Esercizio 2

```
class A {
                                                                              class B: public A {
protected:
                                                                               public:
 virtual void j() { cout<<" A::j "; }</pre>
                                                                                 virtual void g() const override { cout <<" B::g "; }</pre>
                                                                                 virtual void m() { cout <<" B::m "; g(); j(); }
void k() { cout <<" B::k "; A::n(); }</pre>
public:
 virtual void g() const { cout <<" A::g "; }</pre>
  virtual void f() { cout <<" A::f "; g(); j(); }</pre>
                                                                                A* n() override { cout <<" B::n "; return this; }
  void m() { cout <<" A::m "; g(); j(); }</pre>
  virtual void k() { cout <<" A::k "; j(); m(); }</pre>
  virtual A* n() { cout <<" A::n "; return this; }</pre>
                                                                             static_cast<B*>(p3->n()))->g() -> A::n A::g
                                                                             dynamic_cast < B^* > (p3->n()))->g() -> NC
                                                                              class D: public B {
class C: public A {
private:
                                                                               protected:
  void j() { cout <<" C::j "; }</pre>
                                                                                 void j() { cout <<" D::j "; }</pre>
public:
                                                                               public:
 virtual void g() { cout <<" C::g "; }
void m() { cout <<" C::m "; g(); j();
void k() const { cout <<" C::k "; k()</pre>
                                                                                 B* n() final { cout <<" D::n "; return this; }
void m() { cout <<" D::m "; g(); j(); }</pre>
                                                    0
= new C(); B* p4 = new D(); const A* p5 = new C();
A \star p1 = \text{new D()}; A \star p2 = \text{new B()}; A \star p3
```

STATICICASI -D SUBINO DYNAMI CICASI -D QUINTA De promo

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