```
class B {
                                                                           class C: virtual public B {
public:
                                                                           public:
  int x;
                                                                            virtual void g() const {cout << "C::g() ";}</pre>
  B(int z=1): x(z) {}
                                                                             virtual void h() const {cout << "C::h() ";}</pre>
 virtual void f() const {cout << x << " B::f() ";}</pre>
class D: virtual public B {
                                                                           class E: public C {
public:
                                                                           public:
 virtual void f() const {cout << "D::f() ";}</pre>
                                                                            virtual void f() const {cout << "E::f() ";}</pre>
                                                                             virtual void h() const {cout << "E::h() ";}</pre>
                                                                                    - M1
                                                                                             _ 152
                                                                                &d) &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c }
class F: public E, public D {
                                                             vector<B*> v =
public:
                                                                 Fun(v);
 F(): B(3) {}
  virtual void f() const {cout << x << " F::f() ";}</pre>
  virtual void g() const {cout << "F::g() ";}</pre>
};
void Fun(const vector<B*>& v) {
  auto it1 = v.begin();
  vector<B*>::const_iterator it2;
  C* q;
  for(int i=1; it1 != v.end(); ++it1, ++i) {
   std::cout << "#" << i << " ";
                                                                         (D) F (2)
   (*it1) ->f();
it2 = it1 + 1;
                      -> 0:: F (1)
    if(it2 != v.end() && typeid(**it1) == typeid(**it2)) (*it2)->f();
    q = dynamic_cast<C*>(*it1);
    if (q) \{ \text{static\_cast} < C *> (q) -> g(); q -> h(); \}
    cout << endl;
int main() {
 B b; C c; D d; E e; F f;
  vector < B \star > v = \{ \sqrt{\&d}, \&d, 
                             &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
  Fun(v):
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```
class B {
                                                                         class C: virtual public B {
public:
                                                                         public:
  int x;
                                                                           virtual void g() const {cout << "C::g() ";}</pre>
  B(int z=1): x(z) {}
                                                                           virtual void h() const {cout << "C::h() ";}</pre>
 virtual void f() const {cout << x << " B::f() ";}</pre>
class D: virtual public B {
                                                                         class E: public C {
public:
                                                                         public:
 virtual void f() const {cout << "D::f() ";}</pre>
                                                                           virtual void f() const {cout << "E::f() ";}</pre>
                                                                           virtual void h() const {cout << "E::h() ";}</pre>
class F: public E, public D {
                                                 vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
public:
 F(): B(3) {}
  virtual void f() const {cout << x << " F::f() ";}</pre>
                                                                      1-1
                                                                             LT2
  virtual void g() const {cout << "F::g() ";}</pre>
};
void Fun(const vector<B*>& v) {
 auto it1 = v.begin();
  vector<B*>::const_iterator it2;
  C* q;
  for(int i=1; it1 != v.end(); ++it1, ++i) {
    _std::cout << "#" << i << " ";
    (*it1)->f(); - p: < -
                                                      5
    it2 = it1 + 1;
                                       \triangleright
    if(it2 != v.end() && typeid(**it1) == typeid(**it2)) (*it2)->f()
    q = dynamic_cast<C*>(*it1);
    if (q) \{ static\_cast < C *> (q) -> g(); q->h(); \}
   cout << endl;
int main() {
 B b; C c; D d; E e; F f;
  vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
 Fun(v);
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class B {
                                                                        class C: virtual public B {
                                                                        public:
public:
                                                                          virtual void g() const {cout << "C::g() ";}</pre>
 int x;
  B(int z=1): x(z) {}
                                                                           virtual void h() const {cout << "C::h() ";}</pre>
  virtual void f() const {cout << x << " B::f() ";}
class D: virtual public B {
                                                                        class E: public C {
public:
                                                                        public:
 virtual void f() const {cout << "D::f() ";}</pre>
                                                                          virtual void_f() const {cout << "E::f() ";}</pre>
                                                                           virtual void h() const {cout << "E::h() ";}</pre>
class F: public E, public D {
                                      vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
public:
 F(): B(3) {}
  virtual void f() const {cout << x << " F::f() ";}</pre>
  virtual void g() const {cout << "F::g() ";}</pre>
};
void Fun(const vector<B*>& v) {
 auto it1 = v.begin();
  vector<B*>::const_iterator it2;
  C* q;
  for(int i=1; it1 != v.end(); ++it1, ++i) {
    std::cout << "#" << i << " ";
    (*it1)->f();
                      > 6:1F -> (2)
    it2 = it1 + 1;
    if(it2 != v.end() && typeid(**it1) == typeid(**it2)) (*it2)->f();
  >q = dynamic_cast<C*>(*it1);
    if (q) \{ \text{static\_cast} < C * > (q) - > g(); q - > h(); \}
    cout << endl;
int main() {
 B b; C c; D d; E e; F f;
  vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
  Fun(v):
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```
class B {
                                                                      class C: virtual public B {
public:
                                                                      public:
                                                                        virtual void g() const {cout << "C::g() ";}</pre>
 int x;
  B(int z=1): x(z) {}
                                                                        virtual void h() const {cout << "C::h() ";}</pre>
 virtual void f() const {cout << x << " B::f() ";}
class D: virtual public B {
                                                                      class E: public C {
public:
                                                                      public:
 virtual void f() const {cout << "D::f() ";}</pre>
                                                                        virtual void f() const {cout << "E::f() ";}</pre>
                                                                        virtual void h() const {cout << "E::h() ";}</pre>
class F: public E, public D {
                                      vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
public:
 F(): B(3) {}
 virtual void f() const {cout << x << " F::f() ";}</pre>
 virtual void g() const {cout << "F::g() ";}</pre>
};
void Fun(const vector<B*>& v) {
 auto it1 = v.begin();
  vector<B*>::const_iterator it2;
 C* q;
 for(int i=1; it1 != v.end(); ++it1, ++i) {
   std::cout << "#" << i << " ";
    (*it1)->f();
                     <del>→</del> 5::F
    it2 = it1 + 1;
    if(it2 != v.end() && typeid(**it1) == typeid(**it2)) (*it2)->f(); -> \n
    q = dynamic_cast<C*>(*it1);
 if(q) {static_cast<C*>(q)->g(); q->h();}
    cout << endl;
                         C:16
                                            57. At
int main() {
 B b; C c; D d; E e; F f;
 vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
 Fun(v);
```

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```
class B {
                                                                       class C: virtual public B {
public:
                                                                       public:
                                                                         virtual void g() const {cout << "C::g() ";}</pre>
 int x;
  B(int z=1): x(z) {}
                                                                         virtual void h() const {cout << "C::h() ";}</pre>
 virtual void f() const {cout << x << " B::f() ";}
class D: virtual public B {
                                                                       class E: public C {
public:
                                                                       public:
 virtual void f() const {cout << "D::f() ";}</pre>
                                                                         virtual void f() const {cout << "E::f() ";}</pre>
                                                                         virtual void h() const {cout << "E::h() ";}</pre>
class F: public E, public D {
                                   vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
public:
 F(): B(3) {}
 virtual void f() const {cout << x << " F::f() ";}</pre>
  virtual void g() const {cout << "F::g() ";}</pre>
};
void Fun(const vector<B*>& v) {
 auto it1 = v.begin();
  vector<B*>::const_iterator it2;
  C* q;
 for(int i=1; it1 != v.end(); ++it1, ++i) {
   std::cout << "#" << i << " ";
                                                                        > B:: (= (2)
    (*it1)->f(); -> B: z F (1)
    it2 = it1 + 1;
                                                B
   if(it2 != v.end() && typeid(**it1) == typeid(**it2)) (*it2)->f();
    q = dynamic_cast<C*>(*it1);
    if (q) \{ \text{static\_cast} < C *> (q) -> g(); q -> h(); \}
    cout << endl;
int main() {
 B b; C c; D d; E e; F f;
  vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
 Fun(v);
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```
class B {
                                                                  class C: virtual public B {
public:
                                                                  public:
                                                                    virtual void g() const {cout << "C::g() ";}</pre>
 int x;
 B(int z=1): x(z) {}
                                                                    virtual void h() const {cout << "C::h() ";}</pre>
 virtual void f() const {cout << x << " B::f() ";}</pre>
class D: virtual public B {
                                                                  class E: public C {
public:
                                                                  public:
 virtual void f() const {cout << "D::f() ";}</pre>
                                                                   virtual void f() const {cout << "E::f() ";}</pre>
                                                                    virtual void h() const {cout << "E::h() ";}</pre>
class F: public E, public D {
                              vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
public:
 F(): B(3) {}
 virtual void f() const {cout << x << " F::f() ";}</pre>
 virtual void g() const {cout << "F::g() ";}</pre>
};
void Fun(const vector<B*>& v) {
 auto it1 = v.begin();
 vector<B*>::const_iterator it2;
 C* q;
 for(int i=1; it1 != v.end(); ++it1, ++i) {
   std::cout << "#" << i << " ";
   (*it1)->f();
it2 = it1 + 1;
   q = dynamic_cast<C*>(*it1);
   if(q) {static_cast<C*>(q)->g(); q->h();}
   cout << endl;</pre>
int main() {
 B b; C c; D d; E e; F f;
 vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
 Fun(v);
```

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```
class B {
                                                                      class C: virtual public B {
public:
                                                                      public:
                                                                       virtual void g() const {cout << "C::g() ";}</pre>
 int x;
  B(int z=1): x(z) {}
                                                                       virtual void h() const {cout << "C::h() ";}</pre>
 virtual void f() const {cout << x << " B::f() ";}
class D: virtual public B {
                                                                      class E: public C {
public:
                                                                      public:
                                                                       virtual void f() const {cout << "E::f() ";}</pre>
 virtual void f() const {cout << "D::f() ";}</pre>
                                                                       virtual void h() const {cout << "E::h() ";}</pre>
class F: public E, public D {
                                 vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
public:
 F(): B(3) {}
 virtual void f() const {cout << x << " F::f() ";}
  virtual void g() const {cout << "F::g() ";}</pre>
};
void Fun(const vector<B*>& v) {
 auto it1 = v.begin();
  vector<B*>::const_iterator it2;
  C* q;
 for(int i=1; it1 != v.end(); ++it1, ++i) {
    std::cout << "#" << i << " ";
    (<u>*it1)</u>->f(); → F;: F (1)
    it2 = it1 + 1;
    if(it2 != v.end() && typeid(**it1) == typeid(**it2)) (*it2)->f(); — 7: \FC2>
   q = dynamic_cast<C*>(*it1);
   if(q) {static_cast<C*>(q)->g(); q->h();}
  Cout << endl;</pre>
                          F:: 6 (3)
int main() {
 B b; C c; D d; E e; F f;
  vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
 Fun(v);
```

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```
class B {
                                                                      class C: virtual public B {
public:
                                                                      public:
                                                                        virtual void g() const {cout << "C::g() ";}</pre>
 int x;
  B(int z=1): x(z) {}
                                                                        virtual void h() const {cout << "C::h() ";}</pre>
 virtual void f() const {cout << x << " B::f() ";}
class D: virtual public B {
                                                                      class E: public C {
public:
                                                                      public:
 virtual void f() const {cout << "D::f() ";}</pre>
                                                                        virtual void f() const {cout << "E::f() ";}</pre>
                                                                      virtual void h() const {cout << "E::h() ";}
class F: public E, public D {
                                vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
public:
 F(): B(3) {}
 F(): B(3) {}

virtual void f() const {cout << x << " F::f() ";}
 virtual void g() const {cout << "F::g() ";}</pre>
};
void Fun(const vector<B*>& v) {
 auto it1 = v.begin();
  vector<B*>::const_iterator it2;
  C* q;
 for(int i=1; it1 != v.end(); ++it1, ++i) {
   std::cout << "#" << i << " ";
    (*it1)→f(); → F: (F())
    it2 = it1 + 1;
   if(it2 != v.end() && typeid(**it1) == typeid(**it2)) (*it2)->f();  
    q = dynamic_cast<C*>(*it1);
    if (q) \{static\_cast < C *> (q) -> g(); q -> h(); \}
    cout << endl;
                      F: 6 (1)
int main() {
 B b; C c; D d; E e; F f;
  vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
 Fun(v);
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```
class B {
                                                                          class C: virtual public B {
public:
                                                                          public:
                                                                           virtual void g() const {cout << "C::g() ";}</pre>
 int x;
  B(int z=1): x(z) {}
                                                                            virtual void h() const {cout << "C::h() ";}</pre>
 virtual void f() const {cout << x << " B::f() ";}
class D: virtual public B {
                                                                          class E: public C {
public:
                                                                          public:
                                                                           virtual void f() const {cout << "E::f() ";}</pre>
 virtual void f() const {cout << "D::f() ";}</pre>
                                                                           virtual void h() const {cout << "E::h() ";}</pre>
class F: public E, public D {
                                        vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
public:
 F(): B(3) {}
 virtual void f() const {cout << x << " F::f() ";}</pre>
  virtual void g() const {cout << "F::g() ";}</pre>
};
void Fun(const vector<B*>& v) {
 auto it1 = v.begin();
  vector<B*>::const_iterator it2;
  C* q;
 for(int i=1; it1 != v.end(); ++it1, ++i) {
   std::cout << "#" << i << " ";
    (\star it1) \rightarrow f(); \sim 6; F
    it2 = it1 + 1;
   if(it2 != v.end() && typeid(**it1) == typeid(**it2)) (*it2)->f();
    q = dynamic_cast<C*>(*it1);
    if (q) \{\text{static\_cast}<\text{C}*>(\text{q})-\text{>g}(); \text{q}-\text{>h}();\}
    cout << endl;
int main() {
 B b; C c; D d; E e; F f;
  vector<B*> v = { &d, &d, &e, &e, &b, &b, &f, &f, &e, &f, &c, &c };
 Fun(v);
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