

## 2nd part: Approximation Algorithms

### Preamble: NP-Hardness

In the 30s we started to understand what is or isn't effectively computable

In the 70s we started to understand what is or isn't efficiently computable

In 1965 Edmonds defined what efficient means:  
an algorithm is "efficient" if its running time is  $O(n^k)$  for some constant  $k$  ( $n = \text{input size}$ )

Problems for which a polynomial algorithm exists  
are called tractable  $\rightarrow$  all the algorithms seen so far

If no polynomial algorithm exists the problem is  
said intractable

Examples:

1) Eulerian Circuit Problem: given an undirected graph, an Eulerian Circuit is a cycle that traverses all the edges only once.

almost  
the  
same

This problem can be solved in linear time (exercise)

2) Hamiltonian Circuit Problem: given an undirected graph, an Hamiltonian Circuit is a cycle that traverses all the vertices only once.

To date, no one knows a polynomial algorithm to solve it!

3) Minimum Spanning Trees: given a connected, undirected graph and a function  $w: E \rightarrow \mathbb{R}$ , output a spanning tree  $T \subseteq E$  minimizing  $\sum_{e \in T} w(e)$ .

almost  
the  
same

4) Traveling Salesperson Problem<sup>(TSP)</sup>: given a complete undirected graph and a function  $w: E \rightarrow \mathbb{R}$ , output a tour (i.e. a cycle that visits every vertex exactly once)

$T \subseteq E$  minimizing  $\sum_{e \in T} w(e)$ .

To date, no one knows a polynomial algorithm to solve it!

A much easier task: given a graph and a list of vertices  $C$ , check if  $C$  is an Hamiltonian circuit

Easy to solve : class  $P$  ("polynomial time")

1), 3)  $\in P$

Easy to verify : class  $NP$  ("nondeterministic polynomial")

1), 3), 2), 4)

rookie mistake :  $NP \neq$   
not-polynomial

Decision problems :

to simplify the study of the complexity of problems, we limit our attention to the following class of problems:

decision problems: problems with a Boolean answer  $\begin{matrix} \nearrow \text{YES} \\ \searrow \text{NO} \end{matrix}$

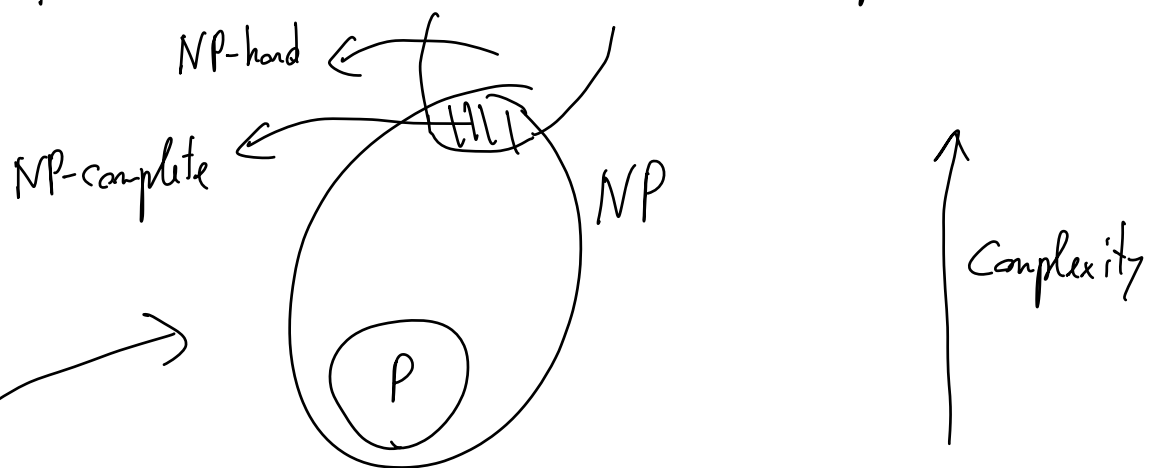
$[P]$  is the set of decision problems that can be solved in polynomial time

$[NP]$  is the set of decision problems with the following

property: if the answer is YES, then there is a  
"certificate" ← proof of this fact that can be checked in polynomial time.

CoNP essentially the opposite of NP:

property: if the answer is NO, then there is a  
proof of this fact that can be checked in polynomial time.



NP-hardness: a computational problem is NP-hard if  
(a polynomial-time algorithm for it would imply a  
polynomial-time algorithm for every problem in NP.

→ are the hardest problems in NP

A problem is NP-Complete if it is both NP-hard and in NP

→ what we think it would look like

today

the P vs NP question:  $P \stackrel{?}{=} NP$

Why study NP-hardness:

- being NP-hard is strong evidence that a problem is intractable
- it suggests you should use a  $\neq$  approach, such as
  - identify tractable special cases
  - compromise on correctness:  $\rightarrow$  approximation alg.

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Cook-Levin Theorem: 3SAT is NP-hard

$\checkmark$

SAT: formula satisfiability

input: a Boolean formula like  $(b \wedge \bar{c}) \vee (\bar{a} \wedge b)$

output: it is possible to assign Boolean values to the variables  $a, b, c, \dots$  so the entire formula evaluates to TRUE?

A special case of SAT:

3SAT: a Boolean formula is in conjunctive normal form (CNF) if it is a conjunction (AND) of several clauses, each of which is the disjunction (OR) of several literals, each of which is either a variable or its negation

example:  $(a \vee b \vee c) \wedge (b \vee \bar{c} \vee \bar{a}) \wedge (\bar{a} \vee c \vee d)$

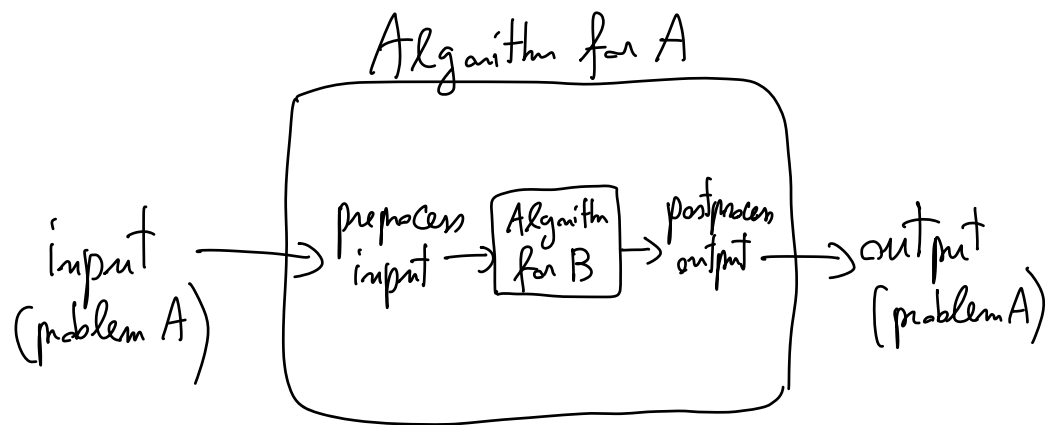
a 3-CNF formula is a CNF formula with exactly 3 literals per clause.

How to show a problem is NP-hard?

## Reductions

To prove that a problem is NP-hard we use a reduction:

Reducing problem A to problem B means describing an algorithm to solve A under the assumption that an algorithm for B exists



$A < B$

↑  
"reduces to"

B is then as hard as A