

ACM ICPC Reference

University of São Paulo

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1 Começo da prova

Vim

```
1 set ai si noet ts=4 sw=4 sta sm nu rnu
1 inoremap {<CR> {<CR>}<Esc>O
1 inoremap <NL> <ESC>o
2 nnoremap <NL> o
3 "carry lines insert
3 inoremap <C-up> <C-o>:m-2<CR>
3 inoremap <C-down> <C-o>:m+1<CR>
3 "carry lines
3 nnoremap <C-up> :m-2<CR>
3 nnoremap <C-down> :m+1<CR>
5 "carry lines visual
5 vnoremap <C-up> :m-2<CR>gv
5 vnoremap <C-down> :m'+1<CR>gv
6 colors evening
6 set t_Co=8
6 syntax on
highlight Normal ctermbg=NONE "No background
highlight nonText ctermbg=NONE
hi Normal ctermbg=none
highlight NonText ctermbg=none
```

2 Fluxo

Max Flow

```
namespace f {
    const int maxv = ;
    const int maxe = * 2;
    typedef int num;
    num inf = /*INT_MAX*/;
    int n = maxv;

    int to[maxe], en, nx[maxe], es[maxe], lv[maxv], qu[maxv], cr[maxv];
    num cp[maxe], fl[maxe];
}
```

```

bool bfs(int s, int t) {
    memset(lv, -1, sizeof(int) * n);
    lv[s] = 0;
    int a = 0, b = 0;
    qu[b++] = s; cr[s] = es[s];
    while(a < b) {
        for(int i = es[qu[a]]; i != -1; i = nx[i]) {
            if(cp[i] > fl[i] && lv[to[i]] == -1) {
                lv[to[i]] = lv[qu[a]] + 1;
                qu[b++] = to[i];
                cr[to[i]] = es[to[i]];
                if(to[i] == t) return true;
            }
        }
        a++;
    }
    return false;
}

num dfs(int u, int t, num mx) {
    if(u == t) return mx;
    for(int &i = cr[u]; i != -1; i = nx[i])
        if(cp[i] > fl[i] && lv[to[i]] == lv[u] + 1)
            if(num a = dfs(to[i], t, min(mx, cp[i] - fl[i])) {
                fl[i] += a;
                fl[i ^ 1] -= a;
                return a;
            }
    return 0;
}

num max_flow(int s, int t) {
    num fl = 0, a;
    while(bfs(s, t))
        while(a = dfs(s, t, inf))
            fl += a;
    return fl;
}

void reset_all(int n2=maxv) { n = n2; en = 0; memset(es, -1, sizeof(int) * n);
void reset_flow() { memset(fl, 0, sizeof(num) * en); }

void add_edge(int a, int b, num c, num rc=0) {
    fl[en] = 0; to[en] = b; cp[en] = c; nx[en] = es[a]; es[a] = en++;
    fl[en] = 0; to[en] = a; cp[en] = rc; nx[en] = es[b]; es[b] = en++;
}
}

```

Min Cost

```
namespace f {
```

```

const int N = , M = * 2;
typedef int val;
typedef int num;
int es[N], to[M], nx[M], en, pai[N];
val fl[M], cp[M];
num cs[M], d[N];
const num inf = 1e8, eps = 0;
const val infv = INT_MAX;
int seen[N], tempo;
int qu[N];

num tot;
bool spfa(int s, int t) {
    tempo++;
    int a = 0, b = 0;
    for(int i = 0; i < N; i++) d[i] = inf;
    d[s] = 0;
    qu[b++] = s;
    seen[s] = tempo;
    while(a != b) {
        int u = qu[a++]; if(a == N) a = 0;
        seen[u] = 0;
        for(int e = es[u]; e != -1; e = nx[e])
            if(cp[e] - fl[e] > val(0) && d[u] + cs[e] < d[to[e]] - eps) {
                d[to[e]] = d[u] + cs[e]; pai[to[e]] = e ^ 1;
                if(seen[to[e]] < tempo) { seen[to[e]] = tempo; qu[b++] = to[e]; }
            }
        if(d[t] == inf) return false;
        val mx = infv;
        for(int u = t; u != s; u = to[pai[u]])
            mx = min(mx, cp[pai[u] ^ 1] - fl[pai[u] ^ 1]);
        tot += d[t] * val(mx);
        for(int u = t; u != s; u = to[pai[u]])
            fl[pai[u]] -= mx, fl[pai[u] ^ 1] += mx;
        return mx;
    }
}

void init(int n) {
    en = 0;
    memset(es, -1, sizeof(int) * n);
}

val flow;
num mncost(int s, int t) {
    tot = 0; flow = 0;
    while(val a = spfa(s, t)) flow += a;
    return tot;
}

void add_edge(int u, int v, val c, num s) {
    fl[en] = 0; cp[en] = c; to[en] = v; nx[en] = es[u]; cs[en] =
s; es[u] = en++;
    fl[en] = 0; cp[en] = 0; to[en] = u; nx[en] = es[v]; cs[en] = -s; es[v] = en++;
}

```

```
}
}
```

3 Strings

Z Algorithm

```
// Z Algorithm
//////////
const int MAXS = ;

int L, R, Z[MAXS];

char seq[MAXS];

inline void ZAlgorithm(char s[]){
    int tam = strlen(s);
    L = R = 0;
    for(int i=1;i<tam;i++){
        if(i > R){
            L = R = i;
            while(R < tam && s[R] == s[R-L])
                R++;
            Z[i] = R-L;
            R--;
        }
        else{
            if(Z[i-L] >= R-i+1){
                L = i;
                while(R < tam && s[R] == s[R-L])
                    R++;
                Z[i] = R-L;
                R--;
            }
            else
                Z[i] = Z[i-L];
        }
    }
}

int main (){
    scanf("%s", seq);
    ZAlgorithm(seq);
    return 0;
}
```

4 Grafos

Heavy Light Decomposition

```
int pai[MAXN][LOGN], chainNo[MAXN], chainInd[MAXN], subsize[MAXN], nchain, degs, inicha

vector <int> adj[MAXN], pes[MAXN];
vector <pair<pii,int> > ares;

int tree[8*MAXN];

int h[MAXN], custopai[MAXN];

int res;

void dfs(int v,int ant){
    pai[v][0] = ant;
    h[v] = h[ant]+1;
    for(int a=1;a<LOGN;a++){
        pai[v][a] = pai[pai[v][a-1]][a-1];
    }
    subsize[v] = 1;
    for(int a=0;a<adj[v].size();a++){
        int nxt = adj[v][a];
        if(nxt != ant){
            custopai[nxt] = pes[v][a];
            dfs(nxt,v);
            subsize[v] += subsize[nxt];
        }
    }
}

void HLD(int v){
    chainInd[v] = degs;
    chainNo[v] = nchain;
    int mai=-1, ind=-1, maip = -1;
    for(int a=0;a<adj[v].size();a++){
        int nxt = adj[v][a];
        int cus = pes[v][a];
        if(nxt == pai[v][0]) continue;
        if(mai < subsize[nxt]){
            mai = subsize[nxt];
            maip = cus;
            ind = nxt;
        }
    }
    if(mai != -1){
        if(inichain[nchain] == -1){
            inichain[nchain] = v;
        }
        s[degs++] = maip;
        HLD(ind);
    }
    else{
```

```

        // eh uma folha
        if(inichain[nchain] == -1){
            inichain[nchain] = v;
        }
        s[degs++] = 0; //para que todo no tenha uma valor na seg
    }
    for(int a =0;a<adj[v].size();a++){
        int nxt = adj[v][a];
        int cus = pes[v][a];
        if(nxt == pai[v][0] || nxt == ind) continue;
        nchain++;
        HLD(nxt);
    }
}

void build(int idx,int i,int j){
    if(i==j){
        tree[idx] = s[i];
        return;
    }
    int m = (i+j)/2;
    build(idx*2,i,m);
    build(idx*2+1,m+1,j);
    tree[idx] = max(tree[idx*2],tree[idx*2+1]);
}

int LCA(int i,int j){
    if(h[j] > h[i]) swap(i,j);

    if(h[i] > h[j]){
        for(int a = LOGN-1;a>=0;a--){
            if(h[pai[i][a]] > h[j]){
                i = pai[i][a];
            }
        }
        i = pai[i][0];
    }

    if(i==j) return i;

    for(int a=LOGN-1;a>=0;a--){
        if(pai[i][a] != pai[j][a]){
            i = pai[i][a];
            j = pai[j][a];
        }
    }
    return pai[i][0];
}

void qry(int idx,int i,int j,int l, int r){
    if(i > r || j < l) return ;
    if(i>=l && j<=r){
        res = max(res,tree[idx]);
        return;
    }

```

```

        int m = (i+j)/2;
        qry(idx*2,i,m,l,r);
        qry(idx*2+1,m+1,j,l,r);
    }

    void qryup(int i,int j){
        while(chainNo[i] != chainNo[j]){
            int j2 = inichain[chainNo[i]];
            int ii = chainInd[i], jj = chainInd[j2];
            if(ii!=jj)
                qry(1,1,degs-1,jj,ii-1);
            res = max(res, custopai[j2]);
            i = pai[j2][0];
        }
        int ii = chainInd[i], jj = chainInd[j];
        if(ii==jj) return;
        qry(1,1,degs-1,jj,ii-1);
    }

    void upd(int idx,int i, int j, int l, int val){
        if(i>l || j<l) return ;
        if(i == j){
            tree[idx] = val;
            return ;
        }
        int m = (i+j)/2;
        upd(idx*2,i,m,l,val);
        upd(idx*2+1,m+1,j,l,val);
        tree[idx] = max(tree[idx*2],tree[idx*2+1]);
    }

    void reset(){
        degs=1;
        nchain = 0;
        memset(inichain,-1,sizeof(inichain));
        memset(tree,0,sizeof(tree));
        ares.clear();
        for(int a=0;a<=n;a++){
            adj[a].clear();
            pes[a].clear();
        }
        h[pri] = -1;
        dfs(pri,pri);
        nchain = 0;
        HLD(pri);
        build(1,1,degs-1);
    }
}

```

5 Geometria

Header

```
/////Header de Geometria/////
```

```
// area de calota 2.pi.R.h (h altura)
// volume de calota pi.h/6 * (3r^2 + h^2)
```

```
#include <cmath>
#define temp template<typename num>
#define ptn point<num>
temp struct point {
    num x, y;
    ptn() {}
    ptn(num a, num b) : x(a), y(b) {}
    ptn operator + (ptn o) const { return ptn(x + o.x, y + o.y); }
    ptn operator - (ptn o) const { return ptn(x - o.x, y - o.y); }
    num operator * (ptn o) const { return x * o.x + y * o.y; }
    num operator ^ (ptn o) const { return x * o.y - y * o.x; }
    ptn operator * (num i) const { return ptn(x * i, y * i); }
    ptn operator / (num i) const { return ptn(x / i, y / i); }
    point<double> rotate(double deg) {
        double cs = cos(deg), sn = sin(deg);
        return point<double>(x*cs - y*sn, x*sn + y*cs);
    }
    num dist_sqr(ptn o) const { return (*this - o) * (*this - o); }
    bool operator < (ptn o) const { return x < o.x || (x == o.x && y < o.y); }
};
typedef point<int> pti;
typedef point<double> ptd;
temp inline num cross(ptn a, ptn b, ptn c) { return (c - a) ^ (b - a); }
// o ponto c esta no segmento [a, b]?
temp inline bool between_seg(ptn a, ptn b, ptn c) { return cross(a, b, c) == 0 && ((b - c) * (a - c) <= 0); }
// sqr dist de c pro segmento [a, b]
temp double dist_seg_sqr(ptn a, ptn b, ptn c) {
    if((b - a) * (c - b) > 0) return b.dist_sqr(c);
    if((a - b) * (c - a) > 0) return a.dist_sqr(c);
    double d = (b - a) ^ (c - a);
    return d * d / ((b - a) * (b - a));
}
temp int sign(num x) { return (x > 0) - (x < 0); }
// [a, b] intersecta [c, d]?
temp bool inter_seg(ptn a, ptn b, ptn c, ptn d) {
    if(between_seg(a, b, c) || between_seg(a, b, d) || between_seg(c, d, a) || between_seg(c, d, b)) return true;
    if((sign(cross(a, b, c)) * sign(cross(a, b, d)) == -1) && (sign(cross(c, d, a)) * sign(cross(c, d, b)) == -1)) return true;
    return false;
}

temp struct line {
    num a, b, c;
    line() {}
    line(num aa, num bb, num cc) : a(aa), b(bb), c(cc) {}

    line(ptn s, ptn e) : a(e.y - s.y), b(s.x - e.x), c(a*s.x + b*s.y) {}
    line pass(ptn p) { return line(a, b, a*p.x + b*p.y); }
    bool parallel(const line &o) const { return a * o.b - o.a * b == 0; }
    point<double> inter(line o) {
        double d = a * o.b - o.a * b;
        if(d == 0) return point<double>(0, 0); // fudeu
        return point<double>((o.b * c - b * o.c)/d, (a * o.c - o.a * c)/d);
    }
};
typedef line<int> lni;
typedef line<double> lnd;

// convex hull - modifique como necessario
void convex_hull(pti p[], pti st[], int n) {
    sort(p, p + n);
    int sn = 0;
    for(int i = 0; i < n; i++) {
        while(sn >= 2 && cross(st[sn - 2], st[sn - 1], p[i]) > 0)
            sn--;
        st[sn++] = p[i];
    }
    int k = sn;
    for(int i = n - 2; i >= 0; i--) {
        while(sn > k && cross(st[sn - 2], st[sn - 1], p[i]) > 0)
            sn--;
        st[sn++] = p[i];
    }
    sn--;
    // st[0..sn-1] agora tem o convex hull dos pontos p
}
```

6 FFTs

Marcos

```
typedef complex<long double> Complex;
const long double PI = acos(-1.0L);

// Computes the DFT of vector v if type = 1, or the IDFT if type = -1
// If you are calculating the product of polynomials, don't forget to set both
// vectors' degrees to at least the sum of degrees of both polynomials, regardless
// of whether you will use only the first few elements of the resulting array
vector<Complex> FFT(vector<Complex> v, int type) {
    int n = v.size();
    while (n & (n - 1)) { v.push_back(0); n++; }
    int logn = __builtin_ctz(n);
    vector<Complex> v2(n);
    for (int i = 0; i < n; i++) {
        int mask = 0;
        for (int j = 0; j < logn; j++)
            if (i & (1 << j))
                mask |= (1 << (logn - 1 - j));
        v2[mask] = v[i];
    }
    for (int len = 1; 2 * len <= n; len <= 1) {
        Complex wm(cos(type * PI / len), sin(type * PI / len));
        for (int i = 0; i < n; i += 2 * len) {
            Complex w = 1;
            for (int j = 0; j < len; j++) {
                Complex t = w * v2[i + j + len], u = v2[i + j];
                v2[i + j] = u + t; v2[i + j + len] = u - t;
                w *= wm;
            }
        }
    }
    if (type == -1) for (Complex &c: v2) c /= n;
    return v2;
}
```

Nath

```
#include <bits/stdc++.h>
using namespace std;
using ll = int64_t;
using ull = uint64_t;

const int P = 7*17*(1<<23) + 1;
const int g = 3;

struct mod{
    int x;
    mod(ll y) : x((y+ll(P))%P) {}
    mod() : x(0) {}
```

```
mod operator+(mod b) { return ll(x) + ll(b.x); }
mod operator-(mod b) { return ll(x) - ll(b.x); }
mod operator*(mod b) { return ll(x) * ll(b.x); }
};

mod fexp(mod a, ll e){
    mod t = 1;
    for(;e;a = a*a, e>>=1) if(e&1) t = t*a;
    return t;
}

namespace FFT {
    int n;
    vector<int> p;
    vector<mod> fft, w;
    void dft(vector<mod> &a, bool inv){
        mod t, odd; w[0] = 1;
        for(int i=0;i<n;i++) fft[p[i]] = a[i];
        for(int s=1;s<n;s*=2){
            t = fexp(g, (P-1)/(2*s));
            if(inv) t = fexp(t, 2*s-1);
            for(int i=1;i<s;i++) w[i] = t*w[i-1];
            for(int l=0;l<n;l+=2*s)
                for(int i=l;i<l+s;i++){
                    fft[i+s] = fft[i] - (odd = w[i-l]*fft[i+s]);
                    fft[i] = fft[i] + odd;
                }
        }
        if(inv) {
            t = fexp(n, P-2);
            for(int i=0;i<n;i++) fft[i] = t*fft[i];
        }
        a = fft;
    }

    void conv(vector<mod> a, vector<mod> b, vector<mod> &c){
        n = a.size() + b.size();
        for(;n!=(n&-n);n-= (n&-n)); n*=2;
        a.resize(n); b.resize(n); c.resize(n);
        fft.resize(n); w.resize(n); p.resize(n);
        for(int i=0;i<n;i++) p[i] = ((i&1)*(n>>1))|(p[i>>1]>>1);
        dft(a, 0); dft(b, 0);
        for(int i=0;i<n;i++) c[i] = a[i]*b[i];
        dft(c, 1);
    }
}
```

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1 Tudo

1.1 Dinic

```
// Dinico da massa
// Generico:  $O(V^2 E)$ 
// BipMatch:  $O(V^{(1/2)} E)$ 
// UnitCap:  $O(\min\{V^{(2/3)}, E^{(1/2)}\} E)$ 
#include <bits/stdc++.h>
using namespace std;

struct dinic {
    int hd[N], nx[M], to[M], ht[M], es;
    ll fl[M], cp[M];
    int n, src, snk;
    int dist[N], seen[N], visi[N], turn;
    int qi, qf, qu[N];

    inline void init () // antes de montar o grafo
    { es = 2; }

    inline void reset () {
        es = 2;
        memset(hd, 0, sizeof hd);
        memset(seen, 0, sizeof seen);
        memset(visi, 0, sizeof visi);
    }

    inline void connect (int i, int j, ll cap) {
//        printf("%d-%d [%lld]\n", i, j, cap);
        nx[es] = hd[i]; hd[i] = es; to[es] = j; cp[es] = cap; fl[es] = 0;
        es++;
        nx[es] = hd[j]; hd[j] = es; to[es] = i; cp[es] = fl[es] = 0; es++;
    }

    bool bfs () {
        turn++;
        qi = qf = 0;

        qu[qf++] = snk;
        dist[snk] = 0;
        seen[snk] = turn;

        while (qi < qf) {
            int u = qu[qi++];
```



```

        if (visi[u] == turn)
            continue;
        visi[u] = turn;

        for (int ed = hd[u]; ed; ed = nx[ed]) {
            if (cp[ed^1] == fl[ed^1])
                continue;
            int v = to[ed];

            if (seen[v] == turn && dist[v] <= dist[u]+1)
                continue;
            seen[v] = turn;
            dist[v] = dist[u]+1;
            qu[qf++] = v;
        }
    }

    return (seen[src] == turn);
}

11 dfs (int u, ll flw) {
    if (u == snk || flw == 0)
        return flw;

    for (int & ed = ht[u]; ed; ed = nx[ed]) {
        int v = to[ed];
        if (fl[ed] >= cp[ed] || seen[v] != turn || dist[v]+1 != dist[u])
            continue;
        if (ll ret = dfs(v, min(flw, cp[ed] - fl[ed]))) {
            fl[ed] += ret;
            fl[ed^1] -= ret;
            return ret;
        }
    }

    return 0;
}

11 debug () {
    for (int i = 0; i < n; i++){
        printf("%d:", i);
        for (int ed = hd[i]; ed; ed = nx[ed])
            printf(" %d[%11d/%11d]", to[ed], fl[ed], cp[ed]);
        printf("\n");
    }
}

```

```

ll maxflow () {
    ll res = 0;
    while (bfs()) {
        for (int i = 0; i < n; i++)
            ht[i] = hd[i];
        while (ll val = dfs(src, LLONG_MAX))
            res += val;
    }
    return res;
}
};

```

1.2 HLD

```

#include <bits/stdc++.h>
using namespace std;
typedef int node;
typedef int edge;
const int N = 1e5;
const int M = 2*N;

int n;
int hd[N];
int to[M], nx[M], es;

int id[N], *leaf, *sz;
int chain[N], d[N], anc[N], tree[2*N];
int ps, ls;
int dfs(node u, node p)
{
    int bst = 0, spc = u;
    sz[id[ps++] = u] = 1;
    d[u] = d[anc[u] = p] + 1;
    for (edge e = hd[u]; e != -1; e = nx[e])
        if (sz[to[e]] == 0)
        {
            sz[u] += dfs(to[e], u);
            if (sz[to[e]] > bst)
                bst = sz[to[e]], spc = to[e];
        }
    if (sz[u] == 1) leaf[ls++] = u;
    return sz[chain[u] = chain[spc] = u];
}
void build(node root)

```

```

{
    leaf = tree;
    sz   = tree + n;
    ps = ls = 0;
    dfs(root, root);
    for(int i=0;i<n;i++) chain[id[i]] = chain[chain[id[i]]];
    while(ls)
    {
        node u = leaf[--ls];
        while(u != chain[u])
            u = anc[tree[id[u]=ps++]=u];
        tree[id[u]=ps++] = u;
    }
}

```

1.3 Treap (Implicit)

```

#include <bits/stdc++.h>
using namespace std;

const int N = 2e5+7;
struct treap {
    int x[N], y[N], sz[N], T[N][2], ts;
    int s[2];
    void init() {
        srand(time(NULL));
        ts = 1;
        for(int i=0;i<N;i++) y[i] = i;
        random_shuffle(y, y+N);
    }
    void split(int t, int k){
        if(!t) return (void)(s[0] = s[1] = 0);
        bool d = sz[T[t][0]] < k;
        split(T[t][d], k - d*(1+sz[T[t][0]])); T[t][d] = s[!d]; s[!d] = t;
        sz[t] = 1 + sz[T[t][0]] + sz[T[t][1]];
    }
    int merge(int tl, int tr){
        int r;
        if(!min(tl,tr)) return max(tl, tr);
        if(y[tl] < y[tr]) T[r=tr][0] = merge(tl, T[tr][0]);
        else T[r=tl][1] = merge(T[tl][1], tr);
        sz[r] = 1 + sz[T[r][0]] + sz[T[r][1]];
        return r;
    }
}
// Tudo abaixo opcional

```

```

int count_less(int tree, int k){
    int ans = 0, t = tree;
    for(;t && x[t] != k;t=T[t][x[t] < k])
        ans += (x[t] < k)*(1 + sz[T[t][0]]);
    return ans + sz[T[t][0]];
}

int kth_element(int tree, int k){
    int t;
    if(sz[tree] < k) return -1;
    split(tree, k);
    for(t=s[0];T[t][1];t=T[t][1]);
    merge(s[0], s[1]);
    return t;
}

int insert(int tree, int k){
    int t = tree, less = 0;
    for(;t && x[t] != k;t=T[t][x[t] < k]) less += (x[t] <
        k)*(1+sz[T[t][0]]);
    if(t) return tree;
    split(tree, less); x[ts] = k; sz[ts] = 1;
    return merge(s[0],merge(ts++,s[1]));
}

int remove(int t, int k){
    if(!t) return t;
    if(x[t] == k) return merge(T[t][0], T[t][1]);
    T[t][x[t] < k] = remove(T[t][x[t] < k], k);
    sz[t] = 1 + sz[T[t][0]] + sz[T[t][1]];
    return t;
}

};

int q, tree;
int main(){
    treap T;
    T.init();

    scanf(" %d", &q);
    while(q--){
        char cmd; int tgt;
        scanf(" %c%d", &cmd, &tgt);
        if(cmd == 'I') tree = T.insert(tree, tgt);
        else if(cmd == 'D') tree = T.remove(tree, tgt);
        else if( cmd == 'C') printf("%d\n", T.count_less(tree, tgt));
        else {
            int tgt = T.kth_element(tree, tgt);
            if(tgt == -1) puts("invalid");
        }
    }
}

```

```

        else printf("%d\n", T.x[tgt]);
    }
}

```

1.4 KMP

```

#include <bits/stdc++.h>
using namespace std;
const int S = 1e6;
// Usa string indexada em 1
int kmp[S+1], m, n;
char P[S+1], T[S+1];

void build()
{
    int k;
    kmp[0] = k = -1;
    for(int i=1; i<m+1; i++)
    {
        while(k >= 0 && P[k+1] != P[i]) k = kmp[k];
        kmp[i] = ++k;
    }
}

void match()
{
    int j = 0;
    for(int i=1; i<n+1; i++)
    {
        while(j >= 0 && P[j+1] != T[i]) j = kmp[j];
        if(++j == m)
        {
            printf("Match comeando em %d\n", i-j+1);
            j = kmp[j];
        }
    }
}

```

1.5 Ordered Set (GCC only)

```

#include <bits/stdc++.h>
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>

```

```

#define GNU __gnu_pbds

using namespace std;
typedef unsigned long long int ull;
typedef long long int ll;
namespace GNU { typedef tree<int, null_type, less<int>, rb_tree_tag,
    tree_order_statistics_node_update> ordered_set; }
// null_type pode mudar pra virar map
// multiset e multimap no tem suporte aqui, tem que sair usando pair pelo
    jeito
// aquele less ali o comparador, louco n?
using GNU::ordered_set;

#ifdef ONLINE_JUDGE
#define lld I64d
#define DEBUG(...) {fprintf(stderr, __VA_ARGS__);}
#else
#define DEBUG(...) {}
#endif

ordered_set s;
int q;
int a;

int main () {
    while (scanf("%d %d", &q, &a) != EOF) {
        if (q == 1) {
            s.insert(a);
        } else if (q == 2){
            if (end(s) == s.find_by_order(a))
                printf("no\n");
            else
                printf("%d\n", (int) *s.find_by_order(a)); // se voc
                esquecer do cast ou do *, o gcc vai falar que sua familia
                no presta
        } else {
            printf("%d\n", (int) s.order_of_key(a));
        }
    }
}

```

1.6 Simpson

```

#include <bits/stdc++.h>

```

```

const double eps = 1e-7;

//INTEGRAL NUMERICA PELO METODO DE SIMPSON

// funcao a ser integrada
double f(double x){
    return x*x;
}

//aproximacao da integral no intervalo a,b de Simpson (nao o Homer)
//funciona muito bem para intervalos pequenos
double simpson(double a, double b) {
    return (f(a) + 4*f((a+b)/2) + f(b))*(b-a)/6;
}

//a ideia eh quebrar o intervalo a,b em duas metades e verificar se a
    aproximacao
//ja esta boa o suficiente. se nao estiver, integramos as metades
    recursivamente.
double integrate(double a, double b) {
    double m = (a+b)/2;
    double l = simpson(a,m), r = simpson(m,b), tot = simpson(a,b);
    if(fabs(l+r-tot) < eps) return tot;
    return integrate(a,m) + integrate(m,b);
}

```

1.7 Suffix Array

```

#include<bits/stdc++.h>
using namespace std;
const int S = 5e5+2;
const int L = 30;
char s[S];
int n;
int p[S],
    fst[S], snd[S],
    lcp[S], sa[S];
int buck[S], nx[S], idx[S];

void bucket_sort(int * v)
{
    for(int i=0;i<n;i++)
    {
        idx[i] = sa[i];
        nx[i] = buck[v[sa[i]]];
    }
}

```

```

        buck[v[sa[i]]] = i;
    }
    int pos = n-1, k = max(CHAR_MAX, n-1);
    while(pos >= 0)
    {
        while(buck[k] == -1) k--;
        int nd = buck[k];
        while(nd != -1)
        {
            sa[pos--] = idx[nd];
            nd = nx[nd];
        }
        buck[k] = -1;
    }
}

bool lexLess(int i, int j)
{ return fst[i] == fst[j] ? snd[i] < snd[j] : fst[i] < fst[j]; }
void build_sa()
{
    n = strlen(s);
    memset(buck, -1, sizeof buck);
    int k;
    p[n] = -1;
    for(int i=0;i<n;i++) p[i] = s[i];
    for(k=1;k<ML;k++)
    {
        for(int i=0;i<n;i++)
        {
            fst[i] = p[sa[i] = i];
            snd[i] = p[min(i+(1<<(k-1)), n)];
        }
        bucket_sort(snd);
        bucket_sort(fst);
        p[sa[0]] = 0;
        for(int i=1;i<n;i++)
            p[sa[i]] = p[sa[i-1]] + (fst[sa[i-1]] != fst[sa[i]] ||
                snd[sa[i-1]] != snd[sa[i]]);
        if( p[sa[n-1]] == n-1 ) break;
    }
    for(int i=0;i<n;i++) sa[p[i]] = i;
    int h = 0;
    for(int i=0;i<n;i++)
        if(p[i] == n-1) h = 0;
        else
        {

```



```

        int j = sa[p[i]+1];
        while(i+h < n && j+h < n && s[i+h] == s[j+h]) h++;
        lcp[p[i]]=h;
        h -= (!h);
    }
}

```

1.8 Hungarian

```

// Mtodo Hungaro para Emparelhamento Perfeito Bipartido de Peso Mximo
// O(n^3)
// http://www.ime.usp.br/~oshiro/maratona/bipmat/bipmatching.pdf
#include <bits/stdc++.h>

using namespace std;

typedef long long int num;

const int N = 200;
struct hungarian {
    int n; // tamanho
    int match[N]; // no emparelhado com j (-1 = nenhum)

    num cost[N][N]; // peso da aresta ij
    num pot[2][N]; // potenciais pot[0][i]=y[i] e pot[1][j]=z[j]
    num diff[N]; // delta

    int tree[2][N], empr;
    int visi[N], turn;

    void init() {
        memset(match, -1, sizeof match);

        for (int i = 0; i < n; i++) {
            diff[i] = INT_MAX;
            pot[1][i] = 0;

            pot[0][i] = INT_MIN;
            for (int j = 0; j < n; j++)
                pot[0][i] = max(pot[0][i], cost[i][j]);
        }
    }

    void include (int u) {
        if (tree[0][u] == empr) // muito importante, sem isso vira n^4

```

```

        return;

    tree[0][u] = empr;
    for (int i = 0; i < n; i++)
        diff[i] = min(diff[i], pot[0][u] + pot[1][i] - cost[u][i]);
}

void upd () {
    num del = INT_MAX;
    for (int i = 0; i < n; i++)
        if (tree[1][i] != empr)
            del = min(del, diff[i]);

    for (int i = 0; i < n; i++)
        if (tree[0][i] == empr)
            pot[0][i] -= del;

    for(int i = 0; i < n; i++)
        if (tree[1][i] == empr)
            pot[1][i] += del;
        else
            diff[i] -= del;
}

bool dfs (int u) {
    if (u == -1)
        return 1;
    if (visi[u] == turn)
        return 0;

    visi[u] = turn;
    include(u);

    for (int i = 0; i < n; i++) {
        if (pot[0][u] + pot[1][i] != cost[u][i])
            continue;

        tree[1][i] = empr;
        if (dfs(match[i])) {
            /* DEBUG: imprime caminhos encontrados
            printf("(%d-%d)", u, i);
            if (match[i] == -1)
                printf(" on empr %d\n", empr);
            else
                printf("->");
            */

```

```

        match[i] = u;
        return 1;
    }
}

return 0;
}

void solve () {
    init();

    for (int i = 0; i < n; i++) {
        for (int j = 0; j < n; j++)
            diff[j] = INT_MAX;

        empr++;
        while (++turn && !dfs(i))
            upd();
    }
}

num value () {
    /* DEBUG: imprime emparelhamento
    for (int i = 0; i < n; i++)
        printf("%d<->%d\n", match[i], i);
    */

    num res = 0;
    for (int i = 0; i < n; i++)
        res += cost[match[i]][i];
    return res;
}
};

```
