

Digital IIR Filter Design



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IIR Band Pass Analog Filter

Abstract—The process of designing analog and digital filters is explained by designing a band-pass filter. IIR LPF,BPF filters are designed. All computations are done in Python. The Chebychev function is employed for designing the IIR filter.

1 Analog Filter Specifications

The filter specifications are available in Table I.

2 DIGITAL FILTER SPECIFICATION

2.1 Bilinear Tranformation

Problem 2.1. Obtain the fiter specifications in the ω domain.

Solution:

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$$\omega = 2\pi \frac{F}{F_s}. (2.1.1)$$

Problem 2.2. The Bilinear transformation is given by

$$s = \frac{1 - z^{-1}}{1 + z^{-1}} \tag{2.2.1}$$

If $s = 1\Omega$, $z = e^{J\omega}$, show that

$$\Omega = \tan \frac{\omega}{2} \tag{2.2.2}$$

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Item	Symbol	Value
Sampling Rate	F_s	48
		kHz
Pass Band Tolerance	δ_1	0.15
Stop Band Tolerance	δ_2	0.15
Passband Lower Cutoff	F_{p2}	6 kHz
Frequency		
Passband Higher Cutoff	F_{p1}	7.2
Frequency		kHz
Transition Band	ΔF	0.3
		kHz
Stopband Lower Cutoff	F_{s2}	5.7
Frequency		kHz
Stopband Higher Cutoff	F_{s1}	7.5
Frequency		kHz

TABLE I

Problem 2.3. Write a Python function to obtain the filter specifications in the Ω domain using (2.2.2) and save it in the file **F** omega.py.

Solution:

return ap1, ap2, as1, as2

3 IIR Low Pass Analog Filter

Problem 3.1. Transform the filter specifications from the bandpass Ω domain to the low pass Ω_L domain.

Solution:

$$\Omega_L = \frac{\Omega^2 - \Omega_0^2}{B\Omega}, \text{ where}$$
(3.1.1)

$$B = \Omega_{p1} - \Omega_{p2}, \Omega_0 = \sqrt{\Omega_{p1}\Omega_{p2}}$$
 (3.1.2)

Problem 3.2. For $\Omega_{s1}\Omega_{s2}$, (3.3.1) yields Ω_{Ls1} , Ω_{Ls2} . Obtain Ω_{Ls} , the low pass stopband cutoff from Ω_{Ls1} , Ω_{Ls2} .

Solution:

$$\Omega_{Ls} = \min(|\Omega_{Ls1}|, |\Omega_{Ls2}|). \tag{3.2.1}$$

Problem 3.3. Obtain Ω_{Lp} .

Solution:

$$\Omega_{Lp} = \frac{\Omega_{p1}^2 - \Omega_0^2}{R\Omega}$$
 (3.3.1)

Problem 3.4. Write a function in Python to obtain $B, \Omega_0, \Omega_{Lp}, \Omega_{Ls}$ from $\Omega_{p1}, \Omega_{p2}, \Omega_{s1}, \Omega_{s2}$. Save it in the file **Omegabp Omegalp.py**.

Solution:

Problem 3.5. The magnitude squared of the Chebychev low pass filter is

$$|H_{LP}(j\Omega_L)|^2 = \frac{1}{1 + \varepsilon^2 c_N^2 (\Omega_L / \Omega_{Lp})},$$
 (3.5.1)

where

$$c_N(x) = \cosh(N\cosh^{-1}x) \tag{3.5.2}$$

The filter parameters are defined to be N and ϵ . Express these in terms of δ_1 and δ_2 defined in Table I

Solution:

$$\frac{\sqrt{D_2}}{c_N(\Omega_{Ls})} \le \varepsilon \le \sqrt{D_1} \tag{3.5.3}$$

$$N \ge \left[\frac{\cosh^{-1}(\sqrt{D_2/D_1})}{\cosh^{-1}(\Omega_{L_s})} \right]$$
 (3.5.4)

where

$$D_1 = \frac{1}{(1 - \delta_1)^2} - 1, D_2 = \frac{1}{\delta_2^2} - 1$$
 (3.5.5)

Problem 3.6. Write a Python function to obtain $N, \varepsilon, \Omega_{Lp}$ and save it in the file titled **N_epsilon.py**.

Solution:

import numpy as np import math

from F_omega import f_Omega from Omegabp_Omegalp import Omega_blp

def parameters (Fp2, Fp1, df, d, Fs):

$$ap1$$
, $ap2$, $as1$, $as2=f_Omega(Fp1, Fp2, df, Fs)$

return N, R1, R2, alp

Problem 3.7. Given N and ε , find the analog IIR low pass Chebychev filter.

Solution:

$$H_{LP}(s) = \begin{cases} \frac{\Omega_{Lp}^{N} C_0 \prod_{k=1}^{(N-1)/2} C_k}{(s + \Omega_{Lp} C_0) \prod_{k=1}^{(N-1)/2} (s^2 + b_k \Omega_{Lp} s + C_k \Omega_{Lp}^2)} & N \text{ odd} \\ \frac{\Omega_{Lp}^{N} \prod_{k=1}^{(N)/2} C_k \frac{1}{\sqrt{1+s^2}}}{\prod_{k=1}^{(N)/2} (s^2 + b_k \Omega_{Lp} s + C_k \Omega_{Lp}^2)} & N \text{ even} \\ \frac{(3.7.1)}{(1+s^2)} & N \end{cases}$$

where

$$C_{0} = y_{N}$$

$$C_{k} = y_{N}^{2} + \cos^{2}((2k - 1)\pi/2N)$$

$$b_{k} = 2y_{N} \sin((2k - 1)\pi/2N)$$

$$y_{N} = \frac{1}{2} \left[\left[\sqrt{1 + \frac{1}{\varepsilon^{2}} + \frac{1}{\varepsilon}} \right]^{1/N} - \left[\sqrt{1 + \frac{1}{\varepsilon^{2}} + \frac{1}{\varepsilon}} \right]^{-1/N} \right]$$

$$(3.7.2)$$

$$(3.7.3)$$

$$(3.7.4)$$

Problem 3.8. Write a function for computing coefficients of numerator and denominator of (3.7.1) and save it in the file titled **Gen_LPF_Coeff.py**.

Solution:

```
import numpy as np
def filt design (N, e, alp):
    yN = (1/2.0) * ((np. sqrt (1+(1/e)
       **2))+(1/e))**(1/N)-(np. sqrt)
       (1+(1/e**2))+(1/e))**(-1/N)
    C0=yN
    C=[]
    b = []
    for k in range (1, (N/2) + 1):
        C. append (yN**2+np.cos)(2*k
            -1)*np.pi/(2.0*N))**2)
        b.append(2*yN*np.sin((2*k)))
            -1)*np.pi/(2.0*N))
    tot ck=1
    pole sum=1
    if (N\%2==0):
```

```
for k in range (N
                /2):
                      tot ck=
                         tot ck*C
                         [k]
                      pole sum=
                         pole sum
                         *np.
                         poly1d
                         ([1,b]k
                         ]* alp ,C[
                         k]*(alp
                         **2)])
             tot ck=np.poly1d
                ([0,1])*(alp**N)
                *tot ck*np.sqrt
                (1/(1+e**2))
             #pole sum=np.array
                (pole sum)
else:
             for k in range (N
                /2):
                      tot ck=
                         tot_ck*C
                         [k]
                      pole sum=
                         pole sum
                         *np.
                         poly1d
                         ([1,b]k
                         ] * alp ,C[
                         k]*(alp
                         **2)])
             tot ck=np.poly1d
                ([0,1])*(alp**N)
                *tot ck*C0
             pole sum=pole sum*
                np.poly1d([1, alp
                *C0])
return tot ck, pole sum
```

Problem 3.9. Plot (3.7.1) for N = 4 and different values of ε .

Solution:

```
import numpy as np import matplotlib.pyplot as plt
```

```
from N epsilon import parameters
from Gen LPF Coeff import
   filt design
#Passband Cutoffs
Fp2 = 6.0
Fp1 = 7.2
#Transition Band
df = 0.3
#Passband && stopband tolerance
d = 0.15
#sampling rate
Fs = 48
N,R1,R2,alp = parameters(Fp2,Fp1,
   df, d, Fs)
e array = np. linspace(R1, R2, 6)
Omga L=np.linspace (0,2,200)
s=1 j*Omga L
for e in e_array:
        b, a=filt design (N, e, alp)
        H lp=np.polyval(b,s)/np.
           polyval(a,s)
         plt.plot(Omga L, abs(H_lp),
            label=round(e,2))
plt.xlabel('$Frequency(\Omega)$')
plt.ylabel('$|H {lp}(j\Omega)|$')
plt.title('Magnitude_response_of_
  LPF_for_different_values_of_$\
   epsilon$')
plt.legend()
plt.grid()
plt.show()
```

Problem 3.10. What value of ε should be selected?

Solution: There is a trade-off between passband and stopband frequencies. So select the ε value which satisfies only passband frequency. For the above example we assume ε =0.6197

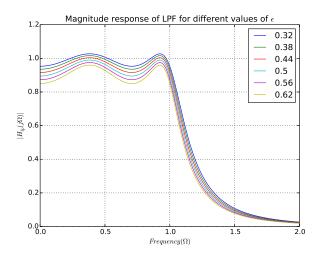


Fig. 3.9

4 IIR BAND PASS ANALOG FILTER

Problem 4.1. Obtain the band pass filter from low pass filter in (3.7.1)

Solution:

The analog band pass filter can be obtained from analog low pass filter as

$$H_{BP}(s) = H_{LP}(s_L)|_{s_L = \frac{s^2 + \Omega_0^2}{Bs}}$$
 (4.1.1)

Problem 4.2. Write a Python script for computing coefficients of analog BPF for N = 4, $\varepsilon = 0.6197$ and plot the magnitude response.

Solution:

import numpy as np
import matplotlib.pyplot as plt

from F_omega import f_Omega
from Omegabp_Omegalp import
 Omega_blp
from Gen_LPF_Coeff import
 filt_design

#Passband Cutoffs
Fp2=6.0
Fp1=7.2

#Transition Band
df=0.3

#Passband && stopband tolerance d=0.15

```
#sampling rate
Fs = 48
ap1, ap2, as1, as2=f Omega(Fp1, Fp2, df
ao, B, alp, als = Omega blp(ap1, ap2,
   as1, as2)
N=4
e = 0.6197
#coefficients of numerator and
   denominator polynomials of LPF
   filter
b, a=filt design(N, e, alp)
b=np.array(b)
a=np.array(a)
a1 = 0
for i in range (N+1):
         coeff = a[i] * (B**i) * (np.
            poly1d([1,0]))**(i)
         poly denom = (np. poly1d
            ([1,0,ao**2]))**(N-i)
         a1=a1+poly denom*coeff
numer = (np.poly1d([1,0]))**(N)
b1 = numer * (B**N) * b
np.savetxt('Numerator ABPF', np.
   array(b1))
np.savetxt('Denominator ABPF', np.
   array(a1))
Omga bp=np.linspace(-1,1,200)
s=1 j*Omga bp
H bp=np.polyval(b1,s)/np.polyval(
   a1,s)
s1=np. array ([1 j*ap1, 1 j*ap2, 1 j*as1)
   ,1 i*as2)
H point=np.polyval(b1, s1)/np.
   polyval(a1,s1)
pt = [5, -80, 5, -80]
for i in range(len(s1)):
        A = [np. around(abs(s1[i]),
```

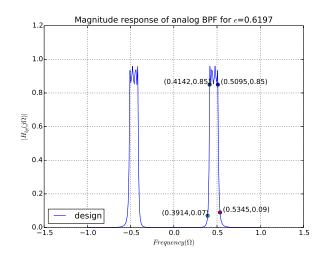


Fig. 4.2

```
decimals=4)
        B=[np.around(abs(H_point[i
            ), decimals = 2)
         plt . plot (A, B, 'o')
         for xy in zip(A,B):
                  plt.annotate('(%s
                     ,\% s) '\%xy , xy=xy ,
                     xytext = (pt[i], 1)
                      , textcoords='
                      offset points')
plt.plot(Omga bp, abs(H bp), 'b',
   label='design')
plt.xlabel('$Frequency(\Omega)$')
plt.ylabel('$|H {bp}(j\Omega)|$')
plt.title('Magnitude_response_of_
   analog \Box BPF \Box for \Box \$ \setminus epsilon \$ = 0.6197
   ')
plt.axis([-1.5, 1.5, 0, 1.2])
plt.legend(loc='lower_left')
plt.grid()
plt.show()
```

5 IIR DIGITAL BAND PASS FILTER

Problem 5.1. Obtain the IIR digital band pass filter from corresponding analog filter using Bilinear transformation.

Solution: The IIR digital BPF can be obtained from the analog BPF as

$$H_{BP}(z) = H_{BP}(s)|_{s = \frac{1-z^{-1}}{1+z^{-1}}}$$
 (5.1.1)

Problem 5.2. Write a Python script for finding the digital BPF coefficients from the analog BPF coefficients and plot the magnitude response of the digital BPF.

Solution:

```
import numpy as np
import matplotlib.pyplot as plt
#Passband Cutoffs
Fp2 = 6.0
Fp1 = 7.2
#Transition Band
df = 0.3
#Passband && stopband tolerance
d = 0.15
#sampling rate
Fs = 48
def W(Fs,F):
    w=2*float(F)/Fs
    return w
wp1=W(Fs, Fp1)
wp2=W(Fs, Fp2)
ws1=W(Fs, Fp1+df)
ws2=W(Fs, Fp2-df)
N=4
b1=np.loadtxt('Numerator ABPF')
al=np.loadtxt('Denominator ABPF')
a2 = 0
for i in range (2*N+1):
        coeff1=a1[i]*np.poly1d
            ([1,1])**i
        poly_denom1=np.poly1d
           ([-1,1])**(2*N-i)
        a2=a2+poly denom1*coeff1
b2 = (np.poly1d([-1,1])**N)*(np.
   poly1d([1,1])**N)*b1[0]
np.savetxt('Numerator DPBF', np.
   array(b2))
np.savetxt('Denominator DBPF', np.
```

```
array(a2))
w bp=np. linspace(-0.5, 0.5, 200)
z inv=np.exp(-1j*w_bp*np.pi)
H bp=np.polyval(b2,z_inv)/np.
   polyval(a2, z inv)
w point=np.array([wp1,wp2,ws1,ws2
z inv1=np.exp(-1j*w point*np.pi)
H point=np.polyval(b2,z inv1)/np.
   polyval(a2, z inv1)
pt = [1, -80, 1, -80]
for i in range(len(w_point)):
        A=[np.around(w point[i],
            decimals = 4)
        B=[np.around(abs(H point[i
            ), decimals = 2)
        plt . plot (A, B, 'o')
        for xy in zip(A,B):
                 plt.annotate('(%s
                    ,\% s) '\%xy , xy=xy ,
                    xytext = (pt[i], 1)
                     , textcoords='
                     offset_points')
plt.plot(w bp, abs(H bp), 'b', label=
   'design')
plt.xlabel('$Frequency(\omega/\pi)
plt.ylabel('$|H {bp}(\omega)|$')
plt.title('Magnitude_response_of_
   digital_BPF_for_$\epsilon$
   =0.6197')
plt. axis ([-1, 1, 0, 1])
plt.legend()
plt.grid()
plt.show()
```

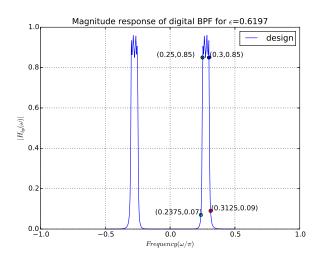


Fig. 5.2