

BFS & DFS (Time & Space complexity)

(1) Algorithm explanation with Graph

* BFS (Breadth first search)

- * Explores level by level, starting from the source
- * visit all neighbours of the current node before moving deeper.
- * Guarantees shortest path in an unweighted graph.

* DFS (Depth first search)

- * Explores as deep as possible along one branch before backtracking.
- * uses recursion (or stack) to track unexplored paths.
- * Does not guarantee shortest path.

(2) Data structures used

* BFS :- Queue (FIFO)

* DFS :- Stack (LIFO) or recursion.

(3) Time complexity

- * Both BFS and DFS must visit all vertices (N) and traverse all edges (E).
- * Each vertex is enqueued/pushed once and dequeued/popped once.
- * Each edge is checked at most twice (undirected graph).

∴ Time complexity :- $O(N+E)$

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(4) SPACE complexity

* BFS

- * Needs a queue that can hold upto $O(N)$ nodes in the worst case.
- * Also requires adjacency list storage: $O(N+E)$
- * Space: $O(N+E)$.

* DFS

- * Needs recursion stack (or explicit stack)
- * In worst case, recursion depth = $O(N)$.
- * Plus adjacency list: $O(N+E)$.
- * Space: $O(N+E)$.

(5) Sparse vs Dense Graphs

- * Sparse graph: $E \approx O(N)$
 - * complexity: $O(N+E) \approx O(N)$.

- * Dense graph: $E \approx O(N^2)$

- * complexity: $O(N+E) \approx O(N^2)$

(6) Assumptions:

- (1) * Graph stored as adjacency list (not adjacency matrix, since that would be $O(N^2)$ space).

- * Graph is connected; otherwise, BFS/DFS must be run on each component.