

John Romero Programming Proverbs

- 8. “Write your code for this game only - not for a future game. You’re going to be writing new code later because you’ll be smarter.”
- John Romero, “The Early Days of Id Software - John Romero @ WeAreDevelopers Conference 2017”

Extending the Remote procedure call API

- `disableAI () : boolean`
 - disable the in game C AI
 - return True/False if successful
 - (completed)

Extending the Remote procedure call API

- enableAI () : boolean
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Implementing these two function calls

- we need to modify the Python remote procedure call interface
- then we need to modify the ioquake source code
 - (completed)

Disable/Enable ioquake AI

- this has been completed in your source file
 - these notes show how the changes were made and
 - importantly also show you which files were altered

Python

- open up `ioquake-latest/python-bot/bot-legoman/botfiles/bots/botlib.py`
- alter
- ```
AI codes
SKILL, CONT = range(1, 3)
```

# Python

- to

- ```
# AI codes  
SKILL, CONT, CAI = range(1, 4)
```

- we now are going to define this new function CAI

Python

- now move to the definition of `class bot:` and continue down to find `def cont (self):`

- we now add

```
def cai (self, boolean):  
    """ enables/disables the C AI engine inside ioquake """  
    """ It returns the previous value of the C AI engine state """  
    """ True means it was on, False means it was off """  
    return calliB(AI, CAI, boolean)
```


Python

- calliB passes the three parameters as integers and returns a boolean result
- we now implement two more Python functions:
- ```
def disableAI ():
 """ disable the C AI and return True if successful """
 return cai(False)=True

def enableAI ():
 """ enable the C AI and return True if successful """
 return cai(True)=False
```
- the Python code is complete!



- open up the file: ioquake-  
latest/ioquake3/code/botlib/be\_ai\_char.c

```
//a bot character
typedef struct bot_character_s
{
 char filename[MAX_QPATH];
 float skill;
 int isPythonBot;
 py_bot_t py;
 bot_characteristic_t c[1];
} bot_character_t;
```



■ and change it to:

■

```
//a bot character
typedef struct bot_character_s
{
 char filename[MAX_QPATH];
 float skill;
 int isPythonBot;
 int c_ai;
 py_bot_t py;
 bot_characteristic_t c[1];
} bot_character_t;
```



■ change:

■

```
#if 1
 if ((strlen(charfile)>3) && (strcmp(&charfile[strlen(charfile)-3], ".py") == 0)) {
 ch->isPythonBot = qtrue;
 if (initPy(&ch->py, ch)) {
 ch->skill = skill;
```



■ to

■

```
#if 1
ch->c_ai = qtrue;
if ((strlen(charfile)>3) && (strcmp(&charfile[strlen(charfile)-3], ".py") == 0)) {
 ch->isPythonBot = qtrue;
 if (initPy(&ch->py, ch)) {
 ch->skill = skill;
```



- add the new function underneath `contrpc`



```
/*
 * cairpc - called by the rpc.
 * Bytes: <length><CODE><FUNCTION>
 * Integer: <True/False>
 *
 * The Integer value turns the C AI on/off.
 */

int cairpc (void *p)
{
 py_bot_t *py = (py_bot_t *)p;
 int *onoff = (int *)&py->inBuf[3];
 bot_character_t *ch = py->ch;
 int oldValue = ch->c_ai;

 ch->c_ai = *onoff;
 returnBoolean(p, (unsigned char)oldValue);
 return qtrue;
}
```



- open up `ioquake-`  
`latest/ioquake3/code/botlib/be_ai_char.h` and add this  
prototype to the end of the file:

```
/*
 * use_c_ai - returns true if, client, should use the C AI engine.
 */

int use_c_ai (int character);
```





- now open up ioquake-  
latest/ioquake3/code/botlib/be\_ai\_char.c and add this  
function after isPythonBot
- ```
/*  
 * use_c_ai - returns true if, client, should use the C AI engine.  
 */  
  
int use_c_ai (int character)  
{  
    return (botcharacters[character] != NULL) && (botcharacters[character]->c_ai);  
}
```



- now we need to add the C AI rpc call, so open up `ioquake-latest/ioquake3/code/botlib/be_ai_py.h` and alter

```
/*
 *  AI codes
 */

typedef enum Aicode_t {
    pyAIDummy, pySKILL, pyCONT, pyAImax,
} Aicode;
```



■ to

■

```
/*  
 *  AI codes  
 */  
  
typedef enum AIcond_t {  
    pyAIDummy, pySKILL, pyCONT, pyCAI, pyAImax,  
} AIcond;
```

- ```

/*
 * initAImethods - initialise the AI methods called by the rpc.
 */

EXTERN void initAImethods (py_bot_t *py,
 int (*skill)(void *),
 int (*cont)(void *),
 int (*cai)(void *));

```



- now we need to modify the call to `initAImethods` (found in file `be_ai_char.c`)

- ```
if (initPy(&ch->py, ch)) {  
    ch->skill = skill;  
    initAImethods(&ch->py, skillrpc, contrpc, cairpc);  
}
```

Exercise for the reader

- at this point the Python rpc mechanism can turn off/on the `c_ai` value
- the C ioquake code can use the function `use_c_ai` to test this bit
- we still need to modify ioquake so that it does not call the C AI if this function returns `TRUE`