Recap: Stochastic Contextual Bandit setup

- Stochastic contextual bandits generalize adversarial contextual bandits by adding a stochastic reward model.
- At each round t:
 - The learner observes a context C_t .
 - Then chooses an action $A_t \in [k]$.
- The reward is given by:

$$X_t = r(C_t, A_t) + \eta_t$$

where:

- r is the expected reward function.
- η_t is a noise term.
- The noise η_t is conditionally 1-subgaussian given past observations.
- This implies:

$$\mathbb{E}[X_t \mid \mathcal{F}_t] = r(C_t, A_t)$$

and the noise has zero mean.



Terminology

- Let:
 - $C_t \in \mathcal{C}$: context at round t
 - $A_t \in [k]$: action chosen at round t
 - $X_t \in \mathbb{R}$: reward received
 - $r: \mathcal{C} \times [k] \to \mathbb{R}$: unknown expected reward function
 - η_t : noise
- Then the stochastic contextual bandit model assumes:

$$X_t = r(C_t, A_t) + \eta_t$$

- With the assumptions:
 - $\mathbb{E}[\eta_t \mid \mathcal{F}_t] = 0$
 - η_t is conditionally 1-subgaussian, i.e.,

$$\mathbb{E}\left[\exp(\lambda\eta_t) \mid \mathcal{F}_t\right] \le \exp\left(\frac{\lambda^2}{2}\right) \quad \forall \lambda \in \mathbb{R}$$

• Here, the filtration \mathcal{F}_t is defined as:

$$\mathcal{F}_t = \sigma(C_1, A_1, X_1, \dots, C_{t-1}, A_{t-1}, X_{t-1}, C_t, A_t)$$

• Because this filtration captures all the past data and the current action, but not the current reward.



Linearity assumption

- If the true reward function r(c,a) were known, the learner could act optimally at each round.
- Regret measures the performance gap due to not knowing r.
- In the worst case, estimating r(c,a) for every pair (c,a) is infeasible especially when the context space is large.
- \bullet A powerful workaround: assume rewards are linear in a feature map $\psi(c,a).$
- This yields the **stochastic linear contextual bandit** model.
- Smoothness of r can be controlled via bounds on $\|\theta^*\|$.

Feature map ψ , and Regret

- Let:
 - $C_t \in \mathcal{C}$: context at round t
 - $A_t \in [k]$: chosen action at round t
 - $\psi: \mathcal{C} \times [k] \to \mathbb{R}^d$: feature map
 - $\theta^* \in \mathbb{R}^d$: unknown parameter vector
 - $X_t = r(C_t, A_t) + \eta_t$: reward with 1-subgaussian noise η_t
- Assume the linear reward model:

$$r(c,a) = \langle \theta^*, \psi(c,a) \rangle \quad \text{for all } (c,a) \in \mathcal{C} \times [k]$$

• Define the optimal action at round t as:

$$A_t^* = \arg\max_{a \in [k]} r(C_t, a)$$

• Then the cumulative **regret** over n rounds is defined as:

$$R_n = \mathbb{E}\left[\sum_{t=1}^{n} \left(r(C_t, A_t^*) - r(C_t, A_t)\right)\right] = \mathbb{E}\left[\sum_{t=1}^{n} \left(\max_{a \in [k]} r(C_t, a) - X_t\right)\right]$$

ullet This measures the cumulative performance gap caused by not knowing the reward function r

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A lower bound on regret

- Lower Bound (Tabular Case):
- If you must learn r(c,a) for all M contexts and k actions, the worst-case cumulative regret is:

$$\Omega(nMk)$$

• This becomes infeasible when M is large (e.g., $M=2^{100}$).

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- Linear contextual bandits simplify into the stochastic linear bandit setting.
- All that matters is the feature vector not the specific identity of the action.
- At round t, the learner selects an action:

$$A_t \in \mathcal{A}_t \subset \mathbb{R}^d$$

The reward is linear in the chosen action:

$$X_t = \langle \theta^*, A_t \rangle + \eta_t$$

where:

- $oldsymbol{ heta}^* \in \mathbb{R}^d$ is an unknown parameter vector,
- η_t is 1-subgaussian noise.
- Pseudo-regret and expected regret are both defined over these chosen actions A_t .
- Special cases include:
 - Finite-armed bandits
 - Contextual bandits
 - Combinatorial linear bandits



• We simplify Eq. (19.1):

$$r(c,a) = \langle \theta^*, \psi(c,a) \rangle \quad \Rightarrow \quad X_t = \langle \theta^*, A_t \rangle + \eta_t$$

- Where:
 - $A_t \in \mathcal{A}_t \subset \mathbb{R}^d$: decision/action in round t
 - $\theta^* \in \mathbb{R}^d$: unknown parameter vector
 - η_t : 1-subgaussian noise, i.e.,

$$\mathbb{E}\left[e^{\lambda\eta_t}\mid \mathcal{F}_t\right] \leq \exp\left(\frac{\lambda^2}{2}\right) \quad \text{for all } \lambda \in \mathbb{R}$$

Pseudo-Regret:

$$\widehat{R}_n = \sum_{t=1}^n \left(\max_{a \in \mathcal{A}_t} \langle \theta^*, a \rangle - \langle \theta^*, A_t \rangle \right)$$

• Expected Regret:

$$R_n = \mathbb{E}[\hat{R}_n] = \mathbb{E}\left[\sum_{t=1}^n \left(\max_{a \in \mathcal{A}_t} \langle \theta^*, a \rangle - X_t\right)\right]$$

- UCB (Upper Confidence Bound) is a powerful method in stochastic bandits.
- It can be generalized to linear bandits using the optimism in the face of uncertainty (OFU) principle.
- The generalization involves:
 - ullet Estimating $heta^*$ with a confidence set $C_t \subset \mathbb{R}^d$
 - Selecting actions by solving:

$$A_t = \arg\max_{a \in \mathcal{A}_t} \max_{\theta \in C_t} \langle \theta, a \rangle$$

- The resulting algorithm is known as LinUCB or OFUL (Optimism in the Face of Uncertainty for Linear bandits).
- **Key challenge:** Constructing the confidence set C_t such that:
 - It contains θ^* with high probability,
 - While remaining as small as possible to ensure good exploration-exploitation balance.

Define Confidence Set:

Let $C_t \subset \mathbb{R}^d$ be a confidence set such that:

$$\mathbb{P}\left[\theta^* \in C_t\right] \ge 1 - \delta$$

Define UCB Estimate:

For any action $a \in \mathbb{R}^d$, define:

$$UCB_t(a) = \max_{\theta \in C_t} \langle \theta, a \rangle$$
 (19.2)

This gives an upper bound on the expected reward of a, under uncertainty about θ^* .

LinUCB Selection Rule:

$$A_t = \arg\max_{a \in \mathcal{A}_t} \mathrm{UCB}_t(a) \tag{19.3}$$

This rule selects the action that has the highest optimistic reward estimate based on the current confidence set C_t .

- Where is the challenge?
- Choosing the confidence set C_t is non-trivial:
 - It is no longer a simple scalar interval (as in basic bandits).
 - It must contain the true parameter θ^* with high probability.
 - Yet, it must also be as small (tight) as possible to avoid unnecessary exploration.
- We will later construct C_t as an ellipsoid:

$$C_t = \left\{ \theta \in \mathbb{R}^d : \left\| \theta - \hat{\theta}_{t-1} \right\|_{V_{t-1}} \le \beta_t \right\}$$

- This is an ellipsoid:
 - Centered at the current estimate $\hat{\theta}_{t-1}$.
 - Shaped by the matrix V_{t-1} .
 - Radius β_t is chosen based on subgaussian concentration bounds.
- We will derive and prove this construction rigorously in the next slides.

- Proof/Derivations (Preview):
- To build the confidence set C_t , we proceed as follows:
- Use **regularized least squares** to estimate θ^* :

$$\hat{\theta}_t = \arg\min_{\theta \in \mathbb{R}^d} \sum_{s=1}^t (X_s - \langle \theta, A_s \rangle)^2 + \lambda \|\theta\|^2$$

• Define the **design matrix** (regularized Gram matrix):

$$V_t = \lambda I + \sum_{s=1}^t A_s A_s^{\top}$$

 Then, using self-normalized martingale inequalities, we can show that with high probability:

$$\left\|\hat{\theta}_{t-1} - \theta^*\right\|_{V_{t-1}} \le \beta_t$$

• This directly yields the confidence ellipsoid:

$$C_t = \left\{ \theta \in \mathbb{R}^d : \left\| \theta - \hat{\theta}_{t-1} \right\|_{V_{t-1}} \le \beta_t \right\}$$

- Let's compute the gradient of the regularized least squares loss function $L(\theta)$, and set it to zero to solve for $\hat{\theta}_t$.
- Expand the loss function:

$$L(\theta) = \sum_{s=1}^{t} \left(X_s - A_s^{\top} \theta \right)^2 + \lambda \|\theta\|^2$$

• Take the gradient with respect to θ :

$$\nabla_{\theta} L(\theta) = -2 \sum_{s=1}^{t} A_s \left(X_s - A_s^{\top} \theta \right) + 2\lambda \theta$$

• Set the gradient to zero:

$$\sum_{s=1}^{t} A_s A_s^{\top} \theta + \lambda \theta = \sum_{s=1}^{t} A_s X_s$$

Group terms:

$$\left(\lambda I + \sum_{s=1}^{t} A_s A_s^{\top}\right) \theta = \sum_{s=1}^{t} A_s X_s$$

• Define the design matrix:

$$V_t := \lambda I + \sum_{s=1}^{t} A_s A_s^{\top}$$
 (19.6)

Then the solution is:

$$\hat{\theta}_t = V_t^{-1} \sum_{s=1}^t A_s X_s \tag{19.5}$$

• Note: Some sources define the estimate as $\hat{\theta}_{t-1}$ to emphasize that data only up to time t-1 is used to choose action A_t .



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• Given a positive definite matrix V, the set:

$$\left\{ x \in \mathbb{R}^d : (x - \mu)^\top V(x - \mu) \le \beta \right\}$$

is an **ellipsoid** centered at μ .

- Let $V = Q\Lambda Q^{\top}$ be the eigendecomposition of V, where:
 - ullet Q is an orthonormal matrix of eigenvectors q_1,\ldots,q_d
 - ullet $\Lambda = \mathsf{diag}(\lambda_1,\ldots,\lambda_d)$ contains the eigenvalues
- Then the Mahalanobis norm becomes:

$$||x - \mu||_V^2 = (x - \mu)^\top Q \Lambda Q^\top (x - \mu) = \sum_{i=1}^d \lambda_i \langle q_i, x - \mu \rangle^2$$

- This shows:
 - ullet The ellipsoid is stretched/scaled along directions q_i
 - Axis length in direction q_i is proportional to $\frac{1}{\sqrt{\lambda_i}}$
- Therefore:
 - As V_t increases in all directions (i.e., more data accumulated),
 - The ellipsoid shrinks indicating improved certainty and better learning
 - Provided β_t doesn't grow too fast, the confidence set contracts

Continued

- Why center at $\hat{\theta}_{t-1}$?
 - $\hat{\theta}_{t-1}$ is the best guess of θ^* using data from rounds 1 to t-1
 - ullet The confidence set C_t is built using this historical data
 - It allows us to apply the UCB principle:

"With high probability,
$$\theta^* \in C_t$$
"

ullet So we choose the action a that maximizes the most optimistic reward:

$$UCB_t(a) = \max_{\theta \in C_t} \langle \theta, a \rangle$$



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LinUCB

Let $\lambda>0$ be a regularization parameter, and let β_t be a confidence radius computed via concentration inequalities. Let d denote the dimension of the feature space.

$$V_0 \leftarrow \lambda I_d$$
$$b_0 \leftarrow 0 \in \mathbb{R}^d$$

① Observe context $C_t \in \mathcal{C}$ and corresponding action set:

$$\mathcal{A}_t = \{ \psi(C_t, 1), \dots, \psi(C_t, k) \} \subset \mathbb{R}^d$$

2 Compute the regularized least squares estimate:

$$\hat{\theta}_{t-1} = V_{t-1}^{-1} b_{t-1}$$

3 For each $a \in \mathcal{A}_t$, compute:

$$UCB_t(a) = \langle \hat{\theta}_{t-1}, a \rangle + \beta_t \cdot ||a||_{V_{t-1}^{-1}}$$



Frame Title

Select action:

$$A_t \in \arg\max_{a \in \mathcal{A}_t} \mathrm{UCB}_t(a)$$

Observe reward:

$$X_t = \langle \theta^*, A_t \rangle + \eta_t$$

Opdate:

$$V_t \leftarrow V_{t-1} + A_t A_t^{\top}$$
$$b_t \leftarrow b_{t-1} + A_t X_t$$

With probability at least $1-\delta$, the following inequality holds for all t:

$$\|\hat{\theta}_{t-1} - \theta^*\|_{V_{t-1}} \le \beta_t$$

where:

$$\beta_t = \sqrt{\lambda}S + \sqrt{2\log\left(\frac{\det(V_t)^{1/2}}{\delta \cdot \lambda^{d/2}}\right)}$$

assuming $\|\theta^*\|_2 \leq S$.



Frame Title

Symbol	Meaning
$\psi(C_t,a)$	Feature vector for context-action pair (C_t, a)
V_t	Regularized design matrix
b_t	Accumulated response-weighted features
$\hat{ heta}_t$	Ridge regression estimate of θ^*
eta_t	Confidence radius
$ x _{V}^{2}$	Mahalanobis norm: $x^{\top}Vx$
$UCB_t(a)$	Optimistic reward estimate
A_t	Selected action at round t