CONTROL SYSTEMS 2018 Q.29 (EC SECTION)

K SRIKANTH EE18BTECH11023

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QUESTION 2018 Q.29 (EC SECTION)

• The state equation and the output equation of a control system are given below:

$$\dot{X} = \left[\begin{array}{cc} -4 & -1.5 \\ 4 & 0 \end{array} \right] X + \left[\begin{array}{c} 4 \\ 0 \end{array} \right] U$$

$$Y = \begin{bmatrix} 1.5 & 0.625 \end{bmatrix} X$$

Then transfer function representation of the system is

(A)
$$\frac{(3s+5)}{(s^2+4s+6)}$$

(B)
$$\frac{(3s-1.875)}{(s^2+4s+6)}$$

(C)
$$\frac{(4s+1.5)}{(s^2+4s+6)}$$

(D)
$$\frac{(6s+5)}{(s^2+4s+6)}$$

• From the given state space representation of the system, we can find matrices as

$$A = \begin{bmatrix} -4 & -1.5 \\ 4 & 0 \end{bmatrix}, B = \begin{bmatrix} 4 \\ 0 \end{bmatrix}, C = \begin{bmatrix} 1.5 & 0.625 \end{bmatrix}$$

when

$$\dot{X} = AX + BU$$
$$Y = CX + DU$$

where A, B, C, D are matrices Then the transfer function can be find using

$$T(s) = C[(sI - A)^{-1}].B + D$$

We can find the transfer function using

$$T(s) = C[(sI - A)^{-1}].B$$
(1)

$$(sI - A) = \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} -4 & -1.5 \\ 4 & 0 \end{bmatrix}$$
$$(sI - A) = \begin{bmatrix} s+4 & -1.5 \\ -4 & s \end{bmatrix}$$
(2)

$$|sI - A| = s(s+4) - (-4) \times (-1.5)$$

$$= s^2 + 4s + 6 (3)$$

$$Adj[sI - A] = \begin{bmatrix} s & -1.5 \\ 4 & s+4 \end{bmatrix}$$

Hence

$$[sI - A]^{-1} = \frac{Adj[sI - A]}{|sI - A|} = \begin{bmatrix} \frac{s}{(s^2 + 4s + 6)} & \frac{-1.5}{(s^2 + 4s + 6)} \\ \frac{4}{(s^2 + 4s + 6)} & \frac{(s + 4)}{(s^2 + 4s + 6)} \end{bmatrix}$$
(4)

$$[sI - A]^{-1}.B = \begin{bmatrix} \frac{s}{(s^2 + 4s + 6)} & \frac{-1.5}{(s^2 + 4s + 6)} \\ \frac{4}{(s^2 + 4s + 6)} & \frac{(s + 4)}{(s^2 + 4s + 6)} \end{bmatrix} \begin{bmatrix} 4 \\ 0 \end{bmatrix}$$
 (5)

$$[sI - A]^{-1}.B = \begin{bmatrix} \frac{2s}{(s^2 + 4s + 6)} \\ \frac{8}{(s^2 + 4s + 6)} \end{bmatrix}$$
 (6)

Substituting values of $[sI - A]^{-1}$. B and C in equation (1)

$$T(s) = \begin{bmatrix} 1.5 & 0.625 \end{bmatrix} \begin{bmatrix} \frac{2s}{(s^2 + 4s + 6)} \\ \frac{8}{(s^2 + 4s + 6)} \end{bmatrix}$$
 (7)

$$T(s) = \left[\frac{3s}{(s^2+4s+6)} + \frac{5}{(s^2+4s+6)} \right]$$

 $the \, transfer \, function \, representation \, of \, the \, system \, is$

$$\mathbf{T(s)} = \left[\begin{array}{c} 3s+5 \\ \hline (s^2+4s+6) \end{array} \right] \tag{8}$$