



# Tutorial: Geocomputation with R



The basics

Jannes Muenchow, Robin Lovelace

ERUM Budapest, 2018-05-14



# Find the slides and code

[https://github.com/jannes-m/erum18\\_geocompr](https://github.com/jannes-m/erum18_geocompr)

Please install following packages:

```
install.packages(c("sf", "raster", "spData", "dplyr", "RQGIS"))
```

Or from **docker**:

```
docker run -d -p 8787:8787 -v ${pwd}:/data robinlovelace/geocompr
```

# Contents of the tutorial

## 1. Basics



# Contents of the tutorial

1. Basics
2. Spatial vector data



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3. Spatial raster data



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4. Mapping



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1. Basics
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5. Bridges to GIS



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6. (Spatial statistical learning)





# Who are we

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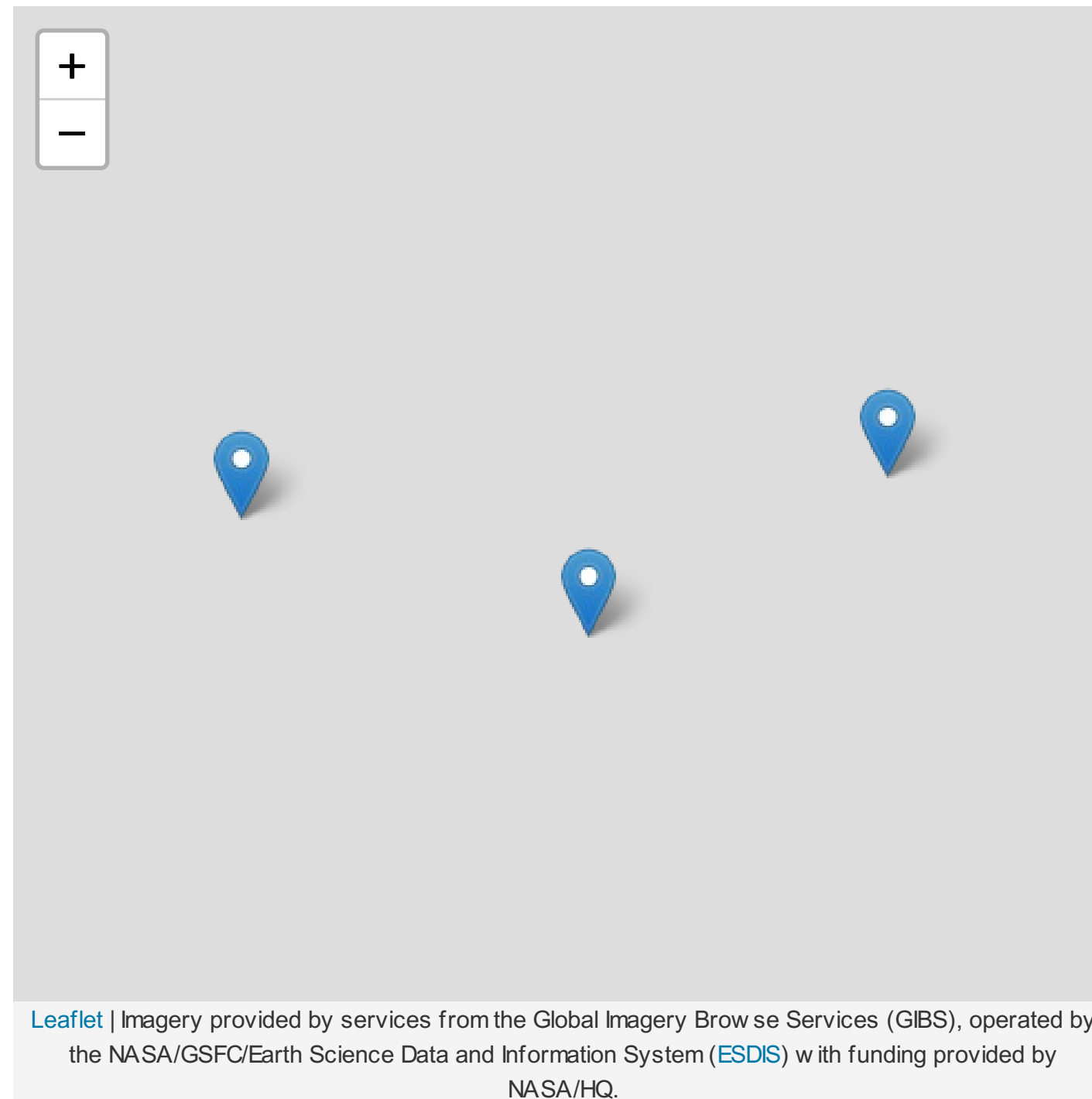
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- **Robin Lovelace** - Geographer and Environmental Scientist focussing on sustainable transport planning; creator of **stplanr**
- together with **Jakub Nowosad** we are writing:

## Geocomputation with R



# Where are we from





# Some definitions

# What is a GIS?

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- Six components of a GIS: software, data, procedures, hardware, people, network
- Typical GIS software packages: QGIS, SAGA-GIS, GRASS-GIS, ArcMap (commercial)







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- GIScience
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Home disciplines	Geography	Computing, Statistics
Software focus	Graphical User Interface	Command line
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Further reading: <https://geocompr.robinlovelace.net/intro.html#what-is-geocomputation>



# Geographic data models



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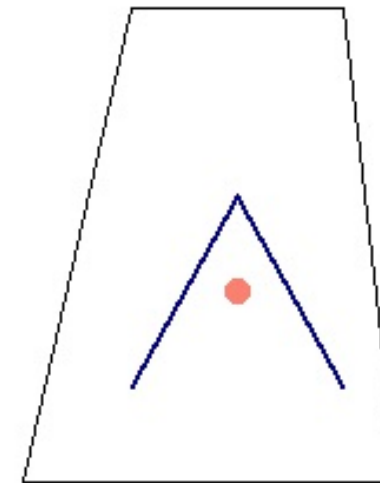
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- Geographic data can quickly become big.
- Two data models for representing digitally geographic data: **the vector** and **the raster** data model



# Vector data model

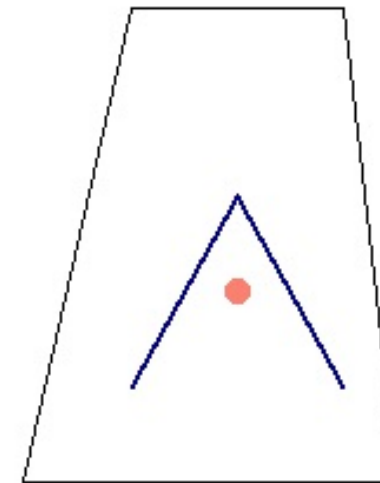
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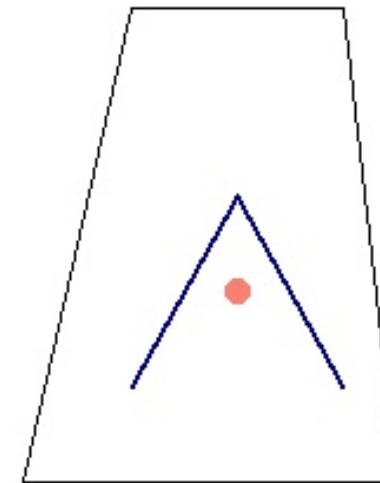
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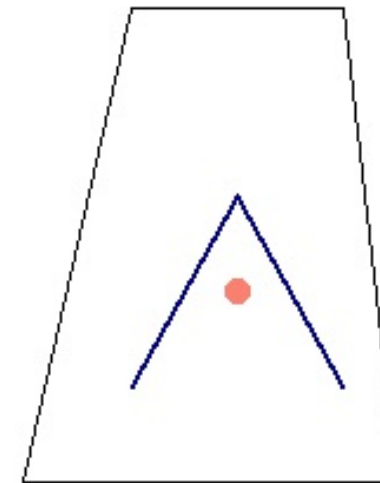
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- Attribute table



Further reading:

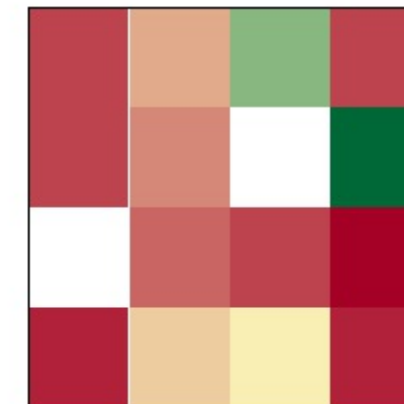
<https://geocompr.robinlovelace.net/spatial-class.html#vector-data>



# Raster data model

- Continuous fields represented by pixels (cells)

19	38	72	18
17	31	NA	96
NA	26	16	9
14	45	50	10

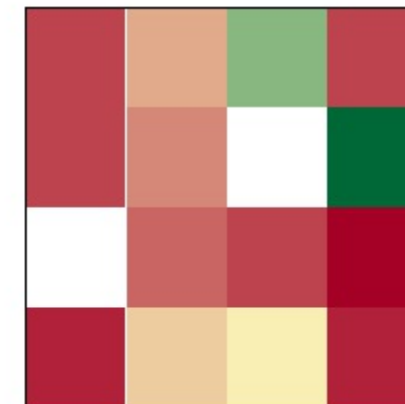




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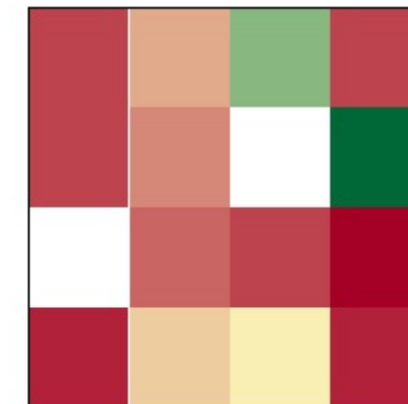




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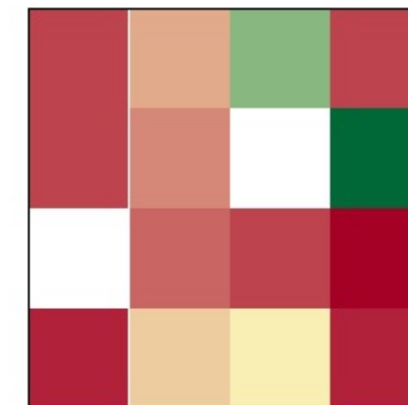




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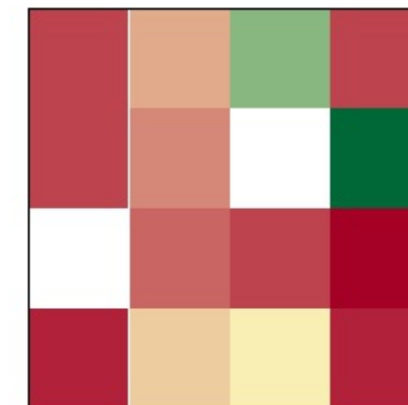




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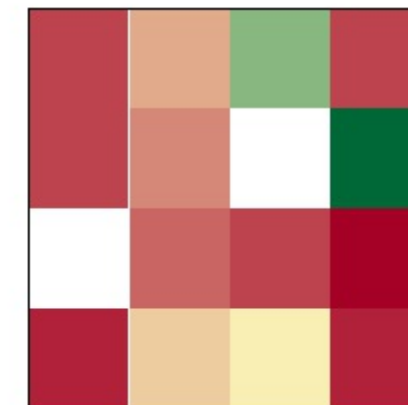




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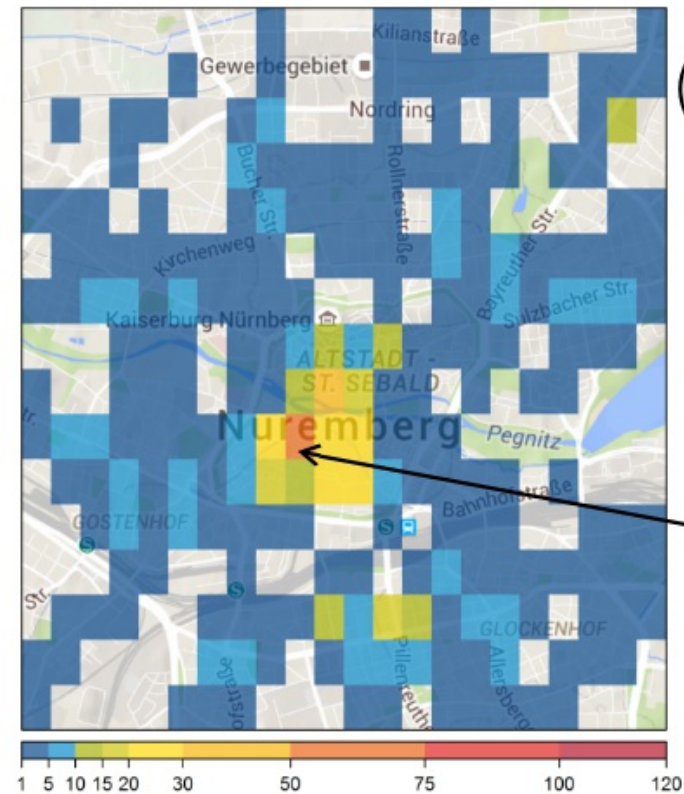
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Further reading: <https://geocompr.robinlovelace.net/spatial-class.html#raster-data>



# Raster header



header

NCOLS 22  
NROWS 16  
XLLCORNER 11.05  
YLLCORNER 49.435  
CELLSIZE 0.0025  
NODATA\_value NA

NA NA NA NA NA NA NA NA NA NA 1 NA NA NA 1 1 NA 1 NA NA NA NA NA 4  
NA NA NA NA NA NA 1 NA NA 3 NA NA NA 2 1 1 2 1 1 NA 2 1 1  
NA 1 NA 1 1 NA NA 3 6 NA NA NA 5 NA 2 NA 1 NA NA 4 12 NA  
NA NA NA 3 NA NA NA 9 2 1 1 1 4 1 1 1 2 NA 2 3 NA NA  
1 2 1 NA 1 NA NA 3 10 3 1 2 2 NA 7 2 NA NA NA NA 2 3  
NA 4 2 5 2 4 4 1 4 NA 3 3 5 4 7 1 6 4 5 2 3 3  
2 5 6 6 2 9 3 1 1 2 NA NA 1 NA 1 1 6 1 7 8 10 1  
NA NA NA 1 1 1 NA 5 2 8 12 7 11 3 3 1 1 NA 4 2 2 NA  
2 NA NA 2 3 3 NA 3 2 13 33 20 4 2 NA 1 NA 1 1 NA NA NA  
3 6 7 3 3 1 2 6 26 **58** 30 25 5 4 1 NA NA NA NA NA NA NA NA  
NA 5 3 7 5 7 5 8 20 12 22 28 10 2 2 2 1 NA 1 NA NA NA  
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# A brief word on CRS



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We use Coordinate Reference Systems (CRS) to locate our geographic data on Earth.

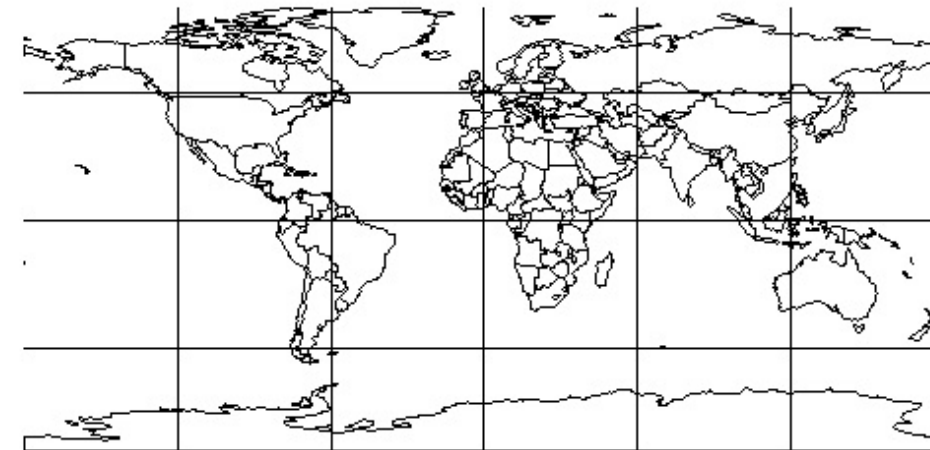
We distinguish between:

- Geographical CRS span the entire world
- Projected CRS are (usually) localized to minimize visual distortion in a particular region (use a specific ellipsoid which is especially suitable for a this particular part of the Earth)

# Geographic CRS



- Usually in decimal degrees
- Used by many people/institutions (GPS)
- Great for locating a place on Earth
- Best for global analysis
- Less suitable if you want to measure distance
- Heavily distorted towards the poles

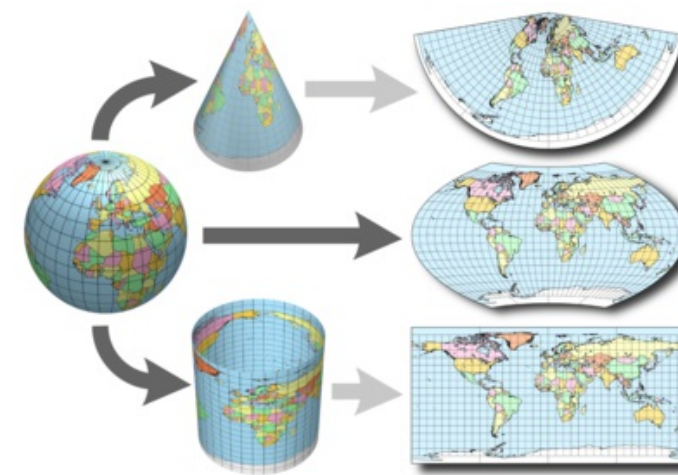






# Projected CRS

- Spatial projections flatten the 3D shape of the Earth onto a 2D plane
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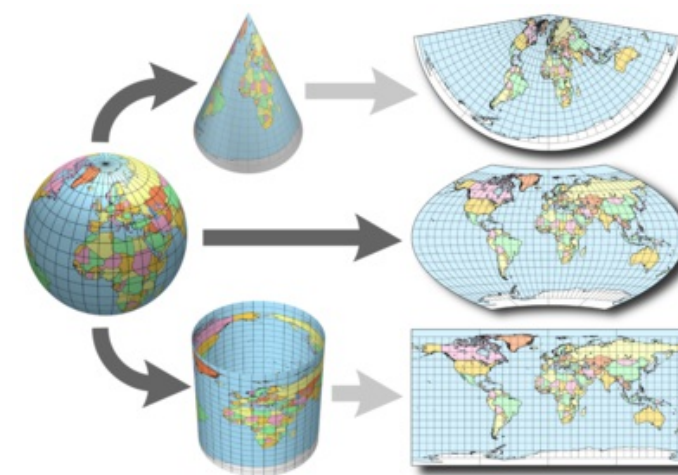


Source: [progonos.com/furuti/](http://progonos.com/furuti/)



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Further reading:

- [Geocomputation with R - Projections](#)
- [QGIS CRS documentation](#)
- [Earth Data Science CRS](#)



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# References

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