

# M2-BIG DATA GPGPU Chapter 3

# **Exercice**



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# **Objectives**

Lean a basic vector addition with basic thread block and grid dimensions specifications.

### Instructions

We are interested on computing

$$C = A + B$$

where A,B and C are vectors of a given size n. To check the correctness of the program, A and B are initialized as follows :  $A=(i)_i$  and  $B=(n-i)_i$ .

Complete the given code Chap3\_Ex1\_vectorAdd.cu to perform the following algorithm:

- Allocate data on host
- Initialize data on host
- Allocate data on device
- Copy data from host to device
- Compute thread block and kernel grid dimensions
- Invoke the CUDA kernel
- Copy results from device to host
- Verify the result correctness
- Free device memory

To understand the thread block and kernel grid dimensions, you will produce 3 different versions of the program :

- 1. Use only one block of threads
- 2. Use only one thread per block
- 3. Use several threads per block and several blocks

Make sure that your programm is correct for any vector size witout re-compiling.

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```
// Initialize host vectors
=void init (int *a, int *b, int n) {
= for (int i=0; i < n; ++i) {
    a[i] = i;
    b[i] = n-i;
}</pre>
// Check result correctness
Evoid check(int *c, int n) {
   int i = 0;
   while (i < n && c[i] == n) {
    ++i;</pre>
   if (i == n)
  printf("Ok\n");
else
     else
printf("Non ok\n");
// Cuda kernel
global__void add(int *a, int *b, int *c, int n) {
      int main (int argc, char **argv)
if(argc!=2) {
printf("Give the vector size as first parameter\n");
exit(2);
    int n = atoi(argv[1]);
printf("Vector size is %d\n",n);
    int *host_a, *host_b, *host_c;
    int *host_a, *host_b, *host_c;
    int *dev_a, *dev_b, *dev_c;
    //@TODO@ : complete here
host_a = (int *) malloc (n * sizeof(int));
host_b = (int *) malloc (n * sizeof(int));
host_c = (int *) malloc (n * sizeof(int));
    // Initialize vectors
init(host_a,host_b,n);
    cudaMalloc(&dev_a, n * sizeof(int));
cudaMalloc(&dev_b, n * sizeof(int));
cudaMalloc(&dev_c, n * sizeof(int));
    cudaMemcpy(dev_a, host_a, n * sizeof(int), cudaMemcpyHostToDevice);
cudaMemcpy(dev_b, host_b, n * sizeof(int), cudaMemcpyHostToDevice);
    //@TODO@ : complete here
dim3 DimGrid((n-1)/256+1,1,1);
dim3 DimBlock(256,1,1);
add<<< DimGrid, DimBlock>>>(dev_a, dev_b, dev_c, n);
    cudaMemcpy(host_c, dev_c, n * sizeof(int), cudaMemcpyDeviceToHost);
    check (host_c,n);
    // Free device memory
cudaFree(dev_b); cudaFree(dev_c);
     free (host_a); free (host_b); free (host_c);
    return 0
```

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The execution result came as follow:

## **Questions**

- 1. How many floating operations are being performed in your vector add kernel? EXPLAIN. The are n floating operations being performed as we indicate to be filled in the argc which means here we have a 1000.
- 2. How many global memory reads are being performed by your kernel? EXPLAIN. It's equal to n+n=2n for each host to device
- 3. How many global memory writes are being performed by your kernel? EXPLAIN. It's equal to n for each device to host
- 4. Which version is the most efficient (use a size of n = 1000)? Explain why. Use the NVIDIA profiler to get kernel execution time: nvprof –print-gpu-trace 1-vectorAdd 1000.

  As we can see from the execution, the most efficient is the second one with 287.24ms and 1.28us in addition to a throughput of 2.9GB/s

La fin.

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