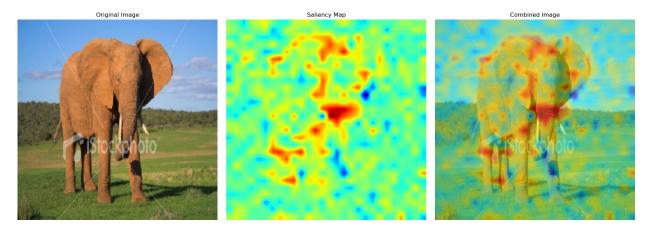
RISE

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import numpy as np
import cv2
import tensorflow as tf
import matplotlib.pyplot as plt
model builder = tf.keras.applications.resnet v2.ResNet50V2
preprocess input = tf.keras.applications.resnet v2.preprocess input
decode predictions =
tf.keras.applications.resnet v2.decode predictions
model = model builder(weights="imagenet",
classifier activation="softmax")
def generate masks randomly(m, input size, p, resolution):
    low res size = (input size[0] // resolution, input size[1] //
resolution)
    masks = np.random.binomial(1, p, size=(m,
*low res size)).astype(np.float32)
    upscaled masks = np.array([cv2.resize(mask, (input size[1],
input size[0]), interpolation=cv2.INTER LINEAR) for mask in masks])
    upscaled masks = upscaled masks[..., np.newaxis]
    return upscaled masks
def perturbed image(masks, image):
    repeated_image = np.repeat(image[np.newaxis, ...], masks.shape[0],
axis=0)
    m_images = masks * repeated image
    return m images
def local explanation(masks, mImages, classImage, model):
    size image = mImages.shape[1:3]
    saliency map = np.zeros(size image, dtype=np.float32)
    # Stack images for batch processing
    preds = model.predict(mImages)
    # Get predicted indices and top labels
    top labels = decode predictions(preds, top=3)
    # Extract scores for the target class using a vectorized approach
    scores = np.array([next((label[2] for label in top labels[i] if
label[1] == classImage), 0) for i in range(len(top labels))])
    # Calculate saliency map using vectorized operations
```

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saliency map = np.sum(masks * scores[:, np.newaxis, np.newaxis,
np.newaxis], axis=0)
    return saliency map /len(masks)
def rise saliency(image, model, target class, m=1000, p=0.5,
resolution=8):
    masks = generate masks randomly(m, image.shape, p, resolution)
    perturbed images = perturbed image(masks, image)
    saliency map = local explanation(masks, perturbed images,
target class, model)
    return saliency map
img_path = "./data/African_elephant/ILSVRC2012_val_00048781.JPEG"
image = tf.keras.preprocessing.image.load img(img path,
target size=(224, 224))
image = tf.keras.preprocessing.image.img to array(image)
image = tf.keras.applications.xception.preprocess input(image)
target class = 'African elephant'
saliency_map = rise_saliency(image, model, target_class, m=7000)
219/219 —
                   _____ 390s 2s/step
originalImage = cv2.resize(image/2 + 0.5, (224, 224))
saliency map normalized = (saliency map - np.min(saliency map)) /
(np.max(saliency map) - np.min(saliency map))
alpha = 0.5
saliency map color = cv2.applyColorMap((saliency map normalized *
255).astype(np.uint8), cv2.COLORMAP JET)
saliency_map_color = cv2.cvtColor(saliency map color,
cv2.COLOR BGR2RGB) / 255.0
combined image = (1 - alpha) * originalImage + alpha *
saliency map color
fig, (ax1, ax2, ax3) = plt.subplots(1, 3, figsize=(18, 6))
# Affichage de l'image originale
ax1.imshow(originalImage)
ax1.set title("Original Image")
ax1.axis("off")
# Affichage de la carte de saillance
ax2.imshow(saliency map normalized, cmap='jet')
ax2.set title("Saliency Map")
ax2.axis("off")
```

```
# Affichage de la combinaison de l'image originale et de la carte de
saillance
ax3.imshow(combined_image, cmap='jet')
ax3.set_title("Combined Image")
ax3.axis("off")

plt.tight_layout()
plt.show()
```



Nous pouvons observer que l'augmentation du nombre de masques entraîne une réduction des zones rouges incohérentes dans la carte de saillance. Cela peut s'expliquer par la loi des grands nombres, les fluctuations aléatoires tendent à se lisser, ce qui permet d'obtenir une carte de saillance plus stable et fiable.

De plus, il est intéressant de noter que les zones qui ressortent dans la carte de saillance correspondent principalement aux contours et aux détails significatifs de l'image. Cela m que le modèle RISE réussit à identifier des caractéristiques essentielles.