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with shalfful view forces

1 Axioms of Probability

1.1 Definitions

- 1. For any event $A, 0 \le \Pr(A) \le 1$.
- 2. $A \cup B \triangleq A + B$.
- 3. $A \cap B \triangleq AB$.
- 4. The null and complete event are $\phi = 0, S = 1$.
- 5. If AB = 0, Pr(A + B) = Pr(A) + Pr(B).
- 6. (A + B)' = A'B'

1.2 Problems

Prove the following:

1.

$$A = AB + AB' \tag{1.2.1.1}$$

2.

$$Pr(A) = Pr(AB) + Pr(AB')$$
(1.2.2.1)

3.

$$A + B = B + AB' \tag{1.2.3.1}$$

4.

$$Pr(A + B) = Pr(A) + Pr(B) - Pr(AB)$$
 (1.2.4.1)

2 Distribution of the sum of random variables

2.1 Definitions

1. The mean of X is defined as

$$E(X) = \sum_{k} k p_X(k)$$
 (2.1.1.1)

2. The Z transform of X is defined as

$$M_X(z) = E(z^{-X}) = \sum_{k=-\infty}^{\infty} z^{-k} p_X(k)$$
 (2.1.2.1)

- 3. There is a one to one relationship between the pmf and its Z transform.
- 4. If If X_1 and X_2 are independent,

$$E[f(X_1)g(X_2)] = E[f(X_1)]E[g(X_2)]$$
 (2.1.4.1)

5. For a Bernoulli random variable X, the pmf is

$$p_X(n) = \begin{cases} p & k = 1\\ 1 - p & k = 0\\ 0 & \text{otherwise} \end{cases}$$
 (2.1.5.1)

6. X_i are said to be i.i.d (independent and identically distributed) if they are independent and have the same pmf.

2.2 Problem

- 1. Find the Z-transform for X, given that X is a Bernoulli random variable with parameter p.
- 2. If X_1 and X_2 are independent, and

$$Y = X_1 + X_2, (2.2.2.1)$$

show that

$$M_Y(z) = M_{X_1}(z)M_{X_2}(z) (2.2.2.2)$$

- 3. Find the Z-transform of Y, given that X_i are i.i.d Bernoulli random variables with parameter p.
- 4. Find the pmf of Y.
- 5. Find the pmf of

$$Y = \sum_{i=1}^{N} X_i, \tag{2.2.5.1}$$

where X_i are i.i.d.

3 Moments and variance

3.1 Definitions

1. The variance of X is defined as:

$$Var(X) = E(X - E(X))^{2}$$
 (3.1.1.1)

2. The Z transform of X is defined as

$$M_X(z) = E(z^{-X}) = \sum_{k=-\infty}^{\infty} z^{-k} p_X(k)$$
 (3.1.2.1)

3. Let X be a random variable with pmf.

$$p_X(k) = \begin{cases} 1/6 & 1 \le k \le 6\\ 0 & \text{otherwise} \end{cases}$$
 (3.1.3.1)

X is said to be Discrete Uniform Random Variable

4. The n^{th} moment of X is defined as:

$$E(X^{n}) = \sum_{k=-\infty}^{\infty} k^{n} p_{X}(k)$$
 (3.1.4.1)

3.2 Problems

- 1. Show that $Var(X) = E(X^2) [E(X)]^2$
- 2. Find $M_X(z)$
- 3. Show that $E(X) = \frac{d}{dz} M_X(z^{-1})|_{z=1}$
- 4. Find $E(X^2)$
- 5. Find Var(X).

4 Convolution

4.1 Definitions

1. The Z transform of X is defined as

$$M_X(z) = E(z^{-X}) = \sum_{k=-\infty}^{\infty} z^{-k} p_X(k)$$
 (4.1.1.1)

2. Let X be a random variable with pmf.

$$p_X(k) = \begin{cases} 1/6 & 1 \le k \le 6\\ 0 & \text{otherwise} \end{cases}$$
 (4.1.2.1)

X is said to be Discrete Uniform Random Variable

3. Convolution of two sequences using Toeplitz matrices

- 4.2 Problems
 - 1. If $\mathbf{x} = \mathbf{h} = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, find \mathbf{y} .
 - 2. Find $p_{X_1}(k) \otimes p_{X_2}(k)$ using toeplitz matrices.
 - 3. Find $M_Y(z)$, such that $Y = X_1 + X_2$
 - 4. Find $p_Y(k)$

5 Z-Transform Applications

5.1 Definitions

1.

$$u(n) = \begin{cases} 1 & n \ge 0 \\ 0 & n < 0 \end{cases}$$
 (5.1.1.1)

2. The Z transform of X is defined as

$$M_X(z) = E(z^{-X}) = \sum_{k=-\infty}^{\infty} z^{-k} p_X(k)$$
 (5.1.2.1)

- 5.2 Problems
 - 1. If

$$p_Y(n) \stackrel{\mathcal{Z}}{\longleftrightarrow} M_Y(z),$$
 (5.2.1.1)

show that

$$p_Y(n-k) \stackrel{\mathcal{Z}}{\longleftrightarrow} M_Y(z)z^{-k},$$
 (5.2.1.2)

2. Show that

$$u(n) \stackrel{\mathcal{Z}}{\longleftrightarrow} \frac{1}{(1-z^{-1})}, \quad |z| > 1 \tag{5.2.2.1}$$

3. Show that

$$nu(n) \stackrel{\mathcal{Z}}{\longleftrightarrow} \frac{z^{-1}}{(1-z^{-1})^2}, \quad |z| > 1$$
 (5.2.3.1)

4. Let

$$M_Y(z) = \left\{ \frac{z^{-1} \left(1 - z^{-6} \right)}{6 \left(1 - z^{-1} \right)} \right\}^2, \quad |z| > 1$$
 (5.2.4.1)

Show that

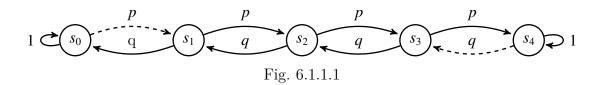
$$p_Y(n) = \frac{(n-1)u(n-1) - 2(n-7)u(n-7) + (n-13)u(n-13)}{36}$$
 (5.2.4.2)

6 Markov Chain

6.1 Definitions

1. Fig. 6.1.1.1 shows a Markovs chain with 5 states. Transition from one state to another happens over time. s_0 and s_4 are absorbing states.

$$p + q = 1 \tag{6.1.1.1}$$



2. At time instant n,

$$\mathbf{p}^{(n)} = \begin{pmatrix} P_0^{(n)} \\ P_1^{(n)} \\ P_2^{(n)} \\ P_3^{(n)} \\ P_4^{(n)} \end{pmatrix}$$
(6.1.2.1)

where $P_i^{(n)}$ are defined to be the stationary probabilities.

3. $P_{i|j}$ is defined as the transition probability of going to state i from state j.

4. For a matrix **A**, let

$$\mathbf{A}\mathbf{x} = \lambda \mathbf{x}.\tag{6.1.4.1}$$

Then λ is a scalar defined to be the eigenvalue of **A** and **x** is the corresponding eigenvector.

6.2 Problems

1. Let

$$P_0^{(n+1)} = P_0^{(n)} (6.2.1.1)$$

$$P_1^{(n+1)} = pP_0^{(n)} + qP_2^{(n)} (6.2.1.2)$$

$$P_2^{(n+1)} = pP_1^{(n)} + qP_3^{(n)} (6.2.1.3)$$

$$P_3^{(n+1)} = pP_2^{(n)} + qP_4^{(n)} (6.2.1.4)$$

$$P_0^{(n+1)} = P_0^{(n)}$$

$$P_1^{(n+1)} = pP_0^{(n)} + qP_2^{(n)}$$

$$P_2^{(n+1)} = pP_1^{(n)} + qP_3^{(n)}$$

$$P_3^{(n+1)} = pP_2^{(n)} + qP_4^{(n)}$$

$$P_4^{(n+1)} = P_4^{(n)}$$

$$(6.2.1.4)$$

$$P_4^{(n+1)} = P_4^{(n)}$$

$$(6.2.1.5)$$

Find the matrix **P** such that $\mathbf{p}^{(n+1)} = \mathbf{P}\mathbf{p}^{(n)}$

- 2. Show that 1 is an eigen value of \mathbf{P} .
- 3. Show that

$$P_2^{(n+1)} = pP_1^{(n)} + qP_3^{(n)} (6.2.3.1)$$

4. If $P_0 = 1, P_N = 0$ and

$$P_i = pP_{i-1} + qP_{i+1} (6.2.4.1)$$

show that

$$P_{i} = \frac{\left(\frac{p}{q}\right)^{i} - \left(\frac{p}{q}\right)^{N}}{1 - \left(\frac{p}{q}\right)^{N}}, 0 \le i \le N$$

$$(6.2.4.2)$$

7 Gaussian Distribution

7.1 Definitions

1. The CDF of X is defined as,

$$F_X(x) = \Pr(X \le x) \tag{7.1.1.1}$$

2. The PDF of X is defined as,

$$p_X(x) = \frac{d}{dx} F_X(x) \tag{7.1.2.1}$$

3. Let $X \sim \mathcal{N}(\mu, \sigma^2)$. Then the Q function is defined as,

$$Q(x) = \Pr(X > x), \quad x \ge 0$$
 (7.1.3.1)

7.2 Problems

1. Find

$$\Pr\left(|X - \mu| \le k\sigma\right) \tag{7.2.1.1}$$

in terms of Q function.

2. Find

$$\Pr\left(X \le x, |X - \mu| \le k\sigma\right) \tag{7.2.2.1}$$

in terms of $F_X(x)$

3. Find

$$F_X(x||X - \mu| \le k\sigma) \tag{7.2.3.1}$$

4. Find

$$p_X(x||X - \mu| \le k\sigma) \tag{7.2.4.1}$$

8 BIVARIATE GAUSSIAN

8.1 Definitions

1. Let

$$\mathbf{X} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \boldsymbol{\mu} = E(\mathbf{X}) \tag{8.1.1.1}$$

$$\Sigma_{\mathbf{x}} = E\left[(\mathbf{x} - \boldsymbol{\mu}) (\mathbf{x} - \boldsymbol{\mu})^{\mathsf{T}} \right]$$
 (8.1.1.2)

Then $\Sigma_{\mathbf{x}}$ is defined to be the *covariance* matrix of \mathbf{x} .

2. For $\mathbf{x} \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma}_{\mathbf{x}})$,

$$f_{\mathbf{X}}(\mathbf{x}) = \frac{1}{2\pi\sqrt{|\Sigma_{\mathbf{x}}|}} \exp{-\frac{1}{2}\left((\mathbf{x} - \boldsymbol{\mu})^{\top} \boldsymbol{\Sigma}_{\mathbf{x}}^{-1} (\mathbf{x} - \boldsymbol{\mu})\right)}$$
(8.1.2.1)

3. The correlation coefficient is defined as

$$\rho = \frac{E\left[(x_1 - \mu_1)(x_2 - \mu_2)\right]}{\sigma_1 \sigma_2} \tag{8.1.3.1}$$

where μ_i, σ_i^2 are the mean and variance of x_i .

- 8.2 Problems
 - 1. Show that

$$E\left[(\mathbf{x} - \boldsymbol{\mu}) (\mathbf{x} - \boldsymbol{\mu})^{\mathsf{T}} \right] = \begin{pmatrix} \sigma_1^2 & \rho \sigma_1 \sigma_2 \\ \rho \sigma_1 \sigma_2 & \sigma_2^2 \end{pmatrix}$$
(8.2.1.1)

- 2. Prove that $\Sigma_{\mathbf{x}}$ is a diagonal matrix when x_1 and x_2 are independent.
- 3. Let

$$z_1 = x_1 + x_2 \tag{8.2.3.1}$$

$$z_2 = x_1 - x_2 \tag{8.2.3.2}$$

Find \mathbf{P} such that

$$\mathbf{z} = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = \mathbf{P}\mathbf{x} \tag{8.2.3.3}$$

4. Show that

$$\Sigma_{\mathbf{z}} = \mathbf{P} \Sigma_{\mathbf{x}} \mathbf{P}^{\mathsf{T}} \tag{8.2.4.1}$$

- 5. Check the independence of z_1 and z_2 given that $\sigma_{x_1} = \sigma_{x_2}$.
- 6. Show that columns of P are eigenvectors of $\Sigma_z.$
- 7. Show that the eigenvectors of \mathbf{P} are orthogonal to each other.
- 8. Summarize your conclusion in one line.