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	1
$V_0 = \frac{V_{op}}{2} + \frac{V_{op}}{2} + \tanh \left(A(x)\right)$ $x = V_{ip} - V_{in}$	
$\frac{1}{\lambda}$ $\frac{1}{\lambda}$	
2-160 Vo = VDD	-
x-1-00 Vo =0	-
$\forall x \rightarrow \delta \qquad \forall_0 = \frac{\forall p}{2} + \frac{\forall p}{2} \cdot A(x)$	-
Vip Typo	-
Vino Tovo (megative feedback	2
(i) Vip = 1V	-
$Vin = 0$ $\rightarrow V_0 = 5V$	+
Agricultura of Landerschips	
(i) Vip = IV	-
Vin = V0 =) Vin=5V	38.55
If the Vin = Vo	
	1
0 VIP =1	
V ₀ = 5	
@ Vip=1	
V ₀ = 0	
3 Vip = 1	
Vo = 5-8	
9 Vo = &	
5 V ₀ = 5-28	
© 3 &	
at steady state $v_0 = IV$ (dose to 1 V)	
at steady state to = ((with to 1)	
V CALL A CALLED OF CALLED	

$$V_0 = \frac{V_{0D} + V_{DD} + V_{DD} + tanh [A (V_{1P} - V_{0})]}{2}$$
Let $V_0 = 2.5 + 2.5 + tanh [1000 (1-V_{0})]$

$$V_0 = 2.5 + 2.5 (1000) (1-V_{0})$$

$$V_0 (1 + 2500) = 2.5 + 2500$$

$$V_0 = 2502.5$$

$$2501$$

$$V_0 = 1.0006$$

$$V_0 = \frac{V_{DD} + V_{DD} - A(V_{1P} - V_{0})}{2}$$

$$V_0 (1 + \frac{AV_{0D}}{2}) = \frac{V_{0D} + V_{0}}{2}$$

$$V_0 = \frac{A - V_{0D} \cdot V_{1P}}{1 + A V_{0D}}$$
Sense voltage at the input and gives august
$$y = 2x_1 + 4x_2 + 6x_3$$

Vip + A

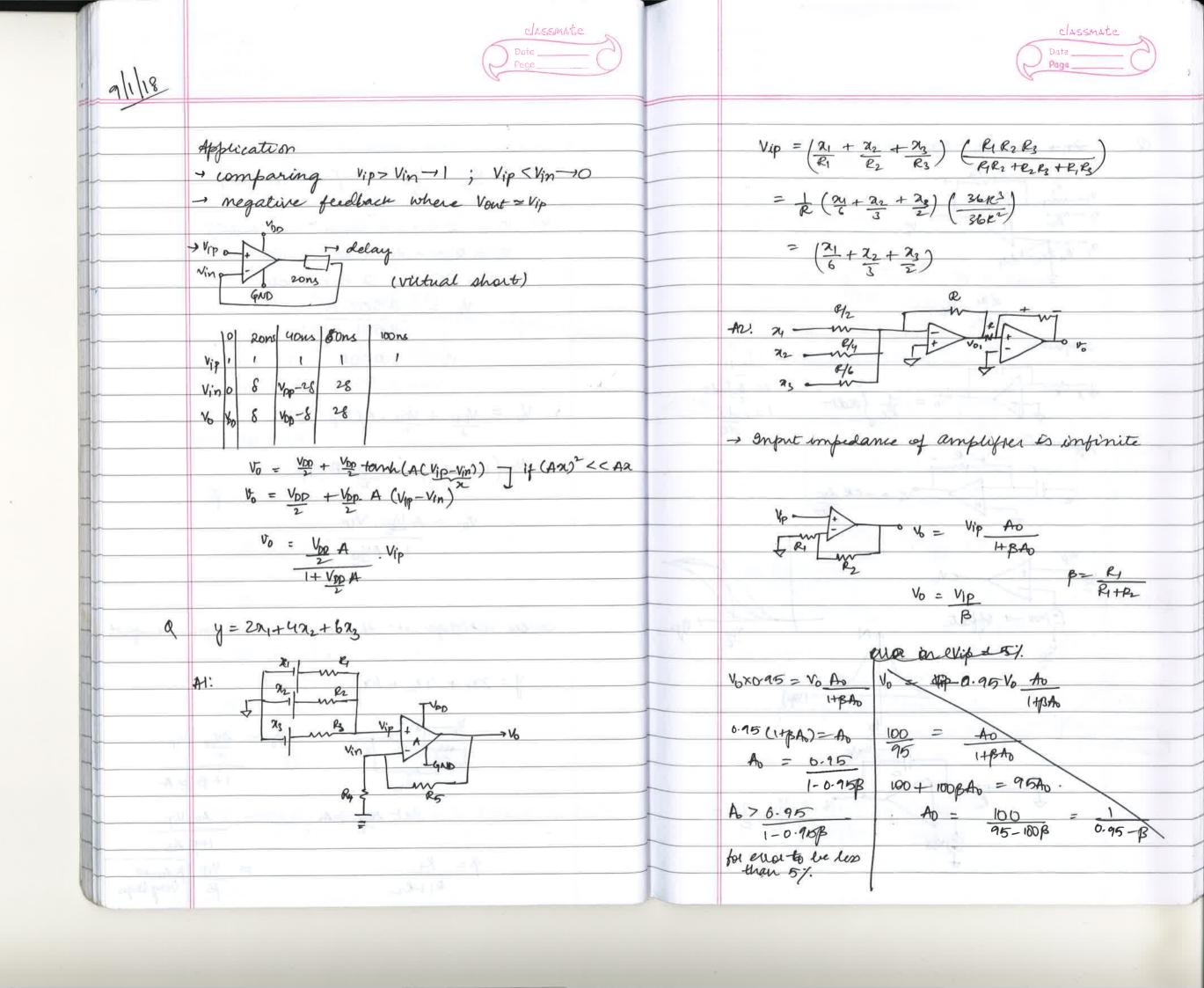
Vip A

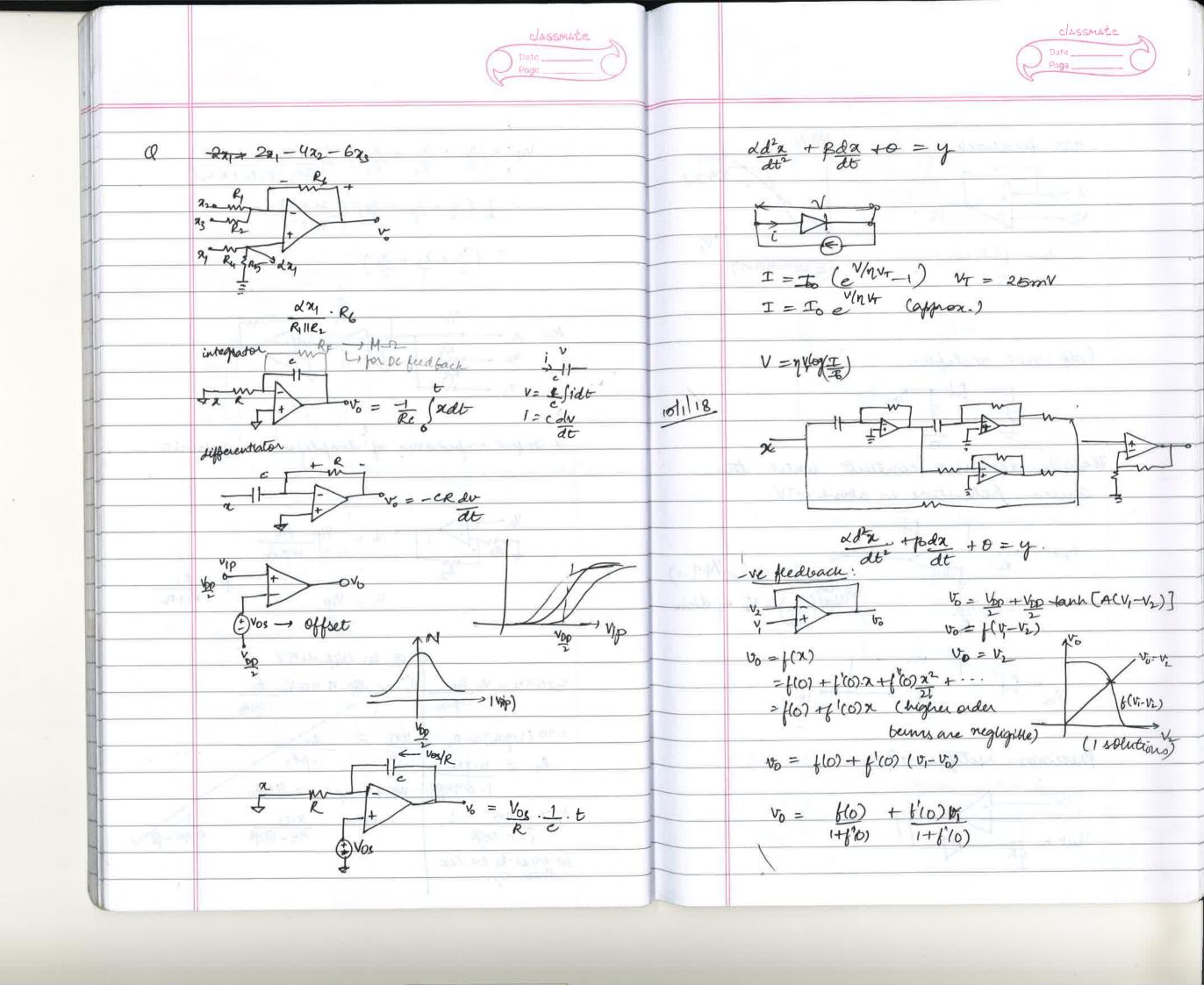
Let AVp = A

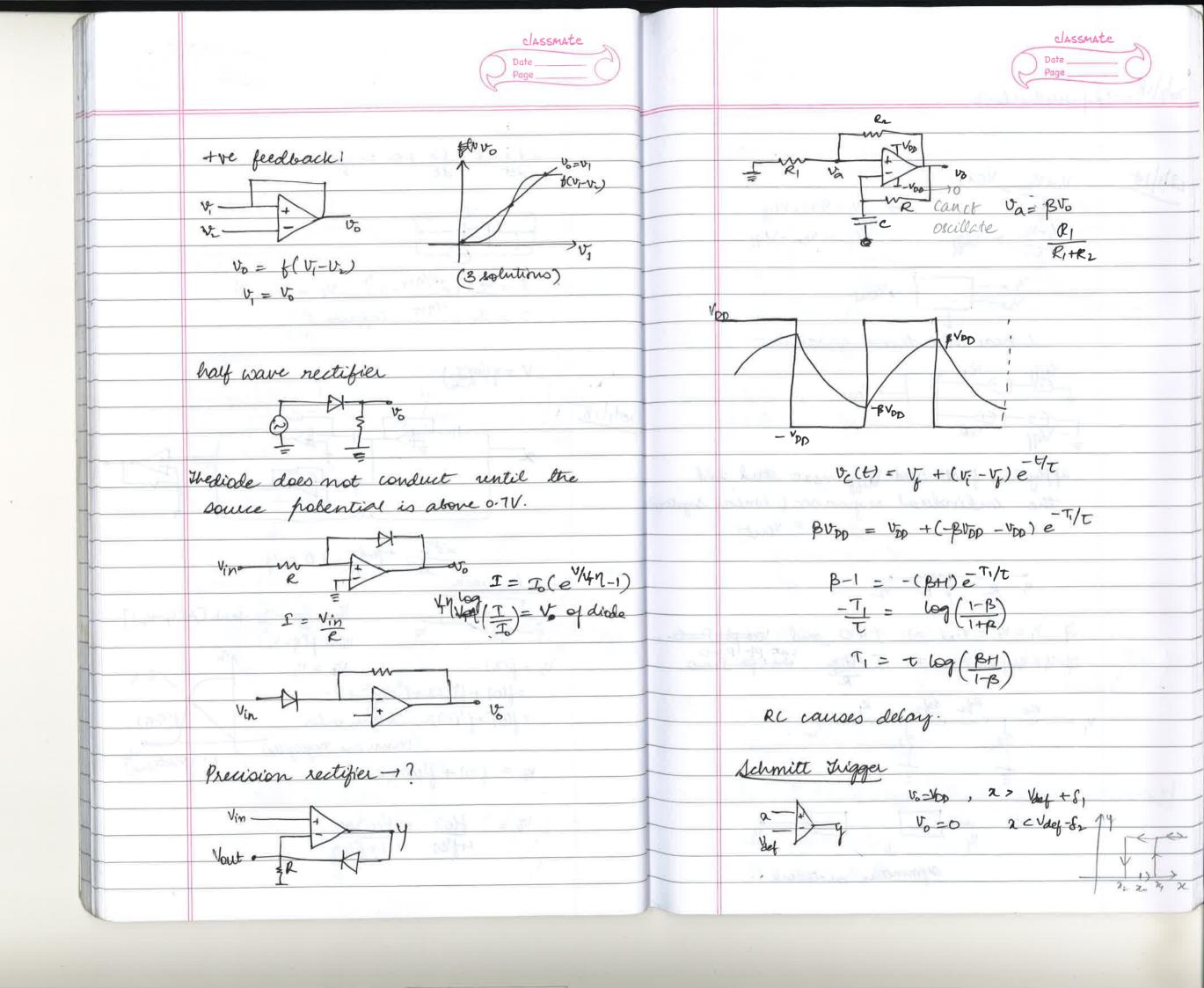
I+B Vp A

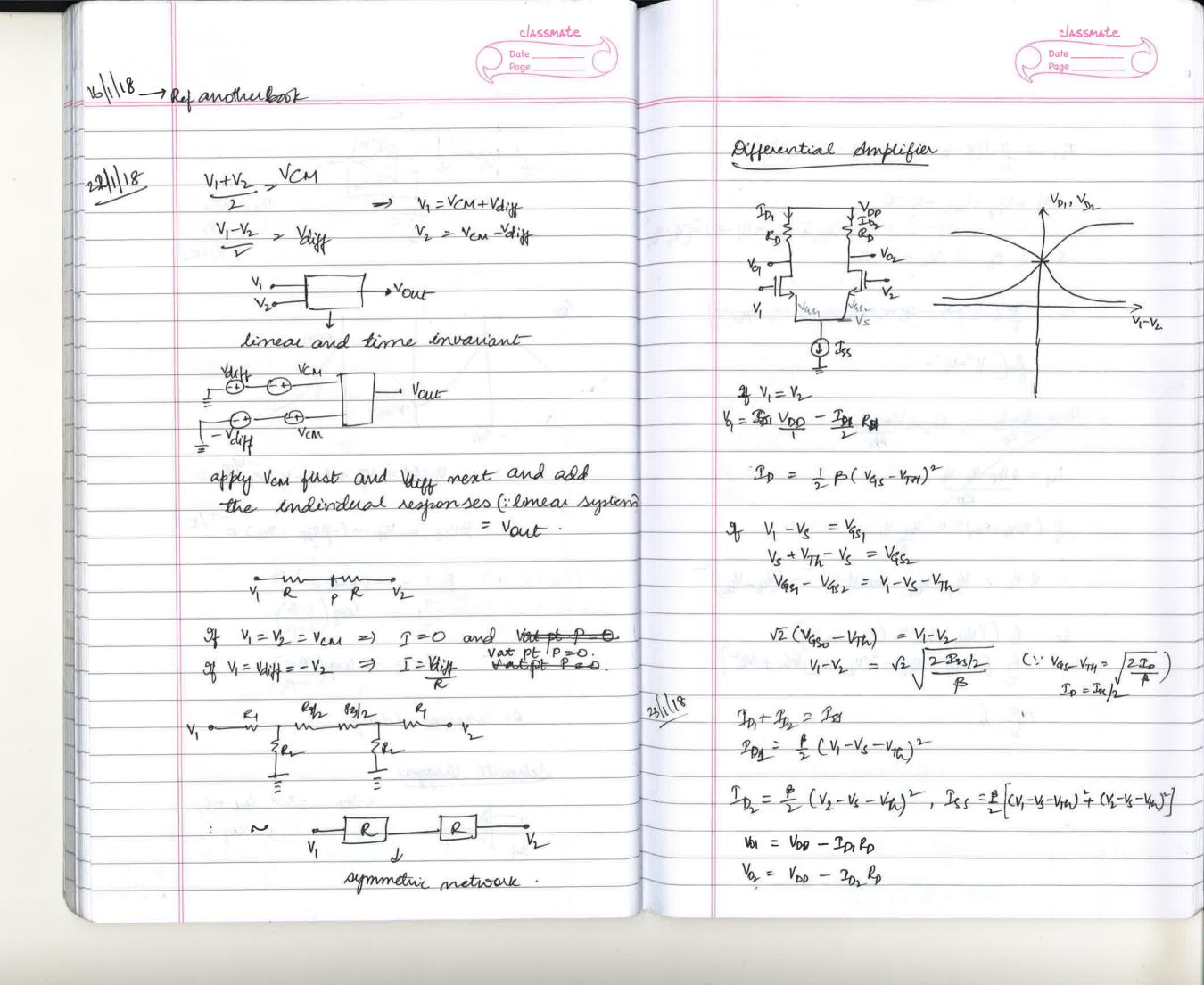
I+B Ao

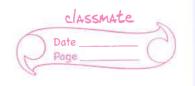
 $B = \frac{R_1}{R_1 + R_2}$ $\approx \frac{\text{Vip}}{B} | BADIS$ RIHR2 $\Rightarrow \text{Vip} | BADIS$ Very large













		1
2 = B [(4-18-44) + (1-1-1-1-1-1)2]		In = 1
-V1 +VG4 -VG52 +V2 =0		Vouti =
V ₁ - V ₂ = + 0 V _{(s1} - V _{(s1}) ² = (V _s -V _s) ² = (H	Vout, =
Va+ Ip, ep = Vox + Iozep.		Let VI-V
In = 8[V12+V22-2(V1+V2)(V3+V4h) + (V3+V1A)2]		Vout,
= B (V + V2		dvown
$\overline{D}_{P} = \frac{V_{DO} - V_{O}}{R_{D}}, \overline{D}_{D} > \frac{V_{DO} - V_{O}}{R_{D}}.$		dibuti
RO RS.		dr
In = a Vop Vo - Voz	20	dunat ne
PD (4-1/4-1/4/)2 = 1/40-1/01 PD	-	+
V1-V2 = Vag-Vasz => (V1-V2) = (Vag-Vasz)2	E)n:	-0.0
Iss = B ((Vas, - Vin) 2+ (Vare-4/2)]		24°
= Bz [Vas, + Vas, - 2(Vas, + Vas,) 4th + 24h2]		\$ Vout,
= B C	1	67.4
2		and the
		2 >
Line we use the state of the second state of t	_	2 =
$u_{ij} = x_{ij}x_{ij} = x_{ij}x_{ij}$	lad in	JB

$$\begin{split} & D_{0} = \frac{T_{SS}}{2} + \frac{V_{1} - V_{2}}{4} \int \beta \left(u T_{18} - \beta \left(V_{1} - V_{1} \right)^{2} \right) \\ & but_{1} = V_{DD} - T_{DR} p \\ & V_{OUT_{1}} = V_{DD} - R_{D} \left(\frac{T_{12}}{2} + \frac{4}{4} \sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} \right) \\ & Let V_{1} - V_{2} = 2. \\ & V_{OUT_{1}} = V_{DD} - R_{D} \left(\frac{T_{13}}{2} + \frac{2}{4} \sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{dV_{OUT_{1}}}{dx} = 0 - R_{D} \left(0 + \frac{1}{4} \sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{dV_{DUT_{1}}}{dx} = - \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{dV_{DUT_{1}}}{dx} = - \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{dV_{DUT_{1}}}{dx} = - \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4} \right) \\ & \frac{1}{4} \left(\sqrt{\beta \left(u T_{13} - \beta x^{2} \right)} + 2 + \frac{\beta^{2} (X_{13})}{4}$$

100×101 × 240= 10000 = 5×10

