- recall our previous example from last week which had two processes
 - one process calls put and another process calls get
- both operate on a shared buffer
 - we use a semaphore called Mutex to protect the buffer

```
void put (char ch)
                       char get (void)
  Wait (Mutex)
                         Wait(Mutex)
   (* safe to alter *) (* safe to alter *)
   (* buffer
                      (* buffer
  place ch into buf
                         remove ch from buf
   Signal (Mutex)
                          Signal (Mutex)
                          return ch;
    char buffer[Max];
                       (* global data *)
                      (* global data *)
    SEMAPHORE Mutex;
```

- what happens if a process calls get before a process calls put?
- there is no character to take from the buffer
 - there is no data to return
- what happens if a process keeps calling put and no process calls get
 - potentially the buffer will be overrun

- both cases can be fixed by using two additional semaphores
- if there is no character in the buffer and we call get then we should wait until data arrives
- if there is no space in the buffer and we attempt to put a character into the buffer then we should *wait* until space becomes available

- we can implement this with two semaphores, which we will declare as
 - itemAvailable
 - spaceAvailable

- before we place a character into a buffer we must wait (spaceAvailable)
- before we extract a character from a buffer we must wait (itemAvailable)
- after we place an item into the buffer we must signal (itemAvailable)
- after we extract an item from the buffer we must signal (spaceAvailable)

- what are their initial values for an empty buffer?
 - for simplicity let us assume the buffer can hold four characters
 - itemAvailable 0
 - spaceAvailable 3
- this buffer mechanism is known as Dijkstra's bounded buffer after its author E.W. Dijkstra who discovered the algorithm in 1960s

Completed implementation of a shared buffer using semaphores

```
void put (char ch)
                        char get (void)
  wait(spaceAvailable)
                          wait(itemAvailable)
  wait(mutex)
                          wait (mutex)
   (* safe to alter *)
                      (* safe to alter *)
   (* buffer
                       (* buffer
  place ch into buf
                          remove ch from buf
   signal(mutex)
                           signal (mutex)
   signal(itemAvailable)
                           signal(spaceAvailable)
                           return ch;
     char buffer[Max];
                        (* global data *)
                        (* global data *)
     SEMAPHORE mutex;
```

Completed implementation of a shared buffer using semaphores

if one process keeps calling put and another process calls get we see that both processes are synchronising against taking data from an empty buffer and also from putting data into a full buffer

- another common classic problem in operating systems is solving the readers/writers problem
- here the problem is defined as some common resource needs to be protected such that
 - multiple readers can read from the resource simultaneously
 - only one writer can write to the resource at a time
 - a writer must wait for all readers to finish reading before it can alter the resource

- how to solve this with the minimal amount of semaphores?
- this problem is common amoung databases or game servers
- we use a mutex semaphore to protect the other data structures used in our lock
- we use another semaphore writers to queue multiple writers trying to access the shared resource
- we use an integer count to count the number of readers reading from the resource readcount

the writer processes can be implemented by:

```
writers = semaphore (value = 1)

while True:
    ...
    wait(writers)
    # the process can now write to the shared resource
    signal(writers)
    ...
```

the reader process can be implemented by:

```
mutex = semaphore (value = 1)
readcount = 0

while True:
    ...
    wait(mutex)
    readcount = readcount+1
    if readcount == 1:  # first reader waits as a writer
        wait(writers)
    signal(mutex)
    # reader can read the shared resource
    wait(mutex)
    readcount = readcount-1
    if readcount == 0:  # last reader signals as a writer
        signal(writers)
    signal(mutex)
    ...
...
```

Interprocess communication: Message passing

- message passing is another form of Interprocess Communication
- it allows processes to communicate and to synchronise their actions without sharing the same address space
- a message passing facility provides at least two operations
 - send(message) and receive(message)
- some message passing libraries allow for variable sized data to be sent/received and other allow a fixed amount of data to be send/received
 - tradoffs between complexity of implementation of the library and complexity of the user program

Interprocess communication: Message passing

- the message passing libraries also may be further complicated by how a process addresses another process
- consider
- send(P, message) # send a message to process P received(Q, message) # receive a message from process Q
- we describe these primitives as having symmetry in addressing
 - that is both processes need to know the name of the other to receive and send a message

Interprocess communication: Message passing

other library implementations might use asymmetric naming for process addressing, consider:

Conclusion

- we have seen how semaphores can be used to solve some classic computer science problems
 - readers/writers and shared buffer
- we have explored the message passing paradigm