$$R_{i+k,j} = \frac{\Delta x_{i,j}}{\Delta x_{i,j}} + \frac{\Delta x_{i+l,j}}{\Delta x_{i+l,j}}$$

$$\frac{\Delta x_{i,j}}{R_{x_{i,j}}} + \frac{\Delta x_{i+l,j}}{R_{x_{i+l,j}}}$$

$$\frac{\Delta x_{i,j}}{R_{x_{i,j}}} + \frac{\Delta x_{i+l,j}}{R_{x_{i+l,j}}}$$

$$R_{i,j+k} = \frac{\Delta y_{i,j} + \Delta y_{i,j+1}}{\Delta y_{i,j}} T_{i,j+k} = \frac{R_{y_{i,j}+k} \left(\Delta x_{i,j} d_{i,j}\right)}{R_{y_{i,j}+k}}$$

$$R_{y_{i,j}} + \Delta y_{i,j+1}$$

$$R_{y_{i,j}+k} = \frac{R_{y_{i,j}+k} \left(\Delta x_{i,j} d_{i,j}\right)}{R_{y_{i,j}+k}}$$

homo, iso.