



Q.9 Given a semicircle with O as the centre, as shown in the figure, the ratio  $\frac{\overline{AC} + \overline{CB}}{\overline{AB}}$  is \_\_\_\_\_ where  $\overline{AC}$ ,  $\overline{CB}$  and  $\overline{AB}$  are chords.

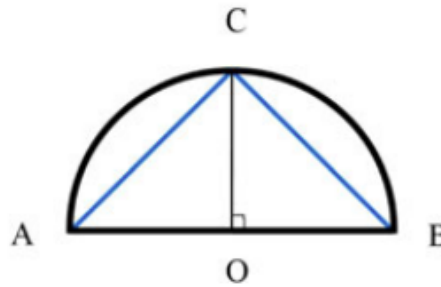


Fig. 1.

- a)  $\sqrt{2}$                       b)  $\sqrt{3}$                       c) 2                      d) 3

(GATE GA 2020)

Q.10 The revenue and expenditure of four different companies P, Q, R and S in 2015 are shown in the figure. If the revenue of company Q in 2015 was 20% more than that in 2014, and company Q had earned a profit of 10% on expenditure in 2014, then its expenditure (in million rupees) in 2014 was \_\_\_\_\_.

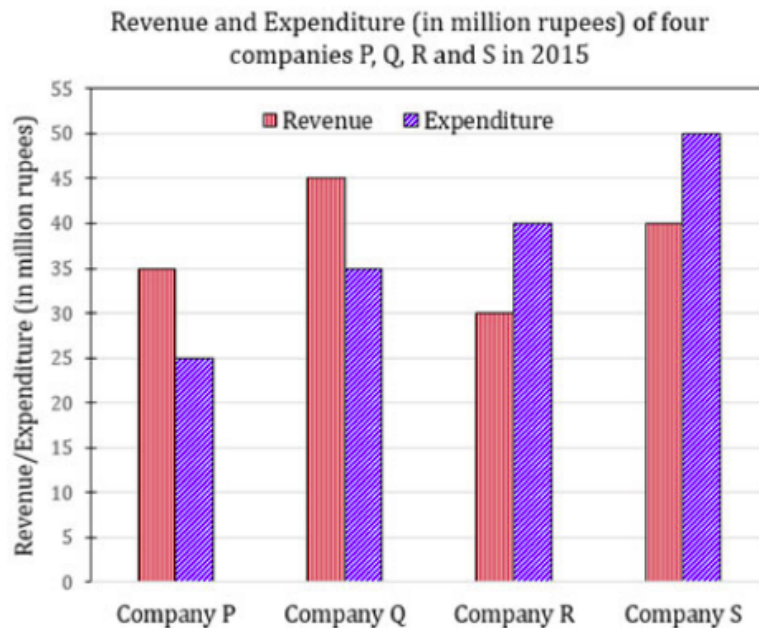


Fig. 2.

- a) 32.7                      c) 34.1  
b) 33.7                      d) 35.1

(GATE GA 2020)

Q.11  $ax^3 + bx^2 + cx + d$  is a polynomial on real  $x$  over real coefficients  $a, b, c, d$  wherein  $a \neq 0$ . Which of the following statements is true?

- a) d can be chosen to ensure that  $x = 0$  is a root for any given set a, b, c.
- b) No choice of coefficients can make all roots identical.
- c) a, b, c, d can be chosen to ensure that all roots are complex.
- d) c alone cannot ensure that all roots are real.

(GATE EE 2020)

Q.12 Which of the following is true for all possible non-zero choices of integers  $m, n; m \neq n$ , or all possible non-zero choices of real numbers  $p, q; p \neq q$ , as applicable?

- a)  $\frac{1}{\pi} \int_0^\pi \sin m\theta \sin n\theta d\theta = 0$
- b)  $\frac{1}{2\pi} \int_{-\pi/2}^{\pi/2} \sin p\theta \sin q\theta d\theta = 0$
- c)  $\frac{1}{2\pi} \int_{-\pi}^\pi \sin p\theta \cos q\theta d\theta = 0$
- d)  $\lim_{\alpha \rightarrow \infty} \frac{1}{2\alpha} \int_{-\alpha}^\alpha \sin p\theta \sin q\theta d\theta = 0$

(GATE EE 2020)

Q.13 Which of the following statements is true about the two sided Laplace transform?

- a) It exists for every signal that may or may not have a Fourier transform.
- b) It has no poles for any bounded signal that is non-zero only inside a finite time interval.
- c) The number of finite poles and finite zeroes must be equal.
- d) If a signal can be expressed as a weighted sum of shifted one sided exponentials, then its Laplace Transform will have no poles.

(GATE EE 2020)

Q.14 Consider a signal  $x[n] = \left(\frac{1}{2}\right)^n 1[n]$ , where  $1[n] = 0$  if  $n < 0$  and  $1[n] = 1$  if  $n \geq 0$ . The z-transform of  $x[n - k]$ ,  $k > 0$  is  $\frac{z^{-k}}{1 - \frac{1}{2}z^{-1}}$  with region of convergence being \_\_\_\_\_.

- a)  $|z| < 2$
- b)  $|z| > 2$
- c)  $|z| < 1/2$
- d)  $|z| > 1/2$

(GATE EE 2020)

Q.15 The value of the following complex integral, with C representing the unit circle centered at origin in the counterclockwise sense, is:

$$\int_C \frac{z^2 + 1}{z^2 - 2z} dz$$

- a)  $8\pi i$
- b)  $-8\pi i$
- c)  $-\pi i$
- d)  $\pi i$

(GATE EE 2020)

Q.16  $x_R$  and  $x_A$  are, respectively, the rms and average values of  $x(t) = x(t - T)$ , and similarly,  $y_R$  and  $y_A$  are, respectively, the rms and average values of  $y(t) = kx(t)$ . k, T are independent of t. Which of the following is true?

- a)  $y_A = kx_A; y_R = kx_R$
- b)  $y_A = kx_A; y_R \neq kx_R$
- c)  $y_A \neq kx_A; y_R = kx_R$
- d)  $y_A \neq kx_A; y_R \neq kx_R$

(GATE EE 2020)

Q.17 A three-phase cylindrical rotor synchronous generator has a synchronous reactance  $X_s$  and a negligible armature resistance. The magnitude of per phase terminal voltage is  $V_A$  and the magnitude of per phase induced emf is  $E_A$ . Considering the following two statements, P and Q,

P: For any three-phase balanced leading load connected across the terminals of this synchronous generator,  $V_A$  is always more than  $E_A$ .

Q: For any three-phase balanced lagging load connected across the terminals of this synchronous generator,  $V_A$  is always less than  $E_A$ .

which of the following options is correct?

- a) P is false and Q is true.
- b) P is true and Q is false.
- c) P is false and Q is false.
- d) P is true and Q is true.

(GATE EE 2020)

Q.18 A lossless transmission line with 0.2 pu reactance per phase uniformly distributed along the length of the line, connecting a generator bus to a load bus, is protected up to 80% of its length by a distance relay placed at the generator bus. The generator terminal voltage is 1 pu. There is no generation at the load bus. The threshold pu current for operation of the distance relay for a solid three phase-to-ground fault on the transmission line is closest to:

- a) 1.00
- b) 3.61
- c) 5.00
- d) 6.25

(GATE EE 2020)

Q.19 Out of the following options, the most relevant information needed to specify the real power ( $P$ ) at the PV buses in a load flow analysis is

- a) solution of economic load dispatch
- b) rated power output of the generator
- c) rated voltage of the generator
- d) base power of the generator

(GATE EE 2020)

Q.20 Consider a linear time-invariant system whose input  $r(t)$  and output  $y(t)$  are related by the following differential equation:

$$\frac{d^2y(t)}{dt^2} + 4y(t) = 6r(t)$$

The poles of this system are at

- a)  $+2j, -2j$
- b)  $+2, -2$
- c)  $+4, -4$
- d)  $+4j, -4j$

(GATE EE 2020)

Q.21 A single-phase, full-bridge diode rectifier fed from a 230 V, 50 Hz sinusoidal source supplies a series combination of finite resistance,  $R$ , and a very large inductance,  $L$ . The two most dominant frequency components in the source current are:

- a) 50 Hz, 0 Hz
- b) 50 Hz, 100 Hz
- c) 50 Hz, 150 Hz
- d) 150 Hz, 250 Hz

(GATE EE 2020)

Q.22 Thyristor  $T_1$  is triggered at an angle  $\alpha$  (in degree), and  $T_2$  at angle  $180^\circ + \alpha$ , in each cycle of the sinusoidal input voltage. Assume both thyristors to be ideal. To control the load power over the range 0 to 2 kW, the minimum range of variation in  $\alpha$  is:





Q.28 Currents through ammeters A2 and A3 in the figure are  $1\angle 10^\circ$  and  $1\angle 70^\circ$ , respectively. The reading of the ammeter A1 rounded off to 3 decimal places is \_\_\_\_\_ A.

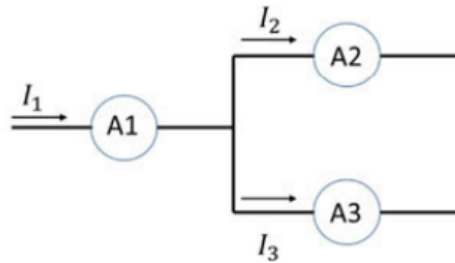


Fig. 5.

(GATE EE 2020)

Q.29 The Thevenin equivalent voltage,  $V_{TH}$ , in V (rounded off to 2 decimal places) of the network shown below, is \_\_\_\_\_.

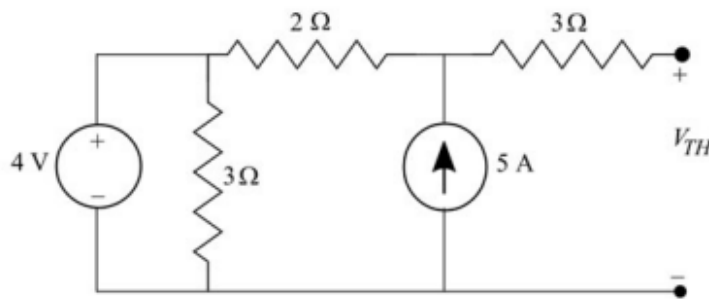


Fig. 6.

(GATE EE 2020)

Q.30 A double pulse measurement for an inductively loaded circuit controlled by the IGBT switch is carried out to evaluate the reverse recovery characteristics of the diode, D, represented approximately as a piecewise linear plot of current vs time at diode turn-off.  $L_{par}$  is a parasitic inductance due to the wiring of the circuit, and is in series with the diode. The point on the plot (indicate your choice by entering 1, 2, 3 or 4) at which the IGBT experiences the highest current stress is \_\_\_\_\_.

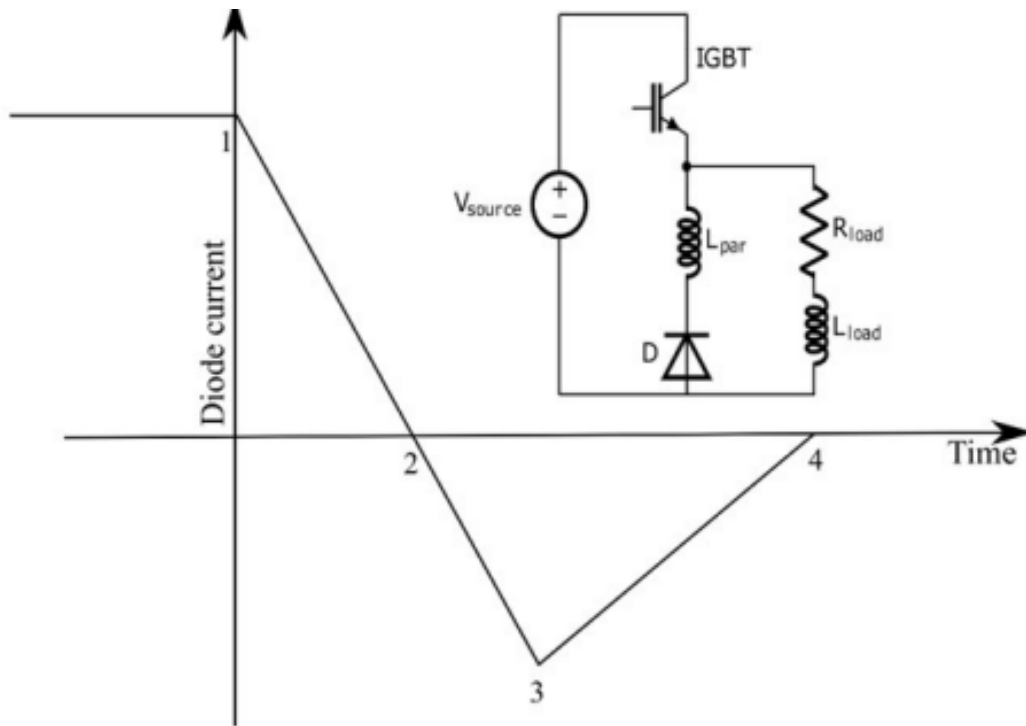


Fig. 7.

(GATE EE 2020)

- Q.31 A single-phase, 4 kVA, 200 V/100 V, 50 Hz transformer with laminated CRGO steel core has rated no-load loss of 450 W. When the high-voltage winding is excited with 160 V, 40 Hz sinusoidal ac supply, the no-load losses are found to be 320 W. When the high-voltage winding of the same transformer is supplied from a 100 V, 25 Hz sinusoidal ac source, the no-load losses will be \_\_\_\_\_ W (*rounded off to 2 decimal places*).

(GATE EE 2020)

- Q.32 A single-phase inverter is fed from a 100 V dc source and is controlled using a quasi-square wave modulation scheme to produce an output waveform,  $v(t)$ , as shown. The angle  $\sigma$  is adjusted to entirely eliminate the 3<sup>rd</sup> harmonic component from the output voltage. Under this condition, for  $v(t)$ , the magnitude of the 5<sup>th</sup> harmonic component as a percentage of the magnitude of the fundamental component is \_\_\_\_\_ (*rounded off to 2 decimal places*).



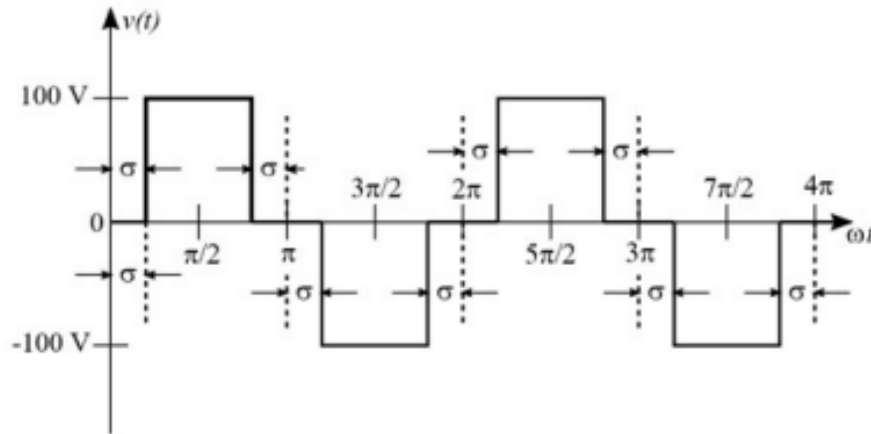


Fig. 8.

(GATE EE 2020)

- Q.33 A single 50 Hz synchronous generator on droop control was delivering 100 MW power to a system. Due to increase in load, generator power had to be increased by 10 MW, as a result of which, system frequency dropped to 49.75 Hz. Further increase in load in the system resulted in a frequency of 49.25 Hz. At this condition, the power in MW supplied by the generator is \_\_\_\_\_ (rounded off to 2 decimal places).

(GATE EE 2020)

- Q.34 Consider a negative unity feedback system with forward path transfer function

$$G(s) = \frac{K}{(s+a)(s-b)(s+c)},$$

where  $K, a, b, c$  are positive real numbers. For a Nyquist path enclosing the entire imaginary axis and right half of the  $s$ -plane in the clockwise direction, the Nyquist plot of  $(1 + G(s))$ , encircles the origin of  $(1 + G(s))$ -plane once in the clockwise direction and never passes through this origin for a certain value of  $K$ . Then, the number of poles of  $\frac{G(s)}{1 + G(s)}$  lying in the open right half of the  $s$ -plane is \_\_\_\_\_.

(GATE EE 2020)

- Q.35 The cross-section of a metal-oxide-semiconductor structure is shown schematically. Starting from an uncharged condition, a bias of +3 V is applied to the gate contact with respect to the body contact. The charge inside the silicon dioxide layer is then measured to be  $+Q$ . The total charge contained within the dashed box shown, upon application of bias, expressed as a multiple of  $Q$  (absolute value in Coulombs, rounded off to the nearest integer) is \_\_\_\_\_.



- b)  $\begin{pmatrix} t_i t_j Y & -t_j^2 Y \\ -t_i^2 Y & t_i t_j Y \end{pmatrix}$   
 c)  $\begin{pmatrix} t_i^2 Y & -t_i t_j Y \\ -t_i t_j Y & t_j^2 Y \end{pmatrix}$   
 d)  $\begin{pmatrix} -t_i^2 Y & t_i t_j Y \\ t_i t_j Y & -t_j^2 Y \end{pmatrix}$

(GATE EE 2020)

Q.40 Consider the diode circuit shown below. The diode, D, obeys the current-voltage characteristic  $I_D = I_S \left( \exp\left(\frac{V_D}{nV_T}\right) - 1 \right)$ , where  $n > 1$ ,  $V_T > 0$ ,  $V_D$  is the voltage across the diode and  $I_D$  is the current through it. The circuit is biased so that voltage,  $V > 0$  and current,  $I < 0$ . If you had to design this circuit to transfer maximum power from the current source  $I_1$  to a resistive load (not shown) at the output, what values of  $R_1$  and  $R_2$  would you choose(?)

- a) Large  $R_1$  and large  $R_2$ .  
 b) Small  $R_1$  and small  $R_2$ .  
 c) Large  $R_1$  and small  $R_2$ .  
 d) Small  $R_1$  and large  $R_2$ .

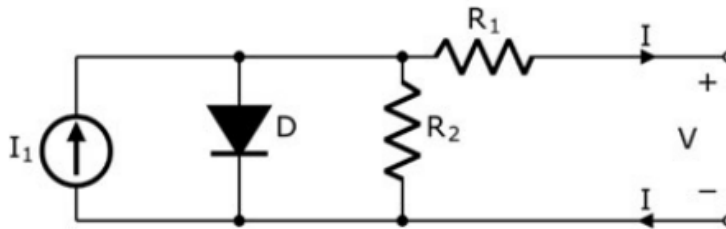


Fig. 11.

(GATE EE 2020)

Q.41 A non-ideal diode is biased with a voltage of  $-0.03\text{ V}$ , and a diode current of  $I_1$  is measured. The thermal voltage is  $26\text{ mV}$  and the ideality factor for the diode is  $15/13$ . The voltage, in  $\text{V}$ , at which the measured current increases to  $1.5I_1$ , is closest to

- a)  $-0.02$   
 b)  $-0.09$   
 c)  $-1.50$   
 d)  $-4.50$

(GATE EE 2020)

Q.42 A benchtop dc power supply acts as an ideal  $4\text{ A}$  current source as long as its terminal voltage is below  $10\text{ V}$ . Beyond this point, it begins to behave as an ideal  $10\text{ V}$  voltage source for all load currents going down to  $0\text{ A}$ . When connected to an ideal rheostat, find the load resistance value at which maximum power is transferred, and the corresponding load voltage and current.

- a) Short,  $0\ \Omega$ ,  $10\text{ V}$   
 b) Open,  $4\text{ A}$ ,  $0\text{ V}$   
 c)  $2.5\ \Omega$ ,  $4\text{ A}$ ,  $10\text{ V}$   
 d)  $2.5\ \Omega$ ,  $4\text{ A}$ ,  $5\text{ V}$

(GATE EE 2020)

Q.43 The static electric field inside a dielectric medium with relative permittivity,  $\epsilon_r = 2.25$ , expressed in cylindrical coordinate system is given by the following expression

$$\mathbf{E} = a_r 2r + a_\phi \left( \frac{3}{r} \right) + a_z 6$$

where  $a_r, a_\phi, a_z$  are unit vectors along  $r, \phi$  and  $z$  directions, respectively. If the above expression represents a valid electrostatic field inside the medium, then the volume charge density associated with this field in terms of free space permittivity,  $\epsilon_0$ , in SI units is given by( )

- a)  $3\epsilon$
- b)  $4\epsilon$
- c)  $5\epsilon$
- d)  $9\epsilon$

(GATE EE 2020)

Q.44 Consider a permanent magnet dc (PMDC) motor which is initially at rest. At  $t = 0$ , a dc voltage of  $5\text{ V}$  is applied to the motor. Its speed monotonically increases from  $0\text{ rad/s}$  to  $6.32\text{ rad/s}$  in  $0.5\text{ s}$  and finally settles to  $10\text{ rad/s}$ . Assuming that the armature inductance of the motor is negligible, the transfer function for the motor is

- a)  $\frac{10}{0.5s + 1}$
- b)  $\frac{2}{0.5s + 1}$
- c)  $\frac{2}{s + 0.5}$
- d)  $\frac{10}{s + 0.5}$

(GATE EE 2020)

Q.45 Which of the following options is correct for the system shown below?

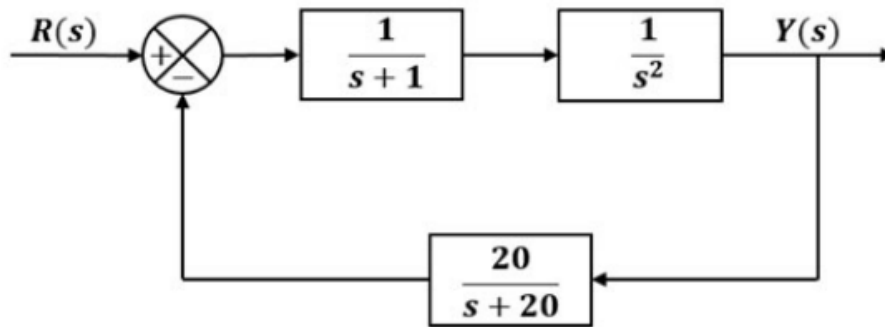


Fig. 12.

- a) 4th order and stable
- b) 3rd order and stable
- c) 4th order and unstable
- d) 3rd order and unstable

(GATE EE 2020)

Q.46 Consider a negative unity feedback system with the forward path transfer function

$$\frac{s^2 + s + 1}{s^3 + 2s^2 + 2s + K},$$

where  $K$  is a positive real number. The value of  $K$  for which the system will have some of its poles on the imaginary axis is \_\_\_\_\_.

- a) 9
- b) 8
- c) 7
- d) 6

(GATE EE 2020)

Q.47 Suppose for input  $x(t)$  a linear time-invariant system with impulse response  $h(t)$  produces output  $y(t)$ , so that  $x(t) * h(t) = y(t)$ . Further, if  $|x(t)| * |h(t)| = z(t)$ , which of the following statements is true?

- a) For all  $t \in (-\infty, \infty)$ ,  $z(t) \leq y(t)$
- b) For some but not all  $t \in (-\infty, \infty)$ ,  $z(t) \leq y(t)$
- c) For all  $t \in (-\infty, \infty)$ ,  $z(t) \geq y(t)$

d) For some but not all  $t \in (-\infty, \infty)$ ,  $z(t) \geq y(t)$

(GATE EE 2020)

Q.48 The causal realization of a system transfer function  $H(s)$  having poles at  $(2, -1)$ ,  $(-2, 1)$  and zeroes at  $(2, 1)$ ,  $(-2, -1)$  will be

- a) stable, real, allpass  
b) unstable, complex, allpass  
c) unstable, real, highpass  
d) stable, complex, lowpass

(GATE EE 2020)

Q.49 Which of the following options is true for a linear time-invariant discrete time system that obeys the difference equation

$$y[n] - ay[n-1] = b_0x[n] - b_1x[n-1]$$

$y[n]$  is unaffected by the values of  $x[n-k]$ ;  $k > 2$ .

The system is necessarily causal.

The system impulse response is non-zero at infinitely many instants.

When  $x[n] = 0$ ,  $n < 0$ , the function  $y[n]$ ;  $n > 0$  is solely determined by the function  $x[n]$ .

- a) Only 1  
b) Only 2  
c) Only 3  
d) Only 4

(GATE EE 2020)

Q.50 Let  $a_r$ ,  $a_\phi$  and  $a_z$  be unit vectors along  $r$ ,  $\phi$  and  $z$  directions, respectively in the cylindrical coordinate system. For the electric flux density given by

$$\mathbf{D} = (a_r 15 + a_\phi 2r - a_z 3rz) \text{ Coulomb/m}^2,$$

the total electric flux, in Coulomb, emanating from the volume enclosed by a solid cylinder of radius  $3\text{ m}$  and height  $5\text{ m}$  oriented along the  $z$ -axis with its base at the origin is(:

- a)  $54\pi$   
b)  $90\pi$   
c)  $108\pi$   
d)  $180\pi$

(GATE EE 2020)

Q.51 A stable real linear time-invariant system with single pole at  $p$ , has a transfer function

$$H(s) = \frac{s^2 + 100}{s - p}$$

with a dc gain of 5. The smallest positive frequency, in rad/s, at unity gain is closest to(:

- a) 8.84  
b) 11.08  
c) 78.13  
d) 122.87

(GATE EE 2020)

Q.52 The number of purely real elements in a lower triangular representation of the given  $3 \times 3$  matrix, obtained through the given decomposition is \_\_\_\_\_.

$$\begin{pmatrix} 2 & 3 & 2 \\ 3 & 2 & 1 \\ 3 & 1 & 7 \end{pmatrix} = \begin{pmatrix} a_{11} & 0 & 0 \\ a_{12} & a_{22} & 0 \\ a_{13} & a_{23} & a_{33} \end{pmatrix} \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & 0 & a_{33} \end{pmatrix}^T$$

- a) 5  
b) 6  
c) 8  
d) 9

(GATE EE 2020)

Q.53 The figure below shows the per-phase Open Circuit Characteristics (measured in V) and Short Circuit Characteristics (measured in A) of a 14 kVA, 400 V, 50 Hz, 4-pole, 3-phase, delta connected alternator, driven at 1500 rpm. The field current,  $I_f$  is measured in A. Readings taken are marked as respective (x, y) coordinates in the figure. Ratio of the unsaturated and saturated synchronous impedances ( $Z_s(\text{unsat})/Z_s(\text{sat})$ ) the alternator is closest to:

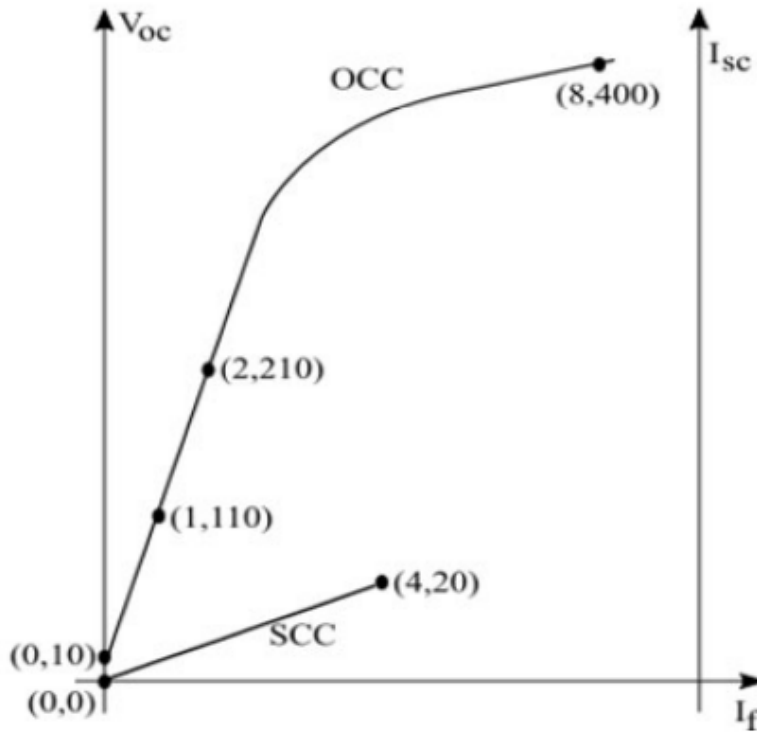


Fig. 13.

- a) 2.100
- b) 2.025
- c) 2.000
- d) 1.000

(GATE EE 2020)

Q.54 Let  $\hat{a}_x$  and  $\hat{a}_y$  be unit vectors along x and y directions, respectively. A vector function is given by

$$\mathbf{F} = \hat{a}_y y - \hat{a}_x x$$

The line integral of the above function

$$\int_C \mathbf{F} \cdot d\mathbf{l}$$

along the curve C, which follows the parabola  $y = x^2$  as shown below is \_\_\_\_\_ (rounded off to 2 decimal places)

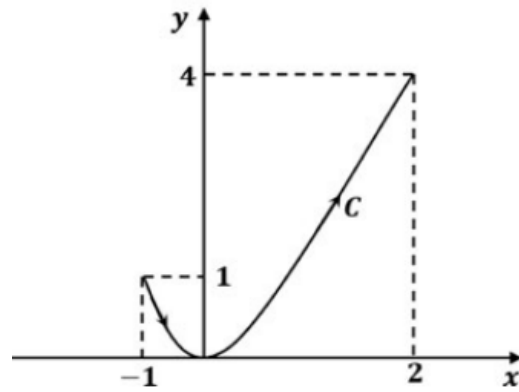


Fig. 14.

(GATE EE 2020)

- Q.55 A resistor and a capacitor are connected in series to a 10 V dc supply through a switch. The switch is closed at  $t = 0$ , and the capacitor voltage is found to cross 0 V at  $t = 0.4\tau$ , where  $\tau$  is the circuit time constant. The absolute value of percentage change required in the initial capacitor voltage if the zero crossing has to happen at  $t = 0.2\tau$  is \_\_\_\_\_ (rounded off to 2 decimal places).

(GATE EE 2020)

- Q.56 The figure below shows the per-phase Open Circuit Characteristics (measured in V) and Short Circuit Characteristics (measured in A) of a 14 kVA, 400 V, 50 Hz, 4-pole, 3-phase, delta connected alternator, driven at 1500 rpm. The field current,  $I_f$  is measured in A. Readings taken are marked as respective (x, y) coordinates in the figure. Ratio of the unsaturated and saturated synchronous impedances ( $Z_s(\text{unsat})/Z_s(\text{sat})$ ) of the alternator is closest to:

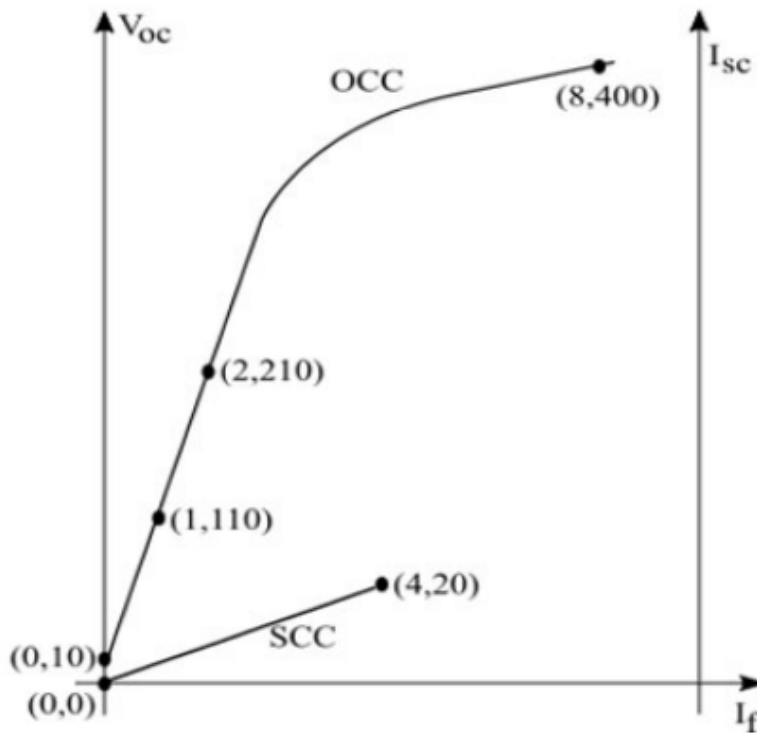


Fig. 15.

- a) 2.100
- b) 2.025
- c) 2.000
- d) 1.000

(GATE EE 2020)

Q.57 Let  $\hat{a}_x$  and  $\hat{a}_y$  be unit vectors along x and y directions, respectively. A vector function is given by

$$\mathbf{F} = \hat{a}_y y - \hat{a}_x x$$

The line integral of the above function

$$\int_C \mathbf{F} \cdot d\mathbf{l}$$

along the curve C, which follows the parabola  $y = x^2$  as shown below is \_\_\_\_\_ (rounded off to 2 decimal places)



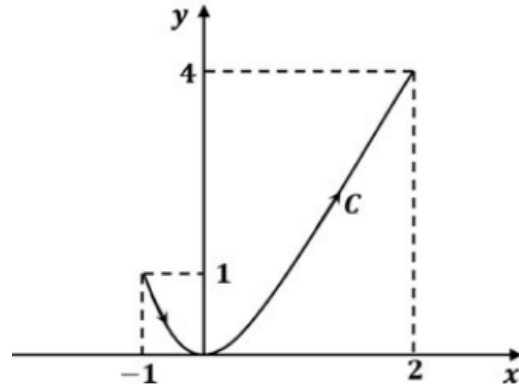


Fig. 16.

(GATE EE 2020)

- Q.58 A resistor and a capacitor are connected in series to a 10 V dc supply through a switch. The switch is closed at  $t = 0$ , and the capacitor voltage is found to cross 0 V at  $t = 0.4\tau$ , where  $\tau$  is the circuit time constant. The absolute value of percentage change required in the initial capacitor voltage if the zero crossing has to happen at  $t = 0.2\tau$  is \_\_\_\_\_ (rounded off to 2 decimal places).

(GATE EE 2020)

- Q.59 A cylindrical rotor synchronous generator with constant real power output and constant terminal voltage is supplying 100 A current to a 0.9 lagging power factor load. An ideal reactor is now connected in parallel with the load, as a result of which the total lagging reactive power requirement of the load is twice the previous value while the real power remains unchanged. The armature current is now \_\_\_\_\_ A (rounded off to 2 decimal places).

(GATE EE 2020)

- Q.60 Bus 1 with voltage magnitude  $V_1 = 1.1$  pu is sending reactive power  $Q_{12}$  towards bus 2 with voltage magnitude  $V_2 = 1$  pu through a lossless transmission line of reactance  $X$ . Keeping the voltage at bus 2 fixed at 1 pu, magnitude of voltage at bus 1 is changed, so that the reactive power  $Q_{12}$  sent from bus 1 is increased by 20%. Real power flow through the line under both the conditions is zero. The new value of the voltage magnitude,  $V_1$ , in pu (rounded off to 2 decimal places), at bus 1 is \_\_\_\_\_.



Fig. 17.

(GATE EE 2020)

- Q.61 Windings A, B and C have 20 turns each and are wound on the same iron core as shown, along with winding X which has 2 turns. The figure shows the sense (clockwise/anti-clockwise) of each of the windings only and does not reflect the exact number of turns. If windings A, B and C are supplied with balanced 3-phase voltages at 50 Hz and there is no core saturation, the no-load RMS voltage (in V, rounded off to 2 decimal places) across winding X is \_\_\_\_\_.

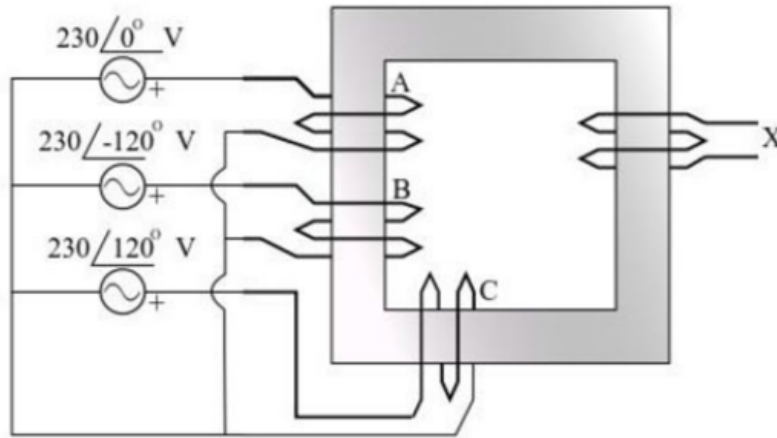


Fig. 18.

(GATE EE 2020)

Q.62 A cylindrical rotor synchronous generator has steady state synchronous reactance of 0.7 pu and subtransient reactance of 0.2 pu. It is operating at  $(1 + j0)$  pu terminal voltage with an internal emf of  $(1 + j0.7)$  pu. Following a three-phase solid short circuit fault at the terminals of the generator, the magnitude of the subtransient internal emf (rounded off to 2 decimal places) is \_\_\_\_\_ pu.

(GATE EE 2020)

Q.63 In the dc-dc converter circuit shown, switch Q is switched at a frequency of 10 kHz with a duty ratio of 0.6. All components of the circuit are ideal, and the initial current in the inductor is zero. Energy stored in the inductor in mJ (*rounded off to 2 decimal places*) at the end of 10 complete switching cycles is \_\_\_\_\_.

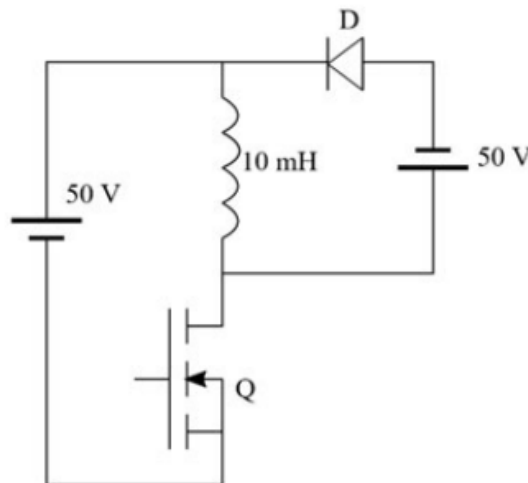


Fig. 19.

(GATE EE 2020)

Q.64 A single-phase, full-bridge, fully controlled thyristor rectifier feeds a load comprising a  $10 \Omega$  resistance in series with a very large inductance. The rectifier is fed from an ideal 230 V, 50 Hz sinusoidal source through cables which have negligible internal impedance and a total inductance of 2.28 mH. If the thyristors are triggered at an angle  $\alpha = 45^\circ$ , the commutation overlap angle in degree (*rounded off to 2 decimal places*) is \_\_\_\_\_.

(GATE EE 2020)

- Q.65 A non-ideal Si-based pn junction diode is tested by sweeping the bias applied across its terminals from  $-5\text{ V}$  to  $+5\text{ V}$ . The effective thermal voltage,  $V_T$ , for the diode is measured to be  $(29 \pm 2)\text{ mV}$ . The resolution of the voltage source in the measurement range is  $1\text{ mV}$ . The percentage uncertainty (rounded off to 2 decimal places) in the measured current at a bias voltage of  $0.02\text{ V}$  is \_\_\_\_\_.

(GATE EE 2020)

- Q.66 The temperature of the coolant oil bath for a transformer is monitored using the circuit shown. It contains a thermistor with a temperature-dependent resistance,  $R_{\text{thermistor}} = 2(1 + \alpha T)\text{ k}\Omega$ , where  $T$  is the temperature in  $^{\circ}\text{C}$ . The temperature coefficient,  $\alpha$ , is  $-(4 \pm 0.25)\text{ \%}/^{\circ}\text{C}$ . Circuit parameters:  $R_1 = 1\text{ k}\Omega$ ,  $R_2 = 1.3\text{ k}\Omega$ ,  $R_3 = 2.6\text{ k}\Omega$ . The error in the output signal (in  $\text{V}$ , rounded off to 2 decimal places) at  $150^{\circ}\text{C}$  is \_\_\_\_\_.

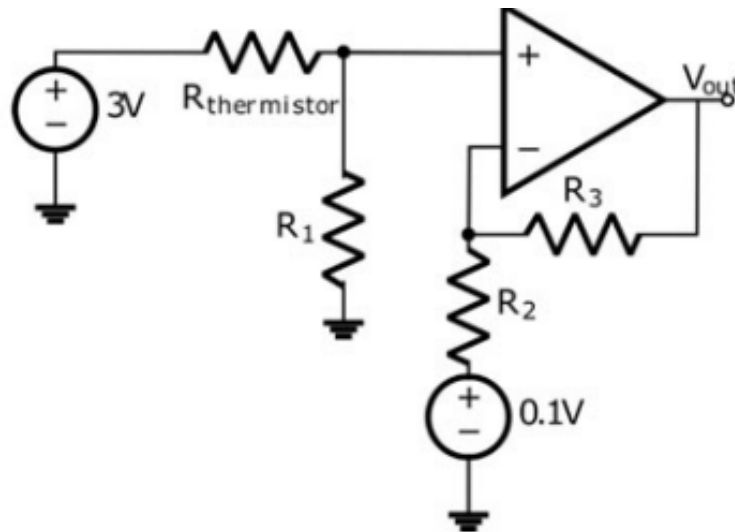


Fig. 20.

(GATE EE 2020)

- Q.67 An 8085 microprocessor accesses two memory locations (2001H) and (2002H), that contain 8-bit numbers 98H and B1H, respectively. The following program is executed:

```
LXI H, 2001H
MVI A, 21H
INX H
ADD M
INX H
MOV M, A
HLT
```

At the end of this program, the memory location 2003H contains the number in decimal (base 10) form \_\_\_\_\_.

(GATE EE 2020)

- Q.68 A conducting square loop of side length  $1\text{ m}$  is placed at a distance of  $1\text{ m}$  from a long straight wire carrying a current  $I = 2\text{ A}$  as shown below. The mutual inductance, in  $\text{nH}$  (rounded off to 2 decimal places), between the conducting loop and the long wire is \_\_\_\_\_.

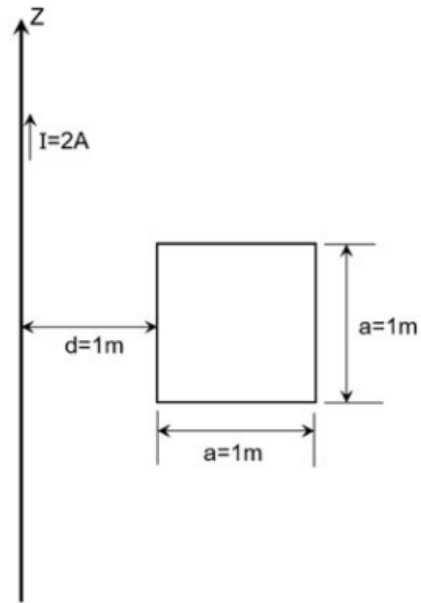


Fig. 21.

(GATE EE 2020)