

# Signal Processing

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**Abstract**—This manual provides solved problems in signal processing from GATE exam papers.

1. Let the state-space representation on an LTI system be  $\dot{x}(t) = Ax(t) + Bu(t)$ ,  $y(t) = Cx(t) + du(t)$  where A,B,C are matrices, d is a scalar, u(t) is the input to the system, and y(t) is its output. Let  $B = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}^T$  and  $d = 0$ . Which one of the following options for A and C will ensure that the transfer function of this LTI system is

$$H(s) = \frac{1}{s^3 + 3s^2 + 2s + 1} \quad (1.1)$$

$$(A) \ A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -2 & -3 \end{pmatrix} \text{ and } C = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix}$$

$$(B) \ A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & -2 & -1 \end{pmatrix} \text{ and } C = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix}$$

$$(C) \ A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -2 & -3 \end{pmatrix} \text{ and } C = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}$$

$$(D) \ A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & -2 & -1 \end{pmatrix} \text{ and } C = \begin{pmatrix} 0 & 0 & 1 \end{pmatrix}$$

**Solution:** From the given information,

$$\begin{pmatrix} \dot{x}(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} A & B \\ C & d \end{pmatrix} \begin{pmatrix} x(t) \\ u(t) \end{pmatrix} \quad (1.2)$$

Taking Laplace transform on both sides,

$$\begin{pmatrix} sX(s) \\ Y(s) \end{pmatrix} = \begin{pmatrix} A & B \\ C & d \end{pmatrix} \begin{pmatrix} X(s) \\ U(s) \end{pmatrix} \quad (1.3)$$

$$\Rightarrow sX(s) = AX(s) + BU(s) \quad (1.4)$$

$$\Rightarrow X(s) = (sI - A)^{-1}BU(s) \quad (1.5)$$

$$\begin{aligned} \Rightarrow Y(s) &= CX(s) + dU(s) \\ &= C(sI - A)^{-1}BU(s) + dU(s) \end{aligned} \quad (1.6)$$

$$(1.7)$$

By definition,

$$Y(s) = H(s)U(s) \quad (1.8)$$

$$\Rightarrow H(s) = C(sI - A)^{-1}B + d \quad (1.9)$$

$$= \frac{1}{s^3 + 3s^2 + 2s + 1} \quad (1.10)$$

$$\Rightarrow C(sI - A)^{-1}B + d = \frac{1}{s^3 + 3s^2 + 2s + 1} \quad (1.11)$$

Now we cross verify the options with eq 1.11.

By using a python script,

(A)

$$C(sI - A)^{-1}B + d = \frac{1}{s^3 + 3s^2 + 2s + 1} \quad (1.12)$$

(B)

$$C(sI - A)^{-1}B + d = \frac{1}{s^3 + 1s^2 + 2s + 3} \quad (1.13)$$

(C)

$$C(sI - A)^{-1}B + d = \frac{s^2}{s^3 + 3s^2 + 2s + 1} \quad (1.14)$$

(D)

$$C(sI - A)^{-1}B + d = \frac{s^2}{s^3 + 1s^2 + 2s + 3} \quad (1.15)$$

Hence A is the correct option.

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