

$$[S_{m,n}] \rightarrow \text{KLEIN'S SMN THEOREM}$$

$$[\text{PARAMETERIZATION}] \quad \text{ALSO CALLED... (MORE IMPORTANT!)} \\ f(x) \rightarrow y$$

$$\textcircled{e} \rightarrow [\varphi_{(x)}(y)]$$

$$g(x, y) \rightarrow \text{COMPUTABLE}$$

$$\varphi_{\uparrow}(x)(y)$$

$$[\varphi_{\uparrow}(x)(y)]$$

$$\sum_{m=0}^{\infty}$$

$$A = \{x \in \mathbb{N} \mid \exists u_x \wedge \varphi_x(x) = x^2\}$$

SATURATED  $\rightarrow$  SMN

⑦  $\leftarrow$  NOT RECURSIVE  
 $\nwarrow$  HALTING SET

NOT R.E.

$\rightarrow$   $\underbrace{f(x, y)}_{\text{SMN}} = \begin{cases} y & x \in K \\ \uparrow & \text{otherwise} \end{cases}$

①  $f(x, y) = \begin{cases} y^2 & x \in K \\ \uparrow & \text{otherwise} \end{cases}$   $\downarrow$   $K$

↓ CLASSIC  $K$   
DISTRIBUTION

$$\mathcal{L}_K \rightarrow \left[ f(x, y) = \begin{cases} y & x \in W_x \\ 1 & \text{otherwise} \end{cases} \right]$$

$$f(x, y) = \begin{cases} y^2 & x \in K \\ 1 & \text{otherwise} \end{cases} \quad (x \notin K)$$

$$f(x, y) \approx \mu W \cdot |y^2 - x^2|$$

↓ R.B.  $\dots y^2 \cdot SC_K$

$$SC_K \nearrow = \begin{cases} 1 & x \in K \\ 1 & \text{otherwise} \end{cases}$$

↓ RES. / B

$$\mathcal{L}_K = \begin{cases} 1 & x \in K \\ 0 & \text{otherwise} \end{cases}$$

# SMN-THM

$$\exists s: \mathbb{N} \rightarrow \mathbb{N} \text{ s.t. } \checkmark \text{ PARAM.}$$

$$\exists x, y \in \mathbb{N} \mid \boxed{\varphi_{s(x)}(y)} = \underbrace{\varphi(x, y)}$$

$$\boxed{\varphi(x, y)} = \begin{cases} y^2 & x \in \mathbb{K} \\ 1 & \text{otherwise} \end{cases}$$

We use parametrisation  
to make the function do  
whatever we want!

$$\varphi_{s(x)}(y) = \varphi(x, y)$$

$s$  is a reduction function  
"for something"

$$K \leq A$$

CORE IDEA...

$$\left[ \begin{array}{l} - \text{if } x \in K \rightarrow y^2 \\ - \text{if } x \notin K \rightarrow \uparrow \end{array} \right]$$

$$- \text{if } x \in K$$

$$\varphi_{S(x)}(y) = g(x, y) = y^2 \quad \forall y \in \mathbb{N}$$

→ DOM / CODOM TO COMPUTE

$$\underbrace{W_{S(x)}}_{\uparrow} = y^2 = \mathbb{N}$$

$$\text{DOMAIN OF } \varphi_{S(x)} = y^2$$

$$[\varphi_{S(x)}(S(x))] \Leftrightarrow x^2$$

↑ SUBSTITUTION...

$$= S(x)^2$$

$$\text{if } x \in K \quad | \quad \underbrace{S(x)}_y \in A$$

$S$  is a reduction function of  
 $K$  to  $A$

$$\text{if } x \notin K \Rightarrow$$

$$\varphi_{S(x)}(y) = g(x, y) = 1 \quad \forall y \in \mathbb{N}$$

$$S(x) \notin W_x = \emptyset$$

$$\varphi_{S(x)}(S(x)) = K \quad | \quad K \notin W_x$$

Thus,  $S(x) \notin A$ .

$$A / A^{\mathbb{Z}}$$

$$A = \{x \in \mathbb{N} : x \in W_x \wedge \varphi_x(x) = x^2\}$$

$$\bar{A} = \{x \in N : x \notin W_x \vee \varphi_x(x) \neq x^2\}$$

↑ WRITES THE NEGATED  
VERSION...

## UNIVERSAL ORM - PRACTICES

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# UNIVERSAL TM

$\Psi \rightarrow \underline{PSI} \rightarrow (UPPERCASE)$

PARAMETERS  
...

Theorem (Universal Program)

Let  $k \geq 1$  then the universal function

$$\psi_{\vec{u}}^k : \mathbb{N}^{k+1} \rightarrow \mathbb{N}$$

$$\psi_{\vec{u}}^k(e, \vec{x}) = \varphi_e^{(k)}(\vec{x})$$

is computable

$\uparrow$   
S.M.N.!

$$\varphi_x(x) = \text{Fix } x \text{ on } \mathbb{N} \times \mathbb{N}$$

$$\uparrow \varphi_{\langle x, x \rangle}$$

$A$  is r.e

$\uparrow$

WE CAN WRITE

$\downarrow$

WITH A  $\mu$ -OPERATOR

$$SC_A(x) =$$

SOMETHING!

$$\uparrow \left( \mu y \cdot |x^2 - y^2| = |x^2 - \varphi_x(x)| \right)$$

$\uparrow$  1/0  $\uparrow$  FAKES VAR.  $\uparrow$   $\varphi_{SC(x)}(SC(x))$



$$= 1 / (n \cdot |x|^2 - \Phi_0(x, x))$$

$$= \left[ 1 / (n \cdot |x|^2 - \Phi_0(x, x)) \right] \textcircled{1}$$

$$N^{k-1} \rightarrow \mathbb{N}$$

1 - subscript

$$\textcircled{\Pi} \rightarrow (W_1, W_3)$$

compact form

$$= (1 / (n(y, z, A) \cdot \mathcal{L}(x, y, A)) \wedge$$

$$\mathcal{L}(x, z, y, A) \textcircled{1}$$

$$\left[ = 1 / (n \cdot H(x, (W)_1, (W)_3)) \wedge \right. \\ \left. S(x, (W)_2, (W)_1, (W)_3) \right]$$

compact form!

The smn-theorem states that given a function of two arguments  $g(x, y)$  which is **computable**, there exists a **total** and computable function such that  $\phi_s(x)(y) = g(x, y)$  basically "fixing" the first argument of  $g$ . It's like partially applying an argument to a function. This is generalized over  $m, n$  tuples for  $x, y$ . In other words, it addresses the idea of "parametrization" or "indexing" of computable functions. It's like creating a simplified version of a function that takes an additional parameter (index) to mimic the behavior of a more complex function.

The function  $s_m^n$  is designed to mimic the behavior of  $\phi(x, y)$  when given the appropriate parameters. Essentially, by selecting the right values for  $m$  and  $n$ , you can make  $s$  behave like for a specific computation. Instead of dealing with the complexity of  $\phi(x, y)$ , we can work with a simpler  $s_m^n$  that captures the essence of the computation.

↑

PUNISHING - ~

(THINK ON THAT - IF YOU WILL!)