

ACM ICPC Reference

University of Notre Dame

October 25, 2019

Contents

1	vimrc	2
2	hashify.sh	2
3	STL	2
3.1	Algorithms	2
3.2	Numeric	2
3.3	List	3
3.4	Unordered Map	3
3.5	Map	3
3.6	Set	3
3.7	Vector	4
3.8	Stack	4
3.9	Queue	4
3.10	Deque	5
4	Geometry	5
4.1	Base	5
4.2	Advanced	7
4.3	3D	9
5	Graphs	10
5.1	DFS	10
5.2	BFS	11
5.3	Dinic	11
5.4	MinCost MaxFlow	12
5.5	Cycle Cancellation	12
5.6	Hungarian	14
5.7	Bridges/Cut-Vertices	15
5.8	Strongly Connected Components	15
5.9	Stable Marraige Problem	16
6	Structures	17
6.1	Ordered Set	17
6.2	Treap	17
6.3	Envelope	17
6.4	Centroid	19
6.5	Link Cut Tree	19
6.6	Binary Indexed Tree	20
6.7	Segment Tree	21
7	Strings	23
7.1	Suffix Tree	23
7.2	Z-function	24
8	Math	24
8.1	Linear System Solver	24
8.2	Simplex	24

9	Number Theory	25
9.1	Extended Euclidean Algorithm	25
9.2	Miller-Rabin	26
9.3	Diofantine	26
10	Notes	27
10.1	Modular Multiplicative Inverse	27
10.2	Chinese Remainder Theorem	27
10.3	Euler's Totient Function	27
10.4	Möebius	27
10.5	Burnside	27
10.6	Catalan Number	28
10.7	Landau	28
10.8	Erdős-Gallai	28
10.9	Gambler's Ruin	28
10.10	Extra	28

1 vimrc

```

syntax on
colors evening
set ai si noet ts=4 sw=4 sta sm nu so=7 t_Co=8
imap {<CR> {<CR>}<Esc>O

```

2 hashify.sh

```

#!/bin/bash
while IFS=$'\n' read -r line; do
    trim=$(echo "$line" | tr -d "[:space:]")
    md5=$(echo -n "${trim%\\/*}" | md5sum)
    md5=${md5:0:4}
    [ "${trim:~0}" == "$" ] && md5="@${md5}"
    echo "$md5 $line"
done

```

3 STL

3.1 Algorithms

```

a102 #include <algorithm>
d41d // sort, search, array
1bf7 sort(startaddress, endaddress)
e416 binary_search(startaddress, endaddress, valuetofind)
0c81 reverse(first_iterator, last_iterator)
74d6 *max_element (first_iterator, last_iterator)
e4a8 *min_element (first_iterator, last_iterator)
5324 accumulate(first_iterator, last_iterator, initial value of sum) //summation of vector elements
7c96 count(first_iterator, last_iterator,x) //occurrences of x
d278 find(first_iterator, last_iterator, x) // points to last if not found
9ea6 lower_bound(first_iterator, last_iterator, x) //first element in range [first, last) which has a value not
    less than x
d45e upper_bound(first_iterator, last_iterator, x)
213f arr.erase(position to be deleted) // erased element in vector
5c35 arr.erase(unique(arr.begin(),arr.end()),arr.end()) // erases the duplicate occurrences in sorted vector in a
    single line.
e161 next_permutation(first_iterator, last_iterator)
71d5 prev_permutation(first_iterator, last_iterator)
cc6d distance(first_iterator,desired_position) //very useful while finding the index.
f924 all_of(ar, ar+6, [](int x) { return x>0; }) ?//check every element for condition
3261 any_of() //check if there is an element with condition
ba64 none_of() //check if none
5caa copy_n(source, size, dest) //copy one array into another
39d0 iota(ar, ar+6, 20); // ar = 20, 21, 22, 23, 24, 25
d41d
d41d // partition
5aca partition(beg, end, condition)
5896 is_partitioned(beg, end, condition)
67d6 stable_partition(beg, end, condition) //order is preserved
febd partition_point(beg, end, condition) //returns iterator pointing to partion point
8cba partition_copy(beg, end, beg1, beg2, condition) // separate between true and false
d41d

```

3.2 Numeric

```

646d #include<valarray>
d41d // apply and sum
5d32 valarray<int> varr = { 10, 2, 20, 1, 30 };
4ac0 valarray<int> varr1 = varr.apply([](int x){return x+5;});
e7f1 varr1.sum()
d41d // min and max
5d32 valarray<int> varr = { 10, 2, 20, 1, 30 };

```

```

a6d5 varr.max()
ed45 varr.min()
d41d // shift and cshift
5d32 valarray<int> varr = { 10, 2, 20, 1, 30 };
3f80 valarray<int> varr1 = varr.shift(2); // {20, 1, 30, 0, 0}
92e2 varr1 = varr.cshift(-3); // {20, 1, 30, 10, 2}
d41d // swap
5d32 valarray<int> varr = { 10, 2, 20, 1, 30};
043d valarray<int> varr1 = { 2, 29, 3, 1, 41};
31f0 varr.swap(varr1);
d41d

```

3.3 List

```

c702 #include<list>
148f list <int> list1;
a5b7 list1.push_back(element)
8ba1 list1.push_front(element)
142f list1.front()
8a25 list1.back()
9947 list1.pop_front()
d803 list1.pop_back()
141d list1.reverse()
3722 list1.sort()
ecef list1.rbegin() // reverse iterator last element
2a73 list1.rend() //reverse iterator beginning of list
eee2 list1.empty() //empty 1 or not 0
ef20 list1.insert(pos_iter, ele_num, ele) //insert ele_num elements at position pos_iter of value ele
0e66 list1.erase() //remove element
a68f list1.assign(count, value) //assigns new elements by replacing current elements
3e16 list1.remove(position)
d4bd list1.size()
a460 list1.unique(function)
d41d

```

3.4 Unordered Map

```

efe5 #include <unordered_map>
9418 unordered_map<string, double> umap;
7cae umap.at()
4bf0 umap.begin()
7f7d umap.end()
1d78 umap.bucket(key)
c529 umap.bucket_count()
1bbc umap.count(key)
ea39 umap.equal_range() //can be used as search
d41d

```

3.5 Map

```

7306 #include <map>
59ab map<int, int> map1;
c79e map1.begin()
8aac map1.end()
f588 map1.size()
f503 map1.max_size()
2401 map1.empty()
512c map.insert({key, element})
18b2 map.erase(pos)
9286 map.erase(const g) //remove the key value g
47ff map.clear() //remove all elements

```

3.6 Set

```
bd50 #include <set>
cb62 set <int, greater <int> > set1
c6c0 set1.begin()
12f9 set1.end()
00e1 set1.size()
66c6 set1.empty()
e375 set1.rbegin()
5a33 set1.rend()
70db set1.insert(const g)
75cf set1.erase(pos)
e9ef set1.erase(const g)
5a5b set1.clear()
4d8d set1.find(const g)
a286 set1.upper_bound(const g)
6b2c set1.lower_bound(const g)
ef74 set1.swap()
313a set1.emplace()
d41d
```

3.7 Vector

```
ee72 #include <vector>
82b2 vector<int> v1;
e483 v1.begin()
3e1a v1.end()
c689 v1.rbegin()
840a v1.rend()
4159 v1.size()
289d v1.max_size()
e09b v1.capacity()
7bea v1.resize(n)
c752 v1.empty() //whether is empty
cfe6 v1.shrink_to_fit(n) //reduce capacity and destroys all beyond
68ba v1.reserve(n) //capacity to be at least enough to contain n elements
e106 v1.at()
6345 v1.front()
cac5 v1.back()
026d v1.data()
49a3 v1.assign()
692a v1.push_back()
fa5e v1.pop_back()
8e7e v1.insert()
b498 v1.erase()
2ba5 v1.swap()
5434 v1.clear()
d5cf v1.emplace()
d41d
```

3.8 Stack

```
76cb #include <stack>
4ce3 stack <int> s;
161e s.empty()
e958 s.size()
d03c s.top()
b88a s.push(g)
cc35 s.pop()
```

3.9 Queue

```
1bba #include <queue>
26a5 queue <int> q;
5a9d queue <int> p;
2d70 q.empty()
439a q.size()
```

```

1e4e q.swap(p)
2a43 q.emplace()
3c63 q.front()
df4e q.back()
3be4 q.push(g)
a46b q.pop()
d41d

```

3.10 Deque

```

8467 #include <deque>
1e15 deque <int> d;
fcfe d.insert()
ddcc d.rbegin()
c62e d.rend()
5d62 d.begin()
7cdf d.end()
828d d.assign()
73e7 d.resize()
6a9b d.push_front()
e1e8 d.push_back()
e22a d.pop_front()
623b d.pop_back()
fe45 d.front()
36b8 d.back()
9088 d.clear()
8fe7 d.erase()
8069 d.empty()
23a4 d.size()
d41d

```

4 Geometry

4.1 Base

```

d41d // typedef double cood; cood eps = 1e-8; // risky: XXX, untested: TODO
00a0 const double pi = acos(-1.);
ccb5 template<typename T> inline T sq(T x) { return x*x; }
87bc struct vec {
b86a > cood x, y;
6e4f > vec () : x(0), y(0) {} vec (cood a, cood b) : x(a), y(b) {}
741a > inline vec operator - (vec o) { return {x - o.x, y - o.y}; }
ff7e > inline vec operator + (vec o) { return {x + o.x, y + o.y}; }
b6dd > inline vec operator * (cood o) { return {x * o, y * o}; }
2711 > inline vec operator / (cood o) { return {x / o, y / o}; }
6ac9 > inline cood operator ^ (vec o) { return x * o.y - y * o.x; }
83dd > inline cood operator * (vec o) { return x * o.x + y * o.y; }
46ef > inline cood cross (vec a, vec b) { return ((*this)-a) ^ ((*this)-b); } // |(this)a||this)b|sen(angle)
cbad > inline cood inner (vec a, vec b) { return ((*this)-a) * ((*this)-b); } // |(this)a||this)b|cos(angle)
cddd > inline double angle (vec a, vec b) { return atan2(cross(a,b),inner(a,b)); } // ccw angle from (this)a to
      (this)b in range [-pi,pi]
e4d3 > inline int ccw (vec a, vec b) { cood o = cross(a,b); return (eps < o) - (o < -eps); } // this is to the
      (1 left, 0 over, -1 right) of ab
2e1f > inline int dir (vec a, vec b) { cood o = inner(a,b); return (eps < o) - (o < -eps); } // a(this) is to
      the (1 same, 0 none, -1 opposite) direction of ab
5d26 > inline cood sq (vec o = vec()) { return inner(o,o); }
e7cf > inline double nr (vec o = vec()) { return sqrt(sq(o)); } //$
4e72 > inline vec operator ~ () { return (*this)/nr(); }
f149 > inline vec proj (vec a, vec b) { return a + (b-a)*(a.inner((*this),b) / a.sq(b)); } // projects this onto
      line ab
1664 > inline vec rotate (double a) { return vec(cos(a) * x - sin(a) * y, sin(a) * x + cos(a) * y); } // ccw by
      a radians
3206 > inline vec rot90 () { return vec(-y,x); } // rotate(pi/2)$
2810 > bool in_seg (vec a, vec b) { return ccw(a,b) == 0 && dir(a,b) <= 0; } // tips included
5e56 > double dist2_lin (vec a, vec b) { return a.sq(b) <= eps ? sq(a) : double(::sq(cross(a,b)))/a.sq(b); } //
      see cir.has_inter_lin

```

```

8831 > double dist2_seg (vec a, vec b) { return a.dir>(*this),b) == (b.dir(*this),a) ? dist2_lin(a,b) :
    min(sq(a),sq(b)); }
436b > inline bool operator == (const vec & o) const { return abs(x-o.x) <= eps && abs(y-o.y) <= eps; }
5522 > inline bool operator < (const vec & o) const { return (abs(x-o.x)>eps)?(x < o.x):(y > o.y); } // lex
    compare (inc x, dec y)
d41d > // full ccw angle strict compare beginning upwards (this+(0,1)) around (*this)
d41d > // incresing distance on ties, this is the first
69ad > bool compare (vec a, vec b) {
a482 > > if ((*this < a) != (*this < b)) return *this < b;
bdb1 > > int o = ccw(a,b); return o>0:((a == *this && !(a == b)) || a.dir(*this,b) < 0);
cbb1 > }
2145 > }; // $
baf6 struct lin { // line
6143 > vec p; cood c; // p*(x,y) = c
1105 > lin () {} lin (vec a, cood b) : p(a), c(b) {}
d036 > lin (vec s, vec t) : p((s-t).rot90()), c(p*s) {}
5c8b > inline lin parll (vec v) { return lin(p,v*p); }
1263 > inline lin perp () { return lin(p.rot90(),c); }
3838 > vec inter (lin o) { if (vec(0,0).ccw(p,o.p) == 0) throw 1; cood d = (p^o.p); return vec((c*o.p.y -
    p.y*o.c)/d,(o.c*p.x - o.p.x*c)/d); }
1375 > bool contains (vec v) { return abs(p*v - c) <= eps; }
eda5 > vec at_x (cood x) { return vec(x,(c-p.x*x)/p.y); }
c0fb > vec at_y (cood y) { return vec((c-y*p.y)/p.x,y); }
e1ef > double sign_dist (vec v) { return double(p*v - c)/p.nr(); }
2145 > }; // $
3236 struct cir { // circle
b6d3 > vec c; cood r;
126a > cir () {} cir (vec v, cood d) : c(v), r(d) {}
c118 > cir (vec u, vec v, vec w) { // XXX untreated degenerates
0fb6 > > vec mv = (u+v)/2; lin s(mv, mv+(v-u).rot90());
bf5f > > vec mw = (u+w)/2; lin t(mw, mw+(w-u).rot90());
a0c4 > > c = s.inter(t); r = c.nr(u);
cbb1 > } // $
9e54 > inline bool contains (vec w) { return c.sq(w) <= sq(r) + eps; } // border included
0549 > inline bool border (vec w) { return abs(c.sq(w) - sq(r)) <= eps; }
1cd6 > inline bool has_inter (cir o) { return c.sq(o.c) <= sq(r + o.r) + eps; } // borders included
376d > inline bool has_border_inter (cir o) { return has_inter(o) && c.sq(o.c) + eps >= sq(r - o.r); }
8ab4 > inline bool has_inter_lin (vec a, vec b) { return a.sq(b) <= eps ? contains(a) : sq(c.cross(a,b)) <=
    sq(r)*a.sq(b) + eps; } // borders included XXX overflow
9bf7 > inline bool has_inter_seg (vec a, vec b) { return has_inter_lin(a,b) && (contains(a) || contains(b) ||
    a.dir(c,b)*b.dir(c,a) != -1); } // borders and tips included XXX overflow
7abe > inline double arc_area (vec a, vec b) { return c.angle(a,b)*r*r/2; } // smallest arc, ccw positive
f967 > inline double arc_len (vec a, vec b) { return c.angle(a,b)*r; } // smallest arc, ccw positive$
771f > pair<vec,vec> tan (vec v) { // XXX low precision
84ec > > if (contains(v) && !border(v)) throw 0;
2894 > > cood d2 = c.sq(v); double s = sqrt(d2 - r*r); s = (s==s)?s:0;
0f70 > > double al = atan2(r,s); vec t = (^(c-v));
3a69 > > return pair<vec,vec>(v + t.rotate(al)*s, v + t.rotate(-al)*s);
cbb1 > } // $
c56f > pair<vec,vec> border_inter (cir o) {
c4d4 > > if (!has_border_inter(o) || o.c == (*this).c) throw 0;
2b40 > > double a = (sq(r) + o.c.sq(c) - sq(o.r))/(2*o.c.nr(c));
b647 > > vec v = (o.c - c)/o.c.nr(c); vec m = c + v * a;
65b9 > > double h = sqrt(sq(r) - sq(a)); h = h!=h?0:h;
440c > > return pair<vec,vec>(m + v.rot90()*h, m - v.rot90()*h);
cbb1 > } // $
5182 > pair<vec,vec> border_inter_lin (vec a, vec b) { // first is closest to a than second
c6e7 > > if (a.sq(b) <= eps) { if (border(a)) return pair<vec,vec>(a,a); throw 0; }
40f6 > > if (a.dir(b,c) == -1) swap(a,b);
45ab > > if (!has_inter_lin(a,b)) throw 0;
5cb6 > > double d2 = c.dist2_lin(a,b); vec p = (b-a)/a.nr(b);
0aca > > double h = sqrt(r*r - d2); h = h!=h?0:h;
ddf2 > > double y = sqrt(c.sq(a) - d2); y = y!=y?0:y;
5539 > > return pair<vec,vec>(a + p*(y-h), a + p*(y+h));
cbb1 > } // $
be35 > double triang_inter (vec a, vec b) { // ccw oriented, this with (c,a,b)
53ba > > if (c.sq(a) > c.sq(b)) return -triang_inter(b,a);
148a > > if (contains(b)) return c.cross(a,b)/2;
7434 > > if (!has_inter_seg(a,b)) return arc_area(a,b);

```

```

773a > pair<vec,vec> itr = border_inter_lin(b,a); // order important
12a9 > if (contains(a)) return c.cross(a,itr.first)/2 + arc_area(itr.first,b);
c2f4 > return arc_area(a,itr.second) + c.cross(itr.second,itr.first)/2 + arc_area(itr.first,b);
cbb1 > }
2145 > };//$
a71b bool inter_seg (vec a, vec b, vec c, vec d) {
2397 > if (a.in_seg(c, d) || b.in_seg(c, d) || c.in_seg(a, b) || d.in_seg(a, b)) return true;
bbbd > return (c.ccw(a, b) * d.ccw(a, b) == -1 && a.ccw(c, d) * b.ccw(c, d) == -1);
cbb1 > }
e0fd double dist2_seg (vec a, vec b, vec c, vec d){return inter_seg(a,b,c,d)?0.:min({ a.dist2_seg(c,d),
b.dist2_seg(c,d), c.dist2_seg(a,b), d.dist2_seg(a,b) });}

```

4.2 Advanced

```

484c cir min_spanning_circle (vec * v, int n) { // n
flea > srand(time(NULL)); random_shuffle(v, v+n); cir c(vec(), 0); int i,j,k;
b11a > for (i = 0; i < n; i++) if (!c.contains(v[i]))
e5b6 > for (c = cir(v[i],0), j = 0; j < i; j++) if (!c.contains(v[j]))
a47c > for (c = cir((v[i] + v[j])/2,v[i].nr(v[j])/2), k = 0; k < j; k++) if (!c.contains(v[k]))
3dd3 > c = cir(v[i],v[j],v[k]);
807f > return c;
cbb1 > };//$
d45c int convex_hull (vec * v, int n, int border_in) { // nlg | border_in (should border points stay?)
4f17 > swap(v[0], *min_element(v,v+n)); int s, i;
f37e > sort(v+1, v+n, [&v] (vec a, vec b) { int o = b.ccw(v[0], a); return (o?o==1:v[0].sq(a)<v[0].sq(b)); });
a69c > if (border_in) {
9492 > for (s = n-1; s > 1 && v[s].ccw(v[s-1],v[0]) == 0; s--);
0bb0 > reverse(v+s, v+n);
cbb1 > }
c497 > for (i = s = 0; i < n; i++) if (!s || !(v[s-1] == v[i])) {
cea9 > for (; s >= 2 && v[s-1].ccw(v[s-2],v[i]) >= border_in; s--);
ceca > swap(v[s++],v[i]);
cbb1 > }
0478 > return s;
cbb1 > };//$
79b9 int monotone_chain (vec * v, int n, int border_in) { // nlg | border_in (should border points stay?)
5031 > vector<vec> r; sort(v, v+n); n = unique(v, v+n) - v;
d885 > for (int i = 0; i < n; r.pb(v[i++])) while (r.size() >= 2 && r[r.size()-2].ccw(r.back(),v[i]) <=
-border_in) r.pop_back();
dd80 > r.pop_back(); unsigned int s = r.size();
c19d > for (int i = n-1; i >= 0; r.pb(v[i--])) while (r.size() >= s+2 && r[r.size()-2].ccw(r.back(),v[i]) <=
-border_in) r.pop_back();
a255 > return copy(r.begin(), r.end() - (r.size() > 1), v) - v;
cbb1 > };//$
f80f double polygon_inter (vec * p, int n, cir c) { // signed area
2eae > return inner_product(p, p+n-1, p+1, c.triang_inter(p[n-1],p[0]), std::plus<double>(), [&c] (vec a, vec b)
{ return c.triang_inter(a,b); });
cbb1 > };//$
3214 int polygon_pos (vec * p, int n, vec v) { // lg | p should be simple (-1 out, 0 border, 1 in)
6c2a > int in = -1; // it's a good idea to randomly rotate the points in the double case, numerically safer
6033 > for (int i = 0; i < n; i++) {
2bca > vec a = p[i], b = p[(i+1)%n]; if (a.x > b.x) swap(a,b);
c9e9 > if (a.x + eps <= v.x && v.x < b.x + eps) { in *= v.ccw(a,b); }
c3b1 > else if (v.in_seg(a,b)) { return 0; }
cbb1 > }
091d > return in;
cbb1 > };//$
271f int polygon_pos_convex (vec * p, int n, vec v) { // lg(n) | (-1 out, 0 border, 1 in) TODO
a868 > if (v.sq(p[0]) <= eps) return 0;
088f > if (n <= 1) { return 0; } if (n == 2) { return v.in_seg(p[0],p[1])?0:-1; }
2ceb > if (v.ccw(p[0],p[1]) < 0 || v.ccw(p[0],p[n-1]) > 0) return -1;
fcfd > int di = lower_bound(p+1,p+n-1,v, [&p] (vec a,vec v) { return v.ccw(p[0],a) > 0; }) - p;
adf3 > if (di == 1) return v.ccw(p[1],p[2]) >= 0?0:-1;
cfa4 > return v.ccw(p[di-1],p[di]);
cbb1 > };//$
d41d // v is the pointset, w is auxiliary with size at least equal to v's
bf98 cood closest_pair (vec * v, vec * w, int l, int r, bool sorted = 0) { // nlg | r is exclusive TODO (AC on
cf, no test)

```



```

91d7 > if (l + 1 >= r) return inf;
900b > if (!sorted) sort(v+l,v+r,[](vec a, vec b){ return a.x < b.x; });
89cd > int m = (l+r)/2; cood x = v[m].x;
1a44 > cood res = min(closest_pair(v,w,l,m,1),closest_pair(v,w,m,r,1));
d046 > merge(v+l,v+m,v+m,v+r,w+l,[](vec a, vec b){ return a.y < b.y; });
2dd0 > for (int i = l, s = 1; i < r; i++) if (sq((v[i] = w[i]).x - x) < res) {
ad96 >     for (int j = s-1; j >= 1 && sq(w[i].y - w[j].y) < res; j--)
c3b1 >         res = min(res, w[i].sq(w[j]));
1991 >     w[s++] = v[i];
cbb1 > }
b505 > return res;
cbb1 }//$

ac2e double union_area (cir * v, int n) { // n^2lg | XXX joins equal circles TODO (AC on szkopol, no tests)
c765 > struct I { vec v; int i; } c[2*(n+4)];
cf66 > srand(time(NULL)); cood res = 0; vector<bool> usd(n);
dd83 > cood lim = 1./0.; for (int i = 0; i < n; i++) lim = min(lim, v[i].c.y - v[i].r - 1);
0b02 > for (int i = 0, ss = 0; i < n; i++, ss = 0) {
dc37 >     vec fp = v[i].c + vec(0,v[i].r).rotate(rand()); // rotation avoids corner on cnt initialization
6e87 >     int cnt = 0, eq = 0;
578e >     for (int j = 0; j < n; j++) {
df48 >         cnt += (usd[j] = v[j].contains(fp));
2311 >         if (!v[i].has_border_inter(v[j])) continue;
8daa >         if (v[i].c == v[j].c) eq++;
4e6b >         else {
e59e >             pair<vec,vec> r = v[i].border_inter(v[j]);
0782 >             c[ss++] = {r.first, j}; c[ss++] = {r.second, j};
cbb1 >         }
cbb1 >     }
d21b >     vec d = vec(v[i].r,0); for (int k = 0; k < 4; k++, d = d.rot90()) c[ss++] = {v[i].c + d, i};
85d3 >     int md = partition(c,c+ss,[v,i,fp](I a){return a.v.ccw(v[i].c,fp) > 0;}) - c;
19c7 >     sort(c,c+md,[v,i](I a,I b){return a.v.ccw(v[i].c,b.v) < 0;});
7430 >     sort(c+md,c+ss,[v,i](I a,I b){return a.v.ccw(v[i].c,b.v) < 0;});
56cd >     for (int j = 0; j < ss; j++) {
2b5e >         if (c[j].i != i) { cnt -= usd[c[j].i]; usd[c[j].i] = !usd[c[j].i]; cnt += usd[c[j].i]; }
b115 >         vec a = c[j].v, b = c[(j+1)%ss].v;
7c4a >         cood cir = abs(v[i].arc_area(a,b) - v[i].c.cross(a,b)/2), tra = abs((b.x-a.x)*(a.y+b.y-2*lim)/2);
e20b >         cood loc = (a.x<b.x)?cir-tra:tra+cir; res += (cnt==eq)?loc/eq:0;
cbb1 >     }
cbb1 > }
b505 > return res;
cbb1 }//$

4ede pii antipodal (vec * p, int n, vec v) { // lg(n) | extreme segments relative to direction v TODO
d41d > // po: closest to dir, ne: furthest from dir
3bd9 > bool sw = ((p[1]-p[0])*v < 0);
d189 > if (sw) v = vec(0,0) - v; // lower_bound returns the first such that lambda is false
0303 > int md = lower_bound(p+1, p+n, v, [p] (vec & a, vec v) { return (a-p[0])*v > eps; }) - p; // chain
separation
25f1 > int po = lower_bound(p, p+md-1, v, [p,n] (vec & a, vec v) { return (p[(&a+1-p)%n]-a)*v > eps; }) - p; //
positive
9dc9 > int ne = (lower_bound(p+md, p+n, v, [p,n] (vec & a, vec v) { return (p[(&a+1-p)%n]-a)*v <= eps; }) -
p)%n; // negative
5703 > if (sw) swap(po,ne);
ef0b > return pii(po,ne);
cbb1 }//$

34e2 int mink_sum (vec * a, int n, vec * b, int m, vec * r) { // (n+m) | a[0]+b[0] should belong to sum, doesn't
create new border points TODO
8d81 > if (!n || !m) { return 0; } int i, j, s; r[0] = a[0] + b[0];
de54 > for (i = 0, j = 0, s = 1; i < n || j < m; s++) {
1ab0 >     if (i >= n) j++;
1dc4 >     else if (j >= m) i++;
4e6b >     else {
4f09 >         int o = (a[(i+1)%n]+b[j%m]).ccw(r[s-1],a[i%n]+b[(j+1)%m]);
e43c >         j += (o >= 0); i += (o <= 0);
cbb1 >     }
f5b4 >     r[s] = a[i%n] + b[j%m];
cbb1 > }
162b > return s-1;
cbb1 }//$

9e65 int inter_convex (vec * p, int n, vec * q, int m, vec * r) { // (n+m) | XXX

```

```

2d76 > int a = 0, b = 0, aa = 0, ba = 0, inflag = 0, s = 0;
2a6c > while ((aa < n || ba < m) && aa < n+n && ba < m+m) {
b977 > >   vec p1 = p[a], p2 = p[(a+1)%n], q1 = q[b], q2 = q[(b+1)%m];
35b2 > >   vec A = p2 - p1, B = q2 - q1;
1479 > >   int cross = vec(0,0).ccw(A,B), ha = p1.ccw(p2,q2), hb = q1.ccw(q2,p2);
c6e0 > >   if (cross == 0 && p2.ccw(p1,q1) == 0 && A*B < -eps) {
507b > > >   if (q1.in_seg(p1,p2)) r[s++] = q1;
5e83 > > >   if (q2.in_seg(p1,p2)) r[s++] = q2;
ce58 > > >   if (p1.in_seg(q1,q2)) r[s++] = p1;
526a > > >   if (p2.in_seg(q1,q2)) r[s++] = p2;
7b25 > > >   if (s < 2) return s;
e2a8 > > >   inflag = 1; break;
5e6d > > } else if (cross != 0 && inter_seg(p1,p2,q1,q2)) {
f420 > > >   if (inflag == 0) aa = ba = 0;
2b81 > > >   r[s++] = lin(p1,p2).inter(lin(q1,q2));
37fd > > >   inflag = (hb > 0) ? 1 : -1;
cbb1 > > > }
5499 > > if (cross == 0 && hb < 0 && ha < 0) return s;
0872 > > bool t = cross == 0 && hb == 0 && ha == 0;
c0ec > > if (t ? (inflag == 1) : (cross >= 0) ? (ha <= 0) : (hb > 0)) {
9873 > > >   if (inflag == -1) r[s++] = q2;
1146 > > >   ba++; b++; b %= m;
9d97 > > > } else {
5c98 > > >   if (inflag == 1) r[s++] = p2;
5ecb > > >   aa++; a++; a %= n;
cbb1 > > > }
cbb1 > > }
c1b2 > > if (inflag == 0) {
3880 > > >   if (polygon_pos_convex(q,m,p[0]) >= 0) { copy(p, p+n, r); return n; }
115c > > >   if (polygon_pos_convex(p,n,q[0]) >= 0) { copy(q, q+m, r); return m; }
cbb1 > > > }
fc37 > > s = unique(r, r+s) - r;
2629 > > if (s > 1 && r[0] == r[s-1]) s--;
0478 > > return s;
cbb1 > > }/$
03ae bool isear (vec * p, int n, int i, int prev[], int next[]) { // aux to triangulate
7630 > > vec a = p[prev[i]], b = p[next[i]];
2d9f > > if (b.ccw(a,p[i]) <= 0) return false;
578e > > for (int j = 0; j < n; j++) {
97eb > > >   if (j == prev[i] || j == next[i]) continue;
0ef9 > > >   if (p[j].ccw(a,p[i]) >= 0 && p[j].ccw(p[i],b) >= 0 && p[j].ccw(b,a) >= 0) return false;
0639 > > >   int k = (j+1)%n;
2898 > > >   if (k == prev[i] || k == next[i]) continue;
a537 > > >   if (inter_seg(p[j],p[k],a,b)) return false;
cbb1 > > > }
8a6c > > return true;
cbb1 > > }
1851 int triangulate (vec * p, int n, bool ear[], int prev[], int next[], int tri[][3]) { // O(n^2) | n >= 3
d14e > > int s = 0, i = 0;
78d0 > > for (int i = 0, prv = n-1; i < n; i++) { prev[i] = prv; prv = i; next[i] = (i+1)%n; ear[i] =
    isear(p,n,i,prev,next); }
6b3b > > for (int lef = n; lef > 3; lef--, i = next[i]) {
ced7 > > >   while (!ear[i]) i = next[i];
e7a9 > > >   tri[s][0] = prev[i]; tri[s][1] = i; tri[s][2] = next[i]; s++; // tri[i][0],i,tri[i][1] inserted
e0c0 > > >   int c_prev = prev[i], c_next = next[i];
c354 > > >   next[c_prev] = c_next; prev[c_next] = c_prev;
84b6 > > >   ear[c_prev] = isear(p,n,c_prev,prev,next); ear[c_next] = isear(p,n,c_next,prev,next);
cbb1 > > > }
bc1d > > tri[s][0] = next[next[i]]; tri[s][1] = i; tri[s][2] = next[i]; s++; // tri[i][0],i,tri[i][1] inserted
0478 > > return s;
cbb1 > > }

```

4.3 3D

```

f61c const double pi = acos(-1);
d41d // typedef double cood; cood eps = 1e-6; // risky: XXX, untested: TODO
3f73 struct pnt { // TODO it's not tested at all :)
5e43 > cood x, y, z;

```

```

cf2f ▶ pnt () : x(0), y(0), z(0) {} pnt (cood a, cood b, cood c) : x(a), y(b), z(c) {}
4e90 ▶ inline pnt operator - (pnt o) { return pnt(x - o.x, y - o.y, z - o.z); }
2b18 ▶ inline pnt operator + (pnt o) { return pnt(x + o.x, y + o.y, z + o.z); }
7470 ▶ inline pnt operator * (cood o) { return pnt(x*o, y*o, z*o); }
8194 ▶ inline pnt operator / (cood o) { return pnt(x/o, y/o, z/o); }
a269 ▶ inline cood operator * (pnt o) { return x*o.x + y*o.y + z*o.z; } // inner: |this||o|*cos(ang)
079c ▶ inline pnt operator ^ (pnt o) { return pnt(y*o.z - z*o.y, z*o.x - x*o.z, x*o.y - y*o.x); } // cross:
    oriented normal to the plane containing the two vectors, has norm |this||o|*sin(ang)
a2ea ▶ inline cood operator () (pnt a, pnt b) { return (*this)*(a^b); } // mixed: positive on the right-hand
    rule (thumb=this,index=a,mid=b)
d41d
f500 ▶ inline cood inner (pnt a, pnt b) { return (a-(*this))*(b-(*this)); }
4114 ▶ inline pnt cross (pnt a, pnt b) { return (a-(*this))^(b-(*this)); } // its norm is twice area of triangle
fa90 ▶ inline cood mixed (pnt a, pnt b, pnt c) { return (a-(*this))(b-(*this),c-(*this)); } // 6 times the
    oriented area of thetetrahedra
d41d
4f78 ▶ inline cood sq (pnt o = pnt()) { return inner(o,o); }
113b ▶ inline double nr (pnt o = pnt()) { return sqrt(sq(o)); }
6edf ▶ inline pnt operator ~ () { return (*this)/nr(); }
d41d
11c0 ▶ inline bool in_seg (pnt a, pnt b) { return cross(a,b).sq() <= eps && inner(a,b) <= eps; } // tips included
a6b7 ▶ inline bool in_tri (pnt a, pnt b, pnt c) { return abs(mixed(a,b,c)) <= eps && cross(a,b)*cross(b,c) >=
    -eps && cross(a,b)*cross(c,a) >= -eps; } // border included$
d41d
7c26 ▶ inline pnt proj (pnt a, pnt b) { return a + (b-a)*a.inner(b,(*this))/a.sq(b); }
3a26 ▶ inline pnt proj (pnt a, pnt b, pnt c) { pnt n = a.cross(b,c); return (*this) - n*(n-(*this))/n.sq(); }
d41d
8fbb ▶ inline double dist2_lin (pnt a, pnt b) { return cross(a,b).sq()/a.sq(b); }
1880 ▶ inline double dist2_seg (pnt a, pnt b) { return a.inner(b,(*this))*b.inner(a,(*this)) <= eps ?
    min(sq(a),sq(b)) : dist2_lin(a,b); }
39c1 ▶ inline double dist_pln (pnt a, pnt b, pnt c) { return abs((~a.cross(b,c))*(*this)-a)); }
5bc2 ▶ inline double dist2_tri (pnt a, pnt b, pnt c) { pnt p = proj(a,b,c); return p.in_tri(a,b,c) ? sq(p) :
    min({ dist2_seg(a,b), dist2_seg(b,c), dist2_seg(c,a) }); }
2145 };
eb48 inline cood area (pnt a, pnt b, pnt c) { return abs(a.cross(b,c).nr()) / 2; }
a6c7 inline cood vol (pnt a, pnt b, pnt c, pnt d) { return abs(a.mixed(b,c,d)) / 6; } // tetrahedra
084a pnt inter_lin_pln (pnt s, pnt t, pnt a, pnt b, pnt c) { pnt n = a.cross(b,c); return s +
    (t-s)*(n*(a-s))/(n*(t-s)); } //$
fabc struct sph { // TODO it's also not tested at all
af42 ▶ pnt c; cood r;
390f ▶ sph () : c(), r(0) {} sph (pnt a, cood b) : c(a), r(b) {}
baaf ▶ inline pnt operator () (cood lat, cood lon) { return c + pnt(cos(lat)*cos(lon), sin(lon), sin(lat))*r; }
    // (1,0,0) is (0,0). z is height.
171a ▶ inline double area_hull (double h) { return 2.*pi*r*h; }
60a4 ▶ inline double vol_hull (double h) { return pi*h/6 * (3.*r*r + h*h); }
2145 };

```

5 Graphs

5.1 DFS

```

d41d // const int N = ;
a301 vector<int> adj[N]; // adj[i] is the adjacency list of vertex i
a692 bool visited[N]; // visited[i] is true iff vertex i was visited
d41d
58bf void add_edge(int u, int v) {
cc97 ▶ adj[u].push_back(v);
d41d ▶ // if graph is undirected:
d41d ▶ adj[v].push_back(u);
cbb1 }
d41d
9e49 void dfs_util(int u) {
2a95 ▶ visited[u] = true;
895e ▶ for (int v : adj[u])
4373 ▶ ▶ if (!visited[v])
9518 ▶ ▶ ▶ dfs_util(v);
cbb1 }

```

```

d41d
4635 void dfs(int n) {
8300     for (int i = 0; i < n; i++)
88e7         visited[i] = false;
8300     for (int i = 0; i < n; i++)
b1c5     if (!visited[i])
9370         dfs_util(i);
cbb1 }

```

5.2 BFS

```

d41d // const int N = ;
d41d
a301 vector<int> adj[N]; // adj[i] is the adjacency list of vertex i
a692 bool visited[N]; // visited[i] is true iff vertex i was visited
77e0 int dist[N]; // dist[i] is distance from start to vertex i
d41d
58bf void add_edge(int u, int v) {
cc97     adj[u].push_back(v);
d41d     // if graph is undirected:
d41d     adj[v].push_back(u);
cbb1 }
d41d
a20b void bfs(int start) {
26a5     queue<int> q;
7292     q.push(start);
fe25     visited[start] = true;
4c87     dist[start] = 0;
d41d
14d7     while (!q.empty()) {
be15         int u = q.front(); q.pop();
d41d
3722         for (int v : adj[u]) {
451a             if (!visited[v]) {
2ale                 q.push(v);
e758                 visited[v] = true;
8a03                 dist[v] = dist[u] + 1;
cbb1             }
cbb1         }
cbb1     }
cbb1 }
d41d

```

5.3 Dinic

```

d41d //typedef int num; const int N = ; const int M = * 2; const num eps = 0;
582d struct dinic {
656d     int hd[N], seen[N], qu[N], lv[N], ei[N], to[M], nx[M]; num fl[M], cp[M]; int en = 2; int when = 0;
1233     bool bfs(int s, int t) {
876c         seen[t] = ++when; lv[t] = 0; int ql = 0, qr = 0; qu[qr++] = t;
a872         while(ql != qr) {
036d             t = qu[ql++]; ei[t] = hd[t]; if(s == t) return true;
9a44             for(int e = hd[t]; e; e = nx[e]) if(seen[to[e]] != when && cp[e ^ 1] - fl[e ^ 1] > eps) {
d4fb                 seen[to[e]] = when;
de5c                 lv[to[e]] = lv[t] + 1;
f0ff                 qu[qr++] = to[e];
cbb1             }
cbb1         }
d1fe         return false;
cbb1     }
a444     num dfs(int s, int t, num f) {
f449         if(s == t) return f;
cebe         for(int &e = ei[s]; e; e = nx[e]) if(ei[to[e]] && seen[to[e]] == when && cp[e] - fl[e] > eps &&
lv[to[e]] == lv[s] - 1)
7004             if(num rf = dfs(to[e], t, min(f, cp[e] - fl[e]))) {
805c                 fl[e] += rf;
5226                 fl[e ^ 1] -= rf;

```

```

2cb7 ▶ ▶ ▶ ▶ return rf;
cbb1 ▶ ▶ ▶ }
bb30 ▶ ▶ return 0;
cbb1 ▶ ▶ }
d41d ▶ // public $
de22 ▶ num max_flow(int s, int t) {
6cb2 ▶ ▶ num fl = 0;
1c5e ▶ ▶ while (bfs(s, t)) for(num f; (f = dfs(s, t, numeric_limits<num>::max())); fl += f);
e508 ▶ ▶ return fl;
cbb1 ▶ ▶ }
5a3f ▶ void add_edge(int a, int b, num c, num rc=0) {
d03a ▶ ▶ to[en] = b; nx[en] = hd[a]; fl[en] = 0; cp[en] = c; hd[a] = en++;
2f94 ▶ ▶ to[en] = a; nx[en] = hd[b]; fl[en] = 0; cp[en] = rc; hd[b] = en++;
cbb1 ▶ ▶ }
7415 ▶ void reset_flow() { memset(fl, 0, sizeof(num) * en); }
ae0a ▶ void init(int n=N) { en = 2; memset(hd, 0, sizeof(int) * n); } // resets all
2145 ▶ };

```

5.4 MinCost MaxFlow

```

d41d //typedef int val; // type of flow
d41d //typedef int num; // type of cost
d41d //const int N = , M = * 2; const num eps = 0;
1854 struct mcmf {
933f ▶ int es[N], to[M], nx[M], en = 2, par[N], seen[N], when, qu[N];
ef55 ▶ val fl[M], cp[M], flow; num cs[M], d[N], tot;
d0cc ▶ val spfa(int s, int t) {
104f ▶ ▶ when++; int a = 0, b = 0;
e0c6 ▶ ▶ for(int i = 0; i < N; i++) d[i] = numeric_limits<num>::max();
3518 ▶ ▶ d[s] = 0; qu[b++] = s; seen[s] = when;
9841 ▶ ▶ while(a != b) {
32d9 ▶ ▶ ▶ int u = qu[a++]; if(a == N) a = 0; seen[u] = 0;
a86f ▶ ▶ ▶ for(int e = es[u]; e; e = nx[e]) if(cp[e] - fl[e] > val(0) && d[u] + cs[e] < d[to[e]] - eps) {
1ee4 ▶ ▶ ▶ ▶ d[to[e]] = d[u] + cs[e]; par[to[e]] = e ^ 1;
85b7 ▶ ▶ ▶ ▶ if(seen[to[e]] < when) { seen[to[e]] = when; qu[b++] = to[e]; if(b == N) b = 0; }
cbb1 ▶ ▶ ▶ }
cbb1 ▶ ▶ }
8e2a ▶ ▶ if(d[t] == numeric_limits<num>::max()) return false;
91fe ▶ ▶ val mx = numeric_limits<val>::max();
bf09 ▶ ▶ for(int u = t; u != s; u = to[par[u]])
05dc ▶ ▶ ▶ mx = min(mx, cp[par[u] ^ 1] - fl[par[u] ^ 1]);
6de0 ▶ ▶ tot += d[t] * val(mx);
bf09 ▶ ▶ for(int u = t; u != s; u = to[par[u]])
ae7b ▶ ▶ ▶ fl[par[u]] -= mx, fl[par[u] ^ 1] += mx;
b9aa ▶ ▶ return mx;
cbb1 ▶ ▶ }
d41d ▶ // public $
8662 ▶ num min_cost(int s, int t) {
3b69 ▶ ▶ tot = 0; flow = 0;
e66e ▶ ▶ while(val a = spfa(s, t)) flow += a;
126a ▶ ▶ return tot;
cbb1 ▶ ▶ }
457a ▶ void add_edge(int u, int v, val c, num s) {
1d08 ▶ ▶ fl[en] = 0; cp[en] = c; to[en] = v; nx[en] = es[u]; cs[en] = s; es[u] = en++;
8015 ▶ ▶ fl[en] = 0; cp[en] = 0; to[en] = u; nx[en] = es[v]; cs[en] = -s; es[v] = en++;
cbb1 ▶ ▶ }
8537 ▶ void reset_flow() { memset(fl, 0, sizeof(val) * en); }
451f ▶ void init(int n) { en = 2; memset(es, 0, sizeof(int) * n); } // XXX must be called
2145 ▶ };

```

5.5 Cycle Cancellation

```

d41d //typedef int val; // type of flow
d41d //typedef int num; // type of cost
d41d //const int N = ; const int M = * 2; const val eps = 0;
afb2 struct cycle_cancel {

```

```

e36d > int hd[N], seen[N], qu[N], lv[N], ei[N], to[M], nx[M], ct[N], par[N]; val fl[M], cp[M], flow; num cs[M],
    d[N], tot; int en = 2, n; int when = 0;
1233 > bool bfs(int s, int t) {
876c > > seen[t] = ++when; lv[t] = 0; int ql = 0, qr = 0; qu[qr++] = t;
a872 > > while(ql != qr) {
036d > > > t = qu[ql++]; ei[t] = hd[t]; if(s == t) return true;
9a44 > > > for(int e = hd[t]; e; e = nx[e]) if(seen[to[e]] != when && cp[e ^ 1] - fl[e ^ 1] > eps) {
d4fb > > > > seen[to[e]] = when;
de5c > > > > lv[to[e]] = lv[t] + 1;
f0ff > > > > qu[qr++] = to[e];
cbb1 > > > }
cbb1 > > }
dife > > return false;
cbb1 > }
e4d9 > val dfs(int s, int t, val f) {
f449 > > if(s == t) return f;
cebe > > for(int &e = ei[s]; e; e = nx[e]) if(ei[to[e]] && seen[to[e]] == when && cp[e] - fl[e] > eps &&
    lv[to[e]] == lv[s] - 1)
9fe1 > > > if(val rf = dfs(to[e], t, min(f, cp[e] - fl[e]))) {
805c > > > > fl[e] += rf;
5226 > > > > fl[e ^ 1] -= rf;
2cb7 > > > > return rf;
cbb1 > > > }
bb30 > > return 0;
cbb1 > }
5cbe > bool spfa() {
e2f3 > > when++; int a = 0, b = 0, u;
91bc > > for(int i = 0; i < n; i++) { d[i] = 0; qu[b++] = i; seen[i] = when; ct[i] = 0; }
9841 > > while(a != b) {
b492 > > > u = qu[a++]; if(a == N) a = 0; seen[u] = 0;
d627 > > > if(ct[u]++ >= n + 1) { a--; break; }
ccce > > > for(int e = hd[u]; e; e = nx[e]) if(cp[e] - fl[e] > val(0) && d[u] + cs[e] < d[to[e]] - eps) {
1ee4 > > > > d[to[e]] = d[u] + cs[e]; par[to[e]] = e ^ 1;
85b7 > > > > if(seen[to[e]] < when) { seen[to[e]] = when; qu[b++] = to[e]; if(b == N) b = 0; }
cbb1 > > > }
cbb1 > > }
5c28 > > if(a == b) return false;
02be > > val mn = numeric_limits<val>::max();
be15 > > when++;
ef15 > > for(; seen[u] != when; u = to[par[u]]) seen[u] = when;
82c8 > > for(int v = u; seen[v] != when + 1; v = to[par[v]]) {
6e6b > > > seen[v] = when + 1;
0f6a > > > mn = min(mn, cp[par[v] ^ 1] - fl[par[v] ^ 1]);
cbb1 > > > }
cb73 > > for(int v = u; seen[v] == when + 1; v = to[par[v]]) {
7618 > > > seen[v] = 0;
c37c > > > fl[par[v]] -= mn;
c905 > > > fl[par[v] ^ 1] += mn;
cbb1 > > > }
8a6c > > return true;
cbb1 > }
2b0e > val max_flow(int s, int t) {
e7a0 > > val fl = 0;
036d > > while (bfs(s, t)) for(val f; (f = dfs(s, t, numeric_limits<val>::max())); fl += f);
e508 > > return fl;
cbb1 > }
d41d > // public $
8662 > num min_cost(int s, int t) {
94a7 > > flow = max_flow(s, t);
6c9f > > while(spfa());
ed25 > > tot = 0;
112e > > for(int i = 2; i < en; i++)
b951 > > > if(fl[i] > 0)
dae8 > > > > tot += fl[i] * cs[i];
126a > > return tot;
cbb1 > }
8537 > void reset_flow() { memset(fl, 0, sizeof(val) * en); }
457a > void add_edge(int u, int v, val c, num s) {
d321 > > fl[en] = 0; cp[en] = c; to[en] = v; nx[en] = hd[u]; cs[en] = s; hd[u] = en++;

```

```

f081 ▶ ▶ fl[en] = 0; cp[en] = 0; to[en] = u; nx[en] = hd[v]; cs[en] = -s; hd[v] = en++;
cbb1 ▶ }
bfc4 ▶ void init(int n) { this->n = n; en = 2; memset(hd, 0, sizeof(int) * n); } // XXX must be called
2145 };

```

5.6 Hungarian

```

d41d //const int N = ; typedef ll num; const num eps = ;
d41d // Solves minimum perfect matching in an n by n bipartite graph with edge costs in c
d41d // y and z will be such that y[i] + z[j] <= c[i][j] and sum of y and z is maximum
55ad struct hungarian {
2f6a ▶ int n, MA[N], MB[N], PB[N], mn[N], st[N], sn; bool S[N], T[N];
6cc1 ▶ num c[N][N], d[N], y[N], z[N];
cd49 ▶ bool increase(int b) {
03dd ▶ ▶ for (int a = PB[b];;) {
9ae2 ▶ ▶ ▶ int n_b = MA[a];
1ba8 ▶ ▶ ▶ MB[b] = a; MA[a] = b;
8f2f ▶ ▶ ▶ if(n_b == -1) break;
5af0 ▶ ▶ ▶ b = n_b; a = PB[b];
cbb1 ▶ ▶ }
8a6c ▶ ▶ return true;
cbb1 ▶ }
3a3b ▶ bool visit(int a) {
cdb1 ▶ ▶ S[a] = true;
f580 ▶ ▶ for(int b = 0; b < n; b++) {
367c ▶ ▶ ▶ if(T[b]) continue;
e782 ▶ ▶ ▶ if(c[a][b] - y[a] - z[b] < d[b] - eps) { d[b] = c[a][b] - y[a] - z[b]; mn[b] = a; }
3f25 ▶ ▶ ▶ if(c[a][b] - eps <= y[a] + z[b]) {
b46d ▶ ▶ ▶ ▶ T[b] = true; PB[b] = a; st[sn++] = b;
f8ab ▶ ▶ ▶ ▶ if(MB[b] == -1) return increase(b);
cbb1 ▶ ▶ ▶ }
cbb1 ▶ ▶ }
dlfe ▶ ▶ return false;
cbb1 ▶ }
415c ▶ bool update_dual() {
2f63 ▶ ▶ int mb = -1, b; num e;
f135 ▶ ▶ for(b = 0; b < n; b++) if(!T[b] && (mb == -1 || d[b] < d[mb])) mb = b;
04ff ▶ ▶ for(e = d[mb], b = 0; b < n; b++)
3c42 ▶ ▶ ▶ if(T[b]) z[b] -= e;
6435 ▶ ▶ ▶ else d[b] -= e;
a915 ▶ ▶ for(int a = 0; a < n; a++)
cbbc ▶ ▶ ▶ if(S[a]) y[a] += e;
eabc ▶ ▶ PB[mb] = mn[mb];
7dcf ▶ ▶ if(MB[mb] == -1) return increase(mb);
e309 ▶ ▶ st[sn++] = mb; T[mb] = true;
dlfe ▶ ▶ return false;
cbb1 ▶ }
c4db ▶ void find_path() {
2cc3 ▶ ▶ int a; for(a = 0; MA[a] != -1; a++);
0351 ▶ ▶ memset(S, 0, sizeof S); memset(T, 0, sizeof T);
e0c6 ▶ ▶ for(int i = 0; i < N; i++) d[i] = numeric_limits<num>::max();
7160 ▶ ▶ sn = 0; if(visit(a)) return;
6679 ▶ ▶ while(true) {
1f3f ▶ ▶ ▶ if(sn) { if(visit(MB[st[--sn]])) break; }
6656 ▶ ▶ ▶ else if(update_dual()) break;
cbb1 ▶ ▶ }
cbb1 ▶ }
7e1e ▶ void reset_all() {
52b4 ▶ ▶ for(int i = 0; i < n; i++) { y[i] = *min_element(c[i], c[i] + n); z[i] = 0; }
e517 ▶ ▶ for(int i = 0; i < n; i++) MA[i] = MB[i] = -1;
cbb1 ▶ }
d41d ▶ // public $
957f ▶ num min_match() { // set n and c then call this function
b989 ▶ ▶ reset_all(); num all = 0;
c13f ▶ ▶ for(int i = 0; i < n; i++) find_path();
fe8e ▶ ▶ for(int a = 0; a < n; a++) all += c[a][MA[a]];
64a8 ▶ ▶ return all;
cbb1 ▶ }

```

2145 };

5.7 Bridges/Cut-Vertices

```

d41d // Finds bridges and cut vertices
d41d // Receives:
d41d // N: number of vertices
d41d // l: adjacency list
d41d // Gives:
d41d // vis, seen, par (used to find cut vertices)
d41d // ap - 1 if it is a cut vertex, 0 otherwise
d41d // brid - vector of pairs containing the bridges
045d typedef pair<int, int> PII;
d41d
060e int N;
b087 vector <int> l[MAX];
d7bf vector <PII> brid;
9938 int vis[MAX], seen[MAX], par[MAX], ap[MAX];
6d2f int cnt, root;
d41d
6c18 void dfs(int x){
6229 if(vis[x] != -1)
505b     return;
7144 vis[x] = seen[x] = cnt++;
d41d
1e7d int adj = 0;
724e for(int i = 0; i < (int)l[x].size(); i++){
bea7     int v = l[x][i];
d1b9     if(par[x] == v)
5e2b         continue;
3c6e     if(vis[v] == -1){
062a         adj++;
20c6         par[v] = x;
6b41         dfs(v);
1214         seen[x] = min(seen[x], seen[v]);
5ec3         if(seen[v] >= vis[x] && x != root)
927e             ap[x] = 1;
d41c         if(seen[v] == vis[v])
0818             brid.push_back(make_pair(v, x));
cbb1     }
4e6b     else{
e09a         seen[x] = min(seen[x], vis[v]);
c943         seen[v] = min(seen[x], seen[v]);
cbb1     }
cbb1 }
63df if(x == root) ap[x] = (adj>1);
cbb1 }
d41d
ece6 void bridges(){
f342 brid.clear();
faad for(int i = 0; i < N; i++){
6939     vis[i] = seen[i] = par[i] = -1;
628e     ap[i] = 0;
cbb1 }
a018 cnt = 0;
9723 for(int i = 0; i < N; i++){
2bec     if(vis[i] == -1){
1c5a         root = i;
1e5d         dfs(i);
cbb1     }
cbb1 }

```

5.8 Strongly Connected Components

```

bf05 struct SCC {
e1bd     int V, group_cnt;
52c2     vector<vector<int> > adj, radj;

```



```

16c0  vector<int> group_num, vis;
eac6  stack<int> stk;
d41d
d41d  // V = number of vertices
8aca  SCC(int V): V(V), group_cnt(0), group_num(V), vis(V), adj(V), radj(V) {}
d41d
d41d  // Call this to add an edge (0-based)
b873  void add_edge(int v1, int v2) {
09e7      adj[v1].push_back(v2);
eb77      radj[v2].push_back(v1);
cbb1  }
d41d
f543  void fill_forward(int x) {
efc4      vis[x] = true;
4e75      for (int i = 0; i < adj[x].size(); i++) {
720f          if (!vis[adj[x][i]]) {
7306              fill_forward(adj[x][i]);
cbb1          }
cbb1      }
b527      stk.push(x);
cbb1  }
d41d
4462  void fill_backward(int x) {
b364      vis[x] = false;
4dfa      group_num[x] = group_cnt;
b46b      for (int i = 0; i < radj[x].size(); i++) {
4b86          if (vis[radj[x][i]]) {
e3ce              fill_backward(radj[x][i]);
cbb1          }
cbb1      }
cbb1  }
d41d
d41d  // Returns number of strongly connected components.
d41d  // After this is called, group_num contains component assignments (0-based)
26d6  int get_scc() {
e3e8      for (int i = 0; i < V; i++) {
4d29          if (!vis[i]) fill_forward(i);
cbb1      }
a231      group_cnt = 0;
07d1      while (!stk.empty()) {
5862          if (vis[stk.top()]) {
5c3a              fill_backward(stk.top());
0b14              group_cnt++;
cbb1          }
f3f7          stk.pop();
cbb1      }
893b      return group_cnt;
cbb1  }
2145 };

```

5.9 Stable Marriage Problem

```

d41d // Gale-Shapley algorithm for the stable marriage problem.
d41d // madj[i][j] is the jth highest ranked woman for man i.
d41d // fpref[i][j] is the rank woman i assigns to man j.
d41d // Returns a pair of vectors (mpart, fpart), where mpart[i] gives the partner of man i, and fpart is
analogous
d474 pair<vector<int>, vector<int>> stable_marriage(vector<vector<int>> & madj, vector<vector<int>> & fpref) {
6f98  > int n = madj.size();
48a7  > vector<int> mpart(n, -1), fpart(n, -1);
7789  > vector<int> midx(n);
c37b  > queue<int> mfree;
6033  > for (int i = 0; i < n; i++) {
1581  >     > mfree.push(i);
cbb1  > }
ca8c  > while (!mfree.empty()) {
ac1d  >     > int m = mfree.front(); mfree.pop();
eca5  >     > int f = madj[m][midx[m]++];

```

```

4777 ▸ ▸ if (fpart[f] == -1) {
85a1 ▸ ▸ ▸ mpart[m] = f; fpart[f] = m;
8862 ▸ ▸ } else if (fpref[f][m] < fpref[f][fpart[f]]) {
fa31 ▸ ▸ ▸ mpart[fpart[f]] = -1; mfree.push(fpart[f]);
85a1 ▸ ▸ ▸ mpart[m] = f; fpart[f] = m;
9d97 ▸ ▸ } else {
2b67 ▸ ▸ ▸ mfree.push(m);
cbb1 ▸ ▸ }
cbb1 ▸ }
2a98 ▸ return make_pair(mpart, fpart);
cbb1 }

```

6 Structures

6.1 Ordered Set

```

7747 #include <ext/pb_ds/assoc_container.hpp>
30f4 #include <ext/pb_ds/tree_policy.hpp>
0d73 using namespace __gnu_pbds;
4519 template <typename tA, typename tB=null_type> using ord_set = tree<tA, tB, less<tA>, rb_tree_tag,
tree_order_statistics_node_update>;
d41d // map: tA -> tB with the less<tA> comparison function
d41d // can be used as a normal map
d41d // s.find_by_order(k) :: returns iterator to the k-th element (0-indexed) (or s.end())
d41d // s.order_of_key(x) :: returns how many elements are strictly less than x

```

6.2 Treap

```

d41d //const int N = ; typedef int num;
5463 num X[N]; int en = 1, Y[N], sz[N], L[N], R[N];
8b25 void calc (int u) { // update node given children info
d4c7 ▸ sz[u] = sz[L[u]] + 1 + sz[R[u]];
d41d ▸ // code here, no recursion
cbb1 }
234f void unlaze (int u) {
e39f ▸ if(!u) return;
d41d ▸ // code here, no recursion
cbb1 }
ee5e void split_val(int u, num x, int &l, int &r) { // l gets <= x, r gets > x
754f ▸ unlaze(u); if(!u) return (void) (l = r = 0);
4bc1 ▸ if(X[u] <= x) { split_val(R[u], x, l, r); R[u] = l; l = u; }
81a7 ▸ else { split_val(L[u], x, l, r); L[u] = r; r = u; }
aaa8 ▸ calc(u);
cbb1 }
9374 void split_sz(int u, int s, int &l, int &r) { // l gets first s, r gets remaining
754f ▸ unlaze(u); if(!u) return (void) (l = r = 0);
e06d ▸ if(sz[L[u]] < s) { split_sz(R[u], s - sz[L[u]] - 1, l, r); R[u] = l; l = u; }
f524 ▸ else { split_sz(L[u], s, l, r); L[u] = r; r = u; }
aaa8 ▸ calc(u);
cbb1 }
c870 int merge(int l, int r) { // els on l <= els on r
67f0 ▸ unlaze(l); unlaze(r); if(!l || !r) return l + r; int u;
7801 ▸ if(Y[l] > Y[r]) { R[l] = merge(R[l], r); u = l; }
ae90 ▸ else { L[r] = merge(l, L[r]); u = r; }
0ffd ▸ calc(u); return u;
cbb1 }
500b void init(int n=N-1) { // XXX call before using other funcs
7d1c ▸ for(int i = en = 1; i <= n; i++) { Y[i] = i; sz[i] = 1; L[i] = R[i] = 0; }
8c5a ▸ random_shuffle(Y + 1, Y + n + 1);
cbb1 }

```

6.3 Envelope

```

d41d // typedef ll num; const num eps = 0;
d41d // XXX double: indicates operations specific to integers, not precision related

```

```

d79f template<typename line> struct envelope {
5e0f > deque<line> q; num lo,hi; envelope (num _lo, num _hi) : lo(_lo), hi(_hi) {}
01ca > void push_front (line l) { // amort. O(inter) | l is best at lo or never
a86b > > if (q.size() && q[0](lo) < l(lo)) return;
89b8 > > for (num x; q.size(); q.pop_front()) {
cc18 > > > x = (q.size()<=1?hi:q[0].inter(q[1],lo,hi)-1); // XXX double (-1)
4202 > > > if (l(x) > q[0](x)) break;
cbb1 > > }
45bc > > q.push_front(l);
cbb1 > }
f644 > void push_back (line l) { // amort. O(inter) | l is best at hi or never
0334 > > if (q.size() && q[q.size()-1](hi) <= l(hi)) return;
b71c > > for (num x; q.size(); q.pop_back()) {
4e80 > > > x = (q.size()<=1?lo:q[q.size()-2].inter(q[q.size()-1],lo,hi));
1747 > > > if (l(x) >= q[q.size()-1](x)) break;
cbb1 > > }
5e56 > > q.push_back(l);
cbb1 > }
e732 > void pop_front (num _lo) { for (lo=_lo; q.size()>1 && q[0](lo) > q[1](lo); q.pop_front()); } // amort.
    O(n)
218a > void pop_back (num _hi) { for (hi=_hi; q.size()>1 && q[q.size()-2](hi) <= q[q.size()-1](hi);
    q.pop_back()); } // amort. O(n)
7155 > line get (num x) { // O(lg(R))
e32f > > int lo, hi, md; for (lo = 0, hi = q.size()-1, md = (lo+hi)/2; lo < hi; md = (lo+hi)/2)
c1fb > > > if (q[md](x) > q[md+1](x)) { lo = md+1; }
b029 > > > else { hi = md; }
adf9 > > return q[lo];
cbb1 > }
2145 };
b3a6 struct line { // inter = O(1)
7bd4 > num a,b; num operator () (num x) const { return a*x+b; }
2417 > num inter (line o, num lo, num hi) { return
    abs(o.a-a)<=eps?((b<o.b)?hi+1:lo):min(hi+1,max(lo,(o.b-b-(o.b-b<0)*(a-o.a-1))/(a-o.a) + 1)); }
2145 };
16ed struct generic_line { // inter = O(lg(R))
7bd4 > num a,b; num operator () (num x) const { return a*x+b; }
3cfe > num inter (generic_line o, num lo, num hi) { // first point where o strictly beats this
ca4f > > for (num md = lo+((++hi)-lo)/2; lo < hi; md = lo+(hi-lo)/2) { // XXX double
760b > > > if ((*this)(md)<=o(md)) { lo = md+1; } // XXX double
b029 > > > else { hi = md; }
cbb1 > > }
2532 > > return lo;
cbb1 > }
2145 };
11a2 template<typename line> struct full_envelope { // XXX ties are broken arbitrarily
85c9 > vector<envelope<line>> v; full_envelope(envelope<line> c) : v({c}) {} // v.reserve(30);
6aed > void add (line l) { // amort. O(lg(n)*inter)
8cca > > envelope<line> cur(v.back().lo,v.back().hi); cur.push_back(l);
bb4a > > while (!v.empty() && v.back().q.size() <= cur.q.size()) {
ce29 > > > deque<line> aux; swap(aux,cur.q); int i = 0, j = 0;
31d2 > > > for (; i < aux.size(); i++) {
542d > > > > for (; j < v.back().q.size() && v.back().q[j](cur.hi) > aux[i](cur.hi); j++)
0015 > > > > cur.push_back(v.back().q[j]);
70a1 > > > > cur.push_back(aux[i]);
cbb1 > > > }
a0e7 > > > for (; j < v.back().q.size(); j++) cur.push_back(v.back().q[j]);
deff > > > v.pop_back();
cbb1 > > }
026e > > v.push_back(cur);
cbb1 > }
7155 > line get (num x) { // O(lg(n)lg(R)) | pop_back/pop_front can optimize
9351 > > line a = v[0].get(x);
ad67 > > for (int i = 1; i < (int) v.size(); i++) {
bcbe > > > line b = v[i].get(x);
ad0f > > > if (b(x)<a(x)) a = b;
cbb1 > > > }
3f53 > > return a;
cbb1 > }
2145 };

```

6.4 Centroid

```

0eca vector<int> adj[N]; int cn_sz[N], n;
c864 vector<int> cn_chld[N]; int cn_dep[N], cn_dist[20][N]; // removable
ace4 void cn_setdist (int u, int p, int depth, int dist) { // removable
989e > cn_dist[depth][u] = dist;
59dd > for (int v : adj[u]) if (p != v && cn_sz[v] != -1) // sz = -1 marks processed centroid (not dominated)
4ce5 > > cn_setdist(v, u, depth, dist+1);
cbb1 }
e897 int cn_getsz (int u, int p) {
08c9 > cn_sz[u] = 1;
59dd > for (int v : adj[u]) if (p != v && cn_sz[v] != -1)
b2f6 > > cn_sz[u] += cn_getsz(v,u);
37a9 > return cn_sz[u];
cbb1 }
912c int cn_build (int u, int depth) {
28a0 > int siz = cn_getsz(u,u); int w = u;
0168 > do {
9847 > > u = w;
a786 > > for (int v : adj[u]) if (cn_sz[v] != -1 && cn_sz[v] < cn_sz[u] && cn_sz[v] + cn_sz[v] >= siz)
9a13 > > > w = v;
06ba > } while (u != w); // u becomes current centroid root
094e > cn_setdist(u,u,depth,0); // removable, here you can iterate over all dominated tree
32c2 > cn_sz[u] = -1; cn_dep[u] = depth;
5cfe > for (int v : adj[u]) if (cn_sz[v] != -1) {
1df5 > > int w = cn_build(v, depth+1);
2e31 > > cn_chld[u].pb(w); // removable
cbb1 > }
03f4 > return u;
cbb1 }

```

6.5 Link Cut Tree

```

d41d //const int N = ; typedef int num;
8db1 int en = 1, p[N], sz[N], pp[N]; bool lzswp[N];
c7d4 int C[N][2]; // {left, right} children
fc41 inline void calc(int u) { // update node given children info
5665 > sz[u] = sz[C[u][0]] + 1 + sz[C[u][1]];
d41d > // code here, no recursion
cbb1 }
93d8 inline void unlaze(int u) {
e39f > if(!u) return;
a2c4 > if(lzswp[u]) {
3550 > > swap(C[u][0], C[u][1]);
20b7 > > if(C[u][0]) lzswp[C[u][0]] ^= 1;
8917 > > if(C[u][1]) lzswp[C[u][1]] ^= 1;
53e1 > > lzswp[u] = 0;
cbb1 > }
cbb1 }
0584 int rotate(int u, int dir) { // pulls C[u][dir] up to u and returns it
05db > int v = C[u][dir];
5b77 > swap(pp[v], pp[u]);
2116 > C[u][dir] = C[v][!dir];
6c8a > if(C[u][dir]) p[C[u][dir]] = u;
ed1d > C[v][!dir] = u; p[v] = p[u];
b9c1 > if(p[v]) C[p[v]][C[p[v]][1] == u] = v;
6967 > p[u] = v; calc(u); calc(v);
6dc7 > return v;
cbb1 }
3ca5 void unlz_back(int u) { if(!u) return; unlz_back(p[u]); unlaze(u); }
81a1 void splay(int u) { // pulls node u to root
c46d > unlz_back(u);
bdd0 > while(p[u]) {
2a84 > > int v = p[u], w = p[p[u]];
c76a > > int du = (C[v][1] == u);

```

```

448e > > if(!w) { rotate(v, du); assert(!p[u]); }
4e6b > > else {
d499 > > > int dv = (C[w][1] == v);
4780 > > > if(du == dv) { rotate(w, dv); assert(C[v][du] == u); rotate(v, du); }
e576 > > > else { rotate(v, du); assert(C[w][dv] == u); rotate(w, dv); }
cbb1 > > }
cbb1 > }
cbb1 }
a7c2 int find_sz(int u, int s) { // returns s-th node (0-index)
d9d5 > unlaze(u);
3939 > while(sz[C[u][0]] != s) {
da07 > > if(sz[C[u][0]] < s) { s -= sz[C[u][0]] + 1; u = C[u][1]; }
afa2 > > else u = C[u][0];
d9d5 > > unlaze(u);
cbb1 > }
49a4 > splay(u); return u;
cbb1 }
498d int new_node() {
a2cc > int i = en++; assert(i < N);
bea5 > pp[i] = C[i][0] = C[i][1] = p[i] = 0;
0db4 > lzswp[i] = 0; sz[i] = 1; return i;
cbb1 }
c538 int access(int u) {
10c3 > if(!u) return u;
6d13 > splay(u);
f206 > if(int v = C[u][1]) { p[v] = 0; pp[v] = u; C[u][1] = 0; }
aaa8 > calc(u);
566b > while(pp[u]) {
0068 > > int w = pp[u]; splay(w);
33f4 > > if(int v = C[w][1]) { p[v] = 0; pp[v] = w; }
db1d > > C[w][1] = u; p[u] = w; pp[u] = 0; calc(w); splay(u);
cbb1 > }
03f4 > return u;
cbb1 }
0782 int find_root(int u) { // root of u's tree
29bf > access(u);
3980 > while(C[u][0]) { unlaze(u = C[u][0]); }
c607 > access(u); return u;
cbb1 }
4d88 int get_parent(int u) { // u's parent, rootify might change it
29bf > access(u);
c6f1 > if(!C[u][0]) return pp[u];
e123 > unlaze(u = C[u][0]);
323c > while(C[u][1]) unlaze(u = C[u][1]);
c607 > access(u); return u;
cbb1 }
c63a void link(int u, int v) { // adds edge from u to v, v must be root
961c > if(find_root(u) == find_root(v)) return;
78b9 > access(u); access(v);
612a > assert(C[v][0] == 0 && pp[v] == 0 && sz[v] == 1); // v must be root
8e1a > C[u][1] = v; p[v] = u; calc(u);
cbb1 }
d41d // XXX cut + rootify require get_parent, cut unlinks u from parent, rootify makes u root
e166 void cut(int u) { access(u); assert(C[u][0]); p[C[u][0]] = 0; C[u][0] = 0; calc(u); }
1cea void rootify(int u) { access(u); lzswp[u] = 1; access(u); }
b59a void init() { en = 1; } // XXX initialize

```

6.6 Binary Indexed Tree

```

d41d // Binary indexed tree supporting binary search.
7148 struct BIT {
1a88     int n;
1160     vector<int> bit;
d41d     // BIT can be thought of as having entries f[1], ..., f[n]
d41d     // which are 0-initialized
f6ad     BIT(int n):n(n), bit(n+1) {}
d41d     // returns f[1] + ... + f[idx-1]
d41d     // precondition idx <= n+1

```

```

f3df  int read(int idx) {
a604      idx--;
11e1      int res = 0;
89ae      while (idx > 0) {
8e68          res += bit[idx];
23b5          idx -= idx & -idx;
cbb1      }
b505      return res;
cbb1  }
d41d  // returns f[idx1] + ... + f[idx2-1]
d41d  // precondition idx1 <= idx2 <= n+1
c747  int read2(int idx1, int idx2) {
a3a4      return read(idx2) - read(idx1);
cbb1  }
d41d  // adds val to f[idx]
d41d  // precondition 1 <= idx <= n (there is no element 0!)
9c0d  void update(int idx, int val) {
29b7      while (idx <= n) {
eabd          bit[idx] += val;
ff79          idx += idx & -idx;
cbb1      }
cbb1  }
d41d  // returns smallest positive idx such that read(idx) >= target
724e  int lower_bound(int target) {
6182      if (target <= 0) return 1;
c05c      int pwr = 1; while (2*pwr <= n) pwr*=2;
b1a4      int idx = 0; int tot = 0;
e438      for (; pwr; pwr >>= 1) {
b489          if (idx+pwr > n) continue;
4075          if (tot + bit[idx+pwr] < target) {
1438              tot += bit[idx+=pwr];
cbb1          }
cbb1      }
354e      return idx+2;
cbb1  }
d41d  // returns smallest positive idx such that read(idx) > target
855f  int upper_bound(int target) {
a7a2      if (target < 0) return 1;
c05c      int pwr = 1; while (2*pwr <= n) pwr*=2;
b1a4      int idx = 0; int tot = 0;
e438      for (; pwr; pwr >>= 1) {
b489          if (idx+pwr > n) continue;
b0eb          if (tot + bit[idx+pwr] <= target) {
1438              tot += bit[idx+=pwr];
cbb1          }
cbb1      }
354e      return idx+2;
cbb1  }
2145 };

```

6.7 Segment Tree

```

d41d // This is set up for range minimum queries, but can be easily adapted for computing other quantities.
d41d // To enable lazy propagation and range updates, uncomment the following line.
d41d // #define LAZY
1a25 struct Segtree {
1a88     int n;
1d95     vector<int> data;
dea8 #ifdef LAZY
8cdd #define NOLAZY 2e9
b869 #define GET(node) (lazy[node] == NOLAZY ? data[node] : lazy[node])
c68a     vector<int> lazy;
8c16 #else
0458 #define GET(node) data[node]
f2ee #endif
c5b1     void build_rec(int node, int* begin, int* end) {
c22b         if (end == begin+1) {
10c5             if (data.size() <= node) data.resize(node+1);

```

```

4669 ▸ ▸ ▸ data[node] = *begin;
9d97 ▸ ▸ } else {
8e29 ▸ ▸ ▸ int* mid = begin + (end-begin+1)/2;
409c ▸ ▸ ▸ build_rec(2*node+1, begin, mid);
3780 ▸ ▸ ▸ build_rec(2*node+2, mid, end);
807b ▸ ▸ ▸ data[node] = min(data[2*node+1], data[2*node+2]);
cbb1 ▸ ▸ }
cbb1 ▸ }
7a43 #ifndef LAZY
3167 ▸ void update_rec(int node, int begin, int end, int pos, int val) {
c22b ▸ ▸ if (end == begin+1) {
a677 ▸ ▸ ▸ data[node] = val;
9d97 ▸ ▸ } else {
9685 ▸ ▸ ▸ int mid = begin + (end-begin+1)/2;
6035 ▸ ▸ ▸ if (pos < mid) {
1474 ▸ ▸ ▸ ▸ update_rec(2*node+1, begin, mid, pos, val);
9d97 ▸ ▸ ▸ } else {
a049 ▸ ▸ ▸ ▸ update_rec(2*node+2, mid, end, pos, val);
cbb1 ▸ ▸ ▸ }
807b ▸ ▸ ▸ data[node] = min(data[2*node+1], data[2*node+2]);
cbb1 ▸ ▸ }
cbb1 ▸ }
8c16 #else
dfc5 ▸ void update_range_rec(int node, int tbegin, int tend, int abegin, int aend, int val) {
297c ▸ ▸ if (tbegin >= abegin && tend <= aend) {
1a83 ▸ ▸ ▸ lazy[node] = val;
9d97 ▸ ▸ } else {
3841 ▸ ▸ ▸ int mid = tbegin + (tend - tbegin + 1)/2;
7ef7 ▸ ▸ ▸ if (lazy[node] != NOLAZY) {
2d31 ▸ ▸ ▸ ▸ lazy[2*node+1] = lazy[2*node+2] = lazy[node]; lazy[node] = NOLAZY;
cbb1 ▸ ▸ ▸ }
ca4d ▸ ▸ ▸ if (mid > abegin && tbegin < aend)
a566 ▸ ▸ ▸ ▸ update_range_rec(2*node+1, tbegin, mid, abegin, aend, val);
d7ab ▸ ▸ ▸ if (tend > abegin && mid < aend)
f8e6 ▸ ▸ ▸ ▸ update_range_rec(2*node+2, mid, tend, abegin, aend, val);
ef60 ▸ ▸ ▸ data[node] = min(GET(2*node+1), GET(2*node+2));
cbb1 ▸ ▸ }
cbb1 ▸ }
f2ee #endif
b241 ▸ int query_rec(int node, int tbegin, int tend, int abegin, int aend) {
297c ▸ ▸ if (tbegin >= abegin && tend <= aend) {
c377 ▸ ▸ ▸ return GET(node);
9d97 ▸ ▸ } else {
dea8 #ifdef LAZY
7ef7 ▸ ▸ ▸ if (lazy[node] != NOLAZY) {
04fe ▸ ▸ ▸ ▸ data[node] = lazy[2*node+1] = lazy[2*node+2] = lazy[node]; lazy[node] = NOLAZY;
cbb1 ▸ ▸ ▸ }
f2ee #endif
3841 ▸ ▸ ▸ int mid = tbegin + (tend - tbegin + 1)/2;
a3e6 ▸ ▸ ▸ int res = INT_MAX;
ca4d ▸ ▸ ▸ if (mid > abegin && tbegin < aend)
52fa ▸ ▸ ▸ ▸ res = min(res, query_rec(2*node+1, tbegin, mid, abegin, aend));
d7ab ▸ ▸ ▸ if (tend > abegin && mid < aend)
1071 ▸ ▸ ▸ ▸ res = min(res, query_rec(2*node+2, mid, tend, abegin, aend));
b505 ▸ ▸ ▸ return res;
cbb1 ▸ ▸ }
cbb1 ▸ }
d41d
d41d ▸ // Create a segtree which stores the range [begin, end) in its bottommost level.
b5e6 ▸ Segtree(int* begin, int* end): n(end - begin) {
db18 ▸ ▸ build_rec(0, begin, end);
dea8 #ifdef LAZY
c57d ▸ ▸ lazy.assign(data.size(), NOLAZY);
f2ee #endif
cbb1 ▸ }
d41d
7a43 #ifndef LAZY
d41d ▸ // Call this to update a value (indices are 0-based). If lazy propagation is enabled, use
update_range(pos, pos+1, val) instead.

```

```

a69b > void update(int pos, int val) {
0f2e > > update_rec(0, 0, n, pos, val);
cbb1 > }
8c16 #else
d41d > // Call this to update range [begin, end), if lazy propagation is enabled. Indices are 0-based.
ff71 > void update_range(int begin, int end, int val) {
52d3 > > update_range_rec(0, 0, n, begin, end, val);
cbb1 > }
f2ee #endif
d41d > // Returns minimum in range [begin, end). Indices are 0-based.
cfb8 > int query(int begin, int end) {
c8b1 > > return query_rec(0, 0, n, begin, end);
cbb1 > }
2145 };

```

7 Strings

7.1 Suffix Tree

```

4623 namespace sf {
d41d // const int NS = ; const int N = * 2;
1506 int cn, cd, ns, en = 1, lst;
f48b string S[NS]; int si = -1;
08ad vector<int> sufn[N]; // sufn[si][i] no do sufixo S[si][i...]
3c9e struct node {
a322 > int l, r, si, p, suf;
d3ca > map<char, int> adj;
499b > node() : l(0), r(-1), suf(0), p(0) {}
2a9f > node(int L, int R, int S, int P) : l(L), r(R), si(S), p(P) {}
a577 > inline int len() { return r - l + 1; }
48b2 > inline int operator[](int i) { return S[si][l + i]; }
9eae > inline int& operator()(char c) { return adj[c]; }
fbe2 } t[N];
ea71 inline int new_node(int L, int R, int S, int P) { t[en] = node(L, R, S, P); return en++; }
e33b void add_string(string s) {
9a02 > s += '$'; S[++si] = s; sufn[si].resize(s.size() + 1); cn = cd = 0;
c5eb > int i = 0; const int n = s.size();
f90a > for(int j = 0; j < n; j++)
fb3e > > for(; i <= j; i++) {
8d90 > > > if(cd == t[cn].len() && t[cn][s[j]]) { cn = t[cn][s[j]]; cd = 0; }
465b > > > if(cd < t[cn].len() && t[cn][cd] == s[j]) {
c4d2 > > > > cd++;
ce02 > > > > if(j < s.size() - 1) break;
4e6b > > > > else {
aafd > > > > > if(i) t[lst].suf = cn;
ac68 > > > > > for(; i <= j; i++) { sufn[si][i] = cn; cn = t[cn].suf; }
cbb1 > > > > }
7ced > > > } else if(cd == t[cn].len()) {
0a2a > > > > sufn[si][i] = en;
0467 > > > > if(i) t[lst].suf = en; lst = en;
aff4 > > > > t[cn][s[j]] = new_node(j, n - 1, si, cn);
02c2 > > > > cn = t[cn].suf; cd = t[cn].len();
9d97 > > > } else {
f287 > > > > int mid = new_node(t[cn].l, t[cn].l + cd - 1, t[cn].si, t[cn].p);
12ed > > > > t[t[cn].p][t[cn][0]] = mid;
5201 > > > > if(ns) t[ns].suf = mid;
0467 > > > > if(i) t[lst].suf = en; lst = en;
0a2a > > > > sufn[si][i] = en;
cb00 > > > > t[mid][s[j]] = new_node(j, n - 1, si, mid);
7bfa > > > > t[mid][t[cn][cd]] = cn;
07fe > > > > t[cn].p = mid; t[cn].l += cd; cn = t[mid].p;
5967 > > > > int g = cn? j - cd : i + 1; cn = t[cn].suf;
c197 > > > > while(g < j && g + t[t[cn][S[si][g]]].len() <= j) {
6fea > > > > > cn = t[cn][S[si][g]]; g += t[cn].len();
cbb1 > > > > }
71c3 > > > > if(g == j) { ns = 0; t[mid].suf = cn; cd = t[cn].len(); }
f90d > > > > else { ns = mid; cn = t[cn][S[si][g]]; cd = j - g; }

```



```

cbb1 ▸ ▸ ▸ }
cbb1 ▸ ▸ }
cbb1 ▸ }
2145 };

```

7.2 Z-function

```

2a61 void Z(char s[], int n, int z[]) { // z[i] = |lcp(s,s[i..n])|
fc15 ▸ for(int i = 1, m = -1; i < n; i++) {
d69b ▸ ▸ z[i] = (m != -1 && m + z[m] >= i)?min(m + z[m] - i, z[i - m]):0;
8a63 ▸ ▸ while (i + z[i] < n && s[i + z[i]] == s[z[i]]) z[i]++;
bbe8 ▸ ▸ if (m == -1 || i + z[i] > m + z[m]) m = i;
cbb1 ▸ }
cbb1 }

```

8 Math

8.1 Linear System Solver

```

d41d //const int N = ;
d41d
46cc double a[N][N];
3793 double ans[N];
d41d
d41d // sum(a[i][j] * x_j) = a[i][n] for 0 <= i < n
d41d // stores answer in ans and returns det(a)
c42a double solve(int n) {
f99b ▸ double det = 1;
6033 ▸ for(int i = 0; i < n; i++) {
0268 ▸ ▸ int mx = i;
197a ▸ ▸ for(int j = i + 1; j < n; j++)
b83d ▸ ▸ ▸ if(abs(a[j][i]) > abs(a[mx][i]))
672f ▸ ▸ ▸ ▸ mx = j;
28c6 ▸ ▸ if(i != mx) {
e83f ▸ ▸ ▸ swap_ranges(a[i], a[i] + n + 1, a[mx]);
0143 ▸ ▸ ▸ det = -det;
cbb1 ▸ ▸ }
997e ▸ ▸ if(abs(a[i][i]) < 1e-6); // singular matrix
2f40 ▸ ▸ det *= a[i][i];
94fe ▸ ▸ for(int j = i + 1; j < n; j++) {
12fe ▸ ▸ ▸ for(int k = i + 1; k <= n; k++)
ea32 ▸ ▸ ▸ ▸ a[j][k] -= (a[j][i] / a[i][i]) * a[i][k];
efbc ▸ ▸ ▸ a[j][i] = 0;
cbb1 ▸ ▸ }
cbb1 ▸ }
45bd ▸ for(int i = n - 1; i >= 0; i--) {
7634 ▸ ▸ ans[i] = a[i][n];
197a ▸ ▸ for(int j = i + 1; j < n; j++)
9b00 ▸ ▸ ▸ ans[i] -= a[i][j] * ans[j];
35e5 ▸ ▸ ans[i] /= a[i][i];
cbb1 ▸ }
7a32 ▸ return det;
cbb1 }

```

8.2 Simplex

```

d41d //typedef long double dbl;
bec0 const dbl eps = 1e-6;
d41d //const int N = , M = ;
d41d
79ee struct simplex {
0643 ▸ int X[N], Y[M];
6b50 ▸ dbl A[M][N], b[M], c[N];
e268 ▸ dbl ans;
14e0 ▸ int n, m;

```

```

a00d > dbl sol[N];
d41d
c511 > void pivot(int x,int y){
eb91 > > swap(X[y], Y[x]);
c057 > > b[x] /= A[x][y];
8300 > > for(int i = 0; i < n; i++)
7f61 > > > if(i != y)
d311 > > > > A[x][i] /= A[x][y];
3fa2 > > > A[x][y] = 1. / A[x][y];
94f7 > > > for(int i = 0; i < m; i++)
a325 > > > > if(i != x && abs(A[i][y]) > eps) {
6856 > > > > > b[i] -= A[i][y] * b[x];
f90a > > > > > for(int j = 0; j < n; j++)
6739 > > > > > > if(j != y)
8c78 > > > > > > > A[i][j] -= A[i][y] * A[x][j];
e112 > > > > > > A[i][y] = -A[i][y] * A[x][y];
cbb1 > > > }
8c7e > > > ans += c[y] * b[x];
8300 > > > for(int i = 0; i < n; i++)
7f61 > > > > if(i != y)
bec1 > > > > c[i] -= c[y] * A[x][i];
0997 > > > c[y] = -c[y] * A[x][y];
cbb1 > > }
d41d
d41d > // maximize sum(x[i] * c[i])
d41d > // element a
d41d > // sum(a[i][j] * x[j]) <= b[i] for 0 <= i < m (Ax <= b)
d41d > // x[i] >= 0 for 0 <= i < n (x >= 0)
d41d > // (n variables, m constraints)
d41d > // stores the answer in ans and returns optimal value
59d9 > dbl solve(int n, int m) {
1f59 > > this->n = n; this->m = m;
f1bf > > ans = 0.;
b1c6 > > for(int i = 0; i < n; i++) X[i] = i;
3e36 > > for(int i = 0; i < m; i++) Y[i] = i + n;
6679 > > while(true) {
ee39 > > > int x = min_element(b, b + m) - b;
988b > > > if(b[x] >= -eps)
c2be > > > > break;
49a2 > > > int y = find_if(A[x], A[x] + n, [](dbl d) { return d < -eps; }) - A[x];
6f8c > > > if(y == n) throw 1; // no solution
7fb4 > > > pivot(x, y);
cbb1 > > > }
6679 > > while(true) {
f802 > > > int y = max_element(c, c + n) - c;
b7b6 > > > if(c[y] <= eps) break;
d6b5 > > > int x = -1;
06d7 > > > dbl mn = 1. / 0.;
94f7 > > > for(int i = 0; i < m; i++)
5877 > > > > if(A[i][y] > eps && b[i] / A[i][y] < mn)
832b > > > > > mn = b[i] / A[i][y], x = i;
ff22 > > > > if(x == -1) throw 2; // unbounded
7fb4 > > > > pivot(x, y);
cbb1 > > > }
d094 > > > memset(sol, 0, sizeof(dbl) * n);
94f7 > > > for(int i = 0; i < m; i++)
cfff > > > > if(Y[i] < n)
09d7 > > > > > sol[Y[i]] = b[i];
ba75 > > > return ans;
cbb1 > > > }
2145 > };

```

9 Number Theory

9.1 Extended Euclidean Algorithm

```

c25f int egcd(int a, int b, int& x, int& y) { // a*x + b*y = gcd(a, b) [Bezout's Theorem]

```

```

8273 ▸ if (b == 0) return x = 1, y = 0, a;
98d1 ▸ int xx, yy;
0c0d ▸ int g = egcd(b, a % b, xx, yy);
512d ▸ x = yy;
a9d0 ▸ y = xx - (a / b) * yy;
96b5 ▸ return g;
cbb1 }

```

9.2 Miller-Rabin

```

a288 llu llrand() { llu a = rand(); a<= 32; a+= rand(); return a;}
0a9c int is_probably_prime(llu n) {
8dbf     if (n <= 1) return 0;
2373     if (n <= 3) return 1;
7de1     llu s = 0, d = n - 1;
66b4     while (d % 2 == 0) {
90f4         d/= 2; s++;
cbb1     }
6b3a     for (int k = 0; k < 64; k++) {
12c0         llu a = (llrand() % (n - 3)) + 2;
dc17         llu x = exp_mod(a, d, n);
1181         if (x != 1 && x != n-1) {
f0ea             for (int r = 1; r < s; r++) {
708d                 x = mul_mod(x, x, n);
61d9                 if (x == 1)
bb30                     return 0;
68b2                 if (x == n-1)
c2be                     break;
cbb1             }
34bc             if (x != n-1)
bb30                 return 0;
cbb1         }
cbb1     }
6a55     return 1;
cbb1 }

```

9.3 Diofantine

```

d41d // find all solutions in the form ax + by = c
d41d
080f void shift_solution(int & x, int & y, int a, int b, int cnt) {
526a     x += cnt * b;
fdfb     y -= cnt * a;
cbb1 }
d41d
f0f5 int find_all_solutions(int a, int b, int c, int minx, int maxx, int miny, int maxy) {
ede5     int x, y, g;
7968     if (!find_any_solution(a, b, c, x, y, g))
bb30         return 0;
fe72     a /= g;
ee2d     b /= g;
d41d
0750     int sign_a = a > 0 ? +1 : -1;
f8be     int sign_b = b > 0 ? +1 : -1;
d41d
ab53     shift_solution(x, y, a, b, (minx - x) / b);
5969     if (x < minx)
8a96         shift_solution(x, y, a, b, sign_b);
6bcc     if (x > maxx)
bb30         return 0;
57f8     int lx1 = x;
d41d
9870     shift_solution(x, y, a, b, (maxx - x) / b);
6bcc     if (x > maxx)
f6f8         shift_solution(x, y, a, b, -sign_b);
eb5e     int rx1 = x;
d41d

```

```

7672  shift_solution(x, y, a, b, -(miny - y) / a);
a697  if (y < miny)
bf53    shift_solution(x, y, a, b, -sign_a);
alde  if (y > maxy)
bb30    return 0;
8e42  int lx2 = x;
d41d
e322  shift_solution(x, y, a, b, -(maxy - y) / a);
alde  if (y > maxy)
b156    shift_solution(x, y, a, b, sign_a);
481c  int rx2 = x;
d41d
473e  if (lx2 > rx2)
e723    swap(lx2, rx2);
2b9f  int lx = max(lx1, lx2);
037c  int rx = min(rx1, rx2);
d41d
f0c5  if (lx > rx)
bb30    return 0;
ebb8  return (rx - lx) / abs(b) + 1;
cbb1 }

```

10 Notes

10.1 Modular Multiplicative Inverse

- If $\gcd(a, m) = 1$, then let $ax + my = \gcd(a, m) = 1$ (Bezout's Theorem). Then $ax \equiv 1 \pmod{m}$.
- If $\gcd(a, m) = 1$, then $a \cdot a^{\phi(m)-1} \equiv 1 \pmod{m}$ (Euler's Theorem).
- If m is prime, then $\phi(m) = m - 1$, so $a \cdot a^{m-2} \equiv 1 \pmod{m}$.

10.2 Chinese Remainder Theorem

We are given $N = n_1 n_2 \cdots n_k$ where n_i are pairwise coprime. We are also given $x_1 \cdots x_k$ such that $x \equiv x_i \pmod{n_i}$. Let $N_i = N/n_i$. There exists M_i and m_i such that $M_i N_i + m_i n_i = 1$ (Bezout). Then, there is only one solution x , given by:

$$x = \sum_{i=1}^k a_i M_i N_i$$

10.3 Euler's Totient Function

Positive integers up to a given integer n that are relatively prime to n . $\varphi(n) = n \prod_{p|n} \left(1 - \frac{1}{p}\right)$ where the product is over the distinct prime numbers dividing n .

10.4 Möebius

If $F(n) = \sum_{d|n} f(d)$, then $f(n) = \sum_{d|n} \mu(d) F(n/d)$.

10.5 Burnside

Let $A: GX \rightarrow X$ be an action. Define:

- $w :=$ number of orbits in X .
- $S_x := \{g \in G \mid g \cdot x = x\}$
- $F_g := \{x \in X \mid g \cdot x = x\}$

Then $w = \frac{1}{|G|} \sum_{x \in X} |S_x| = \frac{1}{|G|} \sum_{g \in G} |F_g|$.

10.6 Catalan Number

C_n is solution for:

- Number of correct bracket sequence consisting of n opening and n closing brackets.
- The number of rooted full binary trees with $n + 1$ leaves (vertices are not numbered). A rooted binary tree is full if every vertex has either two children or no children.
- The number of ways to completely parenthesize $n + 1$ factors.
- The number of triangulations of a convex polygon with $n + 2$ sides (i.e. the number of partitions of polygon into disjoint triangles by using the diagonals).
- The number of ways to connect the $2n$ points on a circle to form n disjoint chords.
- The number of non-isomorphic full binary trees with n internal nodes (i.e. nodes having at least one son).
- The number of monotonic lattice paths from point $(0, 0)$ to point (n, n) in a square lattice of size $n \times n$, which do not pass above the main diagonal (i.e. connecting $(0, 0)$ to (n, n)).
- Number of permutations of length n that can be stack sorted (i.e. it can be shown that the rearrangement is stack sorted if and only if there is no such index $i < j < k$, such that $a_k < a_i < a_j$).
- The number of non-crossing partitions of a set of n elements.
- The number of ways to cover the ladder $1 \dots n$ using n rectangles (The ladder consists of n columns, where i^{th} column has a height i).

Recursive:

$$C_0 = C_1 = 1$$

$$C_n = \sum_{k=0}^{n-1} C_k C_{n-1-k}, n \geq 2$$

Analytical:

$$C_n = \frac{1}{n+1} \binom{2n}{n}$$

10.7 Landau

There is a tournament with outdegrees $d_1 \leq d_2 \leq \dots \leq d_n$ iff:

- $d_1 + d_2 + \dots + d_n = \binom{n}{2}$
- $d_1 + d_2 + \dots + d_k \geq \binom{k}{2} \quad \forall 1 \leq k \leq n.$

In order to build it, let 1 point to $2, 3, \dots, d_1 + 1$ and repeat recursively.

10.8 Erdős-Gallai

There is a simple graph with degrees $d_1 \geq d_2 \geq \dots \geq d_n$ iff:

- $d_1 + d_2 + \dots + d_n$ is even
- $\sum_{i=1}^k d_i \leq k(k-1) + \sum_{i=k+1}^n \min(d_i, k) \quad \forall 1 \leq k \leq n.$

In order to build it, connect 1 with $2, 3, \dots, d_1 + 1$ and repeat recursively.

10.9 Gambler's Ruin

In a game in which we win a coin with probability p and lose a coin with probability $q := 1 - p$, the game stops when we win B or lose A coins. Then $\text{Prob}(\text{win } B) = \frac{1-(p/q)^B}{1-(p/q)^{A+B}}$.

10.10 Extra

- $\text{Fib}(x + y) = \text{Fib}(x + 1)\text{Fib}(y) + \text{Fib}(x)\text{Fib}(y - 1)$