LINEAR ALGEBRA MT2018

WEEK 7

1. Let 1 be an eigenvalue of A.

$$A(A \mu) = J^2 \mu$$

$$A^2 \mu = J^2 \mu$$

By using induction:

$$\frac{1}{1}M = A^{-1}M = \frac{1}{1}$$
 is an eigenvalue of A^{-1}

2.
$$\beta = A^T A$$

(a)
$$B = A^{T}A \Rightarrow B^{T} = (A^{T}A)^{T} = A^{T}(A^{T})^{T} = A^{T}A \Rightarrow B^{T} = B$$

Suppose 1 and u are (possibly complex) eigen values of B. We then have

Bv = 1 v and Bw = 1 w for eigenvectors v and w.

We may then write

Now, suppose I is complex. We then have

(b) Let
$$V_1, V_2, ..., V_m$$
 be the eigenvectors of B and $I_1, I_2, ..., I_n$ the corresponding eigenvalues. Then, we have $||Ax_i||^2 = (Ax_i)^T \cdot (Ax_i) = v_i^T A^T A x_i = v_i^T (A^T A) v_i = x_i^T B x_i$, i.e. $\{1, 2, ..., m\}$

Vi eigenvector => Bvi= 1ivi => ||Avi||2 = Vi 1ivi = 1i ||Vi||2 => 1i = ||Avi||2 > 0 => => 1i≥0 => all eigenvalues are mon-negative.

3. B = A'A, where A is mon-singular

(a) Then, from 2. b) we know that all eigenvalues of B are mon-negative => 1; ≥0 (+) i € 1,2,..., n]. Let's suppose there is an eigenvalue which is o. >>

=> Avi=ovi=> Avi=o=> A-Avi=o=> vi=o (but the eigenvectors are non-zero). So,

(b) We know that there exist D.P matrices such that

D = PTBP, where D = (1,12..., pTP =), P= (V, V2 ... Vn), where V, V2,..., vn are the outhogonal eigenvectors of B. => {v1, v2, ..., va} is a basis for IR".

Let VEIR"=> V = \(\subseteq \varphi_i \varphi_i.

 $\|V\|^2 = V^T \cdot V = \sum_{i=1}^{n} \alpha_i V_i^T \cdot \sum_{i=1}^{n} \alpha_i V_i = \sum_{i=1}^{n} \alpha_i^2 \left(V_i \cdot V_j = 0 \text{ for } i \neq j \right)$

 $v^{T}BV = \sum_{i=1}^{n} \alpha_{i} v_{i}^{T} \cdot \sum_{i=1}^{n} \alpha_{i} BV_{i} = \sum_{i=1}^{n} \alpha_{i} v_{i}^{T} \cdot \sum_{i=1}^{n} \alpha_{i} A_{i} V_{i} = \sum_{i=1}^{n} \alpha_{i}^{2} A_{i} \|v_{i}\|^{2}$

Now, we want to prove that:

1 min ||v||2 < yTBY < 1 max ||v||2

1 min \[\sigma \alpha_{\ill}^{2} ||\nu_{\ill}||^{2} \less \frac{1}{\ill \alpha_{\ill}^{2}} ||\nu_{\ill}||^{2} \less \max \frac{1}{\ill \alpha_{\ill}||^{2}} ||\nu_{\ill}||^{2} \less \max \frac{1}{\ill \alpha_{\ill}||^{2}} ||\nu_{\ill}||^{2} \less \frac{1}{\ill \alpha_{\ill}||^{2}} ||\nu_{\ill}||^{2} \less \frac{1}{\ill \alpha_{\ill}||^{2}} ||\nu_{\ill}||^{2} ||\nu_{\ill}| -> this is true

As Imin & li & Amax for all i e {1,2,..., m}

c) $w^T B w = \sum_{i=1}^{n} A_i \alpha_i^2 \|v_i\|^2 where <math>w = \sum_{i=1}^{n} \alpha_i V_i$ $\|w\| = \sum_{i=1}^{n} \alpha_i^2 \|V_i\|^2$ $\|w\|^2 = \sum_{i=1}^{n} \alpha_i^2 \|V_i\|^2$ $\|w\|^2 = \sum_{i=1}^{n} \alpha_i^2 \|V_i\|^2$

As Imax-1; > 0 (there can be values which one >0), therefore $\alpha_i = 0$ (*) $i \in \{1, 2, ..., m\} \setminus \{j\}$, where j is the value where j = 1 max = 1 $W = CV_{max}$, where c is a constant and V_{max} is the corresponding eigenvector for 1 max. The same thing applies for $y = dV_{min}$.

$$Av_{2} = I_{2}V_{2} \Rightarrow \begin{pmatrix} 2 & 1 & 2 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} P \\ A \\ -1 \end{pmatrix} \Rightarrow \begin{pmatrix} 2 & P + 9 + P & = -P \\ -2 \\ -1 \end{pmatrix} \Rightarrow 3P = Q \Rightarrow P = \frac{1}{3}2 \Rightarrow V_{2} = Q \begin{pmatrix} \frac{1}{3} \\ 1 \\ -1 \end{pmatrix} \Rightarrow WR$$

$$take \ V_{2} = \begin{pmatrix} \frac{1}{3} \\ 1 \\ -1 \end{pmatrix}$$

Take
$$V_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$Av_3 = \lambda_3 V_3 = \begin{pmatrix} 2 & 1 & 2 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} \frac{p}{2} \\ \frac{1}{n} \end{pmatrix} = \begin{pmatrix} \frac{2p}{2q} \\ \frac{2q}{2n} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac$$

$$V_{3} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}.$$
Then, $S = \begin{pmatrix} -3 & \frac{1}{3} & 1 \\ 1 & 1 & 0 \\ 1 & -1 & 0 \end{pmatrix}$ and $S^{-1} = \begin{pmatrix} 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & \frac{1}{2} & -\frac{1}{2} \\ 1 & \frac{1}{3} & \frac{3}{3} \end{pmatrix}$

$$D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{pmatrix}, \text{ and } D = S^{-1}AS$$

(b)
$$A = \begin{pmatrix} 1 & 1 & 0 \\ -1 & 3 & 0 \\ -1 & 4 & -1 \end{pmatrix}$$

$$det(A-1)=0 \Rightarrow det\begin{pmatrix} 1-1 & 1 & 0 \\ -1 & 3-1 & 0 \\ -1 & 4-1 & -1-1 \end{pmatrix} = (1-1)(3-1)(-1-1) + (-1-1) = 0$$

$$(-1-1)(3-3)(3-3)(-1-1) = 0$$

$$(-1)(3-31-141)=0$$

$$(1+1)(1^{2}-11+1)=0$$

$$(1+1)(1-1^{2}-11+1)=0$$

$$Av_{2} = \frac{1}{2}v_{2} = \frac{1}{2} \begin{pmatrix} 1 & 1 & 0 \\ -1 & 3 & 0 \\ -1 & 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 2p \\ 2q \\ 2n \end{pmatrix} = \frac{p+q-2p}{p+3q-2p} = \frac{1}{2} = \frac{1}{$$

=> p=9=1 => Wa only get one vector, $V_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, so me can't create I such that $D = S^{-1}AS$, where D

(c)
$$A = \begin{pmatrix} 2 & 4 & 4 \\ 4 & 2 & 4 \\ 4 & 4 & 4 \end{pmatrix}$$

$$dt (A - AI) = 0 \Rightarrow dt \begin{pmatrix} 2 & -1 & 4 & 4 \\ 4 & 2 & -A & 4 \\ 4 & 4 & 2 & -A \end{pmatrix} = 0 \Rightarrow A^{3} - 6A^{2} + 9A - 9 = 0$$

$$(A - 1)^{2}(A - 6) = 0 \Rightarrow A_{4} = A_{2} = A_{3} \Rightarrow 5$$

$$AV_{4} = A_{4}V_{4} \Rightarrow \begin{pmatrix} 2 & 1 & 1 \\ 1 & 1 & 2 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ A & 2 \end{pmatrix} = \begin{pmatrix} 2 & 2 \\ A & 3 \end{pmatrix} \Rightarrow \begin{pmatrix} 2P + 2P + 4 = P \\ P + 2P + 2P = 1 \end{pmatrix} \Rightarrow P + 2P + 2P = 0 \Rightarrow we choose two indegenses the solution of the solution$$

(c) As m goes to infinity, we have: $m \text{ odd} \Rightarrow A^m \rightarrow \frac{-1}{2} \begin{pmatrix} 1 & -1 \\ -1 & -1 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{pmatrix}$

$$\begin{array}{ccc}
\text{MeVem} & \Rightarrow & A^{\text{M}} & \rightarrow & \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{pmatrix}.$$

(d) Let 1 be the eigenvalue with the smallest modulus. v is the corresponding eigenvector. Then $1=-\frac{1}{2}=$ $M=\propto (\frac{1}{4})$

$$A^{M}_{M} = \alpha \frac{(-1)^{M}}{2} \left(\frac{\frac{1}{2^{M}} + 1}{\frac{1}{2^{M}} - 1} + \frac{\frac{1}{2^{M}} - 1}{\frac{1}{2^{M}} + 1} \right) \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \alpha \frac{(-1)^{M}}{2} \left(\frac{\frac{1}{2^{M}} + 1}{\frac{1}{2^{M}} - 1} + \frac{1}{2^{M}} + 1 \right) = \alpha \begin{pmatrix} (-1)^{M} \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} + 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} = \alpha \begin{pmatrix} (-1)^{M} \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} + 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} = \alpha \begin{pmatrix} (-1)^{M} \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} + 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} = \alpha \begin{pmatrix} (-1)^{M} \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} + 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} = \alpha \begin{pmatrix} (-1)^{M} \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} + 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} + 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} = \alpha \begin{pmatrix} (-1)^{M} \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} + 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2^{M}} - 1 \\ \frac{1}{2^{M}} - 1 \end{pmatrix} \begin{pmatrix}$$

(e)
$$\frac{dy_1}{dt} = -\frac{3}{7}y_1 + \frac{1}{7}y_2$$

 $\frac{dy_2}{dt} = \frac{1}{7}y_1 - \frac{3}{7}y_2$

Waiting this in motrix form:

$$\frac{d}{dt} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = A \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \qquad A = P D P^T$$

We may then write the system of differential equations as:

As the entries of Pare constant this may be written

$$\frac{d}{dt} (p^T y) = (DP^T) y$$

setting z= pTy, me obtain

which may be written

$$\frac{dz_1}{dt} = z_1, \quad \frac{dz_2}{dt} = z_2$$

We then have, for arbitrary constants A,B:

$$z_1 = Ae^{-\frac{1}{2}}, z_2 = Be^{-1}$$

Finally,

$$y = Pz = \frac{1}{12} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} Ae^{-\frac{1}{2}t} \\ Be^{-t} \end{pmatrix} = \begin{pmatrix} \frac{1}{12} Ae^{-\frac{t}{2}} & \frac{1}{12} Be^{-t} \\ \frac{1}{12} Ae^{-\frac{t}{2}} & \frac{1}{12} Be^{-t} \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}.$$