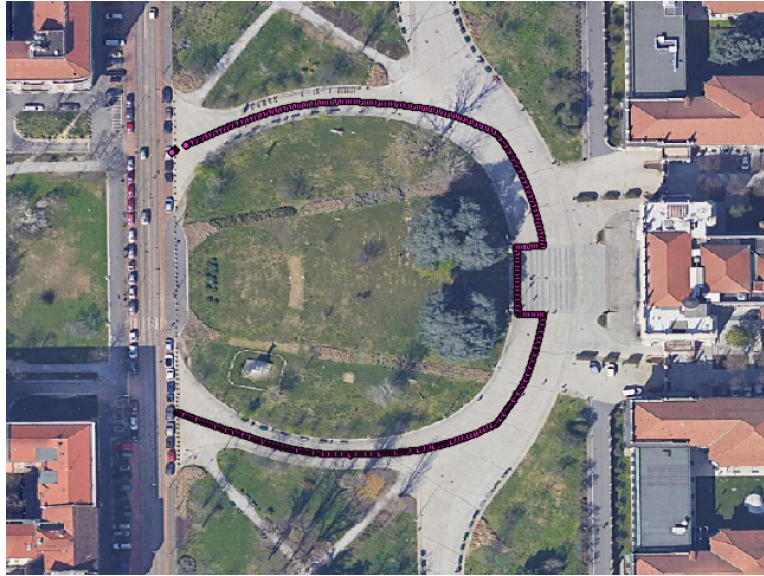**Trajectories: guidelines**

- Import RTK results in Matlab
- Import smartphone results in Matlab (2 files).
- Plot all measurements in one plot (East-North coordinates)
- Estimate the errors of the smartphones trajectories with respect to the RTK:
    1. for each smartphone point find the nearest RTK point,
    2. compute the distance from the nearest RTK point.
- Produce plots of errors for each smartphone dataset, and print the statistics (mean, max, min, STD).