1. First CHECKED CPX CALL - Creating x variables:

2. Second CHECKED_CPX_CALL - Creating y variables:

3. CHECKED_CPX_CALL for Constraint (10) - Flow Conservation:

```
CHECKED_CPX_CALL(CPXaddrows, env, lp, 0, 1, idx.size(), &rhs, &sense,
&matbeg, &idx[0], &coef[0], NULL, NULL);
// Parameters:
// env
           - CPLEX environment pointer
                - CPLEX problem pointer
// lp
                - Number of new columns (0 as we're just adding constraints)
// 0
// 1
                - Number of new rows (1 constraint at a time)
// idx.size() - Number of nonzero coefficients in the constraint
// &rhs
              - Pointer to right hand side value (1.0 for flow
conservation)
// &sense

    Pointer to constraint sense ('E' for equality)

// &matbeg - Pointer to beginning position in the constraint matrix (0)
// &idx[0] - Pointer to array of variable indices in this constraint
// &coef[0] - Pointer to array of coefficients for those variables
```

```
// NULL - No new column names
// NULL - No new row names
```

4. CHECKED_CPX_CALL for Constraints (11)-(12) - Assignment Constraints:

```
CHECKED_CPX_CALL(CPXaddrows, env, lp, 0, 1, idx.size(), &rhs, &sense,
&matbeg, &idx[0], &coef[0], NULL, NULL);
// Parameters:
// env
              - CPLEX environment pointer
// lp
             - CPLEX problem pointer
// 0
              - Number of new columns (0 as we're just adding constraints)
// 1
             - Number of new rows (1 constraint at a time)
// idx.size() - Number of nonzero coefficients in the constraint
// &rhs - Pointer to right hand side value (1.0 for assignment
constraints)

    Pointer to constraint sense ('E' for equality)

// &sense
// &matbeg
            - Pointer to beginning position in the constraint matrix (0)
// &idx[0] - Pointer to array of y variable indices in this constraint
// &coef[0] - Pointer to array of coefficients (all 1.0)
// NULL
            - No new column names
// NULL
              - No new row names
```

5. CHECKED_CPX_CALL for Constraint (13) - Linking Constraints:

```
CHECKED_CPX_CALL(CPXaddrows, env, lp, 0, 1, idx.size(), &rhs, &sense,
&matbeg, &idx[0], &coef[0], NULL, NULL);
// Parameters:
// env

    CPLEX environment pointer

// lp
             - CPLEX problem pointer
// 0

    Number of new columns (0 as we're just adding constraints)

// 1
             - Number of new rows (1 constraint at a time)
// idx.size() - Number of nonzero coefficients (2 for each linking
constraint)
// &rhs
              - Pointer to right hand side value (0.0 for linking
constraints)
// &sense
             - Pointer to constraint sense ('L' for less than or equal)
            - Pointer to beginning position in the constraint matrix (0)
// &matbeg
// &idx[0] - Pointer to array of indices [x_ij, y_ij]
// &coef[0] - Pointer to array of coefficients [1.0, -(N-1)]
// NULL
              - No new column names
// NULL
             - No new row names
```

6. CHECKED_CPX_CALL for Writing the Problem:

```
CHECKED_CPX_CALL(CPXwriteprob, env, lp, "tsp_optimized.lp", NULL);
// Parameters:
// env - CPLEX environment pointer
```

```
// lp - CPLEX problem pointer
// "tsp_optimized.lp" - File name to write to
// NULL - File type (NULL means determine from extension)
```

7. CHECKED_CPX_CALL for Solving:

```
CHECKED_CPX_CALL(CPXmipopt, env, lp);
// Parameters:
// env - CPLEX environment pointer
// lp - CPLEX problem pointer
```

8. CHECKED_CPX_CALL for Getting Objective Value:

9. CHECKED_CPX_CALL for Getting Variable Values:

10. CHECKED CPX CALL for Writing Solution: