# Sorting, Binary Trees, Priority Queues, and Graphs

### Sorting

- 1. Implement the **Selection Sort** algorithm and analyze its best-case and worst-case time complexity.
- 2. Implement the Insertion Sort algorithm and analyze its best-case and worst-case time complexity.
- 3. Implement the Quick Sort algorithm and analyze its best-case and worst-case time complexity.

#### **Binary Trees**

4. Implement the missing methods in the code available at:
https://github.com/rcpsilva/PCC104\_DesignAndAnalysisOfAlgorithms/blob/main/2025-1/
Problem%20sets/Latex%20Source/5\_Sorting\_BinaryTrees\_Heaps\_Graphs/binary\_search\_tree.
py

For each implemented method, present its time complexity analysis. You may define auxiliary methods if needed.

#### Heaps

5. Using the base code available at: https://github.com/rcpsilva/PCC104\_DesignAndAnalysisOfAlgorithms/blob/main/2025-1/

Problem%20sets/Latex%20Source/5\_Sorting\_BinaryTrees\_Heaps\_Graphs/heap.py
Implement a min-heap using a Python list as the underlying data structure. Ensure that the heap supports insertion and removal of the minimum element.

## Graphs

- 6. Implement the **Depth-First Search (DFS)** and **Breadth-First Search (BFS)** algorithms for a graph represented using an adjacency list. Analyze the time and space complexity of both algorithms in terms of the graph's depth h and average branching factor b.
- 7. Implement the **DFS**, **BFS**, and  $A^*$  algorithms to find a path in a maze. The maze is represented as an  $m \times n$  matrix, where each cell may contain:
  - 0: free space;
  - 1: wall;
  - s: starting position;
  - g: goal (maze exit).

Your implementation should return a valid path (if one exists) from the start to the goal position.