

Continuous Maths Sample Paper 2019

Question 1

- (a) To what numerical problems can the method of *interval bisection* be applied? Describe the method and state, without proof, its order of convergence. (5 marks)
- (b) What does it mean to say that an iterative method has *quadratic convergence*? Does quadratic convergence always mean rapid convergence? (3 marks)
- (c) Simplify the Newton iteration for finding a root of $f(x) = x^2 + ax$, where a is a positive constant. Prove that this iteration converges quadratically to zero, as long as $x_0 > 0$.
Hint: to show that the iteration converges, first prove $0 < x_{n+1} < \frac{x_n}{2}$. (4 marks)
- (d) Simplify the Newton iteration for finding a root of $f(x) = x^2 - 2px + p^2$, where p is a positive constant. Prove that this iteration converges linearly to p , for any x_0 . Why does this not contradict the standard result about quadratic convergence of Newton's method? (4 marks)
- (e) Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a convex decreasing function with a root at x^* . Prove that, no matter what the initial point x_0 , applying Newton's method to find x^* produces a sequence (x_1, \dots) where $x_i \leq x^*$ for every $i > 0$.

Hint: first use Taylor's theorem to show that, for some ξ ,

$$x_{n+1} - x^* = \frac{\frac{1}{2}(x^* - x_n)^2 \frac{d^2f}{dx^2}(\xi)}{\frac{df}{dx}(x_n)}.$$

(4 marks)

Question 2

- (a) Let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ be a continuous function. What does it mean to say that f is *convex*? What does it mean to say that f is *concave*? (2 marks)

- (b) Show that the following functions are convex. You may use standard results.

- (i) $f : \mathbb{R} \rightarrow \mathbb{R}, f(x) = e^{-x}$.
- (ii) $g : (0, \infty) \rightarrow \mathbb{R}, g(x) = e^{x - \log x}$.
- (iii) $h : \mathbb{R}^d \rightarrow \mathbb{R}, h(\mathbf{x}) = (\mathbf{x}^T \mathbf{x})^3$.

(4 marks)

Consider methods to approximate the integral

$$I = \int_a^b f(x) \, dx,$$

where f is a continuous function.

- (c) Derive the *Trapezium rule* for this integral, first for a single strip and then (the *composite Trapezium rule*) dividing the interval $[a, b]$ into n equal strips.

Prove that the composite Trapezium rule always equals or over-estimates the value of I when f is convex.

Hint: this can be done without performing a detailed error analysis, and it holds even if f is not differentiable. (5 marks)

- (d) Consider the *Midpoint rule* on a single strip $[0, 2l]$. Assuming that f has two continuous derivatives, use Taylor's theorem to prove that the error $\text{err}(M_1)[f, 0, 2l]$ satisfies

$$-\frac{1}{3}l^3 \max_{x \in [0, 2l]} \frac{d^2 f}{dx^2} \leq \text{err}(M_1)[f, 0, 2l] \leq -\frac{1}{3}l^3 \min_{x \in [0, 2l]} \frac{d^2 f}{dx^2}.$$

Use this to prove that the *composite* Midpoint rule, which divides an interval $[a, b]$ into n strips, always equals or under-estimates the value of I when f is convex. (6 marks)

- (e) Consider a *Monte Carlo* estimate for I . Quoting appropriate standard results, find the approximate probability that this gives an over-estimate of I , when the number of samples is large. (3 marks)

Question 3

Consider the equality-constrained optimization problem

$$\text{minimize } f(x, y) \text{ subject to } g(x, y) = 0,$$

where $f, g : \mathbb{R}^2 \rightarrow \mathbb{R}$ have continuous derivatives.

- (a) What is the *Lagrangian* for this problem? Explain how it is used in an attempt to find the minimum. (2 marks)
- (b) Solve the optimization problem in the case when $f(x, y) = 4x^2 + 2xy + 4y^2$ and $g(x, y) = x^2 + xy + y^2 - 3$. (4 marks)

Now consider the function $f : \mathbb{R}^d \rightarrow \mathbb{R}$ given by

$$f(\mathbf{x}) = -\mathbf{x}^T \mathbf{A} \mathbf{x} (\mathbf{x} - \mathbf{v})^T \mathbf{B} (\mathbf{x} - \mathbf{v})$$

where \mathbf{v} is some fixed nonzero vector, and \mathbf{A} and \mathbf{B} are fixed positive definite, symmetric, matrices.

- (c) Find $\frac{df}{d\mathbf{x}}$ and $\mathbf{H}(f)$, and use them to prove that f has local maxima at $\mathbf{x} = \mathbf{0}$ and $\mathbf{x} = \mathbf{v}$.
Hint: for a multivariate scalar function $p : \mathbb{R}^m \rightarrow \mathbb{R}$ and a vector function $\mathbf{q} : \mathbb{R}^m \rightarrow \mathbb{R}^n$, $\mathbf{J}(p\mathbf{q}) = \mathbf{q} \frac{dp}{d\mathbf{x}}^T + p\mathbf{J}(\mathbf{q})$. (6 marks)
- (d) Assume that f has a unique local minimum which we wish to approximate using an iterative method. How appropriate are the following methods, in the case when d is large?
 - (i) Apply Newton's root-finding method to the system of equations $\frac{df}{d\mathbf{x}} = \mathbf{0}$.
 - (ii) Apply Broyden's root-finding method to the system of equations $\frac{df}{d\mathbf{x}} = \mathbf{0}$.
 - (iii) Apply the method of gradient descent to f .
 - (iv) Apply Newton's minimization method to f .

In each case describe the rate of convergence that you might expect, and how the complexity of the iterative step depends on the dimension d . (6 marks)

- (e) Assume that we implement the chosen numerical method in double-precision arithmetic, and that f can be computed within relative error of machine epsilon. Give (without proof) approximately the best accuracy with which you could hope to find:
 - (i) The *location* of the local minimum of f , and
 - (ii) The *value* of f at this local minimum?

(2 marks)