QUESTION 4

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(a)

> inits:: [a] -> [[a]]

> inits [] = [[]]

> inits (x:xs) = []: map (x:) (inits xs)

(b)

> scanl f e = map (foldl f e). inits
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=> map (fold f e). inits :: [a] -> [b] => scand :: (b->a->b)->b->[a] -> [b]

(c) The previous definition of scanl is inefficient because it requires inits first, which runs in $O(N^2)$, when $N=\text{length} \times S$, as the number of steps for an N-sized list is given by T(N)=1+N-1+T(N-1)=N+T(N-1), with T(0)=1=) $T(N)\approx\frac{N(N+1)}{2}=$, $T(N)=O(N^2)$. After this we obtain a list consisting (N+1) lists, and because we apply (foldle f e), which runs in O(N) on each of them, we again need $O(N^2)$.

What we can do is keep track of the changes that happen in e, the accumulation, and attach them to the list we will return, like a foldl. The new definition looks like this

- > scanl' :: (b-> a-> b) -> b -> [a] -> [b]
- > scanl, t e [] = [6]
- > scanl' f e (x:xs) = e: scanl' f (f ex) xs

This version of scand runs in O(N) because we only apply of N times and we keep track of the intermediate results at each step.

QUESTION: How do I make a derivation? Is what I did close to that? I've seen this type of task several times, but I think I have not fully understood the concept behind it. Can you please show me a way to solve it?

We will now suppose that the equality we want to prove holds for m from the "Natural" datatype, and we will show that it also holds for (Succ m). (f. fold Not g a) (Succ m) = = { definition of (.) } f (fold Not g a (Succe m)) = = { (**)} f (g (fold Not g a m)) = = { definition of (.)} (f.g) (fold Not g a m) = = {3} (h.f) (fold Not g a m) = = { definition of (.)} h (f (fold Nat g a m)) = = { definition of (.)} h ((f. fold Not g a) m) = = {inductive hypothesis} h (fold Nath bm) = = { **} fold Not b b (Succ m)

From I, I and II, we proved that

f. foldNat g a = foldNat h b