## QUESTION 2

```
object Partition {
       def pivot (a: Amay [int], l: int, n: int) = ...
       11 (a)
       def partition (a: Amay [int], l: int, n: int): (int, int) = {
            Van p = pivot (a, l, a)
           // Invariant i: a[l..i)  p 22 l si < j < k < n 22
a [o.. l) = a, [o.. l) ll a [n.. N) = a, [n.. N) ll a [l.. n) is a permutation of a, [l.. n)
           Van i=l; van j=l+1; van K=2
           while (jek)
           if (a(j) == p) j+=1
             else if (a(j) < p) {vont=a(i); a(i)=a(j); a(j)=t; i+=1; j+=1}
             else { van t = a(j); a(j) = a(k-1); a(k-1)=t; k-=1}
          (i,j)
     11 (6)
     def find (a: Amay [int], i: int, l: int, n: int): int = {
          van (m,n) = partition (a, l, n)
          if (i < m) neturn find (a, i, l, m) // l < i < m, so we search in the left part
          else if (i<m) neturn a (m) // m < i < m, so it's in the middle part, which is all
          else neturn find (a, i, m, n) // m = i < n, so we search in the right part
     // (c)
    def select (a: Amay [int], i: int, m: int): int = {
         return find (a, i, o, N)
```

(d) By choosing a pivot which would split the partitioned part into two or thrue equal sides (as size), the find function will run logarithmically, because at each step, we either find what we need, or we reduce the problem by half or by a third.

In the worst-care scenario, if the pivot is the smallest/biggest element of the sequence we want to partition, we end up with a linear-time "find" as we reduce the problem by 1

at each step.

(e) To get aid of the necussion, we keep track of the left and right bounds where we look after the ith smallest value of the array.

```
def findNonRec (a: Amay [int], i: int, l: int, n: int): int = {

Van (m,n) = partition (a, l, n)

Van left = l; van eight = n

while ((m>i) 1) (m <= i))

if (i<m) night = m

else left = m

van double = (0,0)

double = partition (a, left, night)

m = double.__1; m = double.__2

}

neturn a (m)

}
```