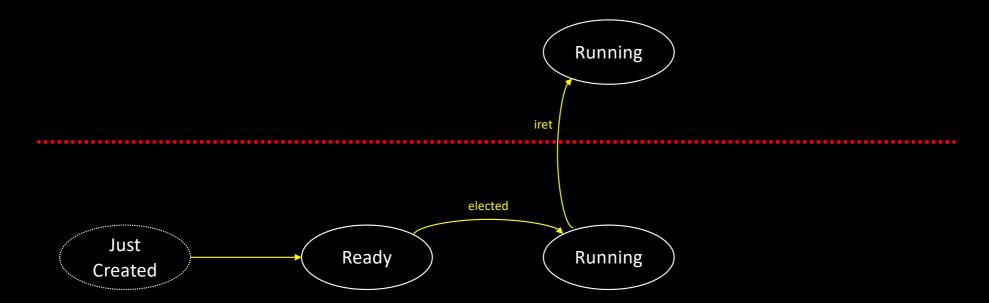


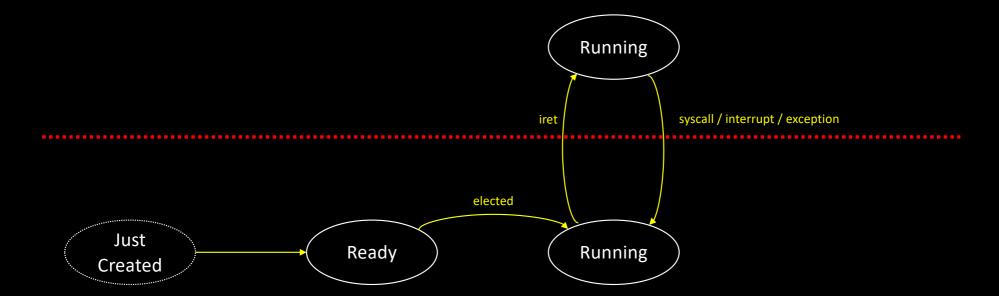
Process States

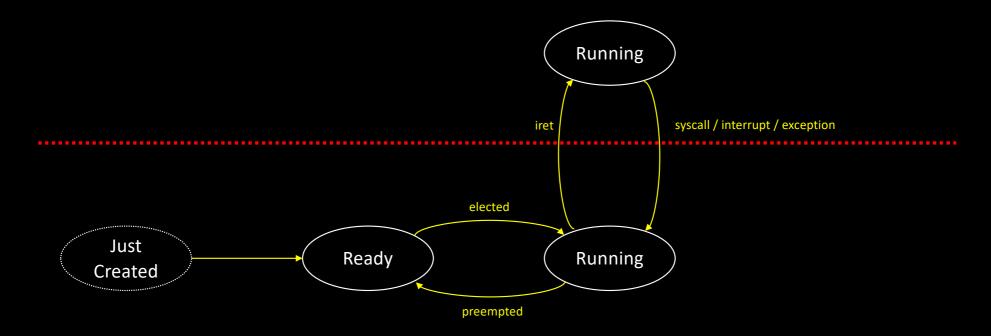
.....

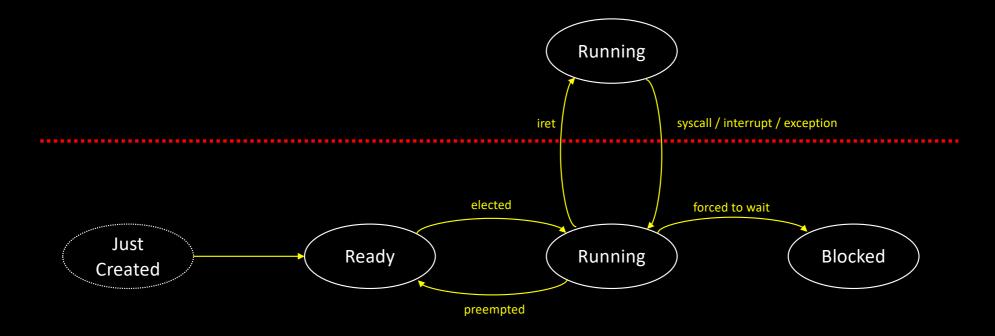


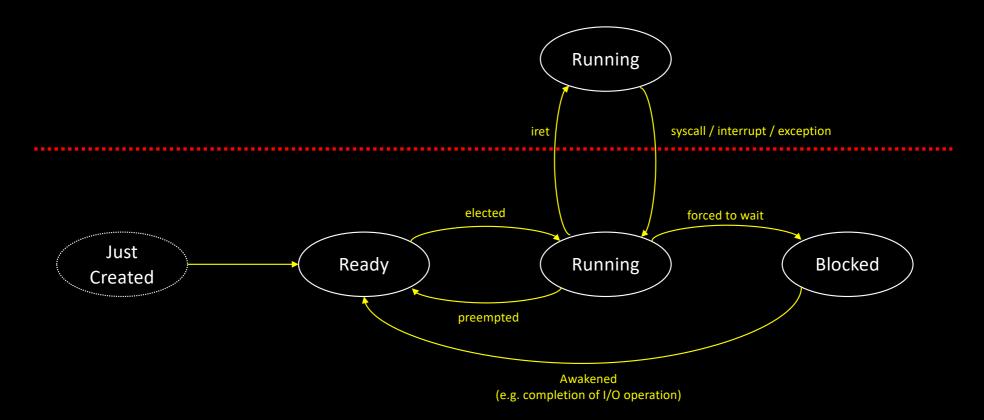


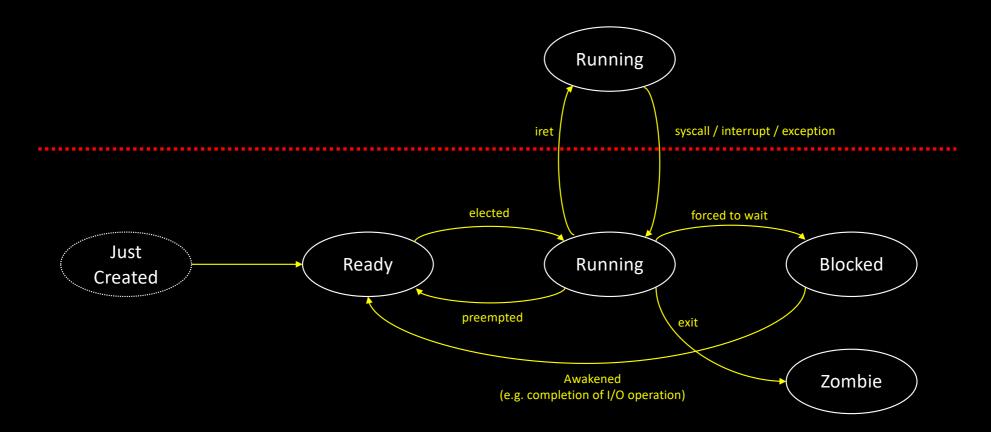




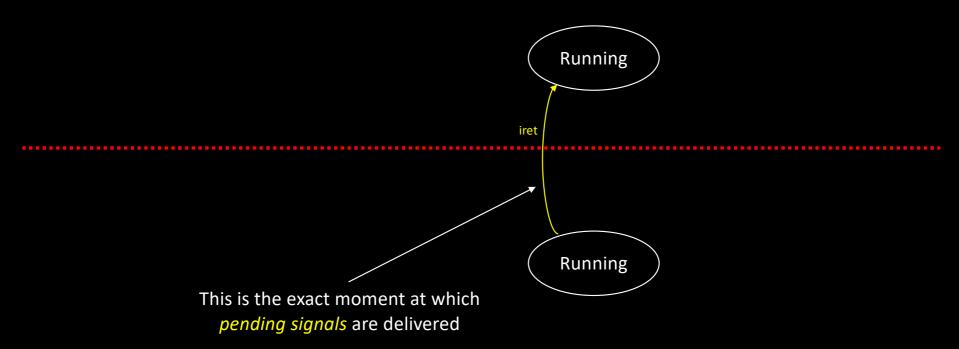


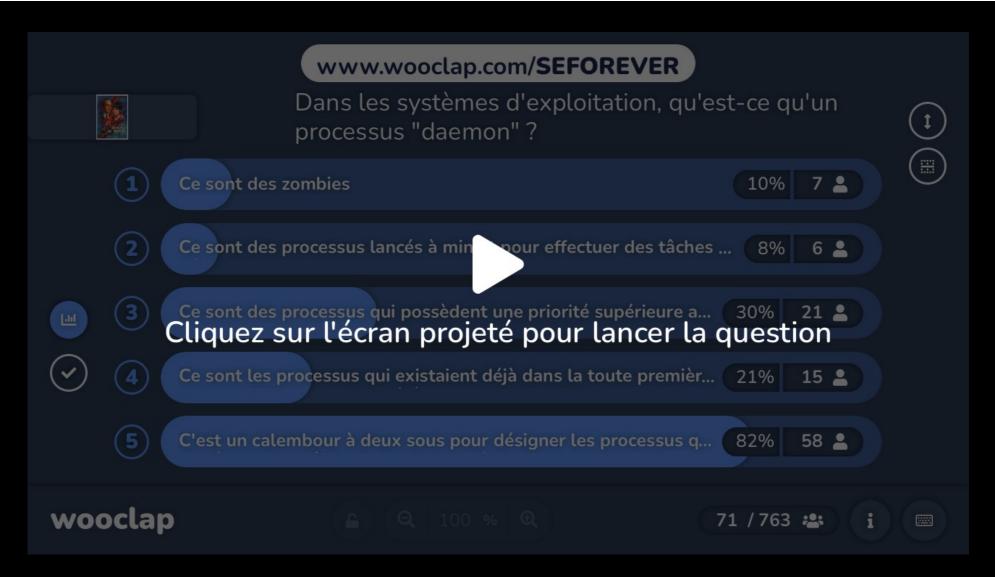


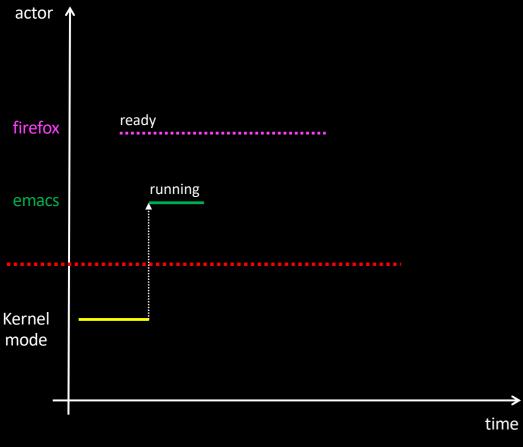




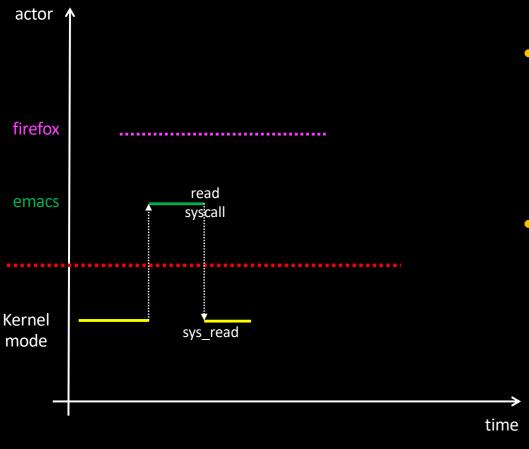
Oh, by the way...



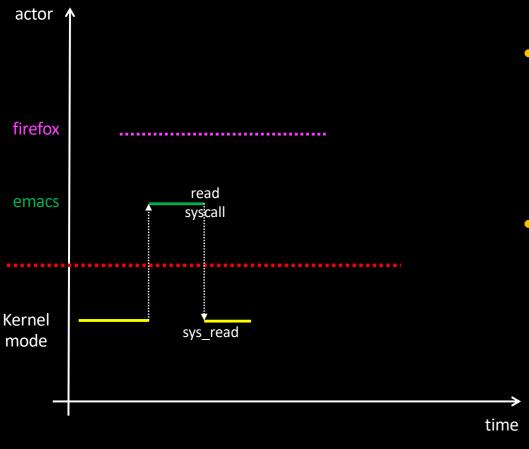




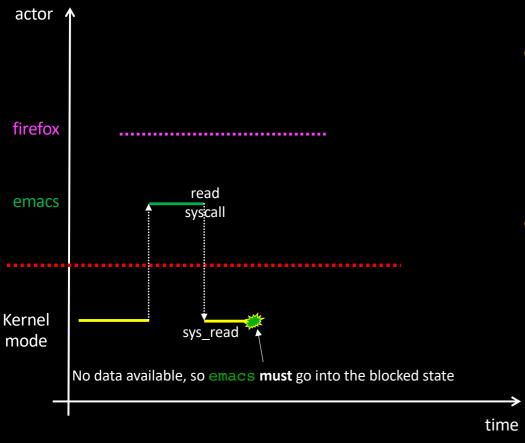
- Let's say emacs is running
 - Emacs spends its life
 - Waiting for keyboard input
 - Refreshing display



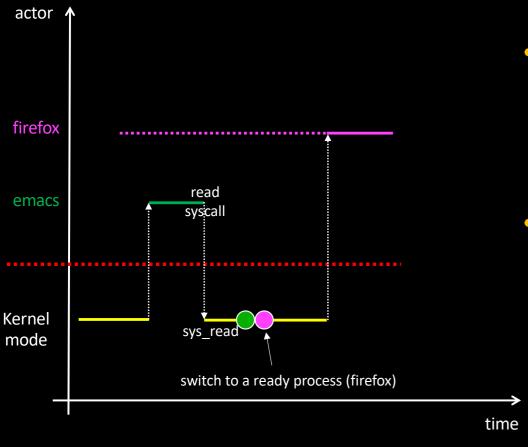
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 - Emacs spends its life
 - Waiting for keyboard input
 - Refreshing display
- Waiting for keyboard input
 - read system call



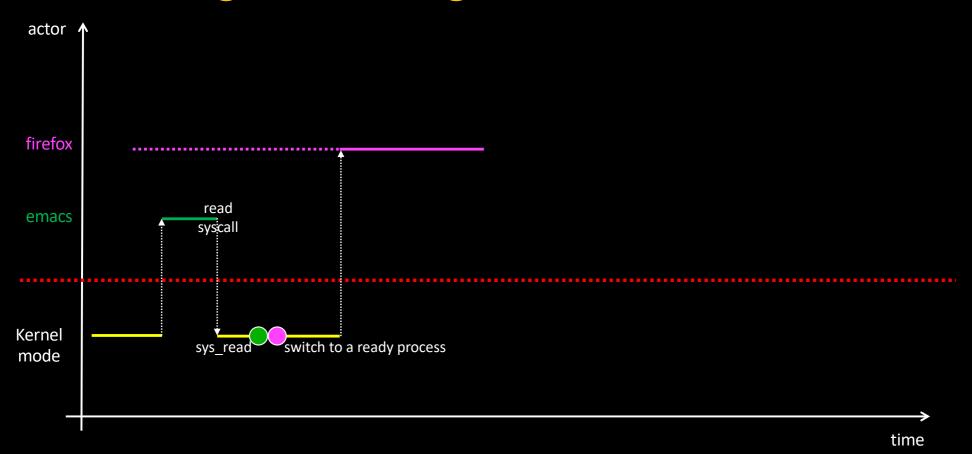
- Let's say emacs is running
 - Emacs spends its life
 - Waiting for keyboard input
 - Refreshing display
- Waiting for keyboard input
 - read system call
 - Most of the time, keyboard buffer is empty



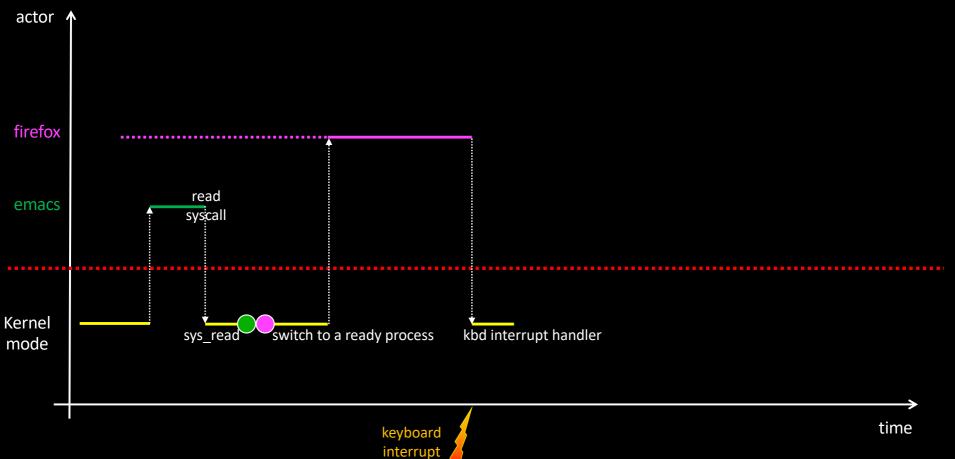
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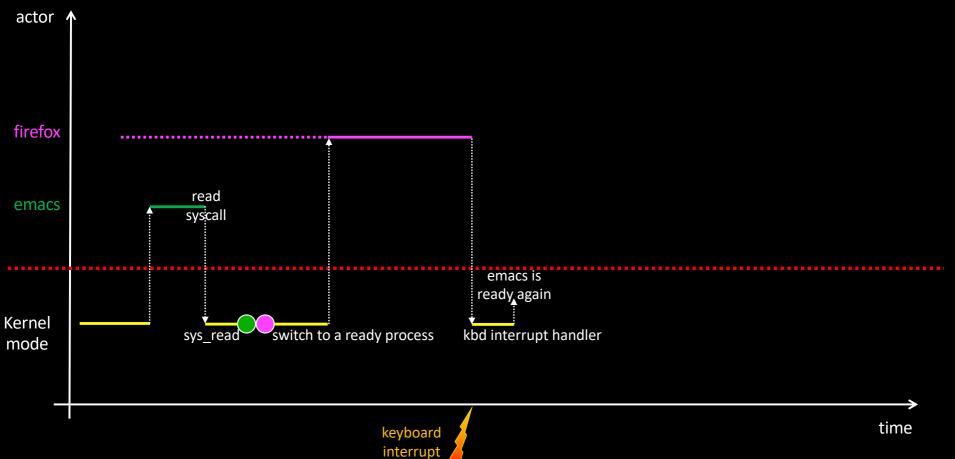


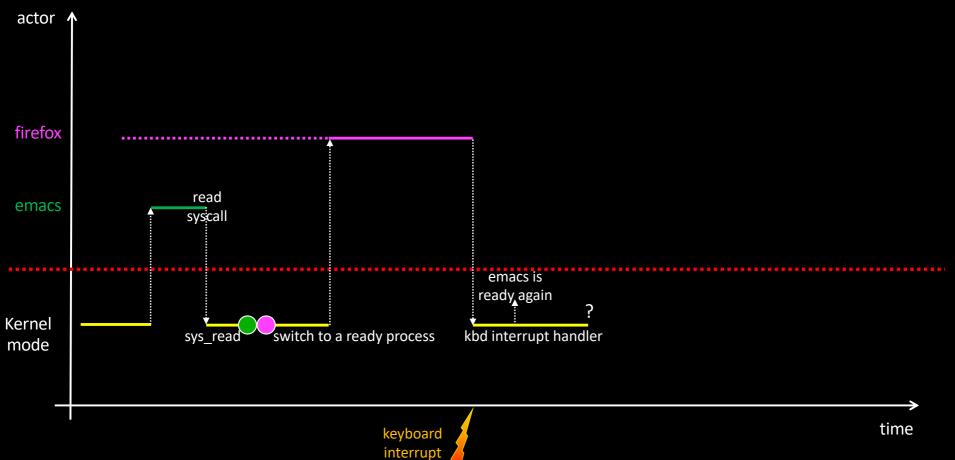
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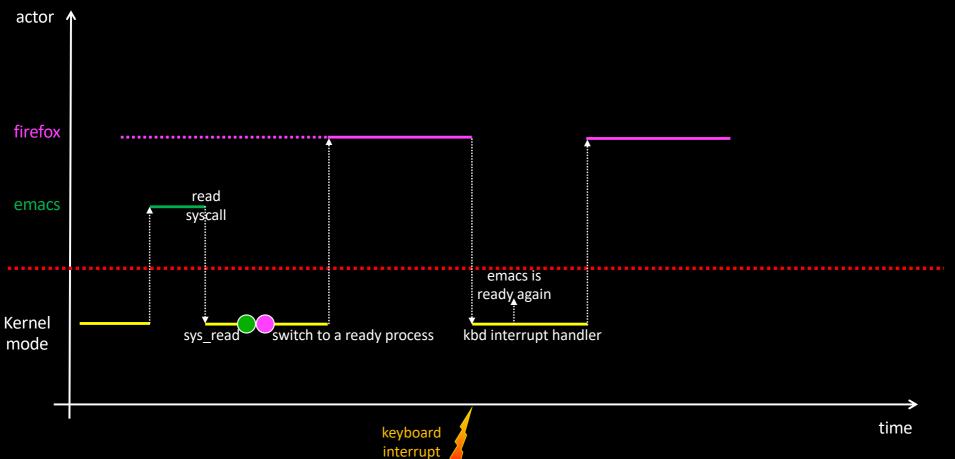


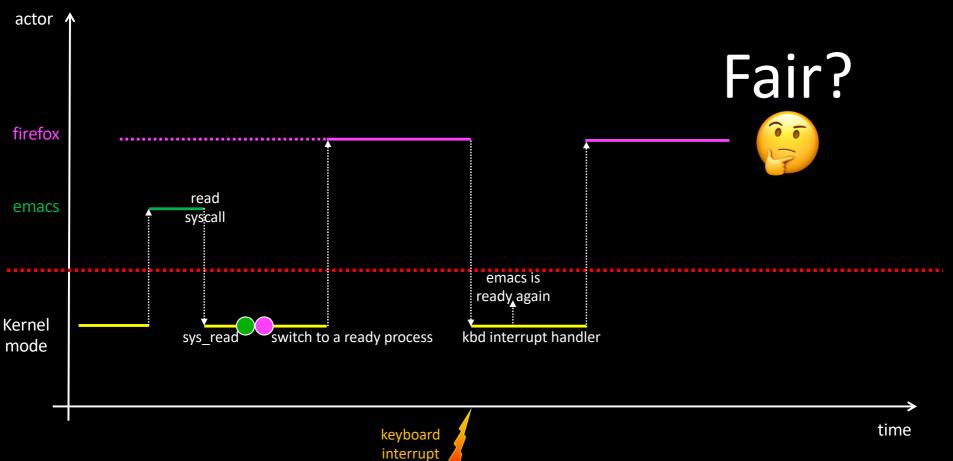












Scheduling

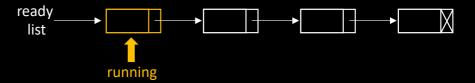
- General goal of a process scheduler
 - Optimize CPU usage and maximize user happiness
 - Each process has a fair access to the CPU
 - CPU is always running at 100%
 - Responsiveness of interactive processes is optimal
 - Completion time of long-running processes is minimal
 - Etc.
 - Satisfying these rules altogether is impossible
 - There is no such thing as a *Universal Scheduler*
 - Scheduling heavily depends on OS type
 - Interactive
 - · Real-time
 - Batch server

Scheduling in an interactive world

- Most critical property
 - Responsiveness of interactive processes is optimal
- Interactive processes
 - Processes reacting to I/O events
- Scheduling strategy
 - Scheduling algorithm
 - Election of next running process among the pool of ready ones
 - Places where the scheduling code is executed

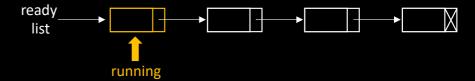
The FIFO Scheduler

- Running process = head of ready list
 - Removed only when blocking or terminating
 - No periodic preemption
- Pros
 - 3
 - 7
- Cons
 - ?



The FIFO Scheduler

- Running process = head of ready list
 - Removed only when blocking or terminating
 - No periodic preemption
- Pros
 - Very small overhead
 - O(1) election algorithm
- Cons
 - Starvation



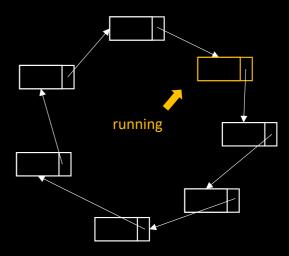
The Round-Robin Scheduler

• FIFO + preemption

 At each timer interrupt, the running process yields CPU to its successor

Pros

- 5
- 5
- Cons
 - ?



The Round-Robin Scheduler

• FIFO + preemption

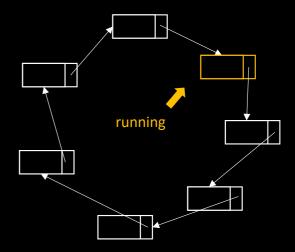
 At each timer interrupt, the running process yields CPU to its successor

Pros

- No starvation
- O(1) scheduler

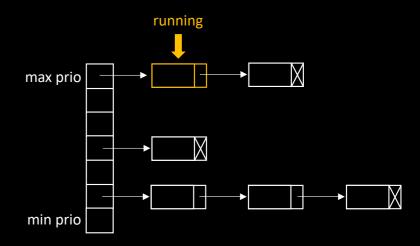
Cons

No priority



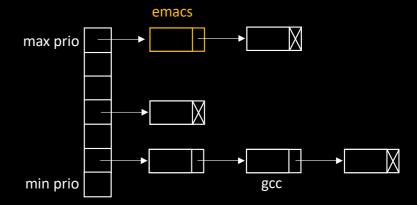
The (strict) Priority Scheduler

- Used in Real-time systems
- One FIFO list per priority level
- Running process = head of highest non-empty priority list
- Pros
 - O(#priorities) scheduler
- Cons
 - ?



The (strict) Priority Scheduler

- Used in Real-time systems
- One FIFO list per priority level
- Running process = head of highest non-empty priority list
- Pros
 - O(#priorities) scheduler
- Cons
 - How to assign priorities to processes?



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Comment attribuer automatiquement des priorités aux ...

- 1

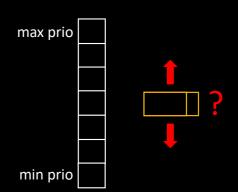
- J'ai pas de préjugé, m'enfin c'est facile : y'a les gentils d'un côté (emacs, shell, vscode) et les méchants de l'autre (tous ceux qu'on connaît pas)
- Pour un monde plus juste, je suis pour donner la même priorité à tous



- Ca dépend surtout de l'utilisateur qui les lance : c'est à lui qu'il faut attribuer une priorité !
- \bigcirc
- Pour un monde moins pollué, je propose : "plus on lance de processus et moins ils seront prioritaires"
- **5** Aucune de ces solutions ne me va

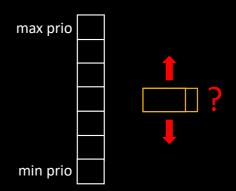
Assigning dynamic priorities to processes

- We'd like to assign higher priorities to "cool" processes
 - Which need to react quickly to events?
 - Which perform a lot of I/O?
 - Which won't use a full quantum of time (10ms) next time?



Assigning dynamic priorities to processes

- We'd like to assign higher priorities to "cool" processes
 - Which need to react quickly to events?
 - Which perform a lot of I/O?
 - Which won't use a full quantum of time (10ms) next time?
- How do we know?
 - People can change...
 - "If I can change, and you can change, everybody can change!" [Rocky Balboa, 1985]



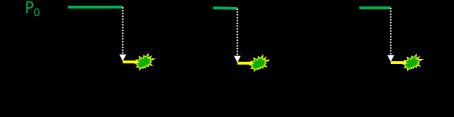
- By looking at the past!
 - If a process kept behaving well so far...

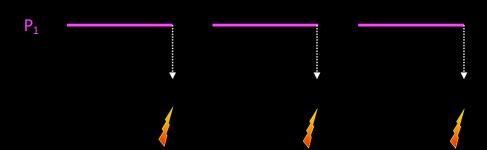
...it will probably do so next time we schedule it!

- By looking at the past!
 - If a process kept behaving well so far...

...it will probably do so next time we schedule it!

• P₀ looks more friendly than P₁



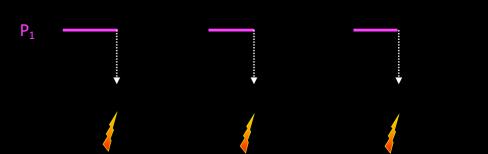


- By looking at the past!
 - If a process kept behaving well so far...

...it will probably do so next time we schedule it!



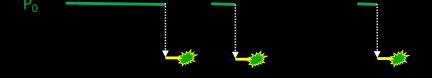
- P₀ looks more friendly than P₁
 - Really?



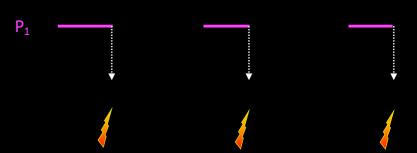
By looking at the past!

• If a process kept behaving well so far...

...it will probably do so next time we schedule it!



- P₀ looks more friendly than P₁
 - Really?
 - Can we forgive P_0 ?



Estimating duration of the next quantum

- T_n: CPU utilization observed at step n
- E_n: estimation of the CPU utilization time at step n

•
$$E_n = \alpha(T_{n-1}) + (1 - \alpha)E_{n-1}$$

Estimating duration of the next quantum

- T_n: CPU utilization observed at step n
- E_n: estimation of the CPU utilization time at step n

•
$$E_n = \alpha(T_{n-1}) + (1 - \alpha)E_{n-1}$$

- $\alpha = 0$
 - Fixed, a priori estimation
- $\alpha = 1$
 - · We only look at the last period
- $\alpha = \frac{1}{2}$
 - $E_1 = T_0$
 - $E_2 = \frac{1}{2}T_1 + \frac{1}{2}T_0$
 - $E_3 = \frac{1}{2}T_2 + \frac{1}{4}T_1 + \frac{1}{4}T_0$

From Estimation to Priority

- OK, we can predict how long each process will run next time it is scheduled
 - Which process do we choose?
- Try to maximize average happiness!
 - Think about queues at the supermarket!



From Estimation to Priority

- To maximize average happiness
 - We should minimize average waiting time
 - Schedule shortest jobs first!



From Estimation to Priority

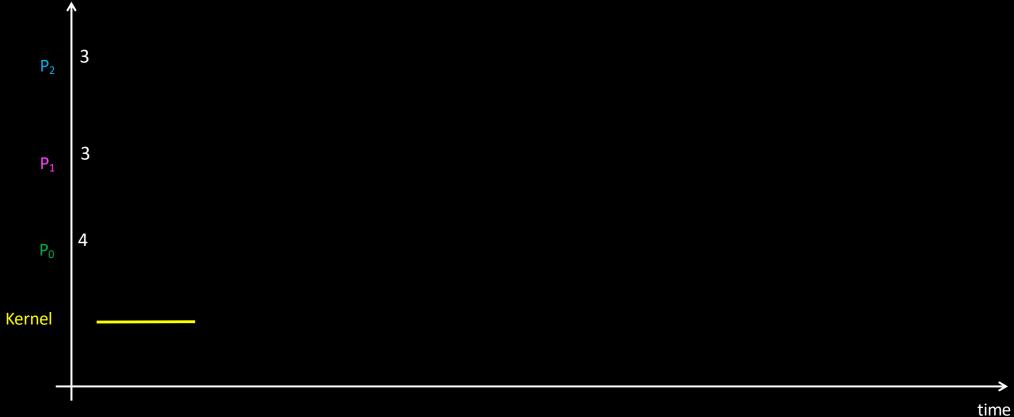
- To maximize average happiness
 - We should minimize average waiting time
 - Schedule shortest jobs first!
- Priority should be inversely proportional to E_n
 - Interactive Operating Systems schedulers try, more or less, to follow this strategy

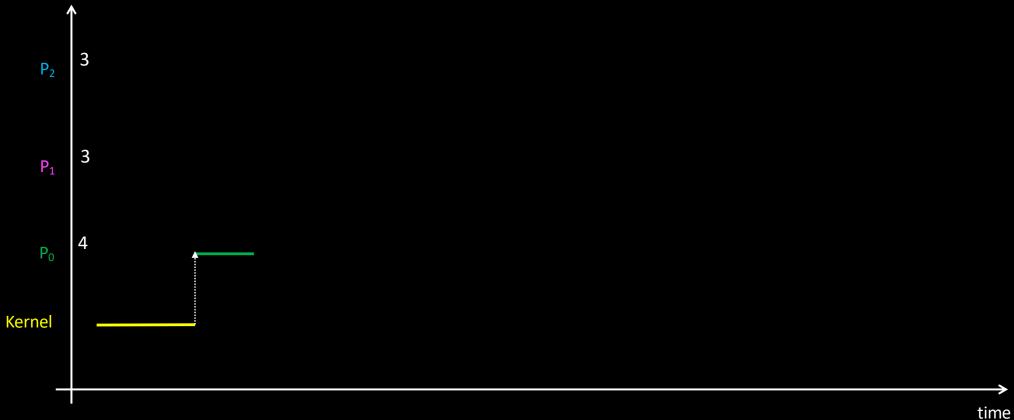


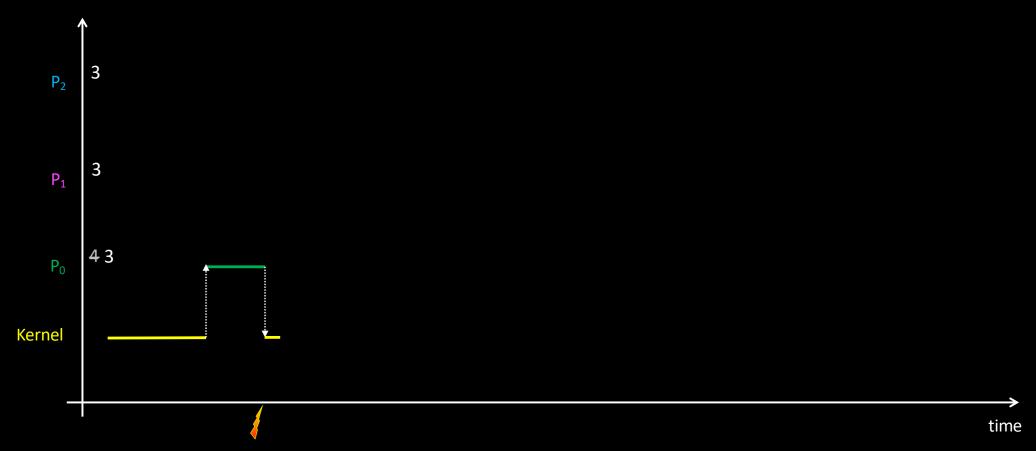
- Credits are assigned to processes, based on their fixed priority
 - Sort of "pocket money"
- To run on the CPU, a process must spend money
 - No more money = no CPU
- At some point, no more ready processes have money left
 - The kernel restarts a new epoch and redistributes credits

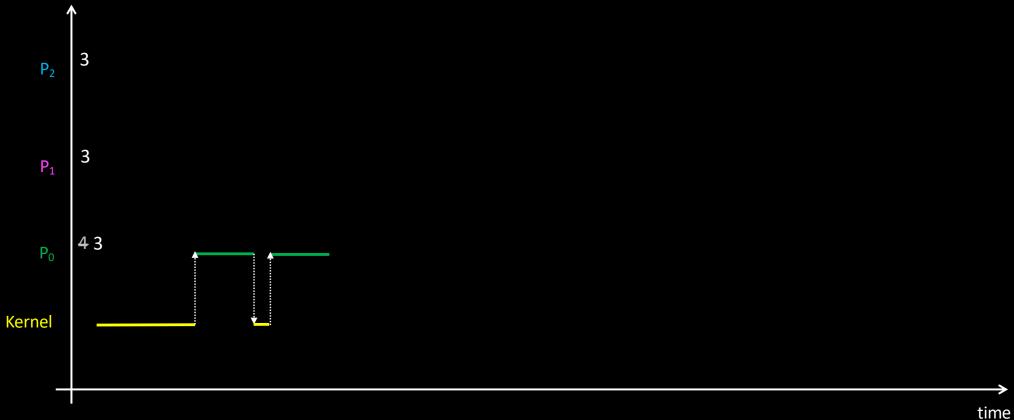
- Credits are assigned to processes, based on their fixed priority
 - Let us take a concrete, simple example with 3 processes
 - Initially:
 - P₀ has 4 credits
 - P₁ has 3 credits
 - P₂ has 3 credits

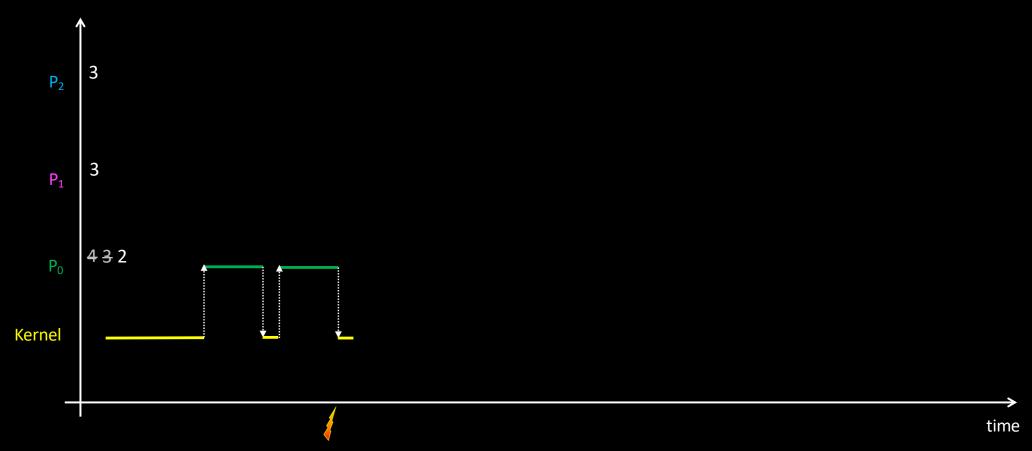
- Credits are assigned to processes, based on their fixed priority
 - Let us take a concrete, simple example with 3 processes
 - Initially:
 - P₀ has 4 credits
 - P₁ has 3 credits
 - P₂ has 3 credits
 - Rich people are usually privileged, aren't they?
 - So P₀ will be the next running process

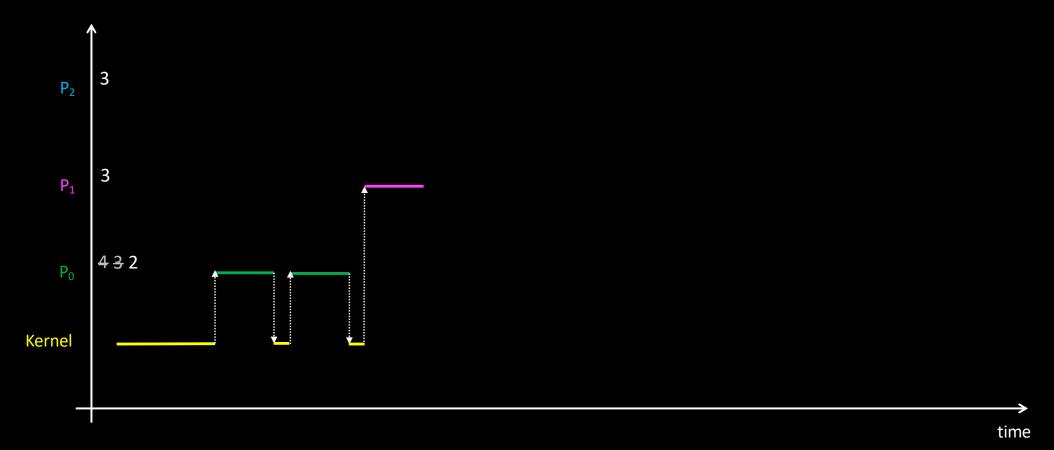


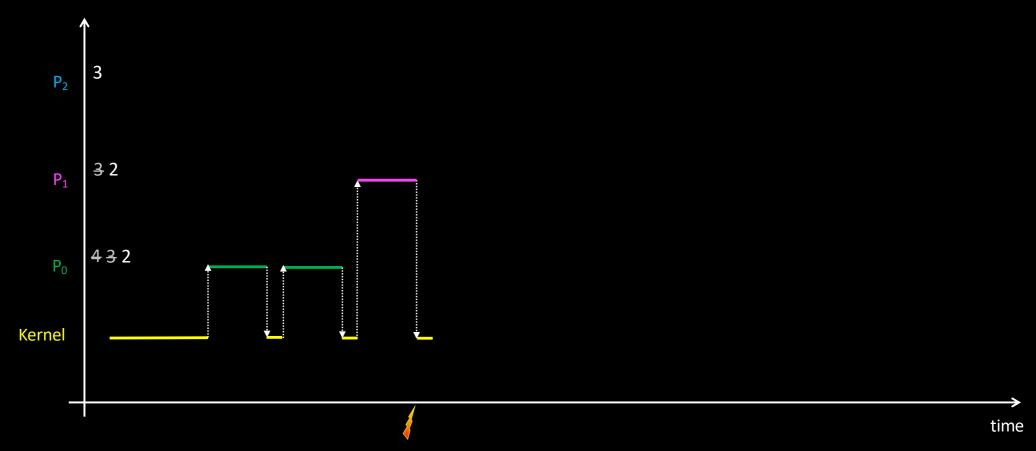


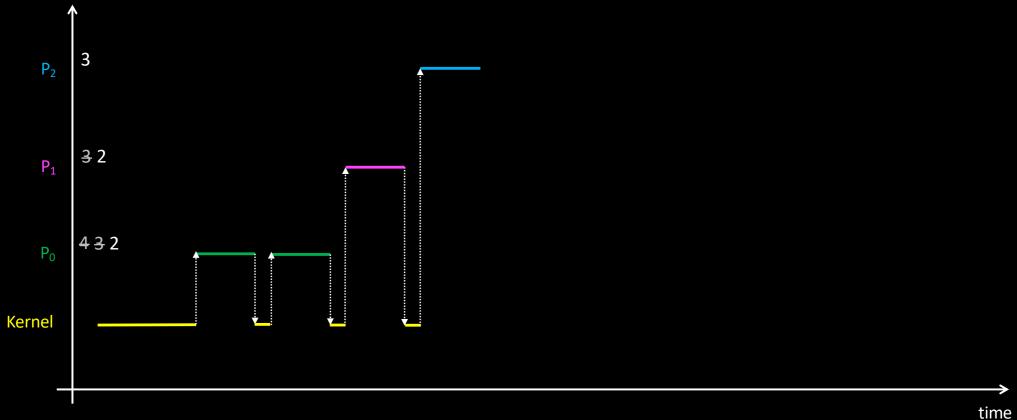


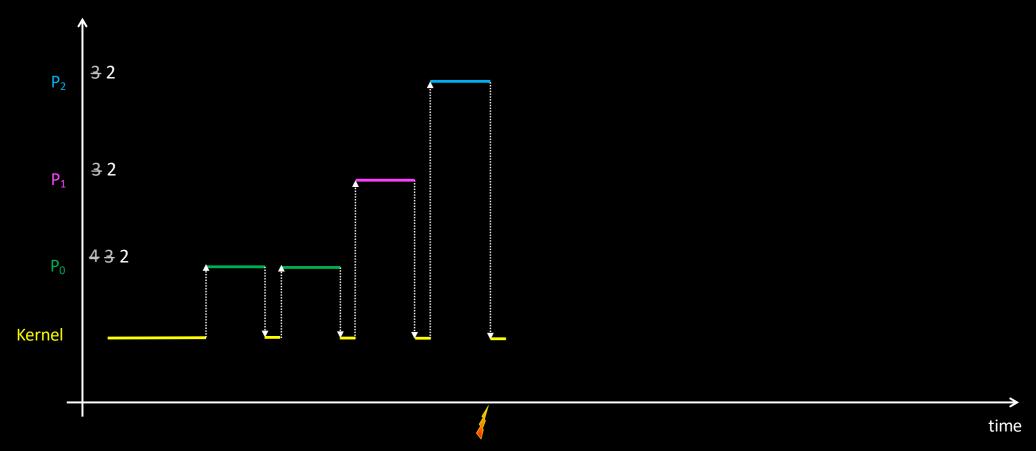


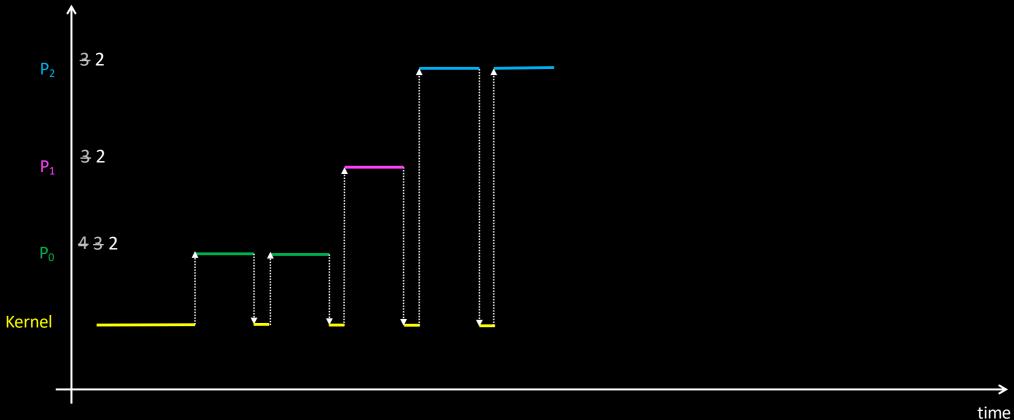


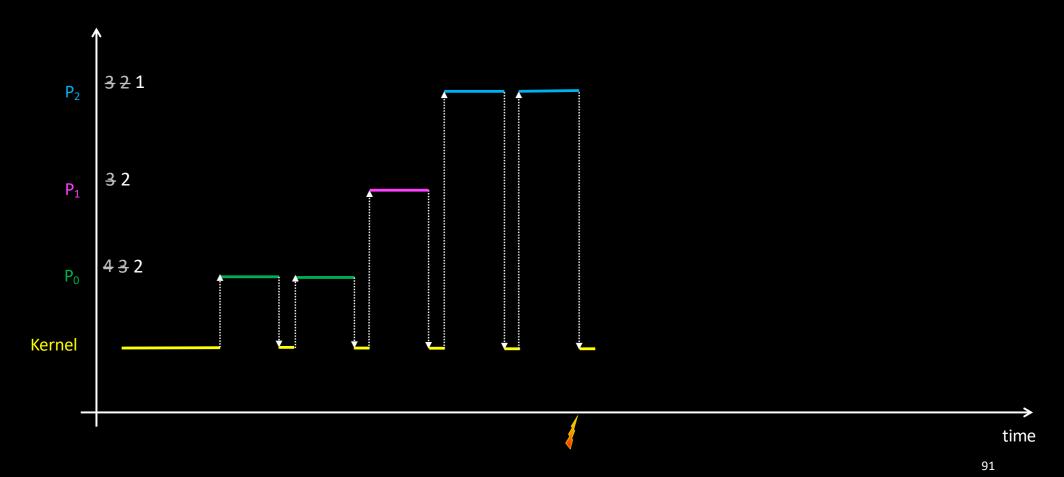


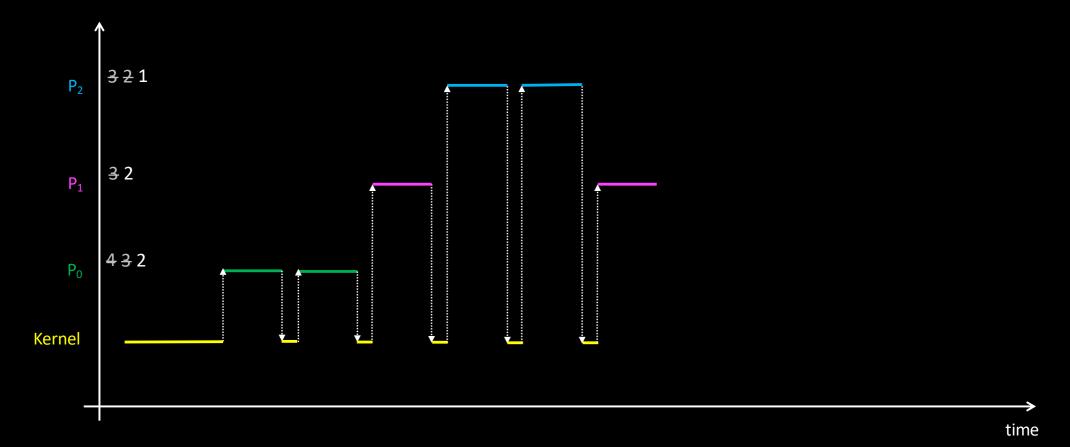


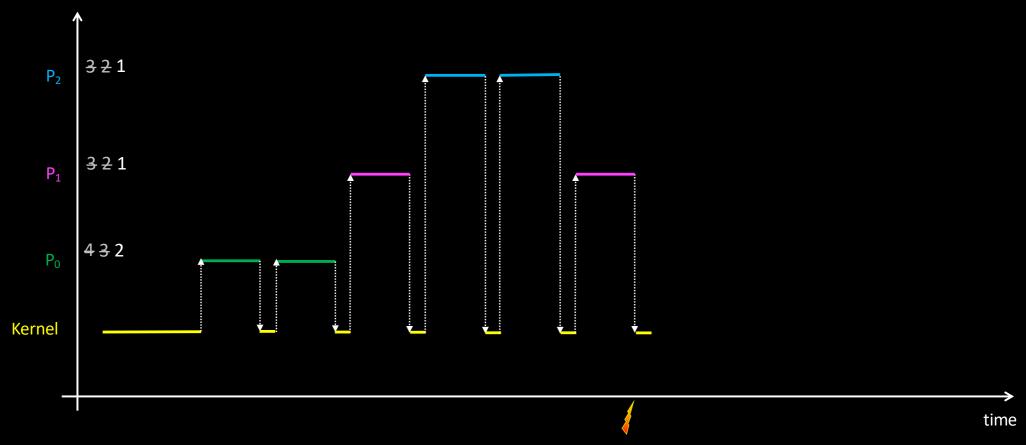


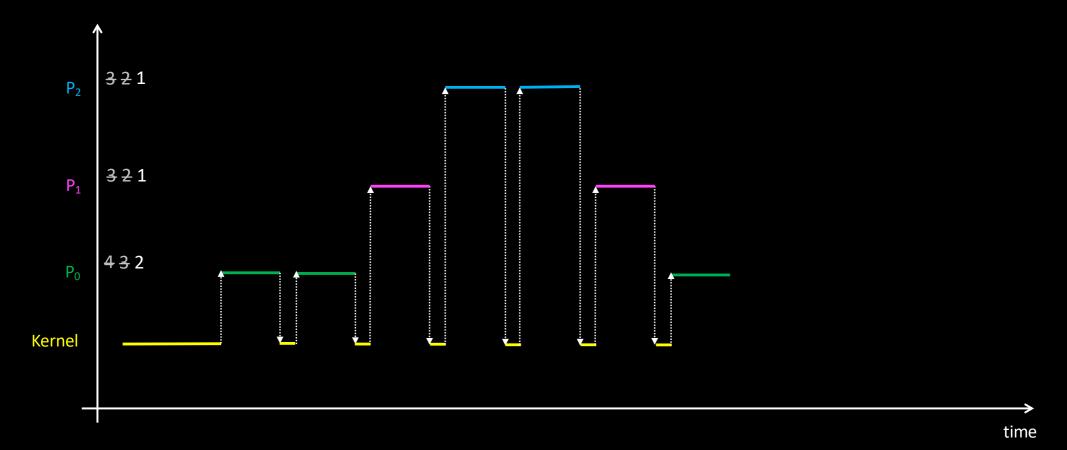


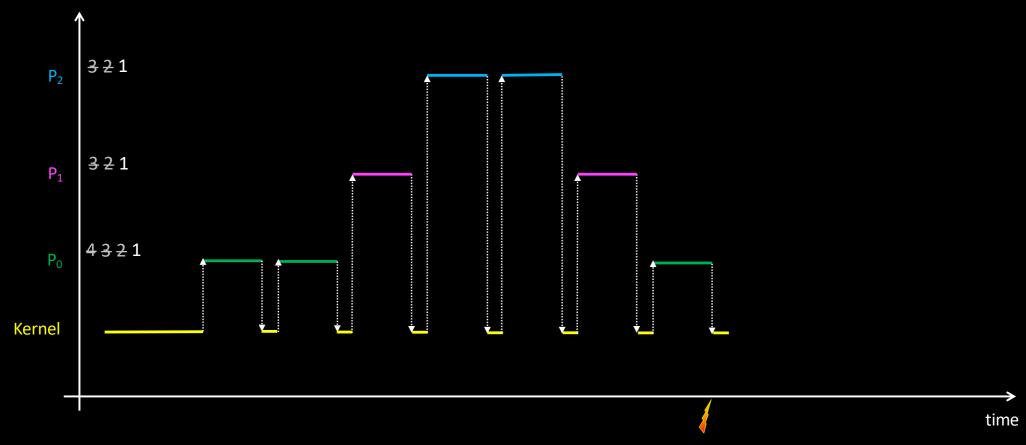


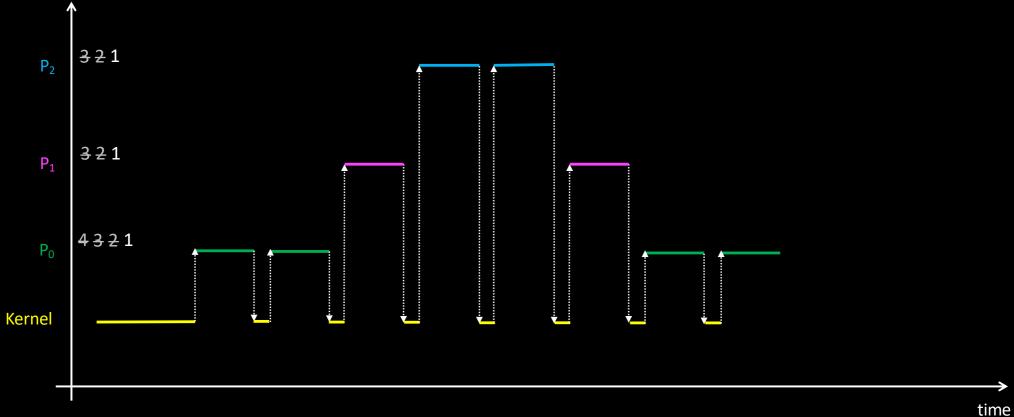


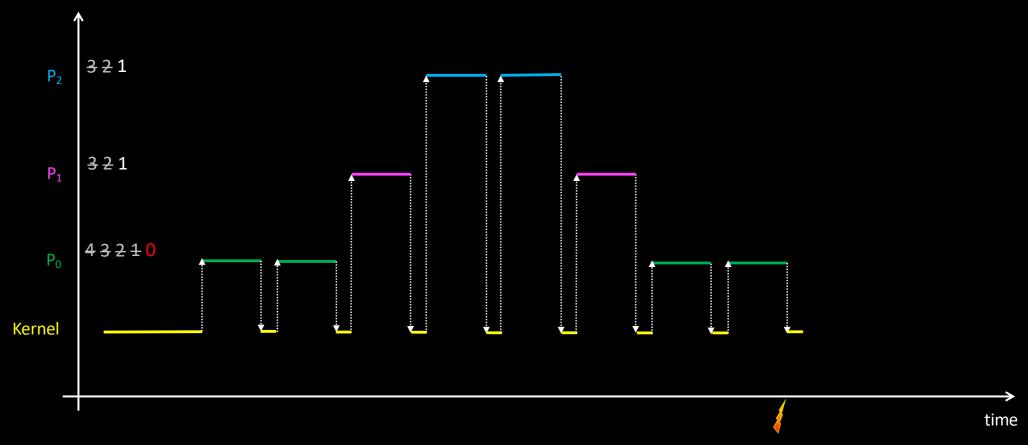


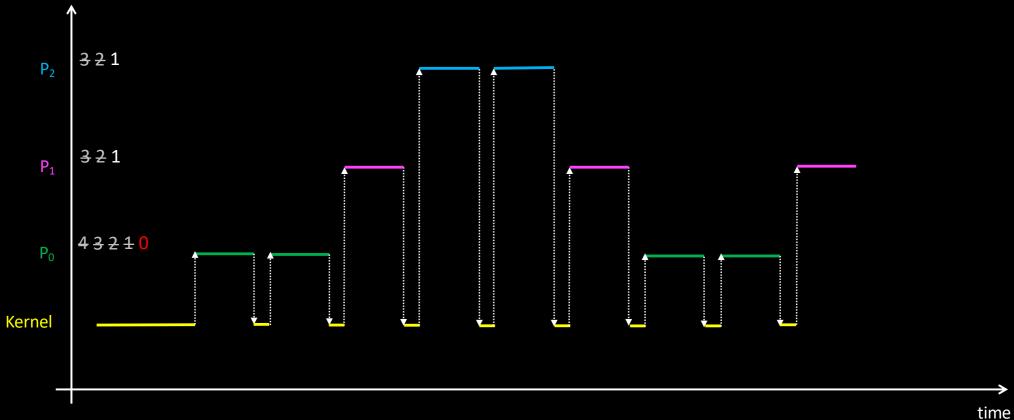


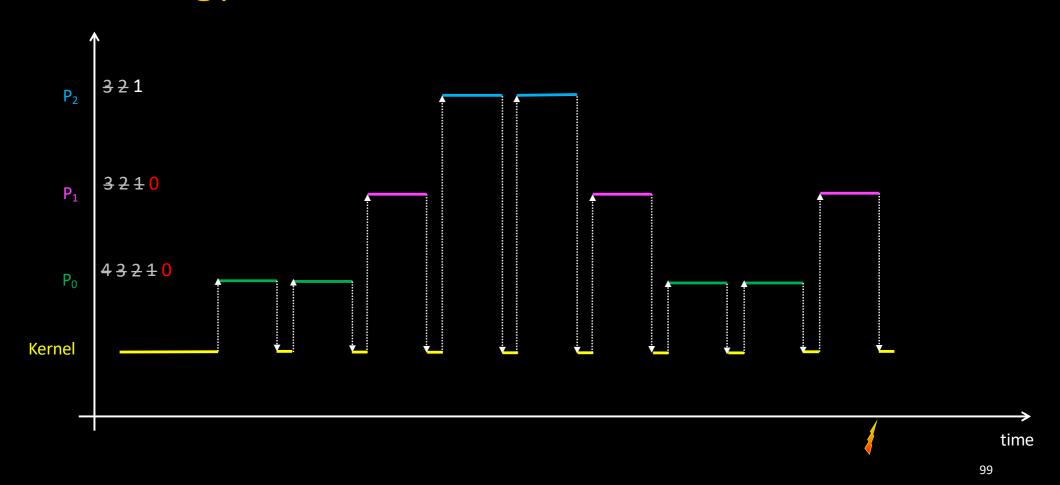


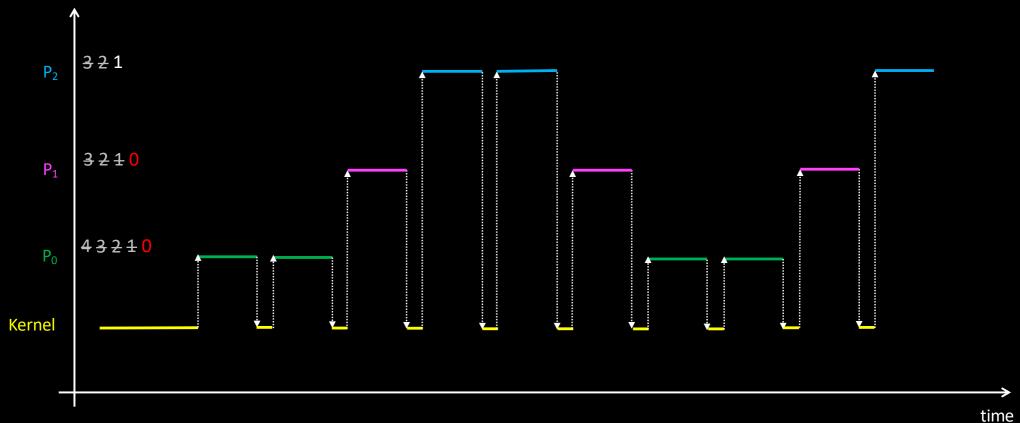


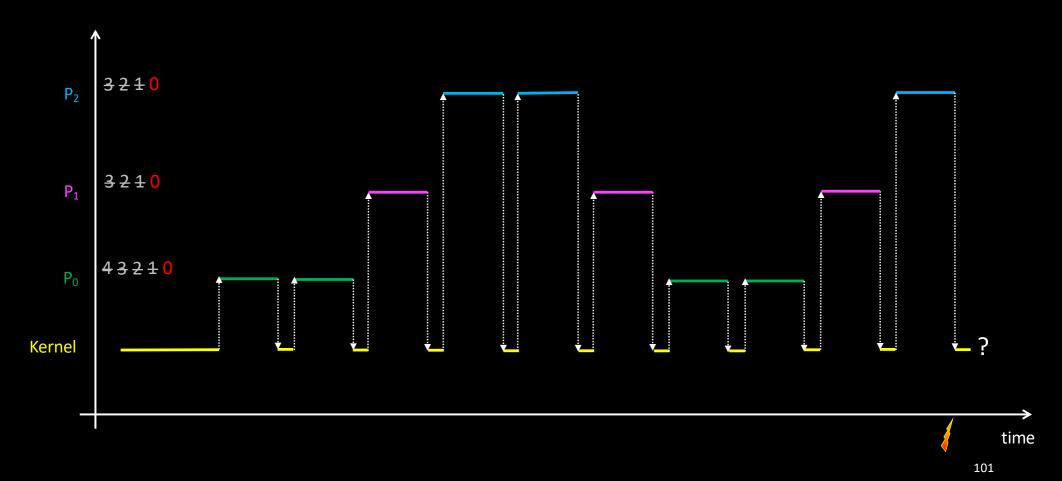


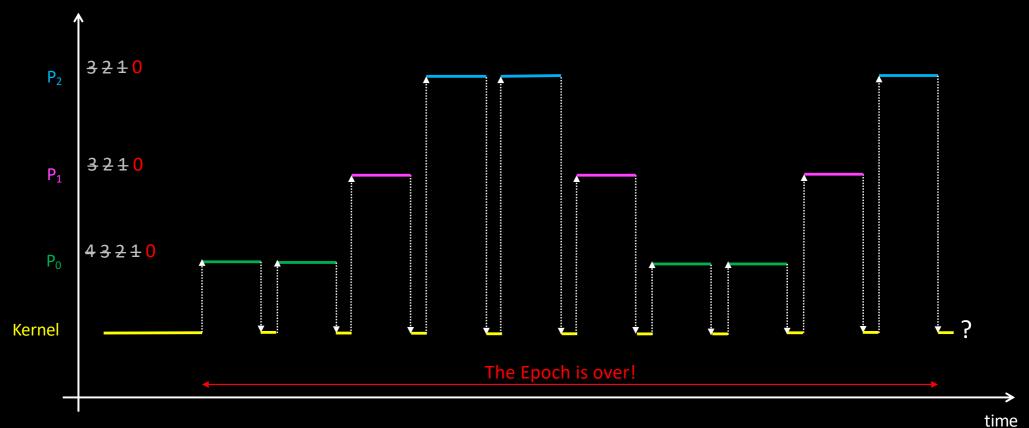












102

- When all "ready processes" are short of credits, Linux starts a new Epoch
 - Money is credited back to all processes
 - The same way you give money to your kids every month...
 - Duration of an Epoch is unknown, though

- When all "ready processes" are short of credits, Linux starts a new Epoch
 - Money is credited back to all processes
 - The same way you give money to your kids every month...
 - Duration of an Epoch is unknown, though
- Uh, wait... Really?
 - What if a process did not spend all its credits?
 - What if one of your kids is secretly saving money?

- In order to avoid infinite accumulation of credits
 - One solution is to introduce a tax!
- At the beginning of a new Epoch, each process receives
 - to_credits(priority) + remaining_credits/2
- In the worst case, a process can accumulate
 - C
 - C + C/2
 - C + C/2 + C/4
 - C + C/2 + C/4 + C/8
 - C + C/2 + C/4 + C+8 + ...
- Bounded by 2C

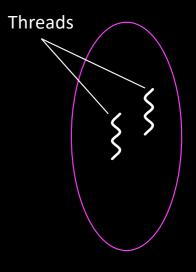
Scheduling on multicore machines

- Each core runs the scheduler asynchronously
 - Timer interrupts not necessarily synchronized
- The ready list can be
 - Shared by all cores
 - How to prevent multiple cores from choosing the same process simultaneously?
 - Distributed among cores
 - How to balance ready threads fairly? How often?
- Local scheduling decisions can require "reschedule" operations on other cores

• We're now ready to explore how this is implemented!

Processes and Threads

- Threads = Execution context
- Process = Thread + Address Space
- Several threads can share the same address space



Process featuring 2 threads

Processes and Threads

```
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>

int NBTHREADS = 1;

void *thread_func (void *arg)
{
   int me = arg;
   printf ("Hello from thread %d\n", me);
   return NULL;
}
```

```
int main (int argc, char *argv[])
{
   if (argc > 1)
     NBTHREADS = atoi (argv[1]);

pthread_t pids[NBTHREADS];

for (int i = 0; i < NBTHREADS; i++)
    pthread_create (&pids[i], NULL, thread_func, i);

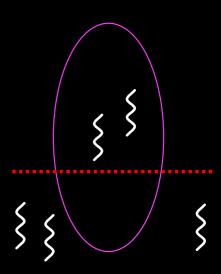
printf ("Hello from main\n");

for (int i = 0; i < NBTHREADS; i++)
    pthread_join (pids[i], NULL);

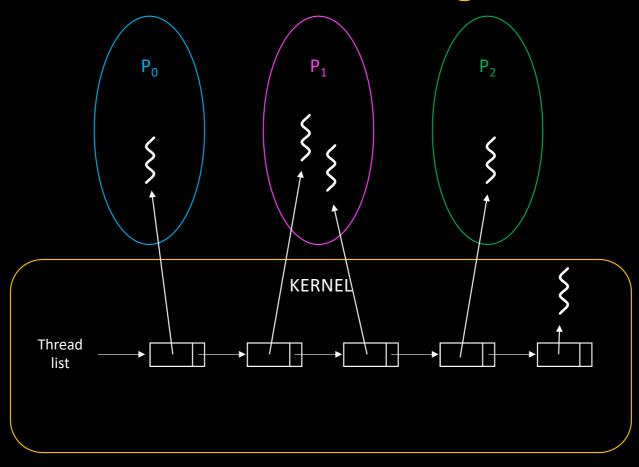
return 0;
}</pre>
```

Processes and Threads

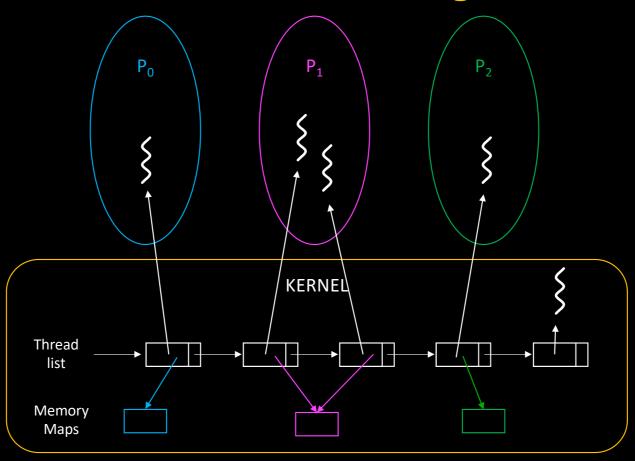
- Some (daemons) threads only run inside the kernel
- Modern kernels manage only threads



Processes and Threads: the Big Picture



Processes and Threads: the Big Picture



- Threads can access the same data simultaneously
 - May lead to undefined behavior, data corruption, ...
 - Think about
 - Linked lists, graphs, hash tables
 - Structures where several fields must be updated consistently
 - Or just integers...
- When executing kernel code, processes share data as well
 - So the kernel must enforce synchronization

for (int i = 0; i < 100; i++) for (int i = 0; i < 100; i++) n++; n++; printf ("n = $%d\n$ ", n); n = 200 ?

volatile int n = 0;

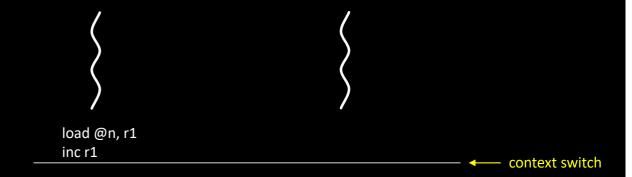
for (int i = 0; i < 100; i++) for (int i = 0; i < 100; i++) n++; n++; printf ("n = $%d\n$ ", n); $n \in [100,200]$?

volatile int n = 0;

```
load @n, r1 ; load from memory
n++ ⇔ inc r1 ; increment register
store r1, @n ; store in memory
```

n:0

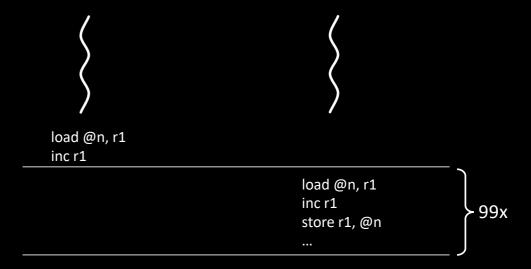
```
\begin{array}{ccc} & load \ @n, r1 & ; load \ from \ memory \\ n++ \Leftrightarrow & inc \ r1 & ; increment \ register \\ & store \ r1, \ @n & ; store \ in \ memory \end{array}
```



n:0

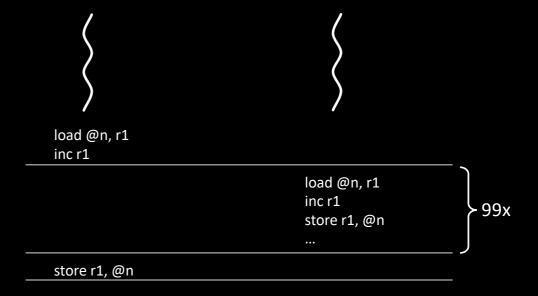
```
\begin{array}{ccc} & load @n, r1 & ; load from memory \\ n++ \Leftrightarrow & inc \ r1 & ; increment \ register \\ & store \ r1, @n & ; store \ in \ memory \end{array}
```

 $n:\theta$ 99



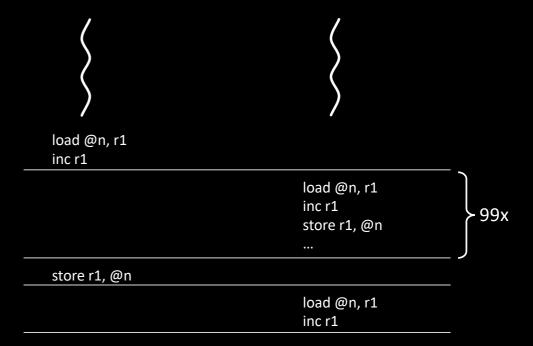
```
load @n, r1 ; load from memory
n++ ⇔ inc r1 ; increment register
store r1, @n ; store in memory
```

n: 099 1



```
load @n, r1 ; load from memory
n++ ⇔ inc r1 ; increment register
store r1, @n ; store in memory
```

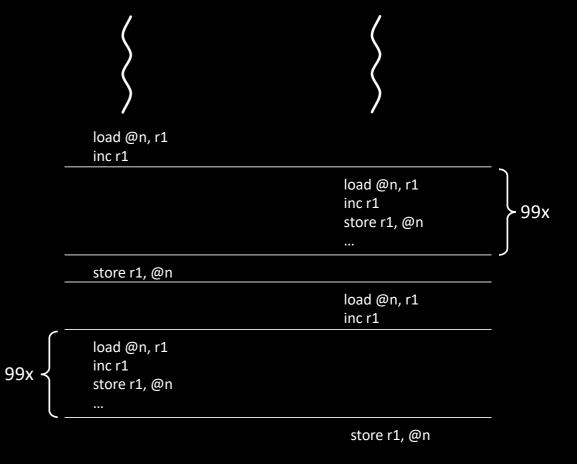
n: 099 1

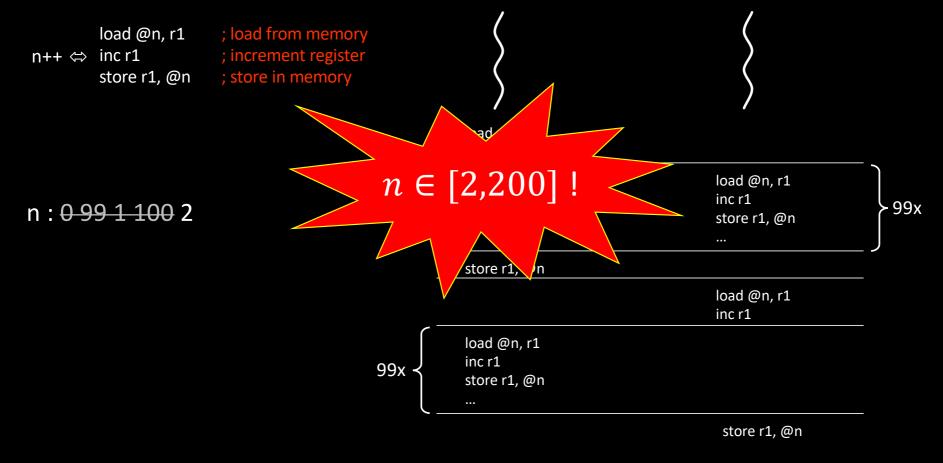


```
load @n, r1
                         ; load from memory
                         ; increment register
n++ ⇔ inc r1
         store r1, @n
                         ; store in memory
                                                          load @n, r1
                                                          inc r1
                                                                                           load @n, r1
                                                                                           inc r1
                                                                                                                  - 99x
n: 0991100
                                                                                           store r1, @n
                                                          store r1, @n
                                                                                           load @n, r1
                                                                                           inc r1
                                                          load @n, r1
                                                          inc r1
                                              99x
                                                          store r1, @n
```

```
load @n, r1 ; load from memory
n++ ⇔ inc r1 ; increment register
store r1, @n ; store in memory
```

n: 09911002





- Even the simple ++ operator is not an *atomic* operation
 - So we must prevent multiple threads to execute this operation concurrently!
- To do so, we need synchronization tools
 - This is the topic of the fascinating next chapter! ©

Additional resources available on

http://gforgeron.gitlab.io/se/