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EE23BTECH11014- Devarakonda Guna vaishnavi

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Consider the state-space description of an LTI system with matrices

$$A = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix}, \quad B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \quad C = \begin{bmatrix} 3 & -2 \end{bmatrix}, \quad D = 1$$

For the input, $\sin(\omega t)$, $\omega > 0$, the value of ω for which the steady-state output of the system will be zero, is _____ (Round off to the nearest integer).