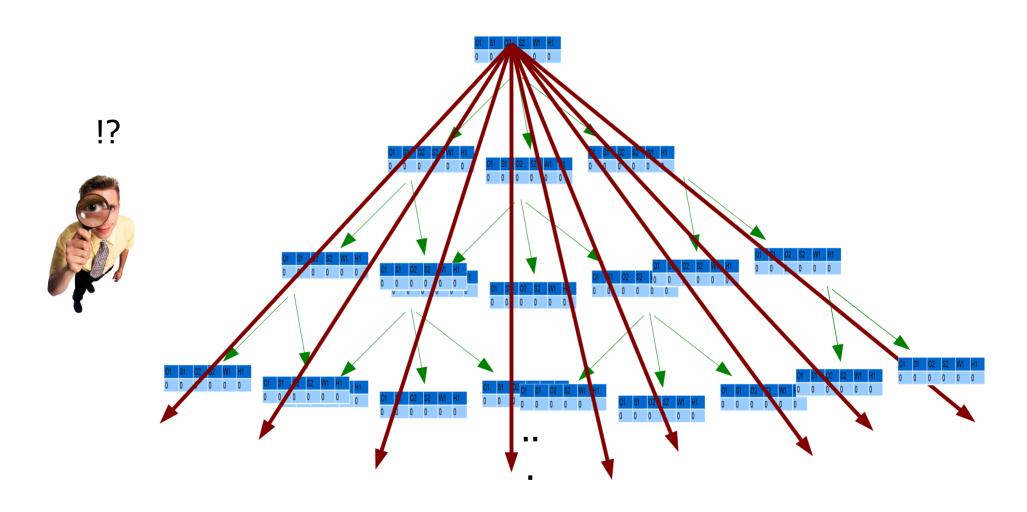
- So far, we can generate unacceptable traces:
  - Finite:
    - BuyOffer(1), SellOffer(1)
  - Infinite:
    - BuyOffer(1), SellOffer(1), BuyOffer(1), SellOffer(1), ...
      (But(1)/Sell(1) never happen)
- Back to enumerating all acceptable traces?
- Why are such traces unacceptable?

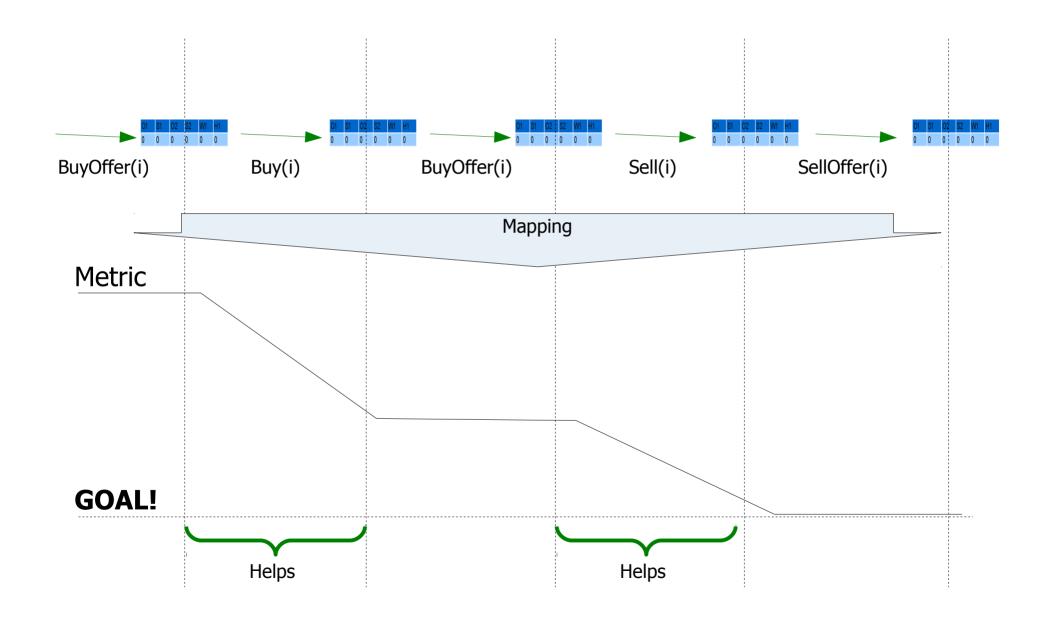
- Weak fair scheduling classes:
  - { Buy(i), for all i }
  - Sell(i), for all i }
  - Don't care about BuyOffer(i) and SellOffer(i)
- A class cannot have transitions enabled forever without ever being taken

- Does this specification meet the desired properties?
- Liveness property:
  - If there are sellers and buyers for at least k items, eventually k items are sold and bought
     (i.e. ΣO≥k and ΣW≥k then eventually ΣS≥k and ΣH≥k)
- Observation:
  - This is not a state invariant



 Again, cannot evaluate all possible traces, but...

- Define a "distance to goal" metric:
  - k-min( $\Sigma S, k$ )+k-min( $\Sigma H, k$ )
- Map each transition to the metric:
  - BuyOffer(i): don't care
  - SellOffer(i): don't care
  - Buy(i): helps, until k bought
  - Sell(i): helps, until k sold



- Until the goal is met, at least one weakly fair helper transition is enabled
  - State invariant!
- No transition makes the metric grow
  - State invariant!
- Can easily prove both...



- Unfortunately, we can still generate unacceptable traces:
  - BuyOffer(1), SellOffer(1), BuyOffer(2), Sell(1), Buy(2), ... (Buy(1) never happens)
- Back to enumerating all acceptable traces?
- Why are such traces unacceptable?

- Strong fair scheduling classes:
  - Buy(i) } for all i
  - { Sell(i) } for all i
  - Don't care about BuyOffer(i) and SellOffer(i)
- A class cannot have transitions enabled infinitely often without ever being taken

- Does this specification meet the desired properties?
- Liveness property:
  - If multiple buyers are competing, make sure no one is left behind

```
(i.e. W<sub>i</sub>≥k and eventually ΣO≥l, for any l, then eventually H<sub>i</sub>≥k)
```

- Observation:
  - This is <u>not</u> a state invariant

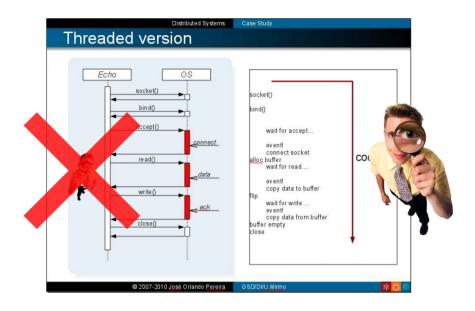
- Until the goal is met, at least one strongly fair helper transition is eventually enabled
  - Liveness property (might require additional fairness assumptions...)
- No transition makes the metric grow
  - State invariant!
- Can now prove both

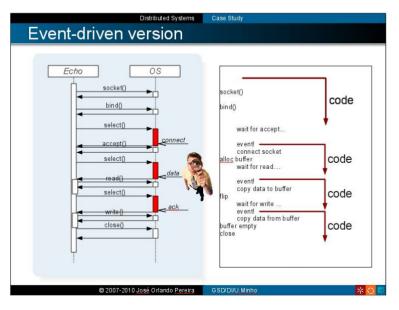


#### Conclusion

- Specification:
  - State machine
    - +
  - Fairness classes
- Can prove both safety and liveness properties:
  - Effort proportional to # of transitions!

### Consequences





- Regardless of how code is written...
  - Always think in terms of transitions
- Consider the impact of each transition in:
  - Safety properties
  - "Metric to goal" for liveness

### Consequences

- Trivially ensure weak fairness:
  - Round-robin for threads and processes
  - FIFO for mutexes/conditions
    - Use java.util.concurrent.\*
  - Iterate over all events before going back to waiting on select()

### Consequences

- Strong fairness is harder to ensure
- Usually, requires keeping explicit queues ordered by last service time