CONTINUOUS MATHEMATICS

HT 2019

PROBLEM SHEET 1

Derivatives, Taylon's Theorem, 1-dimensional optimization

1.1. If f and g are differentiable on IR and KeIN then

$$\frac{d}{dx}\left(\frac{f}{g^{k}}\right) = \frac{g\frac{df}{dx} - kf\frac{dg}{dx}}{g^{k+1}}$$

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$$\frac{d}{dx}\left(\frac{f}{g^{k}}\right) = \frac{g^{k}\frac{df}{dx} - f\frac{dg^{k}}{dx}}{g^{2k}} = \frac{g\frac{df}{dx} - kf\frac{dg}{dx}}{g^{2k}} = \frac{g\frac{df}{dx} - kf\frac{dg}{dx}}{g^{k+1}}$$

For K& We need that the codomain of g does not include o, and the result is the same. For K& Z , we need g to be positive on IR, and the result is the same.

fig: IR = IR profile trule

$$\frac{d}{dx} \left(\frac{f}{g^{k}} \right) = \frac{g^{k} \frac{df}{dx} - f \frac{dg^{k}}{dx}}{g^{2k}} = \frac{g^{k} \frac{df}{dx} - f \cdot k \cdot g^{k-1}}{g^{2k}} = \frac{g \frac{df}{dx} - k \cdot f \cdot \frac{dg}{dx}}{g^{k+1}}$$
The proof is the same, but be obtain a vector this time.

1.2. A symmetric nxn matrix, $x \neq 0 \Rightarrow A = A^{T}$ $f(x) = \frac{x^{T}Ax}{x^{T}X}$ quotient rule $x^{T}X$

$$\frac{\mathrm{d}f}{\mathrm{d}x} = \frac{(\underline{x}^{\mathsf{T}}\underline{x})(\underline{A} + \underline{A}^{\mathsf{T}})\underline{x} - (\underline{x}^{\mathsf{T}}\underline{A}\underline{x}) \cdot 2\underline{x}}{(\underline{x}^{\mathsf{T}}\underline{x})^{2}} = \frac{2(\underline{x}^{\mathsf{T}}\underline{x})\underline{A}\underline{x} - 2(\underline{x}^{\mathsf{T}}\underline{A}\underline{x})\underline{x}}{(\underline{x}^{\mathsf{T}}\underline{x})^{2}}$$

 $\frac{df}{dx} = 0 \implies x \text{ is an eigenvector of } A$

$$\frac{2\left(\underline{x}^{\mathsf{T}}\underline{x}\right)\underline{A}\underline{x}-2\left(\underline{x}^{\mathsf{T}}\underline{A}\underline{x}\right)\underline{x}}{\left(\underline{x}^{\mathsf{T}}\underline{x}\right)^{2}}=\underline{0} \Rightarrow \left(\underline{x}^{\mathsf{T}}\underline{x}\right)\underline{A}\underline{x}=\left(\underline{x}^{\mathsf{T}}\underline{A}\underline{x}\right)\underline{x} \quad | : \left(\underline{x}^{\mathsf{T}}\underline{x}\right)\neq 0$$

$$\underline{A}\underline{x}=\frac{\underline{x}^{\mathsf{T}}\underline{A}\underline{x}}{\underline{x}^{\mathsf{T}}\underline{x}}\underline{x}$$

Let $1 = \frac{x^T A \times}{x^T \times} \in |R = \sum_{i=1}^{n} A \times = A \times = \sum_{i=1}^{n} x^i = \sum_{i=1}$

x is an eigenvector of A => (3) 1 EIR such that Ax=1x

$$\frac{2\left(\underline{X}^{\mathsf{T}}\underline{X}\right)\underline{A}\underline{X}-2\left(\underline{X}^{\mathsf{T}}\underline{A}\underline{X}\right)\underline{X}}{\left(\underline{X}^{\mathsf{T}}\underline{X}\right)^{2}}=\frac{2\left(\underline{X}^{\mathsf{T}}\underline{X}\right)\lambda\underline{X}}{\left(\underline{X}^{\mathsf{T}}\underline{X}\right)^{2}}=\frac{2\lambda\left(\underline{X}^{\mathsf{T}}\underline{X}\right)\underline{X}}{\left(\underline{X}^{\mathsf{T}}\underline{X}\right)^{2}}=\frac{2\lambda\left(\underline{X}^{\mathsf{T}}\underline{X}\right)\underline{X}}{\left(\underline{X}^{\mathsf{T}}\underline{X}\right)^{2}}=\underline{0}.$$
1.

So,
$$\frac{df}{dx} = 0 \iff x \text{ is an eigenvector of } \underline{A}$$

1.3.
$$f(\underline{X}) = \max(X_i), \quad \underline{X} = (X_1 X_2 ... X_n)^T$$

$$l(\underline{X}) = l_n \left(\sum_{i=1}^n e^{X_i}\right)$$

(a)
$$\max x_i \leq l(\underline{x}) \leq \max x_{i+1} m$$

$$\max_{i} x_{i} \leq \lim_{j \neq i} \left(\sum_{j \neq i}^{n} e^{x_{i}} \right) \leq \max_{i} x_{i} + \lim_{n \to \infty} m_{i}$$

$$e^{\max x_i} \leq \sum_{j=1}^m e^{x_i}$$

$$\left(\sum_{i=1}^{N} e^{X_{i}}\right) \leq \max_{i} X_{i}$$

Let max
$$x_i = x_k$$

$$0 \le \sum_{i=1}^{k-1} e^{x_i} + \sum_{i=k+1}^{m} e^{x_i}$$

$$\frac{\sum_{i=1}^{N} e^{X_i}}{N} \leq e^{MQ_i X_i}$$

$$\sum_{j=1}^{m} e^{x_{i}} \leq m e^{mqx x_{i}}$$

Let max
$$x_i = x_k \Rightarrow e^{x_1} \le e^{x_k}$$

$$e^{x_2} \le e^{x_k}$$

$$e^{x_3} \le e^{x_k}$$

(b) As
$$e^{x_i} > 0$$
 (\forall) $x_i \in IR \Rightarrow \sum_{j=1}^{\infty} e^{x_i} > 0 \Rightarrow \lim_{j \neq 1} \left(\sum_{i=1}^{\infty} e^{x_i} \right)$ is diffurntiable
$$\frac{\partial l}{\partial x_j} = \frac{1}{\sum_{i=1}^{\infty} e^{x_i}} \cdot e^{x_j} = \frac{e^{x_j}}{\sum_{i=1}^{\infty} e^{x_i}}$$

$$\frac{\partial x_j}{\partial x_j} = \frac{1}{\sum_{i=1}^{n} e^{x_i}} \cdot e^{x_j} = \frac{e^{x_j}}{\sum_{i=1}^{n} e^{x_i}}$$

$$\frac{\partial^{2} \mathcal{L}}{\partial x_{j}^{2}} \stackrel{\text{quotient inle}}{=} \frac{e^{x_{j}} \sum_{i=1}^{m} e^{x_{i}} - e^{x_{j}} \cdot e^{x_{j}}}{\left(\sum_{j=1}^{m} e^{x_{i}}\right)^{2}} = \frac{e^{x_{j}} \left(\sum_{i=1}^{m} e^{x_{i}} - e^{x_{j}}\right)}{\left(\sum_{i=1}^{m} e^{x_{i}}\right)^{2}}$$

$$= \frac{e^{x_{j}} \left(\sum_{i=1}^{m} e^{x_{i}} - e^{x_{j}}\right)}{\left(\sum_{i=1}^{m} e^{x_{i}}\right)^{2}}$$

$$\frac{\partial^2 k}{\partial x_k \partial x_j} = \frac{-e^{x_j} e^{x_k}}{\left(\sum_{i=1}^n e^{x_i}\right)^2}$$

$$\frac{\left[\frac{1}{2},\frac{1}{4}\right]}{dx} + \frac{\left[\left(\frac{1}{2},\frac{1}{4}\right)\right]}{dx} + \frac{\left[\left(\frac{1}{2},\frac{1}{4}\right)\right]}{dx} + \frac{\left(\frac{1}{2},\frac{1}{4}\right)}{dx} + \frac{\left(\frac$$

 $H(x) = 1 - \frac{(2x-1)^2}{2 \ln 2} + \frac{(x-\frac{1}{2})^4}{24} \cdot \frac{6\xi^2 - 6\xi + 2}{\xi^3(\xi-1)^3 \ln 2}$, where $\xi \in (\frac{1}{2}, x)$

(c) There is no Taylor expansion for H(x) at x=0 because H is not differentiable there.

3.

[1.5.]
$$f: |R \rightarrow R|, f(x) = e^{x} + e^{-x}$$

(a) $\frac{df}{dx} = e^{x} - e^{-x}$
 $\frac{d^{2}f}{dx^{2}} = e^{x} + e^{-x}$

$$\frac{d^3f}{dx^3} = e^{x} - e^{-x}$$

$$\vdots$$

$$\frac{d^kf}{dx^k} = \begin{cases} e^{x} + e^{-x}, & k = e^{x} \neq 0 \\ e^{x} - e^{-x}, & k = odd \end{cases}$$

$$(4) ke IN$$

(b)
$$f(x_0) = e^{x_0} + e^{-x_0}$$

 $\frac{d^k f}{dx^k}(x_0) = \begin{cases} e^{x_0} + e^{-x_0}, & k = e^{x_0} \\ e^{x_0} - e^{-x_0}, & k = odd \end{cases}$

$$X_0 = 1 =$$

$$\frac{d^{-1}k}{dx^{-1}} = \frac{e^1 + e^{-1}}{e} = e + \frac{1}{e} = \frac{e^2 + 1}{e}, \quad k = evan$$
Toulous those $k = 0$

Taylon's theorem
$$f(x) = \frac{e^2 + 1}{e} + (x - 1) \frac{e^2 - 1}{e} + \frac{(x - 1)^2}{2!} \frac{e^2 + 1}{e} + \frac{(x - 1)^3}{3!} \frac{e^2 - 1}{e} + \dots + \frac{(x - 1)^k}{k!} (e + (-1)^k \frac{1}{e}) + \frac{(x - 1)^{k+1}}{(k+1)!} (e^{\frac{x}{2}} + \frac{(-1)^{k+1}}{e^{\frac{x}{2}}})$$

Lagrange remainder term exti(x), se(1,x

(c)
$$X \in (0,1) = X-1 \in (-1,0)$$
, $\xi \in (0,1)$

$$e^{\frac{1}{2}} \frac{(-1)^{k+1}}{e^{\frac{1}{2}}} = e^{\frac{1}{2}} \frac{(-1)^{k+1}}{e^{\frac{1}{2$$

$$e^{\frac{1}{4}} + \frac{(-1)^{k+1}}{e^{\frac{1}{4}}} = e^{\frac{1}{4}} + \frac{1}{e^{\frac{1}{4}}} \cdot e^{\frac{1}{4}} + \frac{1}{e^{\frac{1}{4}}} \cdot e^{\frac{1}{4}} = e^{\frac{1}{4}} + \frac{1}{e^{\frac{1}{4}}} \cdot e^{\frac{1}{4}} =$$

$$\frac{(x-1)^{k+1}}{(k+1)!} \in \left(-\frac{1}{(k+1)!}, 0\right)$$

$$\frac{(x-1)^{k+1}}{(k+1)!} \in \left(-\frac{1}{(k+1)!}, 0\right)$$

$$\frac{5}{6} \cdot \frac{(-1)^{k+1}}{6} = \frac{5}{6} \cdot \frac{1}{6} \cdot \left(-\frac{1}{6}\right) = -\frac{(6-\frac{1}{6})}{(k+1)!} < 6^{k+1}(x) < 0$$

$$\frac{(\frac{1}{6}-6)}{(k+1)!} < 6^{k+1}(x) < 0$$

```
(d) object hoblum {
      def main (angs: Amay [String]) =
      Yan ok=0; Van k=1
            val boundodd: Double = 3.08616127 // boundodd = e + e -1
            val bound even: Double = 2.35040239 // bounderen = e-e-1
           val precision: Double = 0.00000000000001 // precision = 10-15
           val error: Double = 0.0
           while (OK==0)
           if (K% 2 = = 0)
                     ferror = bound even
                        for (1 <- 1 to (x+1)) error = error / i // error = e-e-1
                        if (erron <= precision) OK=1
                     else { erron = boundodd
                                 for (i <-1 to (K+1)) error = error/i // error = e+e-1
                                  if (won c = precision) or = 1}
                K=K+4 }
           K=K-1
       println ("The order of the Taylor polynomial is "+x+" and the error is "+error)}
    The order of the Taylor polynomial is 17 and the error is 4.820339161456492E-16.
1.6. A, b, cell fixed, A symmetric
             f(\underline{X}) = \sin\left(\underline{X}^{T} \underline{A} \underline{X} + \underline{X}^{T} \underline{b} + c\right)
chain rule
 (a) \frac{df}{dx} \stackrel{I}{=} \cos\left(\underline{x}^{T}\underline{A}\underline{x} + \underline{x}^{T}\underline{b} + c\right) \cdot \left(2\underline{A}\underline{x} + \underline{b}\right)
   \underline{\underline{H}}(f) = \underline{\underline{J}}(\frac{df}{dx}) = \underline{J}(\cos(\underline{x}^T\underline{\underline{A}}\underline{x} + \underline{x}^T\underline{\underline{b}} + c) \cdot (2\underline{\underline{\dagger}}\underline{x} + \underline{\underline{b}})) \quad (product of scalar and vector rule)
 \underline{\underline{H}}(f) = (2\underline{\underline{h}}\underline{x} + \underline{b}) \left( -\sin\left(\underline{x}^{T}\underline{\underline{h}}\underline{x} + \underline{x}^{T}\underline{\underline{b}} + c\right) \cdot \left(2\underline{\underline{h}}\underline{x} + \underline{b}\right) \right)^{T} + \cos\left(\underline{x}^{T}\underline{\underline{h}}\underline{x} + \underline{x}^{T}\underline{\underline{b}} + c\right) \cdot \underline{\underline{J}} \left(2\underline{\underline{h}}\underline{x} + \underline{b}\right),
mpre = (5 \( \bar{\pi} \times + \bar{\pi} \) = = = (5 \( \bar{\pi} \times \) + = (\bar{\pi} \) = 5 \( \bar{\pi} \)
 (b) f_2(\underline{x}) = f(\underline{x_0}) + (\underline{x_0})^T \frac{df}{d\underline{x}} (\underline{x_0}) + \frac{1}{2} (\underline{x_0})^T \underline{H}(f)(\underline{x_0})(\underline{x_0}) + e_3 (multivariate Taylon's theorem)
 We have: (x0=9)
  f (2) = sin c
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5.

$$\frac{df}{dx}(Q) = \cos c \cdot \underline{b}$$

$$\frac{H}{H}(f)(Q) = \underline{b} \cdot ((-\sin c) \cdot \underline{b}^{T}) + 2 \cos c \cdot \underline{A}$$
Then, we obtain:
$$f_{2}(\underline{X}) = \sin c + \cos c \cdot \underline{x}^{T}\underline{b} + X^{T}(\cos c \cdot \underline{A} - \frac{\sin c}{2} \underline{b}\underline{b}^{T})\underline{x} + e_{3},$$
where e_{3} is the rumaindan term $g_{1}e_{1}d_{1}$.

$$f_{1}(x) = \sin c + \cos c \cdot \underline{x}^{T}\underline{b} + X^{T}(\cos c \cdot \underline{A} - \frac{\sin c}{2} \underline{b}\underline{b}^{T})\underline{x} + e_{3},$$
where e_{3} is the rumaindan term $g_{1}e_{1}d_{1}$.

$$f_{1}(x) = 3e_{1}x + e_{1}x, \quad f(x) = 3x^{3} - 4(a+b)x^{3} + 6abx^{2}$$

$$f'(x) = 12x^{3} - 12(a+b)x^{2} + 12abx = 12x(x-a)(x-b) \Rightarrow f'(0) = 0, \quad f'(a) = 0, \quad f'(b) = 0$$

$$f''(x) = 36x^{2} - 25(a+b)x + 12ab \Rightarrow f''(0) = 12ab$$

$$f''(x) = 36x^{2} - 25(a+b)x + 12ab \Rightarrow f''(0) = 12ab$$

$$f''(x) = 0 \Rightarrow f \text{ has a stationary point of inflexion}$$

$$f''(0) < 0 \Rightarrow 12ab > 0 \Rightarrow ab > 0$$

$$\frac{\cos a}{\cos a} : x = 0 \text{ is a local minimum}$$

$$f''(0) > 0 \Rightarrow 12ab > 0 \Rightarrow ab > 0$$

$$\frac{\cos a}{\cos a} : x = 0 \text{ is a stationary point of inflexion}$$

$$f''(0) = 0 \Rightarrow 12ab \Rightarrow 0 \Rightarrow ab \Rightarrow 0 \text{ (however for } a = b \Rightarrow 0, x = 0 \text{ is } \frac{\cos a}{3} + \frac{a}{3} + \frac{a}$$

Now, knowing the fact that x=0 is a local minimum i.e. ab >0, we want to determine the

$$f(a) = 3a^{4} - 4(a+b)a^{3} + 6aba^{2} = 3a^{4} - 4a^{4} - 4a^{3}b + 6a^{3}b = 2a^{3}b - a^{4} = a^{3}(2b-a)$$

$$f(b) = 3b^{4} - 4(a+b)b^{3} + 6abb^{2} = 3b^{4} - 4ab^{3} - 4b^{4} + 6ab^{3} = 2ab^{3} - b^{4} = b^{3}(2a-b)$$

In order for x=0 to be a global minimum, f(0) has to be smaller or egual to f(a) and f(b), which are the only ones that could be points of global minimum for f. (Supposing that (7) CEIR, C+0, C+a, C+b, with f(c) global minimum => f'(c) =0 => f'hos 4 roots, but f' is a jolymormial of degree 3, so we reach a contradiction).

We'll treat two cases here:

Case 1:
$$a,b>0$$

We need $f(a) \ge 0 \Rightarrow a^3(2b-a) \ge 0 \Rightarrow 2b-a \ge 0 \Rightarrow a \le 2b$

and $f(b) \ge 0 \Rightarrow b^3(2a-b) \ge 0 \Rightarrow 2a-b \ge 0 \Rightarrow b \le 2a$

Case z: a,b <0

We need that
$$f(a) \ge 0 \Rightarrow a^3(2b-a) \ge 0 \Rightarrow 2b-a \le 0 \Rightarrow a \ge 2b$$

and $f(b) \ge 0 \Rightarrow b^3(2a-b) \ge 0 \Rightarrow 2a-b \le 0 \Rightarrow b \ge 2a$

Therefore X=0 is a global minimum if a,b>0 and aszb, bsza or if a,bco and a>zb, b>za.

7