Matgeo Presentation - Problem 1.10.31

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Question

A vector $\bf r$ has magnitude 14 and direction ratios 2,3,-6. Find the direction cosines and components of $\bf r$, given that $\bf r$ makes an acute angle with X axis

Description

Solution:

Symbol	Description
r	given vector with magnitude=14
r _X	component of r along X axis
r _Y	component of r along Y axis
\mathbf{r}_Z	component of r along Z axis
k	scaling factor

Table: Variables Used

Solution

$$\mathbf{r} = k \begin{pmatrix} 2\\3\\-6 \end{pmatrix} \tag{0.1}$$

$$\|\mathbf{r}\| = |k| \| \begin{pmatrix} 2\\3\\-6 \end{pmatrix} \| \tag{0.2}$$

$$\|\mathbf{r}\| = |k| \, 7 \tag{0.3}$$

$$14 = |k| 7 \tag{0.4}$$

$$|k| = 2 \tag{0.5}$$

$$\implies \mathbf{r} = \begin{pmatrix} 4 \\ 6 \\ 12 \end{pmatrix} \tag{0.6}$$

(but k=2 not -2 because given that vector r makes acute angle with X axis)

conclusion

The unit vector in the direction of \mathbf{r} is

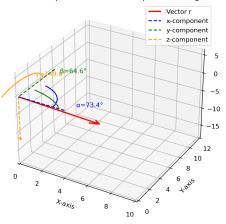
$$\frac{\mathbf{r}}{\|\mathbf{r}\|} = \frac{1}{14} \begin{pmatrix} 4 \\ 6 \\ -12 \end{pmatrix} = \begin{pmatrix} \frac{2}{7} \\ \frac{3}{7} \\ \frac{-6}{7} \end{pmatrix} \tag{0.7}$$

The component of
$$\mathbf{r}$$
 along X axis $=\mathbf{r}_X = \begin{pmatrix} 4 \\ 0 \\ 0 \end{pmatrix}$
The component of \mathbf{r} along Y axis $=\mathbf{r}_Y = \begin{pmatrix} 0 \\ 6 \\ 0 \end{pmatrix}$

The component of **r** along Z axis =
$$\mathbf{r}_Z = \begin{pmatrix} 0 \\ 0 \\ -12 \end{pmatrix}$$

Plot

3D Vector Representation with Components & Angles



Figure

C Code: code.c

```
#include <stdio.h>
#include <math.h>
int main() {
   FILE *fp;
   double magnitude, 1, m, n;
   double dr1, dr2, dr3; // direction ratios
   double k; // normalization factor
   double comp_x, comp_y, comp_z;
   // Open file vector.dat
   fp = fopen("vector.dat", "r");
   if (fp == NULL) {
       printf("Error! Could not open file. \n");
       return 1;
   // Reading magnitude and direction ratios
   fscanf(fp, "%lf, %lf, %lf, %lf", &magnitude, &dr1, &dr2, &dr3);
   fclose(fp):
   // Calculate normalization factor
   k = sqrt(dr1*dr1 + dr2*dr2 + dr3*dr3);
   // Direction cosines
   1 = dr1 / k;
   m = dr2 / k:
   n = dr3 / k:
   // Verify that angle with X-axis is acute
   if (1 <= 0) {
       printf("Error:, The, vector, does, not, make, an, acute, angle, with, the, X-axis.\n");
       return 1:}
```

C Code: code.c

```
// Components of vector
comp_x = magnitude * 1;
comp_y = magnitude * m;
comp_z = magnitude * n;

// Display results
printf("Direction_Cosines:__1_=__%.3f,__m_=__%.3f,__n_=__%.3f\n", 1, m, n);
printf("Components__of__vector__r:__(%.3f,__%.3f,__%.3f)\n", comp_x, comp_y, comp_z);
return 0;
}
```

Python: call.py

```
import subprocess
# Step 1: Create vector.dat automatically
with open("vector.dat", "w") as f:
   f.write("14, 2, 3, -6\n") # You can change values here if needed
# Step 2: Compile the C code with -lm (math library)
compile result = subprocess.run(["gcc", "code.c", "-o", "vector", "-lm"], capture output=True, text=True)
if compile_result.returncode != 0:
   print("Compilation failed:\n", compile result.stderr)
else:
   print("Compilation successful. Running program...\n")
   # Step 3: Run the compiled program
   run result = subprocess.run(["./vector"], capture output=True, text=True)
   # Step 4: Print program output (results or error from C code)
   if run result.stdout.strip():
       print(run result.stdout.strip())
   if run_result.stderr.strip():
       print("Runtimemerror:\n", run result.stderr.strip())
```

Python: plot.py

```
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
# -----
# Read magnitude and direction ratios from file
# vector.dat should contain: 14 2 3 -6
# _____
data = np.loadtxt("vector.dat")
magnitude, a, b, c = data
# Normalize direction ratios direction cosines
d = np.sqrt(a**2 + b**2 + c**2)
1. m. n = a/d. b/d. c/d
# Vector components (scaled by magnitude)
x, v, z = magnitude * np.arrav([1, m, n])
# Angles with axes
alpha = np.degrees(np.arccos(1)) # angle with x-axis
beta = np.degrees(np.arccos(m)) # angle with y-axis
gamma = np.degrees(np.arccos(n)) # angle with z-axis
 _____
# Verify condition: r makes acute angle with x-axis
# -----
if alpha >= 90:
   print(f"Vector, r, does, NOT_make_an_acute_angle_with_x-axis_(=_{{1}}{alpha:.2f})._No_figure_generated.")
else:
   print(f"Vector_r_makes_an_acute_angle_with_x-axis_(=={alpha:.2f})...Generating,figure...")
   # -----
   # Plot setup (one figure only)
```

Python: plot.py

```
fig = plt.figure(figsize=(8, 6))
ax = fig.add_subplot(111, projection='3d')
# Plot the main vector
ax.quiver(0, 0, 0, x, y, z, color='r', arrow_length_ratio=0.1, linewidth=2, label="Vector_r")
# Plot projections on axes
ax.quiver(0, 0, 0, x, 0, 0, color='b', linestyle='dashed', arrow_length_ratio=0.05, label="x-component"
ax.quiver(0, 0, 0, 0, y, 0, color='g', linestyle='dashed', arrow_length_ratio=0.05. label="y-component"
ax.quiver(0, 0, 0, 0, 0, z, color='orange', linestyle='dashed', arrow_length_ratio=0.05, label="z-
      component")
# Function to draw arc in 3D
def plot arc(ax, radius, angle, axis='x', color='k'):
   t = np.linspace(0, np.radians(angle), 50)
   if axis == 'x':
       xs. vs. zs = radius*np.cos(t), radius*np.sin(t), 0*t
   elif axis == 'v':
       xs, ys, zs = radius*np.cos(t), 0*t, radius*np.sin(t)
   else: # z-axis
       xs, ys, zs = 0*t, radius*np.cos(t), radius*np.sin(t)
   ax.plot(xs, ys, zs, color=color, linewidth=1.5)
# Draw arcs (different radii to avoid overlap)
plot_arc(ax, 3, alpha, axis='x', color='b') # at radius 3
plot_arc(ax, 3.5, beta, axis='y', color='g') # at radius 3.5
plot arc(ax, 4, gamma, axis='z', color='orange') # at radius 4
# Angle labels (separated properly)
```

Python: plot.py

```
ax.text(4.5, 1, 0, f"={alpha:.1f}", color='b') # label far on +x
ax.text(1, 5.0, 1, f"={beta:.1f}", color='g') # label farther on +y
ax.text(1, 1, 5.2, f"={gamma:.1f}", color='orange') # label higher on +z
# -----
# Ares lahels & limits
# -----
ax.set_xlim([0, max(0, x) + 6])
ax.set_vlim([0, max(0, y) + 6])
ax.set zlim([min(0, z) - 6, max(0, z) + 6])
ax.set xlabel("X-axis")
ax.set_ylabel("Y-axis")
ax.set zlabel("Z-axis")
ax.set_title("3D, Vector, Representation, with, Components, &, Angles")
ax.legend()
# Save the figure and show it
plt.savefig("vector plot.png", dpi=300, bbox inches='tight')
plt.show()
```