

# Gabriel Nascarella Hishida

I'm a computer science student passionate about computer vision, robotics and deep learning.

## CONTACT

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(take a better look at my projects)

[gabrielnhn.github.io](https://github.com/gabrielnhn)

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## EDUCATION

2019 - 2023

**BSc. Computer Science (GPA 90%)**

Universidade Federal do Paraná

2023 - 2024\*

**MSc. Informatics**

Universidade Federal do Paraná

Curitiba, Brazil

## SKILLS

Python, C/C++, SQL

OpenCV, Pytorch, Sklearn, Kivy

Robot Operating System (1, 2)

English, Portuguese

## AWARDS

**RoboCore Experience 2023 Innovation Award**

 Line Follower "Maquinaria Cerebral" - Innovati

## PRESS/MEDIA

**RoboCore Experience 2022 Highlights**

([YouTube](#), the robot with a cowboy hat)

## EXPERIENCE

**Robotics Software Developer**

**Yapira UFPR Robotics Team**

October 2019 – July 2023

- Set up ROS2 simulations using Gazebo ([video](#)) and lectured a *Robot Operating System* workshop at the [Informatics Open Week](#).
- Used image processing to power camera-based line follower robots in competitions, participating in 8 robotics competitions (see **Awards**).
- Taught the Python programming language to elementary school students from grades 7 to 9.

**Research Student**

**Laboratory of Vision, Robotics and Imaging**

May 2022 – Present

- Research on 3D Gaze Estimation; calculating where people are looking in real time by using deep learning CNN models.
- Graduation thesis: "Look where you're going: Classifying drivers' attention through 3D gaze estimation" ([PDF](#))
- Pre-print "VRI-GazeNet: 3D Gaze Estimation for Real-time Applications" ([GitHub](#))

**Software Development Intern**

**Automated Guided Vehicle Solutions**

February 2022 – May 2022

- Developed a cross-platform app using Kivy, OpenCV and BeautifulSoup to scan QRCode URLs, scrape websites and organize financial data through Google Drive API and Sheets API.