John Romero Programming Proverbs

- 9. "Encapsulate functionality to ensure design consistency. This minimizes mistakes and saves design time."
- John Romero, "The Early Days of Id Software John Romero @ WeAreDevelopers Conference 2017"

- you will need to back port the changes you made last week into your working chisel \$HOME/Sandpit/chisel
- an easy way to do this is to use diff and patch
 - hint read man diff and man patch

```
$ cd $HOME/Sandpit/labels/chisel
$ git diff
$ git diff > $HOME/Sandpit/labels/label-diffs
$ cd $HOME/Sandpit/chisel
$ patch -p1 < $HOME/Sandpit/labels/label-diffs</pre>
```

- the command git diff generates a list of differences between each file and the last git clone
- the command patch tries to apply these differences to the current directory
 - this is used a lot in industry and it is a very efficient way to distribute source code changes
 - occasionally you need to manual apply a patch which fails
 - normally patch will complain and store a .rej file
- these notes are better read using the pdf version

\$HOME/Sandpit/chisel/maps/label3.txt

- given the map source file above can be transformed into a pen map using
- \$ cd \$HOME/Sandpit/chisel/python
 - \$ python3 txt2pen.py ../maps/label3.txt
- if you want autolights you need to add the -1 option

```
ROOM 1
WALL
1 7 36 7
36 7 36 1
36 1 1 1
1 1 7
MONSTER python_doommarine_mp AT 12 5
AMMO ammo_shells_large AMOUNT 16 AT 24 4
SPAWN PLAYER AT 4 4
INSIDE AT 4 5
LABEL AT 24 4 the_ammo_loc
END
END.
```

keep the comment grammer up to date

```
python/pen2map.py
```

- which states a room starts with a keyword ROOM followed by an integer followed by a description
 - one of which is the labelDesc

python/pen2map.py

```
labelDesc := 'LABEL' 'AT' posDesc string =:
```

the grammer comment is at the top of the source file in a multi line comment

```
class roomInfo:
    def __init__ (self, r, w, d):
        self.walls = orderWalls (r, w)
        ...
        self.floorLevel = None
        self.inside = None
        self.defaultColours = {}
        self.sounds = []
        self.labels = []
```

```
def addSound (self, s, pos):
    self.sounds += [[s, pos]]
  def addLabel (self, label, pos):
    self.labels += [[label, pos]]
```

```
#
# labelDesc := 'LABEL' 'AT' posDesc string =:
#

def labelDesc ():
    expect ('LABEL')
    expect ('AT')
    if posDesc ():
        label = get ()
        curRoom.addLabel (label, curPos)
        return True
    else:
        errorLine ('expecting a position for a label')
    return False
```

```
def generateWeapons (o, e):
   n = 1
   for r in list(rooms.keys ()):
       if debugging:
          print(rooms[r].weapons)
       for weapon_kind, xy in rooms[r].weapons:
          o.write ("// entity " + str (e) + ' \n')
          o.write ("{\n")
          o.write (' "inv item" "4"\n')
          o.write (' "origin" "')
          xyz = toIntList (xy) + [-invSpawnHeight]
          xyz = subVec (xyz, [minx, miny, getFloorLevel (r)])
          v = midReposition (xyz)
          o.write ('%f %f %f"\n' % (v[0], v[1], v[2]))
          o.write ("}\n")
          n += 1
          e += 1
   return o, e
```

```
def generateLabels (o, e):
   n = 1
   for r in list(rooms.keys ()):
       if debugging:
           print (rooms[r].labels)
       for label_desc, xy in rooms[r].labels:
           o.write ("// entity " + str (e) + ' \n')
           o.write ("{\n")
           o.write (' "classname" "item_default"\n')
           o.write (' "label" "' + label_desc + '"\n')
           o.write (' "origin" "')
           xyz = toIntList (xy) + [-invSpawnHeight]
           xyz = subVec (xyz, [minx, miny, getFloorLevel (r)])
           v = midReposition (xyz)
           o.write ('%f %f %f"\n' % (v[0], v[1], v[2]))
           o.write ("}\n")
           n += 1
           e += 1
    return o, e
```

```
def generateMap (o):
    o, e = generateLights (o, e)
    o, e = generateAmmo (o, e)
    o, e = generateSounds (o, e)
    o, e = generateWeapons (o, e)
    o, e = generateLabels (o, e)
    if statistics:
        print("Total rooms =", len (list(rooms.keys ())))
        print("Total cuboids =", len (list(cuboids.keys ())))
```

Testing the tool chain

- \$ cd \$HOME/Sandpit/chisel/python
 \$ python3 txt2pen.py -1 ../maps/label3.txt
 \$ python3 txt2pen.py -1 -o tiny.pen ../maps/label3.txt
 \$ cat tiny.pen
 \$ PYTHONPATH=student python3 pen2map.py tiny.pen
 \$ PYTHONPATH=student python3 pen2map.py -o tiny.map tiny.pen
- if this works then you can simplify these commands to:
- \$ cd \$HOME/Sandpit/chisel/python
 - \$./developer-txt2map ../maps/label3.txt

Testing the tool chain

- now download a new copy of doom3 and try out the new bot code
 - you will need to remove the current pybot-dhewm3 code (or move it out of the way)

```
$ ssh mcgreg
$ cd $HOME/Sandpit
$ git clone https://github.com/gaiusm/pybot-dhewm3
$ exit
```

now recompile doom3

Testing the tool chain

- start the python bot
- \$ cd \$HOME/Sandpit/git-doom3/pybot-dhewm3/python-bot
 - \$ python3 python_doommarine.py 0
- examine the code in \$HOME/Sandpit/git-doom3/pybotdhewm3/python-bot/python_doommarine.py
- look at the code which obtains the label doom3 coordinate
 - the python bot will briefly come to life and then print out the label position