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```
function results = pointMassOrbit(params)

% results = pointMassOrbit(params)
%
% Written by Garrett Ailts
%
% Description: Function simulates a point mass in orbit around planet
% Earth
% using the J2 pertubation model. Only forces modeled are Earth
% gravity.
%
% Inputs:
%   params - struct containing the necessary simulation input
%   parameters
%
% Outputs:
%   results - struct containing all the relevant results from the sim
%
```

Constants

```
deg2rad = pi/180;
```

Extract Necessary Parameters

```
Sim

nOrbits = params.nOrbits;
absTol = params.absTol;
relTol = params.relTol;

% Earth
mu = params.Earth.mu_e;
R = params.Earth.Rmean;

% Orbit
a = params.sc.sma;
e = params.sc.ecc;
inc = params.sc.inc*deg2rad;
```

Find Initial Conditions for Point Mass in Orbit

```
OMEGA = 0; % assume perigee at equator with RAAN = 0;
omega = 0;
theta = 0;

[r,v,~] = orbEl2rv(a, e, theta, OMEGA, omega, inc, mu); % transform
                                                         % orbital
                                                         % to pos. and
                                                         % vel.
x0 = [r; v];
```

Simulate

```
options = odeset('AbsTol',absTol,'RelTol',relTol);

T = 2*pi*sqrt(a^3/mu);
tspan = [0 nOrbits*T];

[t,xout] = ode45(@(t,x) OrbDyn(t,x,params),tspan,x0,options);
```

Post Process Data

```
xout = xout';
Post_Process;
results.t = t;
results.xout = xout;
results.E = E;
results.x0 = x0;
```

Creat Plots

```
Plotter;
EarthPlot(xout(1,:),xout(2,:),xout(3,:),R)
saveas(gcf,'figs/EarthPlot.png');
```

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