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Matrices

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1

1

2

3

CONTENTS

- **Definitions** 1 1.1 Eigenvalues and Eigenvectors 1.2 Determinants
 - 1.3 Inverse of a Matrix 2
- 2 **Cayley-Hamilton Theorem**
- 3 Matrix Polynomials
- 4 **Matrix Inverse**

Abstract—This book provides a computational approach to school geometry based on the NCERT textbooks from Class 6-12. Links to sample Python codes are available in the text.

Download python codes using

svn co https://github.com/gadepall/school/trunk/ ncert/computation/codes

1 DEFINITIONS

- 1.1 Eigenvalues and Eigenvectors
- 1.1.1. The eigenvalue λ and the eigenvector x for a matrix A are defined as,

$$\mathbf{A}\mathbf{x} = \lambda\mathbf{x} \tag{1.1.1.1}$$

equation

$$f(\lambda) = |\lambda \mathbf{I} - \mathbf{A}| = 0 \tag{1.1.2.1}$$

The above equation is known as the characteristic equation.

1.1.3. According to the Cayley-Hamilton theorem,

$$f(\lambda) = 0 \implies f(\mathbf{A}) = 0$$
 (1.1.3.1)

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1.1.4. The trace of a square matrix is defined to be the sum of the diagonal elements.

$$\operatorname{tr}(\mathbf{A}) = \sum_{i=1}^{N} a_{ii}.$$
 (1.1.4.1)

where a_{ii} is the *i*th diagonal element of the matrix A.

- 1.1.5. The trace of a matrix is equal to the sum of 3 the eigenvalues
 - $\operatorname{tr}(\mathbf{A}) = \sum_{i=1}^{N} \lambda_{i}$ (1.1.5.1)
 - 1.2 Determinants
 - 1.2.1. Let

$$\mathbf{A} = \begin{pmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{pmatrix}. \tag{1.2.1.1}$$

be a 3×3 matrix. Then,

$$\begin{vmatrix} \mathbf{A} \end{vmatrix} = a_1 \begin{pmatrix} b_2 & c_2 \\ b_3 & c_3 \end{pmatrix} - a_2 \begin{pmatrix} b_1 & c_1 \\ b_3 & c_3 \end{pmatrix} + a_3 \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix}. \quad (1.2.1.2)$$

1.1.2. The eigenvalues are calculated by solving the 1.2.2. Let $\lambda_1, \lambda_2, \dots, \lambda_n$ be the eigenvalues of a matrix A. Then, the product of the eigenvalues is equal to the determinant of A.

$$\left|\mathbf{A}\right| = \prod_{i=1}^{n} \lambda_i \tag{1.2.2.1}$$

$$|\mathbf{A}\mathbf{B}| = |\mathbf{A}| |\mathbf{B}| \tag{1.2.3.1}$$

$$|k\mathbf{A}| = k^n |\mathbf{A}| \tag{1.2.4.1}$$

1.3 Inverse of a Matrix

1.3.1. For a 2×2 matrix

$$\mathbf{A} = \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix}, \tag{1.3.1.1}$$

the inverse is given by

$$\mathbf{A}^{-1} = \frac{1}{|\mathbf{A}|} \begin{pmatrix} b_2 & -b_1 \\ -a_2 & a_1 \end{pmatrix}, \qquad (1.3.1.2)$$

1.3.2. For higher order matrices, the inverse should be calculated using row operations.

2 CAYLEY-HAMILTON THEOREM

2.1. If

$$\mathbf{A} = \begin{pmatrix} 1 & 0 & 2 \\ 0 & 2 & 1 \\ 2 & 0 & 3 \end{pmatrix}, \tag{2.1.1}$$

prove that

$$\mathbf{A}^3 - 6\mathbf{A}^2 + 7\mathbf{A} + 2\mathbf{I} = 0 \tag{2.1.2}$$

Solution: From (1.1.2.1), the characteristic equation is

$$\begin{vmatrix} 1 - \lambda & 0 & 2 \\ 0 & 2 - \lambda & 1 \\ 2 & 0 & 3 - \lambda \end{vmatrix} = 0$$
 (2.1.3)

which can be expanded to obtain

$$(1 - \lambda)(2 - \lambda)(3 - \lambda) + 2(-2(2 - \lambda)) = 0$$
(2.1.4)

yielding

$$\lambda^3 - 6\lambda^2 + 7\lambda + 2 = 0 \tag{2.1.5}$$

upon simplification. Using the Cayley-Hamilton theorem in (1.1.3.1), (2.1.2) is obtained

2.2. If

$$\mathbf{A} = \begin{pmatrix} 3 & 1 \\ -1 & 2 \end{pmatrix}, \tag{2.2.1}$$

show that

$$\mathbf{A}^2 - 5\mathbf{A} + 7\mathbf{I} = 0 \tag{2.2.2}$$

Solution: The characteristic equation is

$$\left|\mathbf{A} - \lambda \mathbf{I}\right| = 0 \qquad (2.2.3)$$

$$\implies \begin{vmatrix} 3 - \lambda & 1 \\ -1 & 2 - \lambda \end{vmatrix} = 0 \qquad (2.2.4)$$

$$\implies (3 - \lambda)(2 - \lambda) + 1 = 0 \qquad (2.2.5)$$

or,
$$\lambda^2 - 5\lambda + 7 = 0$$
 (2.2.6)

Using the Cayley-Hamilton theorem, (2.2.2) is obtained.

2.3. If A is square matrix such that

$$\mathbf{A}^2 = \mathbf{A},\tag{2.3.1}$$

then

$$g\left(\mathbf{A}\right) = \left(\mathbf{I} + \mathbf{A}\right)^{3} - 7\mathbf{A} \tag{2.3.2}$$

is equal to

- a) **A**
- b) I A
- c) I
- d) 3**A**

Solution: From (2.3.2),

$$g(\lambda) = (1+\lambda)^3 - 7\lambda \tag{2.3.3}$$

Also,

$$\mathbf{A}^2 = \mathbf{A} \implies \mathbf{A}^2 - \mathbf{A} = 0 \tag{2.3.4}$$

Using the Cayley-Hamilton theorem, the eigenvalues satisfy the characteristic equation

$$f(\lambda) = \lambda^2 - \lambda = 0 \tag{2.3.5}$$

: $f(\lambda)$ is of degree 2 and $g(\lambda)$ is of degree 3, (2.3.3) can be expressed as

$$g(\lambda) = f(\lambda) q(\lambda) + a\lambda + b$$
 (2.3.6)

where a, b are real numbers and $q(\lambda)$ is some polynomial. Thus,

$$q(0) = b = 1 (2.3.7)$$

$$g(1) = a + b = 1 (2.3.8)$$

$$\implies a = 90, b = 1$$
 (2.3.9)

Thus,

$$g(\mathbf{A}) = f(\mathbf{A}) q(\mathbf{A}) + a\mathbf{A} + b\mathbf{I}$$
 (2.3.10)
= \mathbf{I} (2.3.11)

upon substituting from (2.3.5) and (2.3.9). Option c is the valid answer.

2.4. If

$$\mathbf{A} = \begin{pmatrix} 1 & 2 & 3 \\ 3 & -2 & 1 \\ 4 & 2 & 1 \end{pmatrix} \tag{2.4.1}$$

then show that

$$\mathbf{A}^3 - 23\mathbf{A} - 40\mathbf{I} = 0 \tag{2.4.2}$$

Solution: The Characteristic equation is given by

$$|\mathbf{A} - \lambda \mathbf{I}| = 0 \quad (2.4.3)$$

$$\implies \begin{vmatrix} 1 - \lambda & 2 & 3 \\ 3 & -2 - \lambda & 1 \\ 4 & 2 & 1 - \lambda \end{vmatrix} = 0 \quad (2.4.4)$$

which can be expressed as

$$\implies (1 - \lambda) ((-2 - \lambda) (1 - \lambda) - 2) -2 (3 (1 - \lambda) - 4) + 3 (6 + 4 (2 + \lambda)) = 0 (2.4.5)$$

and simplified to obtain

$$\implies \lambda^3 - 23\lambda - 40 = 0. \tag{2.4.6}$$

Using the Cayley-Hamilton Theorem, (2.4.2) is obtained.

3 MATRIX POLYNOMIALS

3.1. Find
$$\mathbf{A}^2 - 5\mathbf{A} + 6\mathbf{I}$$
, if $\mathbf{A} = \begin{pmatrix} 2 & 0 & 1 \\ 2 & 1 & 3 \\ 1 & -1 & 0 \end{pmatrix}$

Solution: Factorizing the corresponding polynomial,

$$f(x) = x^{2} - 5x + 6 \quad (3.1.1)$$

$$= (x - 3)(x - 2)$$

$$(3.1.2)$$

$$\implies \mathbf{A}^{2} - 5\mathbf{A} + 6\mathbf{I} = (\mathbf{A} - 3\mathbf{I})(\mathbf{A} - 5\mathbf{I})$$

$$(3.1.3)$$

$$\mathbf{A} - 3\mathbf{I} = \begin{pmatrix} 2 & 0 & 1 \\ 2 & 1 & 3 \\ 1 & -1 & 0 \end{pmatrix} + \begin{pmatrix} -3 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & -3 \end{pmatrix}$$
(3.1.4)

$$= \begin{pmatrix} -1 & 0 & 1\\ 2 & -2 & 3\\ 1 & -1 & -3 \end{pmatrix} \tag{3.1.5}$$

$$\mathbf{A} - 5\mathbf{I} = \begin{pmatrix} 2 & 0 & 1 \\ 2 & 1 & 3 \\ 1 & -1 & 0 \end{pmatrix} + \begin{pmatrix} -5 & 0 & 0 \\ 0 & -5 & 0 \\ 0 & 0 & -5 \end{pmatrix}$$
(3.1.6)

$$= \begin{pmatrix} 0 & 0 & 1 \\ 2 & -1 & 3 \\ 1 & -1 & -2 \end{pmatrix} \tag{3.1.7}$$

Multiplying the above expressions,

$$\mathbf{A}^{2} - 5\mathbf{A} + 6\mathbf{I} = \begin{pmatrix} -1 & 0 & 1\\ 2 & -2 & 3\\ 1 & -1 & -3 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1\\ 2 & -1 & 3\\ 1 & -1 & -2 \end{pmatrix} = \begin{pmatrix} 1 & -1 & -3\\ -1 & -1 & -10\\ -5 & 4 & 4 \end{pmatrix} (3.1.8)$$

4 MATRIX INVERSE

4.1. Using elementary transforamtions, find the inverse of $\begin{pmatrix} 1 & -1 \\ 2 & 3 \end{pmatrix}$

Solution: Given that

$$\mathbf{A} = \begin{pmatrix} 1 & -1 \\ 2 & 3 \end{pmatrix} \tag{4.1.1}$$

The augmented matrix [A|I] is as given below:-

$$\begin{pmatrix}
1 & -1 & | & 1 & 0 \\
2 & 3 & | & 0 & 1
\end{pmatrix}$$
(4.1.2)

We apply the elementary row operations on $[\mathbf{A}|\mathbf{I}]$ as follows :-

$$[\mathbf{A}|\mathbf{I}] = \begin{pmatrix} 1 & -1 & 1 & 0 \\ 2 & 3 & 0 & 1 \end{pmatrix} \tag{4.1.3}$$

$$\stackrel{R_2 \leftarrow R_2 - 2R_1}{\longrightarrow} \begin{pmatrix} 1 & -1 & 1 & 0 \\ 0 & 5 & -2 & 1 \end{pmatrix} \quad (4.1.4)$$

$$\stackrel{R_2 \leftarrow \frac{R_2}{5}}{\longleftrightarrow} \begin{pmatrix} 1 & -1 & 1 & 0 \\ 0 & 1 & \frac{-2}{5} & \frac{1}{5} \end{pmatrix} \tag{4.1.5}$$

$$\stackrel{R_2 \leftarrow R_1 + R_2}{\longrightarrow} \begin{pmatrix} 1 & 0 & \begin{vmatrix} \frac{3}{5} & \frac{1}{5} \\ 0 & 1 & \begin{vmatrix} \frac{-2}{5} & \frac{1}{5} \end{vmatrix} \end{pmatrix} \quad (4.1.6)$$

By performing elementary transformations on augmented matrix [A|I], we obtained the augmented matrix in the form [I|A]. Hence we can conclude that the matrix A is invertible and

$$\mathbf{A}^{-1} = \begin{pmatrix} \frac{3}{5} & \frac{1}{5} \\ \frac{-2}{5} & \frac{1}{5} \end{pmatrix} \tag{4.1.7}$$

4.2. Using elementary transforamtions, find the inverse of $\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$

Solution: Given that

$$\mathbf{A} = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \tag{4.2.1}$$

The augmented matrix [A|I] is as given below:-

$$\begin{pmatrix} 2 & 1 & | & 1 & 0 \\ 1 & 1 & | & 0 & 1 \end{pmatrix} \tag{4.2.2}$$

We apply the elementary row operations on $[\mathbf{A}|\mathbf{I}]$ as follows :-

$$[\mathbf{A}|\mathbf{I}] = \begin{pmatrix} 2 & 1 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{pmatrix} \tag{4.2.3}$$

$$\stackrel{R_1 \leftarrow R_1 - R_2}{\longleftrightarrow} \begin{pmatrix} 1 & 0 & 1 & -1 \\ 1 & 1 & 0 & 1 \end{pmatrix} \tag{4.2.4}$$

$$\stackrel{R_2 \leftarrow R_2 - R_1}{\longleftrightarrow} \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & -1 & 2 \end{pmatrix} \tag{4.2.5}$$

By performing elementary transformations on augmented matrix [A|I], we obtained the augmented matrix in the form [I|A]. Hence we can conclude that the matrix A is invertible and inverse of the matrix is

$$\mathbf{A}^{-1} = \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix} \tag{4.2.6}$$

4.3. Obtain the inverse of the following matrix using elementary operations

$$\mathbf{A} = \begin{pmatrix} 0 & 1 & 2 \\ 1 & 2 & 3 \\ 3 & 1 & 1 \end{pmatrix}.$$

Solution: Given that

$$\mathbf{A} = \begin{pmatrix} 0 & 1 & 2 \\ 1 & 2 & 3 \\ 3 & 1 & 1 \end{pmatrix}, \tag{4.3.1}$$

The augmented matrix $[\mathbf{A}|\mathbf{I}]$ is

$$\begin{pmatrix}
0 & 1 & 2 & | & 1 & 0 & 0 \\
1 & 2 & 3 & | & 0 & 1 & 0 \\
3 & 1 & 1 & | & 0 & 0 & 1
\end{pmatrix}$$
(4.3.2)

Applying elementary row operations on [A|I],

$$[\mathbf{A}|\mathbf{I}] = \begin{pmatrix} 0 & 1 & 2 & | & 1 & 0 & 0 \\ 1 & 2 & 3 & | & 0 & 1 & 0 \\ 3 & 1 & 1 & | & 0 & 0 & 1 \end{pmatrix}$$

$$(4.3.3)$$

$$\stackrel{R_1 \leftrightarrow R_2}{\longleftrightarrow} \begin{pmatrix} 1 & 2 & 3 & | & 0 & 1 & 0 \\ 0 & 1 & 2 & | & 1 & 0 & 0 \\ 3 & 1 & 1 & | & 0 & 0 & 1 \end{pmatrix}$$

$$(4.3.4)$$

$$\stackrel{R_3 \leftarrow R_3 \to 3R_1}{\longleftrightarrow} \begin{pmatrix} 1 & 2 & 3 & | & 0 & 1 & 0 \\ 0 & 1 & 2 & | & 1 & 0 & 0 \\ 0 & -5 & -8 & | & 0 & -3 & 1 \end{pmatrix}$$

$$(4.3.5)$$

$$\stackrel{R_1 \leftarrow R_1 \to 2R_2}{\longleftrightarrow} \begin{pmatrix} 1 & 0 & -1 & | & -2 & 1 & 0 \\ 0 & 1 & 2 & | & 1 & 0 & 0 \\ 0 & -5 & -8 & | & 0 & -3 & 1 \end{pmatrix}$$

$$(4.3.6)$$

$$\stackrel{R_3 \leftarrow R_3 + 5R_2}{\longleftrightarrow} \begin{pmatrix} 1 & 0 & -1 & | & -2 & 1 & 0 \\ 0 & 1 & 2 & | & 1 & 0 & 0 \\ 0 & 0 & 2 & | & 5 & -3 & 1 \end{pmatrix}$$

$$(4.3.7)$$

$$\stackrel{R_3 \leftarrow R_3/2}{\longleftrightarrow} \begin{pmatrix} 1 & 0 & -1 & | & -2 & 1 & 0 \\ 0 & 1 & 2 & | & 1 & 0 & 0 \\ 0 & 0 & 1 & | & \frac{5}{2} & -\frac{3}{2} & \frac{1}{2} \end{pmatrix}$$

$$(4.3.8)$$

$$\stackrel{R_1 \leftarrow R_1 + R_3}{\longleftrightarrow} \begin{pmatrix} 1 & 0 & 0 & | & \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ 0 & 1 & 2 & | & 1 & 0 & 0 \\ 0 & 0 & 1 & | & \frac{5}{2} & -\frac{3}{2} & \frac{1}{2} \end{pmatrix}$$

$$(4.3.9)$$

$$\stackrel{R_2 \leftarrow R_2 - 2R_3}{\longleftrightarrow} \begin{pmatrix} 1 & 0 & 0 & | & \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ 0 & 1 & 0 & | & -4 & 3 & -1 \\ 0 & 0 & 1 & | & \frac{5}{2} & -\frac{3}{2} & \frac{1}{2} \end{pmatrix}$$

By performing elementary transformations on augmented matrix [A|I], we obtained the augmented matrix in the form [I|A]. Hence we can conclude that the matrix A is invertible and inverse of the matrix is

$$\mathbf{A}^{-1} = \begin{pmatrix} \frac{1}{2} & \frac{-1}{2} & \frac{1}{2} \\ -4 & 3 & -1 \\ \frac{5}{2} & \frac{-3}{2} & \frac{1}{2} \end{pmatrix}$$
(4.3.11)

(4.3.2) 4.4. Find P⁻¹, if it exists, given $P = \begin{pmatrix} 10 & -2 \\ -5 & 1 \end{pmatrix}.$

Solution: Using row reduction,

$$\begin{pmatrix} 10 & -2 \\ -5 & 1 \end{pmatrix} \xrightarrow{R_2 \leftarrow R_2 + \frac{R_1}{2}} \begin{pmatrix} 10 & -2 \\ 0 & 0 \end{pmatrix} \tag{4.4.1}$$

Since we obtain a zero row, P^{-1} does not exist.