

# GATE-IN-2008

EE25BTECH11002 - Achat Parth Kalpesh

QUESTIONS 1-20 (1 MARK EACH)

- 1) Given  $y = x^2 + 2x + 10$ , the value of  $\frac{dy}{dx}\bigg|_{x=1}$  is equal to (GATE-IN 2008)
- a) 0                                      b) 4                                      c) 12                                      d) 13
- 2)  $\lim_{x \rightarrow 0} \frac{\sin x}{x}$  is (GATE-IN 2008)
- a) indeterminate                      b) 0                                      c) 1                                      d)  $\infty$
- 3) The power supplied by the dc voltage source in the circuit shown below is Fig. 1 (GATE-IN 2008)

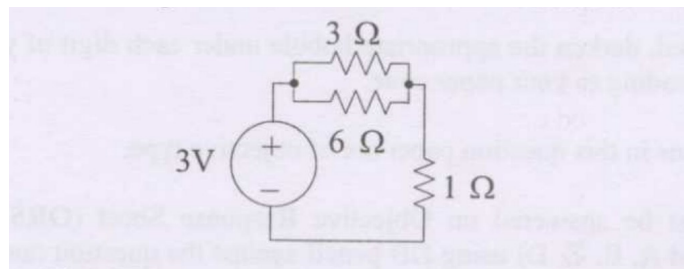


Fig. 1.

- a) 0 W                                      b) 1.0 W                                      c) 2.5 W                                      d) 3.0 W
- 4) The current  $I$  supplied by the dc voltage source in the circuit shown below is Fig. 2 (GATE-IN 2008)

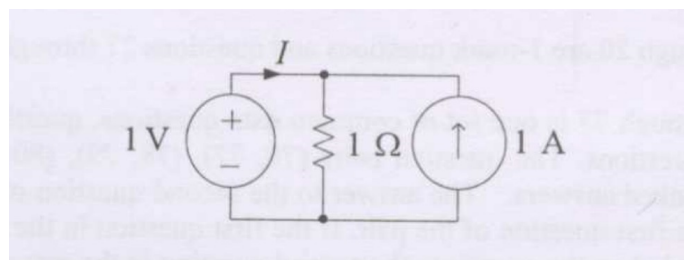


Fig. 2.

- a) 0 A                                      b) 0.5 A                                      c) 1 A                                      d) 2 A
- 5) For signal conditioning of a piezoelectric type transducer we require (GATE-IN 2008)
- a) a charge amplifier                      c) an instrumentation amplifier  
b) a differential amplifier                      d) a transconductance amplifier
- 6) A linear variable differential transformer (LVDT) is (GATE-IN 2008)

- a) a displacement transducer  
b) an impedance matching transformer  
c) a differential temperature sensor  
d) an auto transformer
- 7) The temperature being sensed by a negative temperature coefficient (*NTC*) type thermistor is linearly increasing. Its resistance will (GATE-IN 2008)
- a) linearly increase with temperature  
b) exponentially increase with temperature  
c) linearly decrease with temperature  
d) exponentially decrease with temperature
- 8) For a single stage BJT common base amplifier, (GATE-IN 2008)
- a) current gain as well as voltage gain can be greater than unity  
b) current gain can be greater than unity but voltage gain is always less than unity  
c) voltage gain can be greater than unity but current gain is always less than unity  
d) current gain as well as voltage gain is always less than unity
- 9) In the circuit shown below Fig. 3, the ideality factor  $n$  of the diode is unity and the voltage drop across it is 0.7 V. The dynamic resistance of the diode at room temperature is approximately voltage gain can be greater than unity but current gain is always less than unity (GATE-IN 2008)

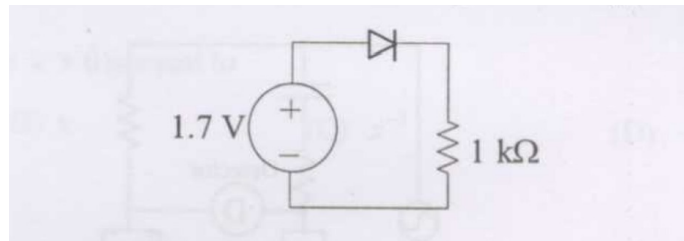


Fig. 3.

- a) 15  $\Omega$   
b) 25  $\Omega$   
c) 50  $\Omega$   
d) 700  $\Omega$
- 10) An ideal op-amp has the characteristics of an ideal (GATE-IN 2008)
- a) voltage controlled voltage source  
b) voltage controlled current source  
c) current controlled voltage source  
d) current controlled current source
- 11) The inverters in the ring oscillator circuit shown below Fig. 4 are identical. If the output waveform has a frequency of 10 MHz, the propagation delay of each inverter is (GATE-IN 2008)

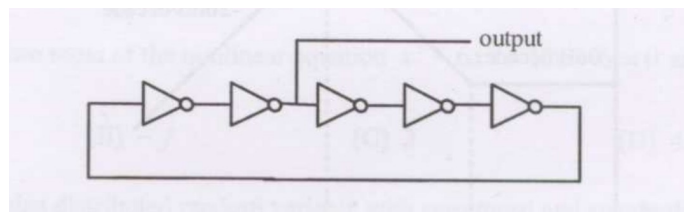


Fig. 4.

- a) 5 ns  
b) 10 ns  
c) 20 ns  
d) 50 ns
- 12) A 2K $\times$ 8 bit RAM is interfaced to an 8-bit microprocessor. If the address of the first memory location in the RAM is 0800H, the address of the last memory location will be (GATE-IN 2008)

- a) 1000H                      b) 0FFFH                      c) 4800H                      d) 47FFH

13) The fundamental period of the discrete-time signal  $x[n] = e^{j(\frac{5\pi}{6})n}$  is (GATE-IN 2008)

- a)  $\frac{6}{5\pi}$                       b)  $\frac{12}{5}$                       c) 6                      d) 12

14) Which one of the following discrete-time systems is time invariant? (GATE-IN 2008)

- a)  $y[n] = nx[n]$                       b)  $y[n] = x[3n]$                       c)  $y[n] = x[-n]$                       d)  $y[n] = x[n-3]$

15) If a current of  $\left[-6\sqrt{2}\sin(100\pi t) + 6\sqrt{2}\cos\left(300\pi t + \frac{\pi}{4}\right) + 6\sqrt{2}\right]$  A is passed through a true RMS ammeter, the meter reading will be (GATE-IN 2008)

- a)  $6\sqrt{2}$  A                      b)  $\sqrt{126}$  A                      c) 12 A                      d)  $\sqrt{216}$  A

16) If the ac bridge circuit shown below Fig. 5 is balanced, the element Z can be a (GATE-IN 2008)

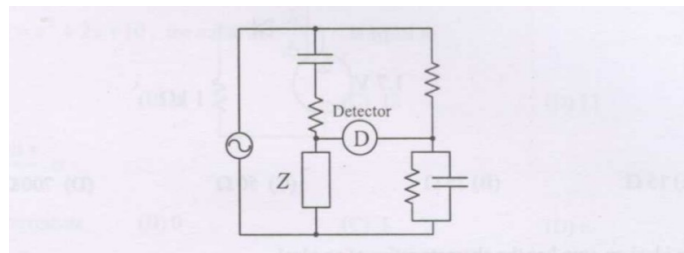


Fig. 5.

- a) pure capacitor                      c) R-L series combination  
b) pure inductor                      d) R-L parallel combination

17) The Bode asymptotic plot of a transfer function is given below Fig. 6. In the frequency range shown, the transfer function has (GATE-IN 2008)

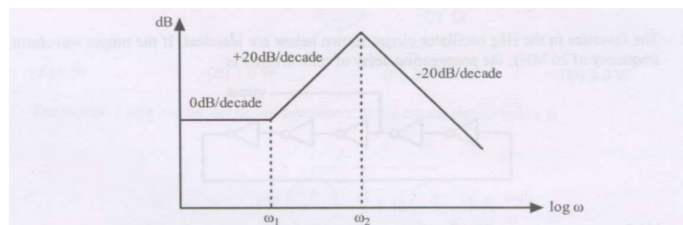


Fig. 6.

- a) 3 poles and 1 zero                      c) 2 poles and 1 zero  
b) 1 pole and 2 zeros                      d) 2 poles and 2 zeros

18) For radioisotope imaging, an Anger camera is fitted with a parallel hole collimator. If the thickness of the collimator is increased, the camera (GATE-IN 2008)

- a) resolution and sensitivity will increase  
b) resolution and sensitivity will decrease  
c) resolution will increase and sensitivity will decrease  
d) resolution will decrease and sensitivity will increase

19) In the standard 12-lead ECG recording system, the minimum number of electrodes required to be attached to a human subject for recording any one of the unipolar chest lead signals is (GATE-IN 2008)

- a) 1                      b) 2                      c) 4                      d) 5

20) A laser light with a wavelength of 633 nm is passed through 1 cm length of tissue and 2 cm length of glass. The refractive indices of tissue and glass are 1.33 and 1.5 respectively. The velocities of laser light in the tissue and in the glass are in the ratio of (GATE-IN 2008)

- a) 1.33: 0.75              b) 1.33: 3.0              c) 1.33: 1.5              d) 1.5: 1.33

QUESTIONS 21-75 (2 MARKS EACH)

21) The expression  $e^{-\ln x}$  for  $x > 0$  is equal to (GATE-IN 2008)

- a)  $-x$                       b)  $x$                       c)  $x^{-1}$                       d)  $-x^{-1}$

22) Consider the differential equation  $\frac{dy}{dx} = 1 + y^2$ . Which one of the following can be a particular solution of this differential equation? (GATE-IN 2008)

- a)  $y = \tan(x + 3)$       b)  $y = \tan x + 3$       c)  $x = \tan(y + 3)$       d)  $x = \tan y + 3$

23) Consider the function  $y = x^2 - 6x + 9$ . The maximum value of  $y$  obtained when  $x$  varies over the interval 2 to 5 is (GATE-IN 2008)

- a) 1                      b) 3                      c) 4                      d) 9

24) It is known that two roots of the nonlinear equation  $x^3 - 6x^2 + 11x - 6 = 0$  are 1 and 3. The third root will be (GATE-IN 2008)

- a)  $j$                       b)  $-j$                       c) 2                      d) 4

25) Consider a Gaussian distributed random variable with zero mean and standard deviation  $\sigma$ . The value of its cumulative distribution function at the origin will be (GATE-IN 2008)

- a) 0                      b) 0.5                      c) 1                      d)  $10\sigma$

26) A random variable is uniformly distributed over the interval 2 to 10. Its variance will be (GATE-IN 2008)

- a)  $\frac{16}{3}$                       b) 6                      c)  $\frac{256}{9}$                       d) 36

27) The Fourier transform of  $x(t) = e^{-at}u(-t)$ , where  $u(t)$  is the unit step function, (GATE-IN 2008)

- a) exists for any real value of  $a$                       c) exists if the real value of  $a$  is strictly negative  
b) does not exist for any real value of  $a$                       d) exists if the real value of  $a$  is strictly positive

28) In the circuit shown below Fig. 7 the maximum power that can be transferred to the load  $Z_L$  is (GATE-IN 2008)

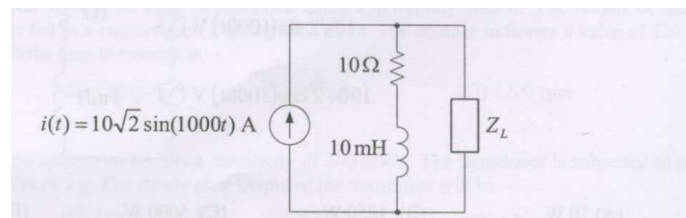


Fig. 7.

- a) 250 W                      b) 500 W                      c) 1000 W                      d) 2000 W

29) A complex variable  $Z = x + j0.1$  has its real part  $x$  varying in the range  $-\infty$  to  $\infty$ . Which of the following is the locus (shown in thick lines) of  $\frac{1}{Z}$  in the complex plane? (GATE-IN 2008)

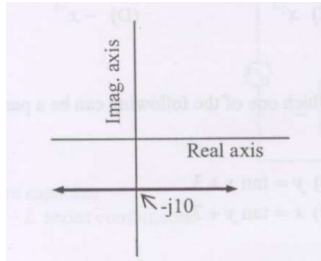


Fig. 8.

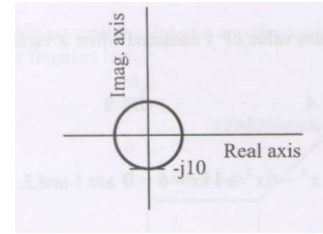


Fig. 10.

a)

c)

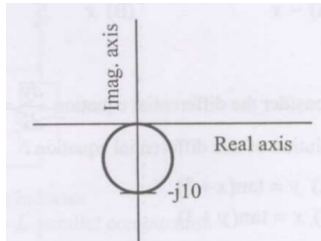


Fig. 9.

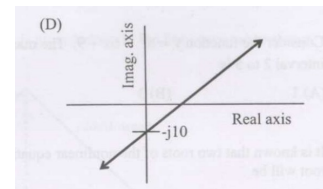


Fig. 11.

b)

d)

30) For the circuit shown below Fig. 12 the input resistance  $R_{11} = \frac{V_1}{I_1} \Big|_{I_2=0}$  is (GATE-IN 2008)

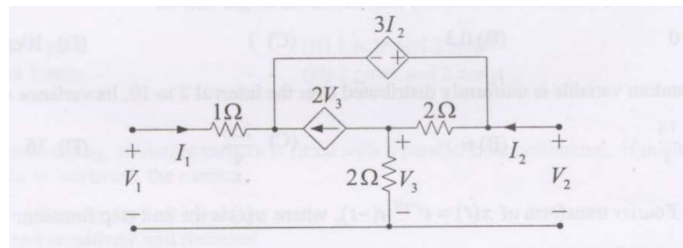


Fig. 12.

a)  $-3 \Omega$

b)  $2 \Omega$

c)  $3 \Omega$

d)  $13 \Omega$

31) In the circuit shown below Fig. 13 the average power consumed by the  $1\Omega$  resistor is (GATE-IN 2008)

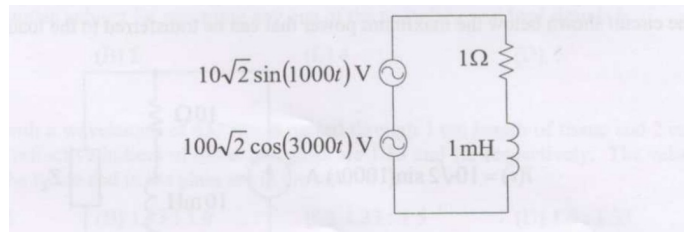


Fig. 13.

- a) 50 W                      b) 1050 W                      c) 5000 W                      d) 10100 W

32) Which one of the following equations is valid for the circuit shown below? Fig. 14 (GATE-IN 2008)

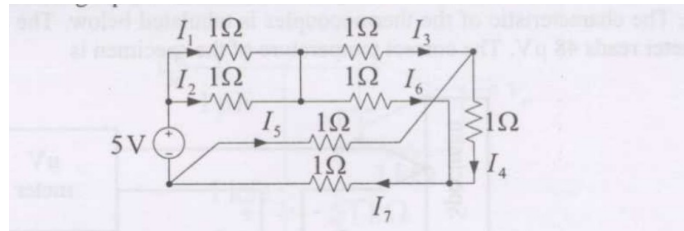


Fig. 14.

- a)  $I_3 + I_5 - I_6 + I_7 = 0$                       c)  $I_3 + I_5 + I_6 + I_7 = 0$   
 b)  $I_3 - I_5 + I_6 + I_7 = 0$                       d)  $I_3 + I_5 + I_6 - I_7 = 0$

33) For the circuit shown below Fig. 15 the steady-state current  $I$  is (GATE-IN 2008)

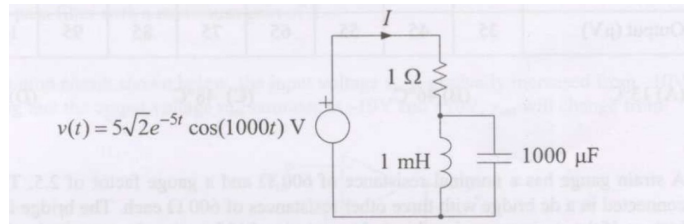


Fig. 15.

- a) 0 A                      b)  $5\sqrt{2} \cos(1000t)$  A                      c)  $5\sqrt{2} \cos\left(1000t - \frac{\pi}{4}\right)$  A                      d)  $5\sqrt{2}$  A

34) For the circuit shown below Fig. 16 the voltage across the capacitor is (GATE-IN 2008)

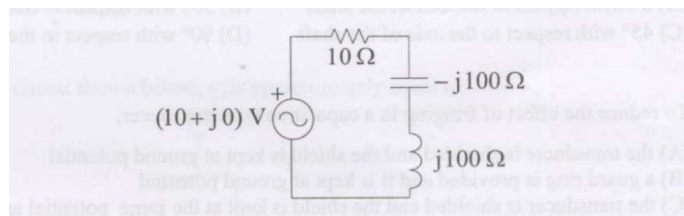


Fig. 16.

- a)  $(10 + j0)$  V      b)  $(100 + j0)$  V      c)  $(0 + j100)$  V      d)  $(0 - j100)$  V

35) The speed of a gear having 60 teeth is measured using a proximity sensor. The output of the proximity sensor is fed to a counter with a gating time of 1s. The counter indicates a value of 120. The speed at which the gear is rotating is (GATE-IN 2008)

- a) 60 rpm      b) 120 rpm      c) 600 rpm      d) 1200 rpm

36) A piezoelectric type accelerometer has a sensitivity of 100 mV/g. The transducer is subjected to a constant acceleration of 5 g. The steady state output of the transducer will be (GATE-IN 2008)

- a) 0 V      b) 100 mV      c) 0.5 V      d) 5 V

37) A pair of identical thermocouples is employed for measuring the temperature of a specimen as shown below. Fig. 17 The characteristic of the thermocouples is tabulated below. The reference junction is at  $2^\circ\text{C}$ . The meter reads  $48 \mu\text{V}$ . The correct temperature of the specimen is (GATE-IN 2008)

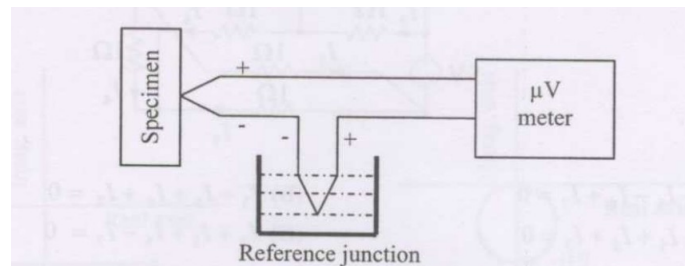


Fig. 17.

Temperature ( $^\circ\text{C}$ )	0	10	20	30	40	50	60	70	80	90
Output ( $\mu\text{V}$ )	35	45	55	65	75	85	95	105	115	125

TABLE I

- a)  $13^\circ\text{C}$       b)  $46^\circ\text{C}$       c)  $48^\circ\text{C}$       d)  $50^\circ\text{C}$

38) A strain gauge has a nominal resistance of  $600\Omega$  and a gauge factor of 2.5. The strain gauge is connected in a dc bridge with three other resistances of  $600\Omega$  each. The bridge is excited by a 4 V battery. If the strain gauge is subjected to a strain of  $100 \mu\text{m/m}$ , the magnitude of the bridge output will be (GATE-IN 2008)

- a) 0V      b)  $250 \mu\text{V}$       c)  $500 \mu\text{V}$       d)  $750 \mu\text{V}$

39) The torque in a rotating shaft is measured using strain gauges. The strain gauges must be positioned on the shaft such that the axes of the strain gauges are at (GATE-IN 2008)

- a)  $0^\circ$  with respect to the axis of the shaft      c)  $45^\circ$  with respect to the axis of the shaft  
b)  $30^\circ$  with respect to the axis of the shaft      d)  $90^\circ$  with respect to the axis of the shaft

40) To reduce the effect of fringing in a capacitive type transducer, (GATE-IN 2008)

- a) the transducer is shielded and the shield is kept at ground potential  
b) a guard ring is provided and it is kept at ground potential  
c) the transducer is shielded and the shield is kept at the same potential as the moving plate

d) a guard ring is provided and it is kept at the same potential as the moving plate

- 41) A differential amplifier shown below Fig. 18 has a differential mode gain of 100 and a CMRR of 40 dB. If  $V_1 = 0.55\text{V}$  and  $V_2 = 0.45\text{V}$ , the output  $V_0$  is (GATE-IN 2008)

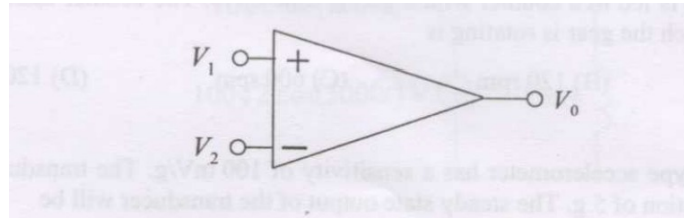


Fig. 18.

- a) 10 V                      b) 10.5 V                      c) 11 V                      d) 15 V

- 42) The op-amp circuit shown below Fig. 19 is that of a (GATE-IN 2008)

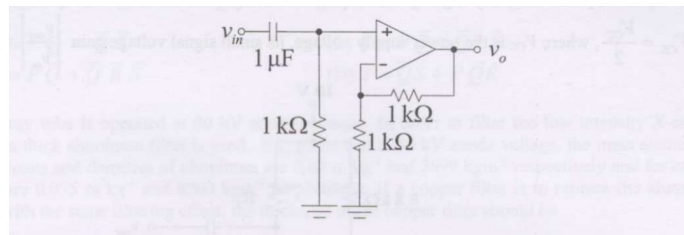


Fig. 19.

- a) low-pass filter with a maximum gain of 1                      c) high-pass filter with a maximum gain of 1  
b) low-pass filter with a maximum gain of 2                      d) high-pass filter with a maximum gain of 2

- 43) In the op-amp circuit shown below Fig. 20, the input voltage  $v_{in}$  is gradually increased from -10V to +10V. Assuming that the output voltage  $v_{out}$  saturates at -10V and +10V,  $V_{out}$  will change from (GATE-IN 2008)

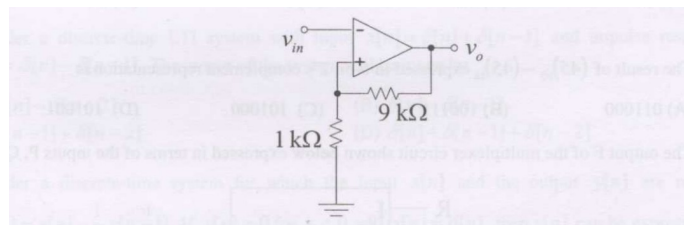


Fig. 20.

- a) -10 V to +10 V when  $v_{in} = -1\text{ V}$                       c) +10 V to -10 V when  $v_{in} = -1\text{ V}$   
b) -10 V to +10 V when  $v_{in} = +1\text{ V}$                       d) +10 V to -10 V when  $v_{in} = +1\text{ V}$

- 44) For the op-amp circuit shown below Fig. 21,  $v_0$  is approximately equal to (GATE-IN 2008)



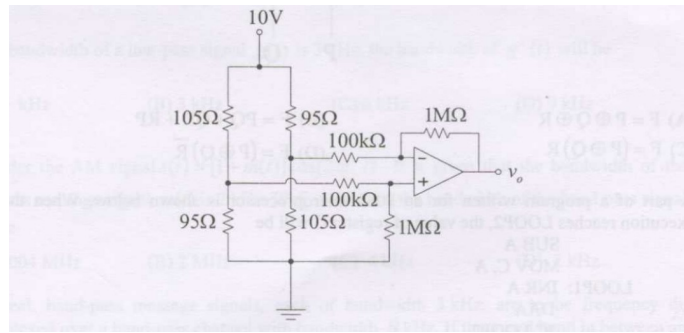


Fig. 21.

- a) -10 V                      b) -5 V                      c) +5 V                      d) +10 V

45) In the amplifier circuit shown below Fig. 22, assume  $V_{BE} = 0.7$  V and the  $\beta$  of the transistor and the values of  $C_1$  and  $C_2$  are extremely high. If the amplifier is designed such that at the quiescent point its  $V_{CE} = \frac{V_{CC}}{2}$  where  $V_{CC}$  is the power supply voltage, its small signal voltage gain  $|\frac{V_{out}}{V_{in}}|$  will be (GATE-IN 2008)

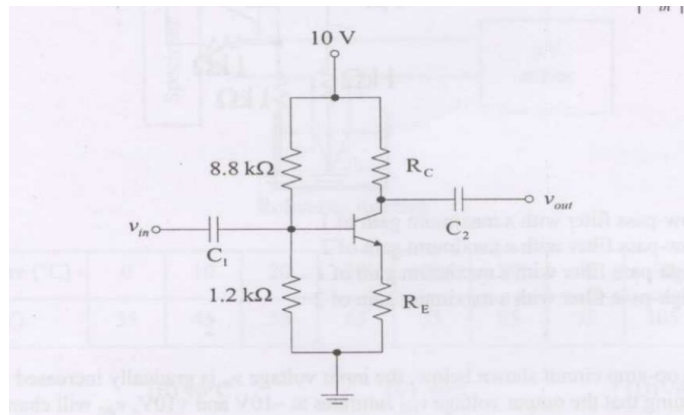


Fig. 22.

- a) 3.75                      b) 4.5                      c) 9                      d) 19

46) The result of  $(45)_{10} - (45)_{16}$  expressed in 6-bit 2's complement representation is (GATE-IN 2008)

- a) 011000                      b) 100111                      c) 101000                      d) 101001

47) The output F of the multiplexer circuit shown below Fig. 23 expressed in terms of the inputs P, Q and R is (GATE-IN 2008)

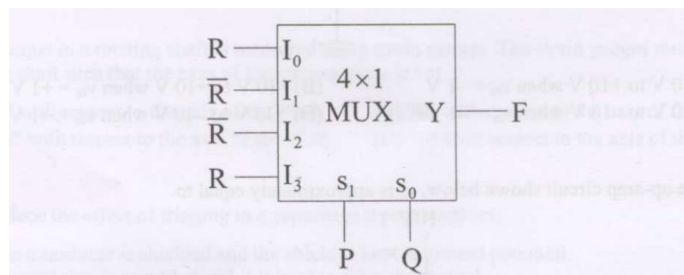


Fig. 23.

- a)  $F = P \oplus Q \oplus R$       b)  $F = PQ + QR + RP$       c)  $F = (P \oplus Q)R$       d)  $F = (P \oplus Q)\bar{R}$

48) A part of a program written for an 8085 microprocessor is shown below. When the program execution reaches LOOP2, the value of register C will be

```
SUB A
MOV C, A
LOOP1: INR A
DAA
JC LOOP2
INR C
JNC LOOP1
LOOP2: NOP
(GATE-IN 2008)
```

- a) 63 H      b) 64 H      c) 99 H      d) 100 H

49) The minimum sum of products form of the Boolean expression  $Y = \bar{P}\bar{Q}\bar{R}\bar{S} + P\bar{Q}\bar{R}\bar{S} + P\bar{Q}\bar{R}S + P\bar{Q}RS + P\bar{Q}R\bar{S} + \bar{P}\bar{Q}R\bar{S}$  (GATE-IN 2008)

- a)  $Y = P\bar{Q} + \bar{Q}\bar{S}$       c)  $Y = P\bar{Q} + \bar{Q}\bar{R}\bar{S}$   
b)  $Y = P\bar{Q} + \bar{Q}R\bar{S}$       d)  $Y = \bar{Q}\bar{S} + P\bar{Q}R$

50) An X-ray tube is operated at 80 kV anode voltage. In order to filter the low intensity X-rays, a 2.5 mm thick aluminum filter is used. It is given that at 80 kV anode voltage, the mass attenuation coefficients and densities of aluminum are  $0.02 \text{ m}^2 \text{ kg}^{-1}$  and  $2699 \text{ kg m}^{-3}$  respectively and for copper these are  $0.075 \text{ m}^2 \text{ kg}^{-1}$  and  $8960 \text{ kg m}^{-3}$  respectively. If a copper filter is to replace the aluminum filter with the same filtering effect, the thickness of the copper filter should be (GATE-IN 2008)

- a) 0.2 mm      b) 0.66 mm      c) 1.5 mm      d) 5 mm

51) A 5 MHz acoustic pulse travels from a transducer through a 2 cm thick fat tissue before it encounters an interface with a liver tissue at normal incidence. The amplitude attenuation factors of fat and liver are  $0.075 \text{ Np cm}^{-1}/\text{MHz}$  and  $0.1 \text{ Np cm}^{-1}/\text{MHz}$  respectively. The amplitude reflectivity coefficient of fat-liver interface is 0.1. Taking both attenuation and reflection losses into account, the amplitude loss ( $\text{indB}$ ) of echo pulse when it returns to the transducer is (GATE-IN 2008)

- a) 0.74      b) -2.6      c) -6      d) -33

52) Consider a discrete-time LTI system with input  $x[n] = \delta[n] + \delta[n-1]$  and impulse response  $h[n] = \delta[n] - \delta[n-1]$ . The output of the system will be given by (GATE-IN 2008)

- a)  $\delta[n] - \delta[n-2]$       c)  $\delta[n-1] + \delta[n-2]$   
b)  $\delta[n] - \delta[n-1]$       d)  $\delta[n] + \delta[n-1] + \delta[n-2]$

53) Consider a discrete-time system for which the input  $x[n]$  and the output  $y[n]$  are related as  $y[n] = x[n] - \frac{1}{3}y[n-1]$ . If  $y[n] = 0$  for  $n < 0$  and  $x[n] = \delta[n]$ , then  $y[n]$  can be expressed in terms of the unit step  $u[n]$  (GATE-IN 2008)

- a)  $\left(\frac{-1}{3}\right)^n u[n]$       b)  $\left(\frac{1}{3}\right)^n u[n]$       c)  $(3)^n u[n]$       d)  $(-3)^n u[n]$

54) If the bandwidth of a low-pass signal  $g(t)$  is 3 kHz, the bandwidth of  $g^2(t)$  will be (GATE-IN 2008)

- a)  $\frac{3}{2}$  MHz                      b) 3 MHz                      c) 6 kHz                      d) 9 kHz
- 55) Consider the AM signal  $s(t) = [1 + m(t)] \cos 2\pi f t$ . It is given that the bandwidth of the real, low-pass message signal  $m(t)$  is 2 kHz. If  $f_c = 2$  MHz, the bandwidth of the band-pass signal  $s(t)$  will be (GATE-IN 2008)
- a) 2.004 Hz                      b) 2 kHz                      c) 4 kHz                      d) 2 kHz
- 56) Ten real, band-pass message signals, each of bandwidth 3 kHz, are to be frequency division multiplexed over a band-pass channel with bandwidth B kHz. If the guard band in between any two adjacent signals should be of 500 Hz width and there is no need to provide any guard band at the edges of the band-pass channel, the value of B should be at least (GATE-IN 2008)
- a) 30                      b) 34.5                      c) 35                      d) 35.5
- 57) The region of convergence of the z-transform of the discrete-time signal  $x[n] = 2^n u[n]$  will be (GATE-IN 2008)
- a)  $|z| > 2$                       b)  $|z| < 2$                       c)  $|z| > \frac{1}{2}$                       d)  $|z| < \frac{1}{2}$
- 58) The step response of a linear time invariant system is  $y(t) = 5 e^{-10t} u(t)$ , where  $u(t)$  is the unit step function. If the output of the system corresponding to an impulse input  $\delta(t)$  is  $h(t)$ , then  $h(t)$  is (GATE-IN 2008)
- a)  $-50 e^{-10t} u(t)$                       c)  $5 u(t) - 50 e^{-10t} \delta(t)$   
b)  $5 e^{-10t} \delta(t)$                       d)  $5 \delta(t) - 50 e^{-10t} u(t)$
- 59) A 2 A full-scale PMMC type dc ammeter has a voltage drop of 100 mV at 2 A. The meter can be converted into a 10 A full-scale dc ammeter by connecting a (GATE-IN 2008)
- a) 12.5 m $\Omega$  resistor in parallel with the meter                      c) 50.0 m $\Omega$  resistor in parallel with the meter  
b) 12.5 m $\Omega$  resistor in series with the meter                      d) 50.0 m $\Omega$  resistor in series with the meter
- 60) A  $3\frac{1}{2}$  digit, 200 mV full scale DVM has an accuracy specification of  $\pm 0.5\%$  of reading plus 5 counts. When the meter reads 100 mV, the voltage being measured is (GATE-IN 2008)
- a) any value between 99.5 mV and 100.5 mV                      c) exactly 99.5 mV  
b) any value between 99.5 mV and 100.5 mV                      d) exactly 100 mV
- 61) A 230 V, 5 A, 50 Hz single phase house service energy meter has a meter constant of 360 rev/kWhr. The meter takes 50 s for making 51 revolutions of the disc when connected to a 10 kW, unity power factor load. The error in the reading of the meter is (GATE-IN 2008)
- a) 0 %                      b) +0.5 %                      c) -2.0 %                      d) +2.0 %
- 62) The op-amp based circuit of a half wave rectifier electronic voltmeter shown below Fig. 24 uses a PMMC ammeter with a full scale deflection (FSD) current of 1 mA and a coil resistance of 1 k $\Omega$ . The value of R that gives FSD for a sinusoidal input voltage of 100 mV (RMS) is (GATE-IN 2008)

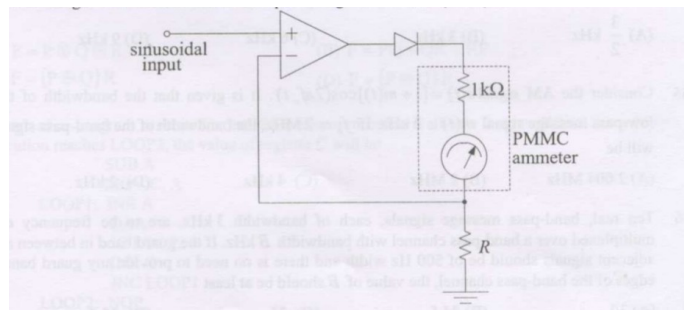


Fig. 24.

- a)  $45 \, \Omega$                       b)  $67.5 \, \Omega$                       c)  $100 \, \Omega$                       d)  $144.4 \, \Omega$

63) The x and y sensitivities of an analog oscilloscope are set as  $2 \text{ ms/cm}$  and  $1 \text{ V/cm}$  respectively. The trigger is set at  $0 \text{ V}$  with negative slope. An input of  $2 \cos(100\pi t + 30^\circ) \text{ V}$  is fed to the y input of the oscilloscope. The waveform seen on the oscilloscope will be (GATE-IN 2008)

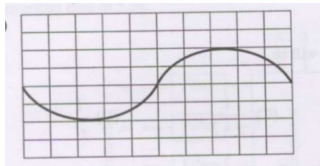


Fig. 25.

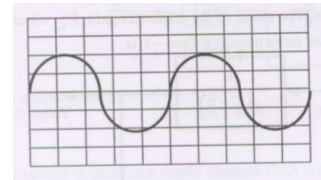


Fig. 27.

a)

c)

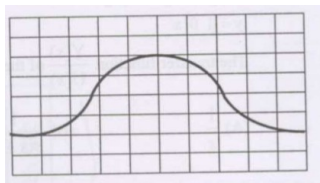


Fig. 26.

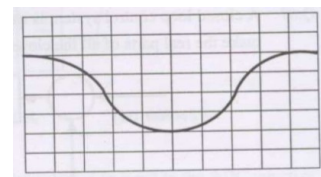


Fig. 28.

b)

d)

64) The open loop transfer function of a unity feedback system is  $G(s) = \frac{K(s+2)}{(s+1+j1)(s+1-j1)}$ . The root locus plot of the system has (GATE-IN 2008)

- a) two breakaway points located at  $s = -0.59$  and  $s = -3.41$   
 b) one breakaway point located at  $s = -0.59$   
 c) one breakaway point located at  $s = -3.41$   
 d) one breakaway point located at  $s = -1.41$

65) If a first order system and its time response to a unit step input are as shown below in Fig. 29, the gain  $K$  is (GATE-IN 2008)

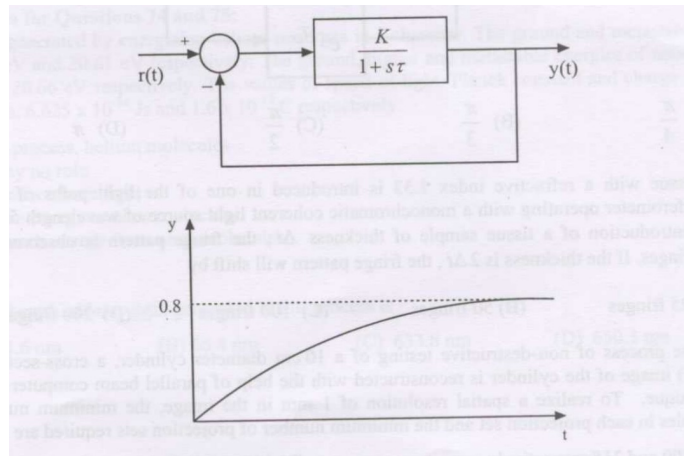


Fig. 29.

- a) 0.25                      b) 0.8                      c) 1                      d) 4

66) The state space representation of a system is given by

$$\dot{x} = \begin{pmatrix} 0 & 1 \\ 0 & -3 \end{pmatrix} x + \begin{pmatrix} 1 \\ 0 \end{pmatrix} u \quad (1)$$

$$y = \begin{pmatrix} 1 & 0 \end{pmatrix} x \quad (2)$$

The transfer function  $\frac{Y(s)}{U(s)}$  of the system will be (GATE-IN 2008)

- a)  $\frac{1}{s}$                       b)  $\frac{1}{s(s+3)}$                       c)  $\frac{1}{s+3}$                       d)  $\frac{1}{s^2}$

67) A closed loop control system is shown below. Fig. 30 The range of the controller gain  $K_C$  which will make the real parts of all the closed loop poles more negative than -1 is (GATE-IN 2008)

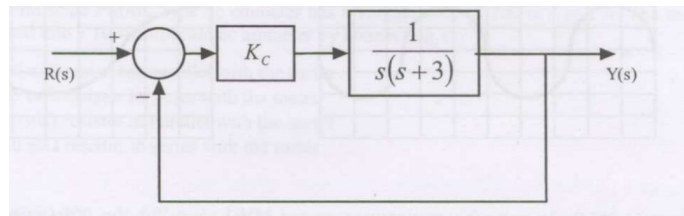


Fig. 30.

- a)  $K_C > -4$                       b)  $K_C > 0$                       c)  $K_C > 2$                       d)  $K_C < 2$

68) For the closed loop system shown below Fig. 31 to be stable, the value of time delay  $T_D$  (inseconds) should be less than (GATE-IN 2008)

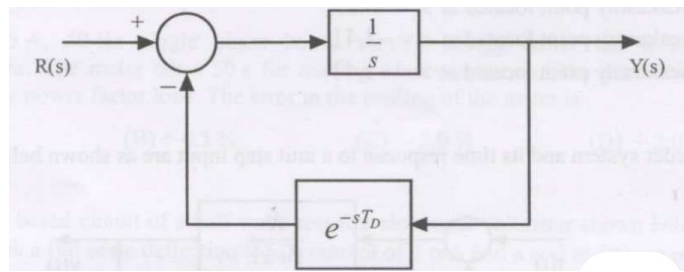


Fig. 31.

- a)  $\frac{\pi}{4}$                       b)  $\frac{\pi}{3}$                       c)  $\frac{\pi}{2}$                       d)  $\pi$

69) A tissue with a refractive index 1.33 is introduced in one of the light paths of a Michelson interferometer operating with a monochromatic coherent light source of wavelength 589 nm. After the introduction of a tissue sample of thickness  $\Delta t$ , the fringe pattern is observed to shift by 50 fringes. If the thickness is  $2 \Delta t$ , the fringe pattern will shift by (GATE-IN 2008)

- a) 25 fringes                      b) 50 fringes                      c) 100 fringes                      d) 200 fringes

70) In the process of non-destructive testing of a 10 cm diameter cylinder, a cross-sectional (*transaxial*) image of the cylinder is reconstructed with the help of parallel beam computer tomography technique. To realize a spatial resolution of 1 mm in the image, the minimum number of ray samples in each projection set and the minimum number of projection sets required are (GATE-IN 2008)

- a) 200 and 315 respectively                      c) 200 and 629 respectively  
b) 100 and 315 respectively                      d) 100 and 629 respectively

#### COMMON DATA QUESTIONS

**Common Data for Questions 71,72 and 73** A data acquisition system (DAS) shown below Fig. 32 employs a successive approximation type 12-bit ADC having a conversion time of  $5 \mu\text{s}$ .

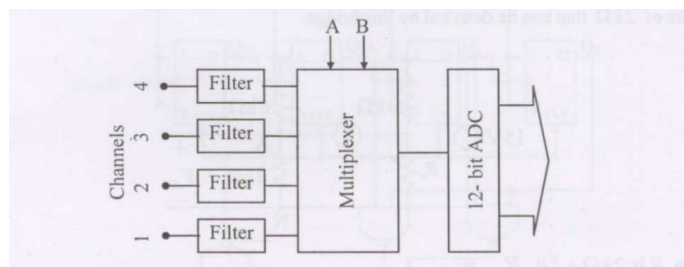


Fig. 32.

71) The quantization error of the ADC is (GATE-IN 2008)

- a) 0                      b)  $\pm 0.012 \%$                       c)  $\pm 0.024 \%$                       d)  $\pm 0.048 \%$

72) The system is used as a single channel DAS with channel 1 selected as input to the ADC which is set in the continuous conversion mode. For avoiding aliasing error, the cutoff frequency  $f_c$  of the filter in channel 1 should be (GATE-IN 2008)







- a) 0.125                      b) 0.25                      c) 0.5                      d) 1

**Statement for Linked Answer Questions 84 and 85 :**

A unity feedback system has open loop transfer function  $G(s) = \frac{100}{s(s+p)}$ . The time at which the response to a unit step input reaches its peak is  $\frac{\pi}{8}$  seconds.

84) The damping coefficient for the closed loop system is (GATE-IN 2008)

- a) 0.4                      b) 0.6                      c) 0.8                      d) 1

85) The value of p is (GATE-IN 2008)

- a) 6                      b) 12                      c) 14                      d) 16