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# Timing Offset Synchronization using Gardner Timing Error Detector (TED) Algorithm

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### 1. TIME OFFSET: GARDNER TED

Let the *m*th sample in the *r*th received symbol time slot be

$$Y_k(m) = X_k + V_k(m), \quad k = 1, ..., N, m = 1, ..., M.$$
(1.1)

where  $X_k$  is the transmitted symbol in the kth time slot and  $V_k(m) \sim \mathcal{N}(0, \sigma^2)$ . The decision variable for the kth symbol is

$$U_k = Y_{k-1} \left( \frac{M}{2} \right) [Y_k (M) - Y_{k-1} (M)]$$
 (1.2)

### A. Plots

2. Frequency Offset: LR Technique Let the frequency offset be  $\Delta f$  [1]. Then

$$Y_k = X_k e^{j2\pi\Delta f k M} + V_k, \quad k = 1, ..., N$$
 (2.1)

From (2.1),

$$Y_k X_k^* = |X_k|^2 e^{j2\pi\Delta f k M} + X_k^* V_k$$
 (2.2)

$$\implies r_k = e^{j2\pi\Delta fkM} + \bar{V}_k \tag{2.3}$$

where

$$r_k = Y_k X_k^*, \bar{V}_k = X_k^* V_k, |X_k|^2 = 1$$
 (2.4)

The autocorrelation can be calculated as

$$R(k) \stackrel{\Delta}{=} \frac{1}{N-k} \sum_{i=k+1}^{N} r_i r_{i-k}^*, 1 \le k \le N-1$$
 (2.5)

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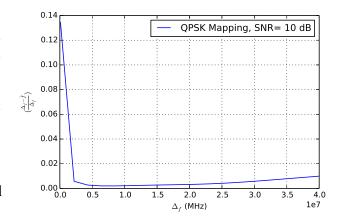


Fig. 1: Error variation with respect to frequency offset.

Where N is the length of the received signal. For large centre frequency, the following yields a good approximation for frequency offset upto 40 MHz.

$$\Delta \hat{f} \approx \frac{1}{2\pi M} \frac{\sum_{k=1}^{P} \text{Im}(R(k))}{\sum_{k=1}^{P} k \text{Re}(R(k))}, \quad P\Delta fM << 1 \quad (2.6)$$

where P is the number of pilot symbols.

## A. Plots

The number of pilot symbols is P = 18. The codes for generating the plots are available at

Fig. 1 shows the variation of the error in the offset estimate with respect to the offset  $\Delta f$  when the SNR = 10 dB. Similarly Fig. ?? shows the variation of the error with respect to the SNR for  $\Delta f = 5MHz$ .

#### REFERENCES

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- [2] U. Mengali and A. N. D'Andrea: synchronization Techniques for Digital Receivers, New York: Plenum, 1997.

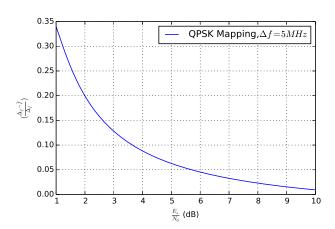


Fig. 2:  $\Delta f = 5$  MHz