1

Quadratic Programming Assignment

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Abstract—This document contains the solution to Question 27 of Exercise 5 in Chapter 6 of the class 12 NCERT textbook.

1) The point on the curve

$$x^2 = 2y \tag{1}$$

which is nearest to the point $\mathbf{P} = \begin{pmatrix} 0 \\ 5 \end{pmatrix}$ is

a)
$$\begin{pmatrix} 2\sqrt{2} \\ 4 \end{pmatrix}$$

b)
$$\begin{pmatrix} 2\sqrt{2} \\ 0 \end{pmatrix}$$

c)
$$\begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

d)
$$\binom{2}{2}$$

Solution: We need to find

$$\min g\left(\mathbf{x}\right) = \|\mathbf{x} - \mathbf{P}\|^2 \tag{2}$$

s.t.
$$h(\mathbf{x}) = \mathbf{x}^{\mathsf{T}} \mathbf{V} \mathbf{x} + 2 \mathbf{u}^{\mathsf{T}} \mathbf{x} = 0$$
 (3)

where

$$\mathbf{V} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \ \mathbf{u} = \begin{pmatrix} 0 \\ -1 \end{pmatrix} \tag{4}$$

First, we show that (3) is nonconvex. Indeed, suppose $\mathbf{x_1}$ and $\mathbf{x_2}$ satisfy $h(\mathbf{x}) = 0$. Then,

$$\mathbf{x_1}^{\mathsf{T}} \mathbf{V} \mathbf{x_1} + 2 \mathbf{u}^{\mathsf{T}} \mathbf{x_1} + f = 0 \tag{5}$$

$$\mathbf{x_2}^{\mathsf{T}} \mathbf{V} \mathbf{x_2} + 2 \mathbf{u}^{\mathsf{T}} \mathbf{x_2} + f = 0 \tag{6}$$

Then, for any $0 \le \lambda \le 1$, substituting

$$\mathbf{x}_{\lambda} \leftarrow \lambda \mathbf{x}_1 + (1 - \lambda) \, \mathbf{x}_2 \tag{7}$$

into (3), we get

$$h(\mathbf{x}_{\lambda}) = \lambda (\lambda - 1) (\mathbf{x}_1 - \mathbf{x}_2)^{\mathsf{T}} \mathbf{V} (\mathbf{x}_1 - \mathbf{x}_2) + f \neq 0$$
(8)

Hence, the optimization problem is nonconvex. The constraints throw an error when *cvxpy* is used, as shown in the erroneous Python code codes/parab cvx.py.

We use the method of Lagrange multipliers instead to find the optima. Here, we need to find $\lambda \in \mathbb{R}$ such that there exists a \mathbf{x} satisfying

$$\nabla g\left(\mathbf{x}\right) = \lambda \nabla h\left(\mathbf{x}\right) \tag{9}$$

$$\implies 2(\mathbf{x} - \mathbf{P}) = 2\lambda(\mathbf{A}\mathbf{x} + \mathbf{u}) \tag{10}$$

$$\implies (\mathbf{I} - \lambda \mathbf{A}) \mathbf{x} = \lambda \mathbf{u} + \mathbf{P} \tag{11}$$

$$\implies \begin{pmatrix} 1 - \lambda & 0 \\ 0 & 1 \end{pmatrix} \mathbf{x} = \begin{pmatrix} 0 \\ 5 - \lambda \end{pmatrix} \tag{12}$$

From (12), we have two cases:

a) $\lambda \neq 1$. In this case, we form the augmented matrix

$$\begin{pmatrix} 1 - \lambda & 0 & 0 \\ 0 & 1 & 5 - \lambda \end{pmatrix} \stackrel{R_1 \leftarrow \frac{R_1}{1 - \lambda}}{\longleftrightarrow} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 5 - \lambda \end{pmatrix} \tag{13}$$

and get that

$$\mathbf{x_m} = \begin{pmatrix} 0 \\ 5 - \lambda \end{pmatrix} \tag{14}$$

Substituting in (3) gives $\lambda = 5$. Thus, $\mathbf{x_m} = \mathbf{0}$.

b) $\lambda = 1$. In this case, (12) becomes

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \mathbf{x} = \begin{pmatrix} 0 \\ 4 \end{pmatrix} \tag{15}$$

$$\implies \mathbf{e_2}^{\mathsf{T}} \mathbf{x} = 4 \tag{16}$$

Substituting (16) into (3) becomes

$$\left(\mathbf{e_1}^{\mathsf{T}}\mathbf{x}\right)^2 = 8\tag{17}$$

$$\implies \mathbf{e_1}^{\mathsf{T}} \mathbf{x} = \pm 2\sqrt{2} \tag{18}$$

Using (18) and (16),

$$\mathbf{x_m} = \begin{pmatrix} \pm 2\sqrt{2} \\ 4 \end{pmatrix} \tag{19}$$

Using these values of x_m , the distances are

$$\left\| \begin{pmatrix} 0 \\ 5 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right\| = 5 \tag{20}$$

$$\left\| \begin{pmatrix} 0 \\ 5 \end{pmatrix} - \begin{pmatrix} \pm 2\sqrt{2} \\ 4 \end{pmatrix} \right\| = 3 \tag{21}$$

Thus, the correct answer is **a**). We demonstrate both of the minima in (21) is obtained using constrained gradient descent in Fig. 1, plotted using the Python code codes/grad pits.py.

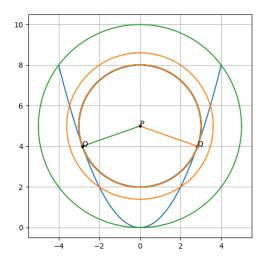


Fig. 1: Gradient descent for a nonconvex optimization problem.