1

Timing Offset Synchronization using Gardner Timing Error Detector(TED) Algorithm.

Theresh Babu Benguluri and G V V Sharma*

CONTENTS

1. Gardner TED

A. Transmitter

$$P = \sin\left(2\pi \frac{[0:T_{sym} - 1]}{2T_{sym}}\right) \tag{1.0.1}$$

Where T_{sym} is the samples per symbol. P is the half sine pulse shaping filter.

$$X = P \circledast C \tag{1.0.2}$$

Where *C* is upsampled by *T sym* to the mapped data. And *X* is the convolution of pulse shaping filter and interpolated data. main equation

B. Receiver

$$Y = X + N \tag{1.0.3}$$

Where Y is the received vector.

$$U_{I}(r) = Y_{I}(r - 0.5) [Y_{I}(r) - Y_{I}(r - 1)]$$

$$+ Y_{O}(r - 0.5) [Y_{O}(r) - Y_{O}(r - 1)]$$
(1.0.4)

Where r is the symbol index number. $Y_I(r - 0.5)$ is the mid sample between $Y_I(r)$ and $Y_I(r - 1)$.

2. Derivation

$$\begin{split} U_{t}(r) &= L(r-1) - E(r) \\ &= Y^{2}(\tau + (r-1)T_{sym}) - Y^{2}(\tau + rT_{sym}) \quad (2.0.7) \\ &+ 2Y(\tau + (r-0.5)T_{sym}) \left\{ Y(\tau + rT_{sym}) - Y(\tau + (r-1)T_{sym}) \right\} \\ &\qquad (2.0.8) \end{split}$$

*The authors are with the Department of Electrical Engineering, Indian Institute of Technology, Hyderabad 502285 India e-mail: gadepall@iith.ac.in.

Average over many samples, first two terms are equal.

$$U_t(r) = Y(\tau + (r - 0.5)T_{sym}) \left\{ Y(\tau + rT_{sym}) - Y(\tau + (r - 1)T_{sym} \right\}$$

$$= Y(r - 0.5) \left\{ Y(r) - Y(r - 1) \right\}$$
(2.0.10)