

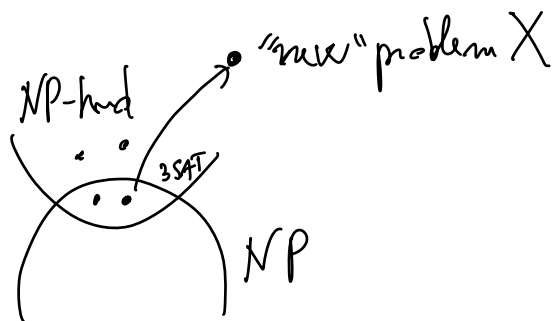
Definition : a problem A reduces in polynomial time to problem B ($A \leq_p B$) if \exists a polynomial-time algorithm that transforms an arbitrary input instance a of A into an input instance b of B such that

- 1) a is a YES instance of $A \Rightarrow b$ is a YES instance of B
- 2) b is a YES instance of $B \Rightarrow a$ is a YES instance of A

Property : $A \leq_p B$ and $B \leq_p C \Rightarrow A \leq_p C$

NP-hardness (formal definition) : a problem is NP-hard if every problem in NP reduces in poly. time to it.

Then, to prove that a problem X is NP-hard reduce a known NP-hard problem Y to X

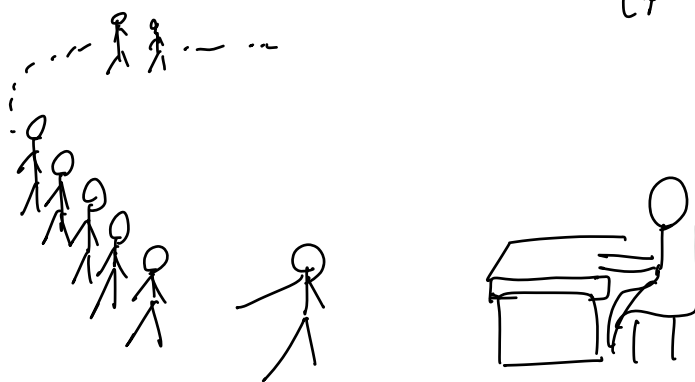


Let's emphasize: the reduction is FROM $Y \rightarrow$ I already know it's NP-hard
To $X \rightarrow$ the "new" problem

rookie mistake: do a reduction in the wrong direction

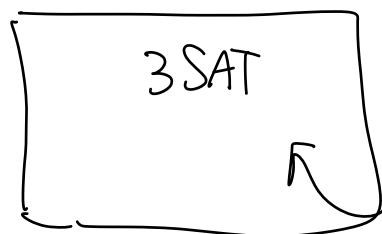
Again, NP-hardness doesn't mean the problem is not in P, but it does provide strong evidence for that:

(from Garey & Johnson)



"I can't find an efficient algorithm, but neither can all these famous people."

Library of NP-hard problems



Karp '72

21 NP-hard problems

Hamiltonian Circuit

our first NP-hardness proof:

Theorem: TSP is NP-hard

Proof: reduction from Hamiltonian Circuit to TSP
(Ham. \leq_p TSP)

but TSP is not a decision problem! No problem:

TSP: input: $G = (V, E)$ complete, undirected, weighted
 $K \in \mathbb{R}$

output: \exists in G a Hamiltonian Circuit of cost $\leq K$?

pick an arbitrary input instance for Ham.; create
the following input for TSP: $\rightarrow G = (V, E)$

$G' = (V, E')$ complete, undir., weighted

with

$$w(e \in E') = \begin{cases} 1 & \text{if } e \in E \\ \infty & \text{otherwise} \end{cases}$$

$$K = n$$

this red. takes poly-time ($O(n^2)$)

Then

- 1) if G has a Ham. circuit, then the TSP algorithm run on G' returns a Ham. circuit of cost n

2) if G doesn't have a Ham. circuit, then any Ham. circuit in G' must have > 1 edge not in G , hence of weight ∞ . Hence in this case a TSP alg. run on G' returns a Ham. circuit of cost $> n$

More problems:

Independent Set: given a graph $G = (V, E)$, an ind. set in G is a subset $I \subseteq V$ with no edges between them.

Maximum Independent Set: compute an ind. set of maximum size

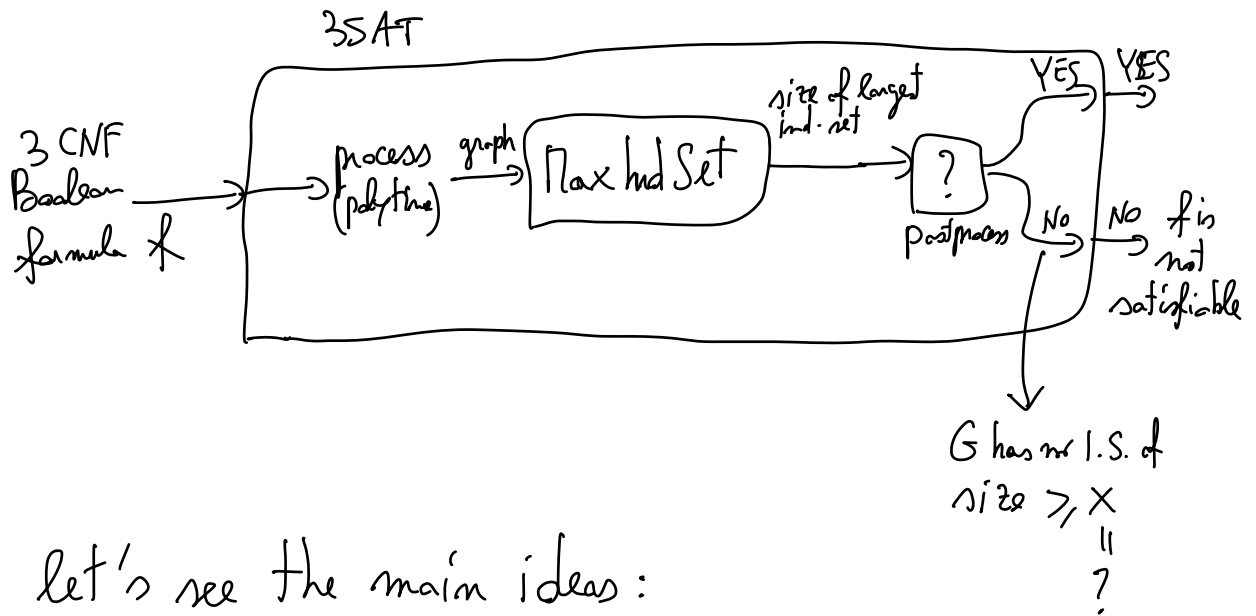
Theorem: Maximum Ind. Set is NP-hard

Proof: reduction from 3SAT to Max. Ind. Set
they seem totally unrelated problems

↓
logic

↓
graphs

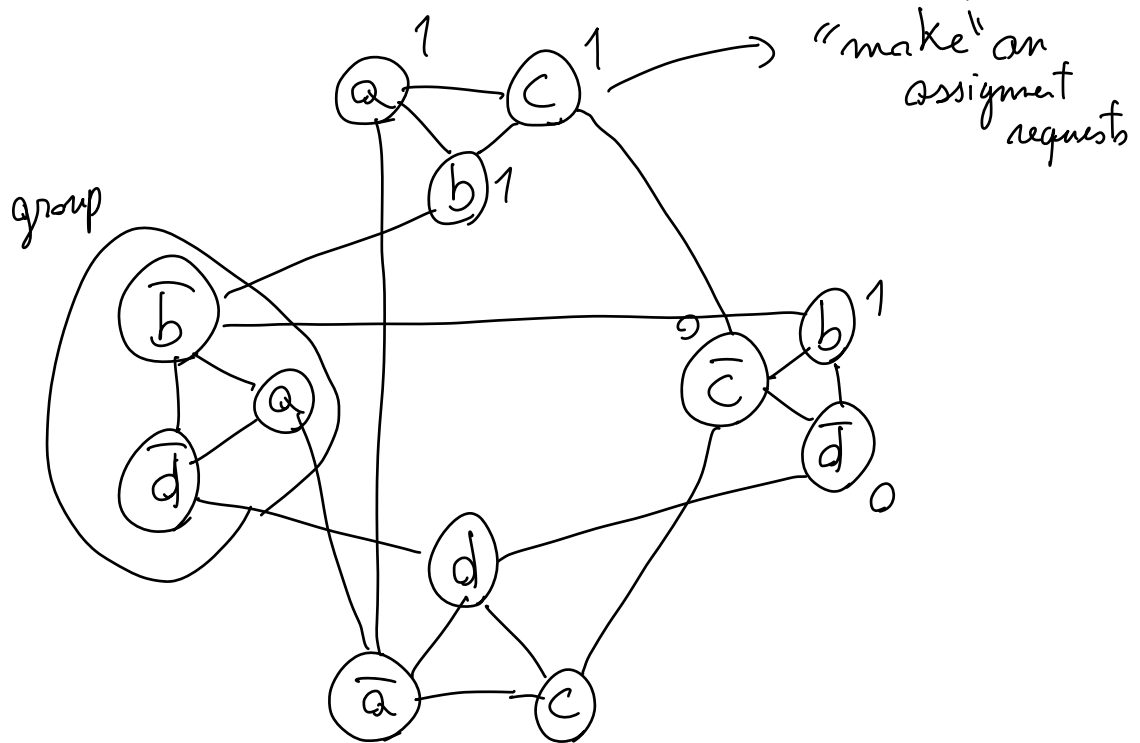
let's see what we have to do:



- pick an arbitrary 3 CNF Boolean formula f with k clauses

$$(a \vee b \vee c) \wedge (b \vee \bar{c} \vee d) \wedge (\bar{a} \vee c \vee d) \wedge (a \vee \bar{b} \vee \bar{d})$$

- vertices: each vertex represents one literal in f



- edges:

1) idea: ind. set represents conflicts \Rightarrow add an edge between every pair of vertices making requests that are inconsistent (asking for opposite assignments to the same variable)

obs.: an ind. set with ≥ 1 vertex in each group gives a satisfying truth assignment \rightarrow should look for ind. sets of size $\geq k$ to say "YES, ϕ is satisfiable"

Issue: an ind. set now is free to recruit multiple vertices from a group, so I might output "YES, ϕ is satisfiable" even if this is not true!

\Rightarrow idea: force the recruitment of one vertex per group

2) add one edge between every pair of vertices that are in the same group.

End of the intuition

Claim: G contains an ind. set of size exactly k
 \Leftrightarrow the formula ϕ is satisfiable