

# **Computer Vision**

## **Fall 2016**

### **Problem Set #3**

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# 1a: Disparity Images (pair0)



$D_L(y,x)$  [matching from left to right] - **ps3-1-a-1.png**



$D_R(y,x)$  [matching from right to left] - **ps3-1-a-2.png**

# 1b: Disparity Images (pair1)



$D_L(y,x)$  [matching from left to right] - ps3-1-b-1.png



$D_R(y,x)$  [matching from right to left] - ps3-1-b-2.png

## 2a: Disparity Images (pair1 noise)



$D_L(y,x)$  [matching from left to right] - ps3-2-a-1.png



$D_R(y,x)$  [matching from right to left] - ps3-2-a-2.png

## 2b: Disparity Images (pair1 contrast)

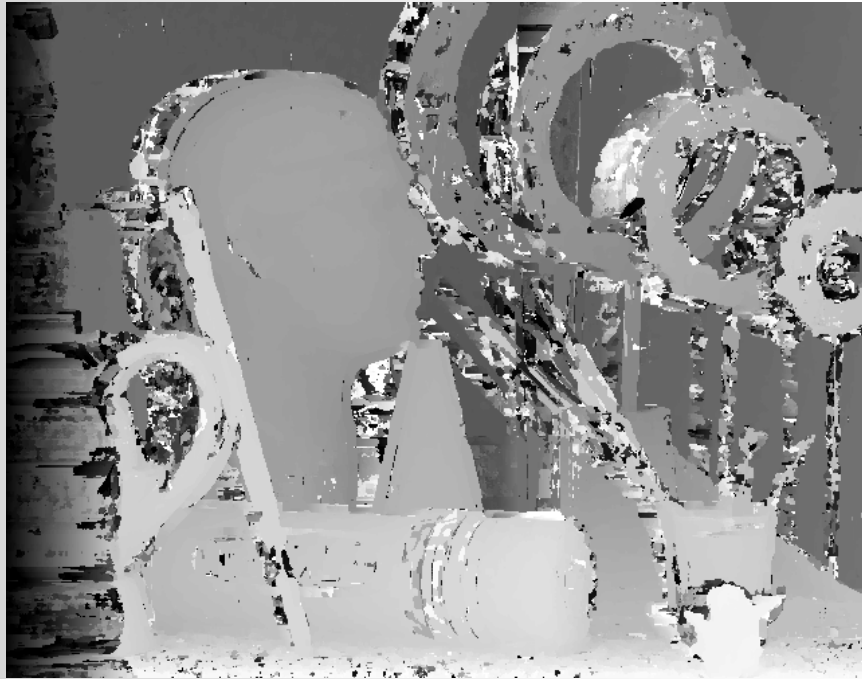


$D_L(y,x)$  [matching from left to right] - **ps3-2-b-1.png**



$D_R(y,x)$  [matching from right to left] - **ps3-2-b-2.png**

# 3a: Disparity Images (pair1 normcorr)



$D_L(y,x)$  [matching from left to right] - **ps3-3-a-1.png**



$D_R(y,x)$  [matching from right to left] - **ps3-3-a-2.png**

### 3b: Disparity Images (pair1 normcorr) using Gaussian noise

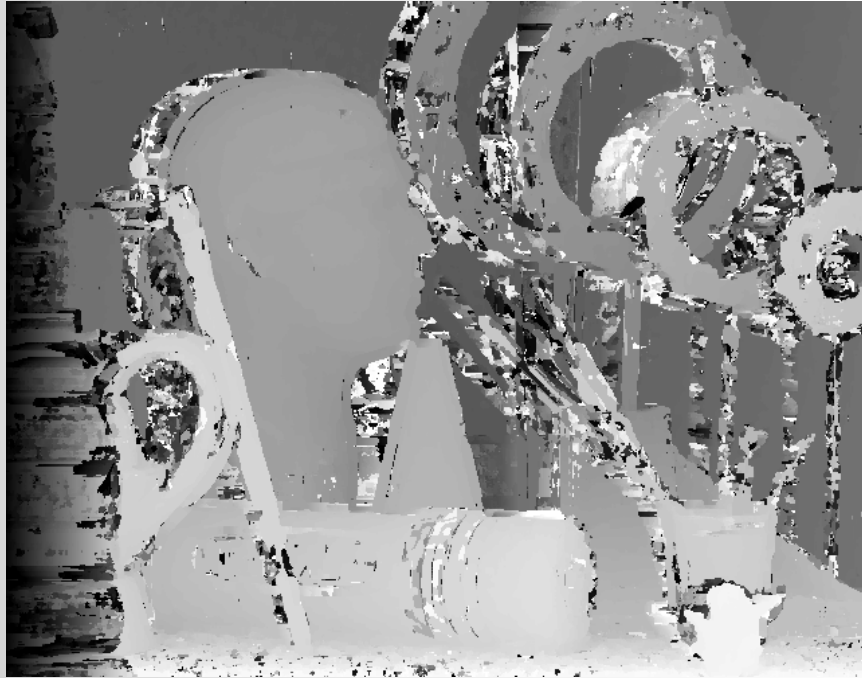


$D_L(y,x)$  [matching from left to right] - **ps3-3-b-1.png**



$D_R(y,x)$  [matching from right to left] - **ps3-3-b-2.png**

### 3b: Disparity Images (pair1 normcorr) using increased contrast



$D_L(y,x)$  [matching from left to right] - **ps3-3-b-3.png**



$D_R(y,x)$  [matching from right to left] - **ps3-3-b-4.png**



# 4a: Disparity Images (pair2)



$D_L(y,x)$  [matching from left to right] - **ps3-4-a-1.png**



$D_R(y,x)$  [matching from right to left] - **ps3-4-a-2.png**

# 5: Discussion

Answer the questions below:

- a. In the input directory are ground truth disparity images pair1-D L.png and pair1-D R.png. Compare your results of the SSD images of 1b and the ground truth. What are the differences that you see? Ans: SSD image does a pretty good job of identifying closer and farther objects. SSD image has lot of white/black strips around the edges of objects, ground truth doesn't have these strips. These strips can be removed either by increasing the window size and maxd.
- b. Now, compare your results of the noisy SSD images of 2a and the ground truth. What are the differences that you see? Ans: Noisy SSD image is slightly dark. It also removes few white/black strips.
- c. How do your normalized correlation image results compare with the SSD image results and with the ground truth? Ans: Discuss the differences that you observe. Normalized correlation image assigns same brightness over all the pixels in an object. Normalized correlation performs better for inputs with higher contrast.
- d. Compare your results of 3a with noisy and contrast-boosted images of 3b. Are there any differences? Ans: Normalized correlation doesn't perform well on noisy images but it performs