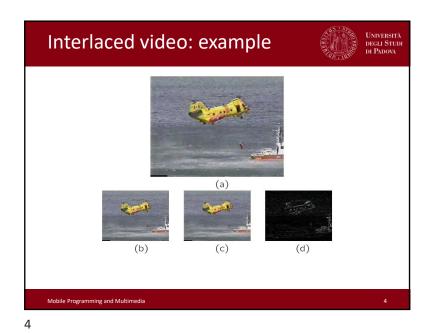


Video: fundamentals DEGLI STUDI DI PADOVA Analog video is encoded as a continuous signal that varies over time - It can be digitalized, but not further elaborated due to the bi-dimensionality of the images Digital video is a sequence of digital images - Direct access to every frame - Nonlinear video editing - Unnecessary supplementary signals (blanking, synchronization, ...)

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# Types of video signals



### Video with separated components

- Each primary signal (RGB, YUV) is transmitted as a separated signal
- It allows a better color reproduction due to the absence of interference phenomenon between signals
- Requires high bandwidth and precise synchronization between the three signals

### Composite Video

- Luminance and chrominance signals are mixed in a single carrier wave
- Interference between signals

### S-Video

 Chrominance signals are mixed in a single carrier wave, while the luminance signal is sent separately

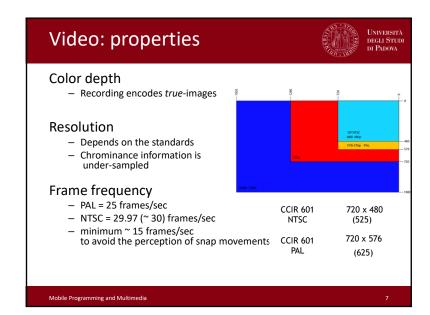
Analog video usually uses a composite signal (always for transmission)

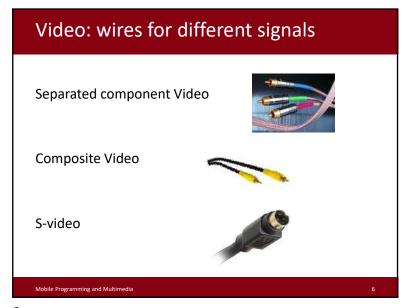
Digital video uses a signal with separated components

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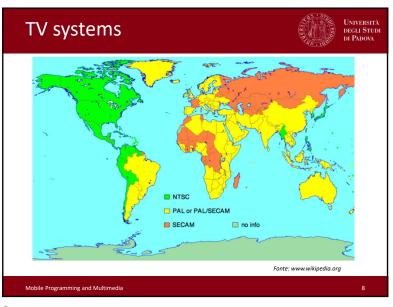
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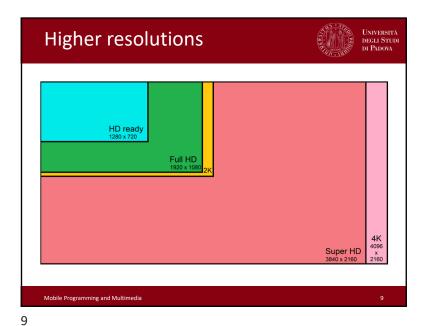




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# The uncompressed video requires a considerable amount of storage

 High Definition Television (HDTV) requires a bit-rate that can be higher than 1 Gbps

### Data must be compressed

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Video: memory usage

 1 hour of MPEG-1 video with VHS (352 x 288, 25 frames/sec) takes~600 Mbyte (a CD-ROM)

### Necessary to use lossy compression techniques

- Elimination of spatial and temporal redundancy
- intra-frame and inter-frame encoding

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# Video: transfer time



Video loading from the network has the same problems of images loading, plus ...

- A video is a temporized and continuous data
- Loading time must be compatible with reproduction time
- Playback must have a constant frame rate

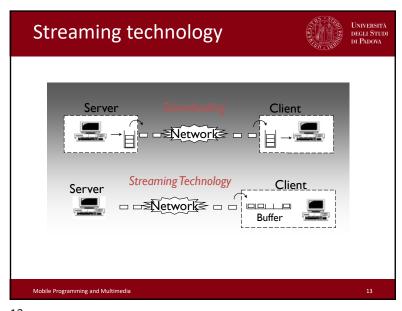
A *download* + *play* solution is not always acceptable

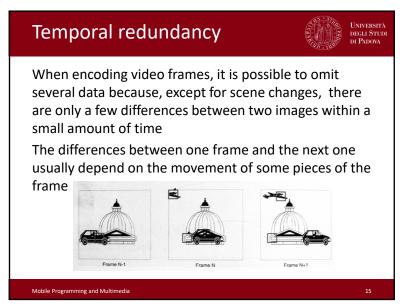
It is necessary to use *streaming* techniques (plaback while transferring data)

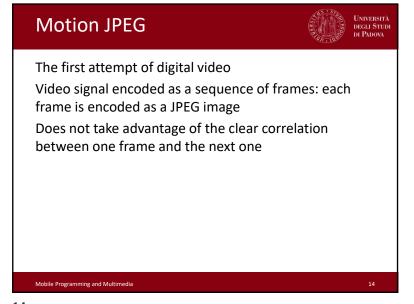
Temporization control requires advanced buffering techniques

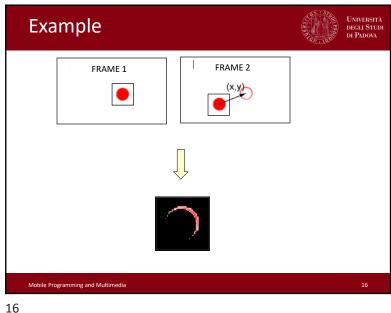
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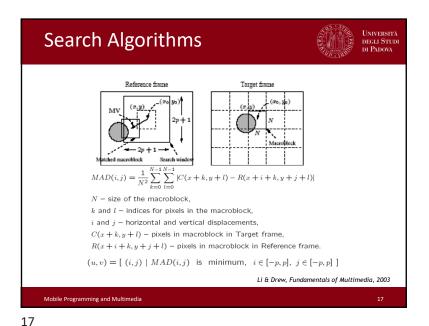
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# Hierarchical research



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The hierarchical research algorithm works using several approximation levels in which initial estimation of the motion vector can be obtained from images with low resolution

Motion Motion Motion

Li & Drew Fundamentals of Multimedia, 2003

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# Sequential Search (Full Search)



The Sequential Search algorithm explores the whole space  $(2p+1) \times (2p+1)$  to find a macroblock similar (minimum MAD) to the considered macroblock

- The target macroblock is compared, bit by bit, with a macroblock centered in every possible position of the research space, and the MAD is calculated
- the difference between the two positions (i.e., the movement) is stored in the
- the output is the difference between the target macroblock and the one with minimum MAD

Computationally very expensive:  $O(p^2N^2)$ 

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# H.261 video standard



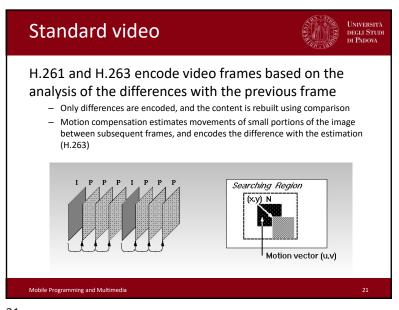
### H. 261, developed by CCITT in 1988-1990

- Developed for videoconferences and video calls using ISDN telephone lines
- Images encoded with CIF (352 x 288) and QCIF (176 x 144) format, 4:2:0
- bit-rate is p x 64 Kb/sec, 1 <= p <= 30</p>

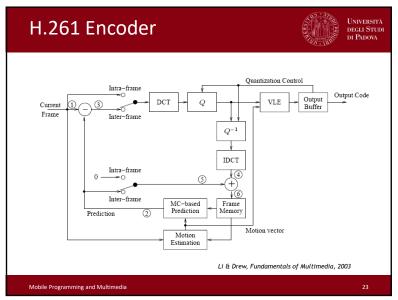
### **Encoding:**

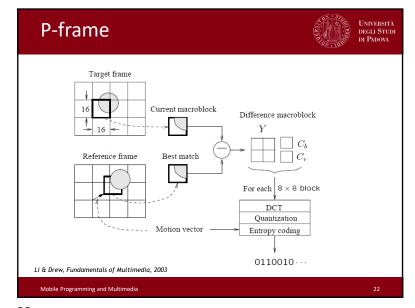
- Encoding and decoding must happen in real-time with a maximum delay of
- Input frame rate must be 29.97 fps (non-interlaced video), while output frame rate varies between 10 and 15 fps
- Color space YCbCr with chrominance components downsampled
- Two different frame types: intra-frames (*I-frames*) and inter-frames (*P-frames*)
- Intra-frames: treated as independent images, frames of the video
- Inter-frames: encoded using information from other frames

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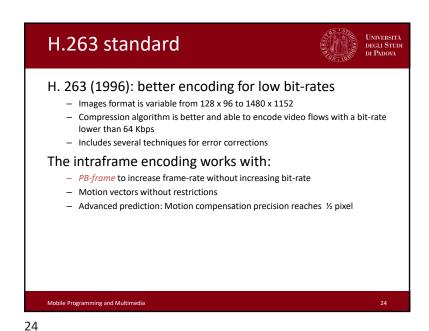


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<u>\_</u>

# **Motion vector**



Once calculated the differences between two frames, only direction and movement entity are transmitted (*motion vector*)

H.263 allows the motion vector to refer pixels outside boundaries of the image (*unrestricted motion vector mode*), associating the nearest pixel to the edges of the image, to the one pointed by the MV, external to the image

### **Integer Pixel Motion Estimation**

- Image divided into macroblock (MB) of 16x16 or 8x8
- For each macroblock, a motion vector is calculated, looking for the most similar MB in the previous frame
- Research takes place in the neighborhood of the original position, moving horizontally and vertically for ± 15 pixels, one pixel per time

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## MPEG, Motion Picture Expert Group (2)

Different resolutions and refresh frequencies allowed (from 23.98 fps to 60 fps)

The video information has:

- Spatial redundancy → encoding of each single image
  - JPEG encoding
- Temporal redundancy → relation between following frames
  - · Diversified encoding for each frame

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# MPEG, Motion Picture Expert Group (1)

The first MPEG version was released in 1991, and allows compression of a sequence of images and storage on a CD It allows random video access and fast searches

The compression algorithm is highly complex but strongly asymmetric: it assures a real-time decompression

As H.261 standard, MPEG video works with the YCbCr (8 bit) color space, with down sampled chrominance components Luminance resolution cannot be higher than 768x576 pixels It does not support interlaced video

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# MPEG Compression algorithm



MPEG expands H.261 and H.263 compression algorithms with a more sophisticated scheme of motion estimation

- I frames (Intra coded frame) are encoded using a JPEG algorithm, independently but with lower quality
- P frames (*Predictive coded frame*) are encoded based on an estimation referred to the previous I or P frame
- B frames (Bidirectionally predictive coded frame) are encoded using two
  motion estimations related to previous and following frames (bidirectional
  estimation)

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# MPEG frames (1)



### The Intracoded frames

- Require higher memory space
- stop errors propagation due to transmission
- Make random access possible

### The *Predictive coded frames*

- Differences calculation is based on the absolute value of luminance components
- "Smaller" but propagate transmission error

### The Bidirectional predictive coded frames

- The most complex

More I-frames allow random access in more time points, but increase bit-rate

- IBBPBBPBBIBBPBBPBB...
- There must be one I-frame every 15 frames

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# Motion Compensation Prediction (1)

### Three phases

- Motion estimation of objects and motion vector creation
- Frames estimation using information collected in the previous phase
- Comparison between the estimated frame and the real one to calculate the error

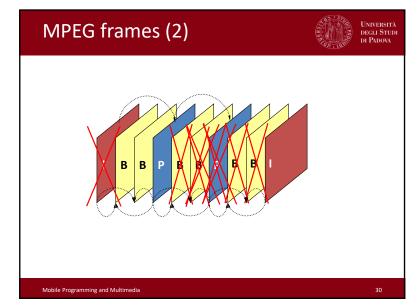
# Only the motion vector and the error estimation are saved MPEG works with a *half bit* precision:

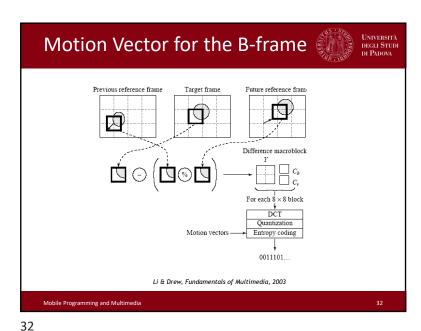
- Each 16x16 block is expanded, using interpolation, to a virtual 32x32 block
- Search of the new position of the original block inside the macroblock
- Result comes from the interpolation of the virtual 32x32 block with the moved original block
- $-\,$  Research space is  $\pm\,512$  pixels for half-pixel precision and  $\pm\,1024$  pixels for whole pixel precision

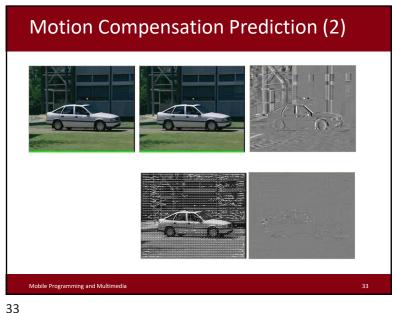
The complexity comes from the research algorithm

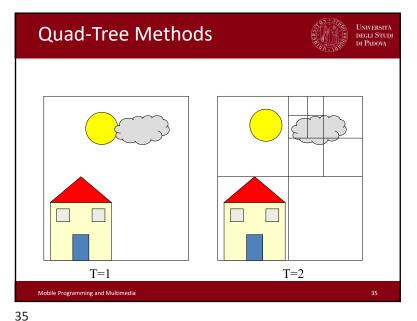
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# Size of Macroblocks



One of the main problems is the size of macroblocks to apply the motion compensation prediction algorithm

- Blocks of bigger size → low precision of prediction algorithm
- Blocks of small size  $\rightarrow$  increasing complexity of the algorithm

### Blocks with variable dimensions:

- Quad-tree methods
- Binary-tree methods
- H.26L

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# Blocks with variable sizes



### Pros

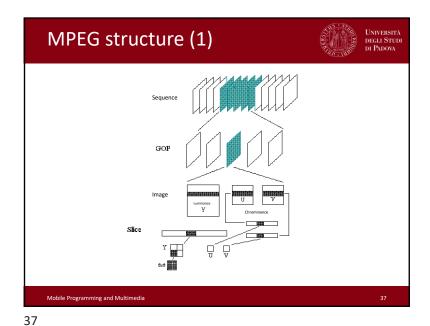
- Prediction is more accurate
- The more accurate is the prediction, the fewer differences must be encoded

### Cons

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- Computationally expensive
- The description of the delimitation of the macroblocks (called *regions*) is highly complex

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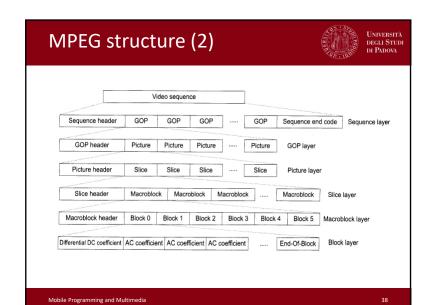


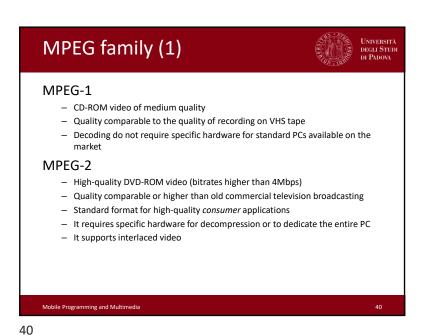
decreasing quality Applications:

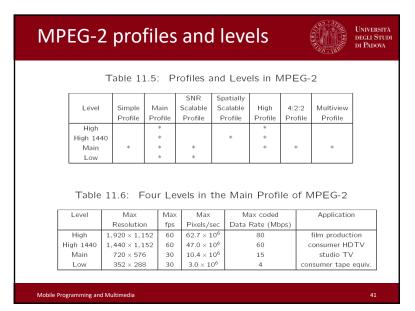
- video on cd (demo cd, museums,..)
- videogames
- Distance education (but not real-time)
- ..

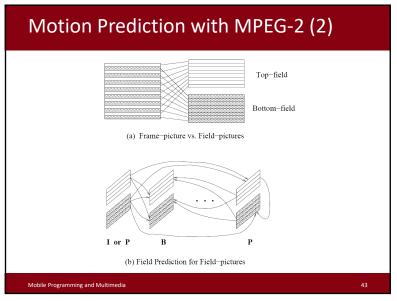
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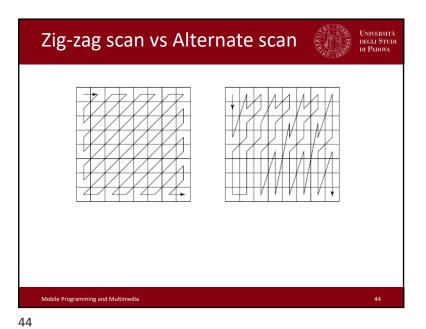
# Motion Prediction with MPEG-2 (1)

MPEG-2 supports 5 different motion prediction procedures:

- Frame prediction for frame-picture
- Field prediction for field-picture
- Field prediction for frame-picture
- 16x8 MC for field-pictures
- Dual-prime for P-pictures

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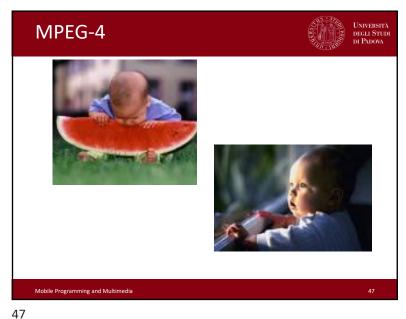
# Differences with MPEG-1

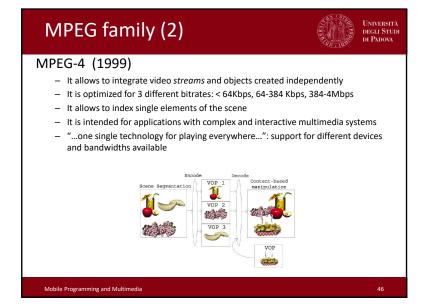


- · Improved error resistance
- Supports chromatic subsampling 4:2:2 and 4:4:4
- Non-linear quantization
- Higher flexibility of video format

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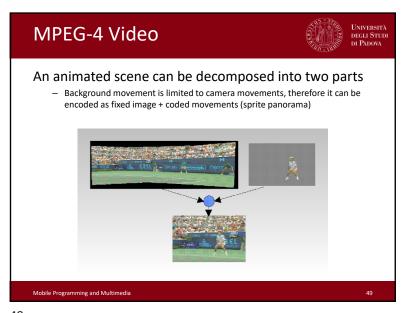
# Application examples



- Video streaming on the Internet
- Videos on smartphones
- · Content-based storage and retrieval
- Interactive DVD
- Television production
- · Remote monitoring and surveillance
- Infotainment
- Virtual meeting



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# Frame encoding vs object-oriented encoding Previous frams (a) Rock described Rock medical frams Previous frams Previous frams Neet frams Neet frams Neet frams Neet frams Neet frams Note frams Note

# Hierarchical description of a scene with MPEG-4

- 1. Video-object Sequence (VS): the complete scene; can contain both natural and synthetic objects
- 2. Video Object (VO): a particular scene object. It can have an arbitrary shape, corresponding to an object or to the background of the scene
- 3. Video Object Layer (VOL): supports scalable encoding; each VO can have several VOL (scalable encoding) or only one (non-scalable encoding)
- 4. Group of Video Object Plane (GOV): is an optional level that allows considering sequences of VOP
- 5. Video Object Plane (VOP): a snapshot of a VO in a particular moment

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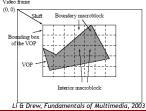
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# Motion compensation with MPEG-4

The shape of each VOP is arbitrary and must be encoded together with *texture* (using grayscales)

Each VOP is divided into 16x16 blocks, and the motion vector for the global object is calculated

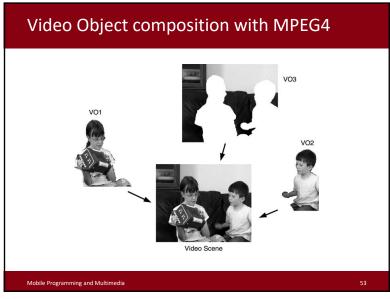
To apply the DCT (that requires squared matrixes), MC uses padding

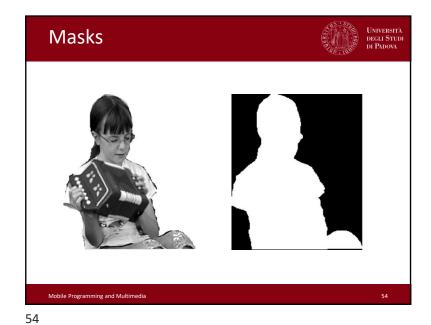


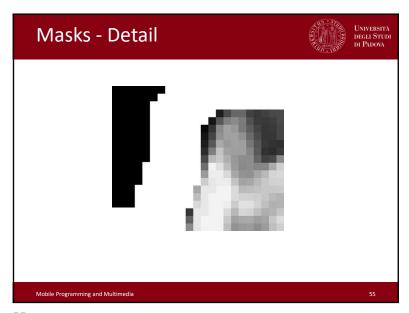
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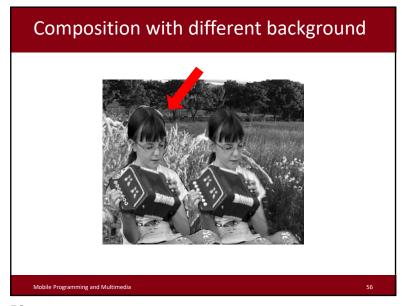
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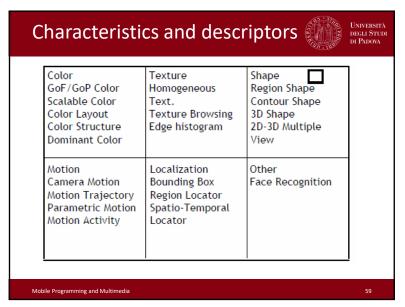






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MPEG-7

Defines how to represent a content descriptor in a standard way
Associates to objects of a multimedia application a set of descriptors to allow classification and content search
Defines generic containers for objects of different media of different standards
Combines descriptions automatically extracted from media with descriptions provided by a human user
Intended for information retrieval
Defined as standard in September 2001

Does not define how to extract content descriptions and how to use those descriptions

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