

here is a example, show how to set the max height.

First step, Set the max height 295mm (#define MANUAL_Z_HOME_POS 290)



```
#endif

#endif

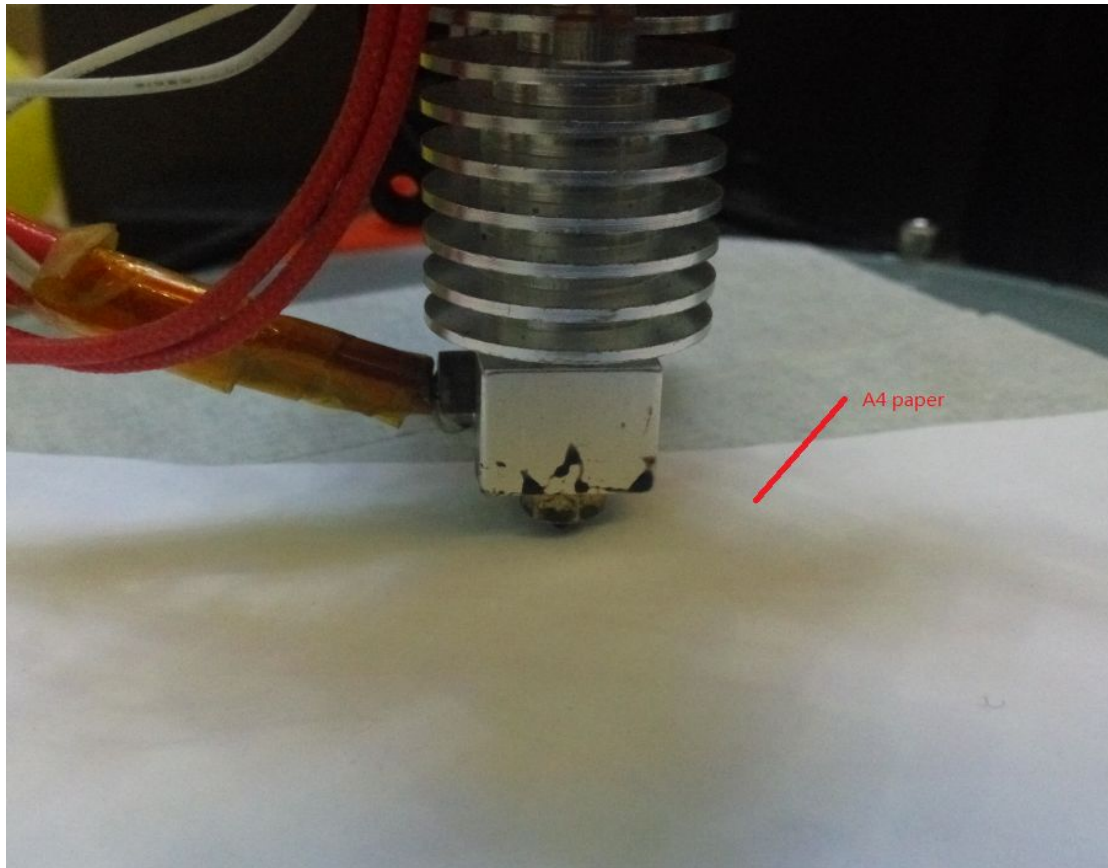
// The position of the homing switches
#define MANUAL_HOME_POSITIONS // If defined, MANUAL*_HOME_POS below will be used
#define BED_CENTER_AT_0_0 // If defined, the center of the bed is at (X=0, Y=0)

//Manual homing switch locations:
// For deltabots this means top and center of the cartesian print volume.
#define MANUAL_X_HOME_POS 0
#define MANUAL_Y_HOME_POS 0
#define MANUAL_Z_HOME_POS 295//306.6 // For delta: Distance between nozzle and print sur:
//Because there will be differences for each machine installation, need your own measurer
```

Second step,flash the firmware to motherborad.

Third step, put one pcs A4 paper on the glass, adjust the nozzle location,when the nozzle could touch the paper is ok. e.g as the pic, the nozzle could almost press the paper,and the Z coordinate show 4.48. So the max height is $295-4.48=291.52\text{mm}$.





Fourth step

Flash firmware with the height value 291.52mm, as the pic show.

```
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#define MANUAL_Z_HOME_POS 290.52//306.6 // For delta: Distance between nozzle
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//// MOVEMENT SETTINGS
#define NUM_AXIS 4 // The axis order in all axis related arrays is X, Y, Z, E
#define HOMING_FEEDRATE {60*60, 60*60, 60*60, 0} // mm/s. X, Y, Z, E
```

正在编译项目...